From the optical flow constraint equation: Zxu+Zyv+Zt=0 we can get the line equation: $V = \left(\frac{-L_{x}}{Ly}\right)V - \frac{Zz}{Ly}$ Because Unin should perpendicular to the line we can know the slop should be In And Vmin Pass through (0,0) =) the line equation is $V=(\frac{Iy}{I})U$ - (2) The interaction point is ~ V=(型) u-芸y L V = (IV) U $\frac{-I_{x}I_{t}}{I_{x}^{2}tI_{y}}, V = \frac{-I_{y}I_{t}}{I_{x}^{2}tI_{y}^{2}}$ = Vmin = (-IxIt / IxtIy')

$$\left| \frac{1}{V} \right| = \frac{It}{Iy} \times \frac{It}{Ix}$$

$$\left| \frac{(0 - It)^{2} + (-It)^{2}}{Iy} + (\frac{-It}{Ix} - 0)^{2}}{IxIy} \right|$$

$$= \frac{It^{2}}{IxIy} / \sqrt{\frac{It^{2}}{Ix^{2}} + \frac{It^{2}}{Iy^{2}}}$$

$$=\frac{Le^{2}}{I_{x}I_{y}}\left/\frac{Ie^{2}}{\sqrt{I_{x}^{2}I_{y}^{2}}}\left(I_{x}^{2}+I_{y}^{2}\right)\right.$$

$$\frac{2.a}{L(x,y,t)} = e^{\frac{1}{20^{2}}(t^{2} - 2(\frac{x}{k_{1}} + \frac{y}{k_{2}})t + (\frac{x}{k_{1}} + \frac{y}{k_{2}})^{2})}$$

$$= e^{\frac{1}{20^{2}}(t - (\frac{x}{k_{1}} + \frac{y}{k_{2}}))^{2}}$$

$$I_{\chi} = I(\chi, y, t) \left[\frac{1}{2\sigma^{2}} \left(2 \left(t - \left(\frac{\chi}{k_{1}} + \frac{\chi}{k_{2}} \right) \right) \right) \left(\frac{1}{k_{1}} \right) \right]$$

$$= I(\chi, y, t) \left[\frac{1}{k_{1}\sigma^{2}} \left(t - \left(\frac{\chi}{k_{1}} + \frac{\chi}{k_{2}} \right) \right) \right]$$

Similarly

$$I_{y} = I(x, y, t) \left[\frac{1}{k_{2}\sigma^{2}} \left(t - \left(\frac{\chi}{k_{1}} + \frac{\chi}{k_{2}} \right) \right) \right]$$

$$It = \frac{dI}{dt} = I(x, y, t) \left\{ \frac{1}{\sigma^2} \left(t - \left(\frac{x}{k_1} + \frac{y}{k_2} \right) \right) \right\}$$

$$\Rightarrow L(x,y,t) = \frac{1}{\sigma^2} \left(t - \left(\frac{x}{k_1} + \frac{y}{k_2}\right) - \left(\frac{u}{k_1} + \frac{v}{k_2} - 1\right) = 0$$

3.a)
$$I(x_{1}y_{1},t)=I_{0}+\frac{1}{2}\{(x-c_{1}t)^{2}+(y-c_{2}t)^{2}\}$$

$$I_{X}=\frac{dI}{dx}=\frac{1}{2}\cdot(x-c_{1}t)$$

$$=x-c_{1}t$$

$$I_{Y}=\frac{dt}{dy}=\frac{1}{2}\cdot(y-c_{2}t)$$

$$=y-c_{2}t$$

$$I_{C}=\frac{1}{2}\left[2\cdot(-c_{1}(x-c_{1}t))+2\cdot-c_{2}\cdot(y-c_{2}t)\right]$$

$$=-c_{1}x+c_{1}^{2}t-c_{2}y+c_{2}^{2}t$$
b) $I_{X}u+I_{Y}v+I_{C}=0$

$$\exists (x-c_{1}t)u+(y-c_{2}t)v-c_{1}x+c_{1}^{2}t-c_{2}y+c_{2}^{2}t$$

$$\exists (u-c_{1})x+(y-c_{2}t)v-c_{1}x+c_{1}^{2}t-c_{2}y+c_{2}^{2}t$$

$$\exists (u-c_{1})x+(y-c_{2}t)v-c_{1}x+c_{1}^{2}t-c_{2}y+c_{2}^{2}t$$

$$\begin{array}{c}
(4. a) \\
(N(X,Y)) = \begin{cases}
\lambda I_{x}^{2} + 4 & \lambda I_{x}I_{y} \\
\lambda I_{x}I_{y} & \lambda I_{y}^{2} + 4
\end{cases} \\
(N(X,Y)) = \begin{cases}
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from a) we know

