There are 4 possible connectivity relations.

- 8 connected, if only one dimension changes.

In this case, neighbors are (x+1, y, Z,t), (x, y+1, z,t), (x, y, Z+1,t) f (x, y, z, t+1) - 32 connected, if one or two dimensions change. In this case neighbors are all from the 8-connected plus 24 (x+1, y+1, z,t), (x, y+1, z+1,t), (x+1, y, z+1,t), (x, y, Z±1, ±±1), (x±1, y, z, ±±1), (x, y±1, 2, ±±1) - 64 connected if three dimensions - 80 - Connected it all dimensions com change.

A is the transformation matrix. A forms a seperate hemogenous coordinate

A point p in 2 different coordinate frames

with different basis years and defined by Similarly

Where BR is rotation from frame (B) to Other frame (A)

3 a) the background and object are equally likely
$$\frac{k}{T_0^2} = \frac{k^2}{T_0^2} = \frac{k^2}{T_0^2} = \frac{V_0^2}{T_0^2}$$

$$\frac{\nabla_b^2}{\nabla_0^2} = e^{\frac{2}{2}\nabla_0^2} - \frac{|e^2|}{2\nabla_b^2}$$

$$\frac{|e^2|}{\nabla_0^2} = e^{\frac{2}{2}\nabla_0^2} - \frac{|e^2|}{2\nabla_b^2}$$

$$|e^2| = e^{\frac{2}{2}\nabla_0^2} - \frac{|e^2|}{2\nabla_b^2}$$

$$|e^2| = e^{\frac{2}{2}\nabla_0^2} - \frac{|e^2|}{2\nabla_b^2}$$

$$\frac{2 \ln (\frac{T_{b}}{T_{0}}) = \frac{12}{2T_{0}^{2}} \frac{1}{2T_{b}^{2}}$$

$$\frac{2}{2T_{0}^{2}} \frac{1}{2T_{0}^{2}} \frac{1}{2T_{0}^{2}}$$

$$\frac{2}{2T_{0}^{2}} \frac{1}{2T_{0}^{2}} \frac{1}{2T_{0}^{2}} \frac{1}{2T_{0}^{2}}$$

$$\frac{2}{T_{0}^{2} - T_{0}^{2}}$$

b) No Polh) = No Poll)

So
$$N_0 \frac{k^2}{V_0^2} e^{\frac{k^2}{2V_0^2}} = N_b \frac{k}{V_b^2} e^{\frac{k^2}{2V_b^2}}$$

$$\frac{N_0 V_b^2}{N_b V_0^2} = e^{\frac{k^2}{2V_0}} - \frac{k^2}{2V_b^2}$$

$$\frac{N_0 V_b^2}{N_b V_0^2} = e^{\frac{k^2}{2V_0}} - \frac{k^2}{2V_b^2}$$

$$\frac{N_0 V_b^2}{N_b V_0^2} = e^{\frac{k^2}{2V_0}} - \frac{k^2}{2V_b^2}$$

$$\frac{N_0 V_b^2}{N_b V_0^2} = e^{\frac{k^2}{2V_b^2}} - \frac{k^2}{2V_b^2}$$