$$\frac{1}{4} = \frac{1}{4\lambda I_{\chi}^{2} + 4\lambda I_{y}^{2} + 16} \left[(\lambda I_{y}^{2} + 4)(\sum u^{old} - \lambda I_{x}I_{t} + (-\lambda I_{x}I_{y})(\sum v^{old} - \lambda I_{y}I_{t}) \right] + (-\lambda I_{x}I_{y})(\sum v^{old} - \lambda I_{y}I_{t})$$

$$= \frac{1}{4\lambda I_{\chi}^{2} + 4\lambda I_{y}^{2} + 16} \left(\lambda I_{y}^{2} \sum u^{old} + 4\sum u^{old} - \lambda I_{x}I_{y}I_{t} \right)$$

$$= \frac{1}{4\lambda I_{\chi}I_{t} - \lambda I_{\chi}I_{y}} \left(\lambda I_{y}^{2} \sum u^{old} + 4\sum u^{old} - 4\lambda I_{\chi}I_{t} \right)$$

$$= \frac{1}{I_{\chi}^{2} + I_{y}^{2} + \frac{4}{\lambda}} \left(\lambda I_{y}^{2} \sum u^{old} + 4\sum u^{old} - 4\lambda I_{\chi}I_{t} \right)$$

$$= \frac{1}{I_{\chi}^{2} + I_{y}^{2} + \frac{4}{\lambda}} \left(I_{\chi}^{2} \frac{\sum u^{old}}{4} + \frac{4}{\lambda} \frac{\sum u^{old}}{4} - I_{\chi}I_{t} - I_{\chi}I_{y} \frac{\sum u^{old}}{4} \right)$$

$$= \frac{1}{I_{\chi}^{2} + I_{y}^{2} + \frac{4}{\lambda}} \left(I_{\chi}^{2} \frac{u^{old}}{4} - I_{\chi} \frac{1}{4} - u^{old}} - I_{\chi}I_{t} - I_{\chi}I_{y} \frac{u^{old}}{4} \right)$$

$$= \frac{1}{I_{\chi}^{2} + I_{y}^{2} + \frac{4}{\lambda}} \left(I_{\chi}^{2} \frac{u^{old}}{4} - I_{\chi} \frac{1}{4} - u^{old}} - I_{\chi} \left(I_{\chi} \frac{u^{old}}{4} + I_{\chi} \frac{u^{old}}{4} - I_{\chi} \frac{u^{old}}{4} \right)$$

$$= \frac{1}{I_{\chi}^{2} + I_{y}^{2} + \frac{4}{\lambda}} \left(I_{\chi}^{2} \frac{u^{old}}{4} - I_{\chi} \frac{u^{old}}{4} - I_{\chi} \left(I_{\chi} \frac{u^{old}}{4} + I_{\chi} \frac{u^{old}}{4} - I_{\chi} \left(I_{\chi} \frac{u^{old}}{4} + I_{\chi} \frac{u^{old}}{4} \right) \right)$$

$$= \frac{1}{I_{\chi}^{2} + I_{y}^{2} + \frac{4}{\lambda}} \left(I_{\chi}^{2} + I_{\chi}^{2} + \frac{4}{\lambda} \frac{u^{old}}{4} - I_{\chi} \left(I_{\chi} \frac{u^{old}}{4} + I_{\chi} \frac{u^{old}}{4} - I_{\chi} \left(I_{\chi} \frac{u^{old}}{4} + I_{\chi} \frac{u^{old}}{4} \right) \right)$$

$$= \frac{-old}{U} - \frac{I_{x}}{Z_{x+}^{2}L_{y} + \frac{\pi}{\lambda}} \left(I_{x} u^{old} + I_{y} v^{old} + I_{t} \right)$$

with same process, V can proof

c)
$$u^{\text{rew}} = \frac{-old}{I_x^2 + I_y^2 + \frac{4}{\lambda}} \left(I_x u + I_y v + I_t \right)$$

When 1=0