

Convolutional Neural Networks

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Outline

Doubts About Feed-forward NN

Convolutional Neural Networks (CNN)

- CNN Motivation

- Sample CNN Architecture

Main Components of the CNN Architecture

- The Input Layer

- The Convolution Layer

- Summary of the Convolution Layer

 - The Activation Layer

 - The Pooling Layer

- Fully Connected Layer

Next - Regularization in CNN and sample Implementation

References

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Convolutional Neural Networks - Motivation

- ▶ Specifically designed to handle image classification.
- ▶ Why not use regular FFNN?
 - ▶ Images are high-dimensional vectors.
 - ▶ It would take a large number of parameters to characterize the network
- ▶ Why not flatten² the images and pass it in as a vector?
 - ▶ Distortion of the spatial features of the image(i.e. a three dimensional object will be compressed into a one dimensional object, huge loss of information).
- ▶ How does CNN address these shortfalls?

²This will eventually be done, but after we've learnt a lot about the spatial composition of the image.

Sample CNN Architecture

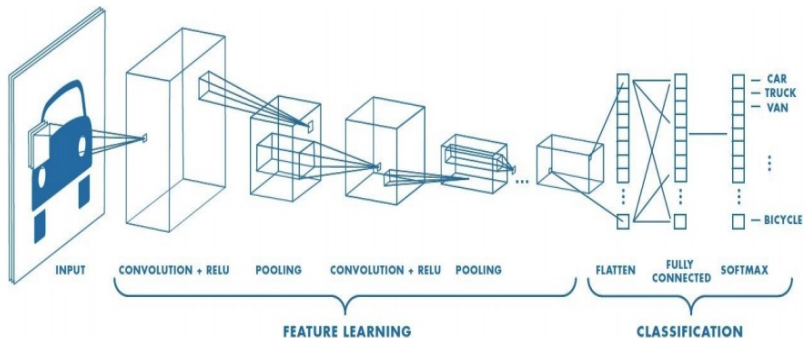


Figure: Sample CNN Architecture. (Source: Google)

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The Input Layer

- ▶ An input will simply be a raw pixels values of an image.
- ▶ Convert the image to it's matrix representation.

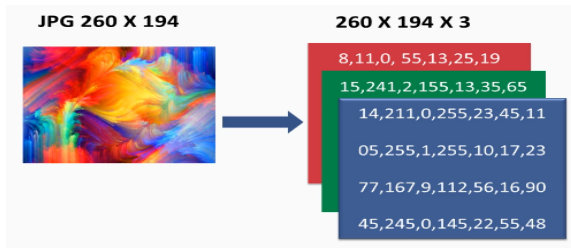


Figure: Sample Image Representation (Source: Google)

- ▶ The depth refers to the color channels(in this case 3, RGB), the height and width in pixels is given by the dimensions of the input image.

The Convolution Layer

- ▶ Pick a local region within the image.
- ▶ Pass the representation of that region to a neuron in the CONV layer.
- ▶ Convert the image to it's matrix representation.
- ▶ The neuron then apply a set of filters.
- ▶ What are filters?
 - ▶ These are a set of learnable weights (can be learned via BP).
 - ▶ These vector of weights (convolve?) the input.
 - ▶ That's, it provides a measure of how close a patch of input is to a feature (e.g. arch, edge).

Example of a Convolved Feature

- Assume we take a local region of the image represented by this 5×7 matrix³, and we want to extract a feature of size 3×3 .

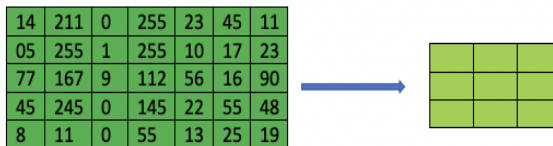


Figure: Initial Representation (1 Channel)

- Then we can define the **stride** size to control how we move or slide around the window. If we choose a stride of size 1, the convolved feature will proceed as follows.

³This has to be a square matrix by design to maintain symmetry

Example of a Convolved Feature

► First slide

14	211	0	255	23	45	11
05	255	1	255	10	17	23
77	167	9	112	56	16	90
45	245	0	145	22	55	48
8	11	0	55	13	25	19

This should be included - zeros

4		

► Second slide

14	211	0	255	23	45	11
05	255	1	255	10	17	23
77	167	9	112	56	16	90
45	245	0	145	22	55	48
8	11	0	55	13	25	19

4	13	

► Third slide

14	211	0	255	23	45	11
05	255	1	255	10	17	23
77	167	9	112	56	16	90
45	245	0	145	22	55	48
8	11	0	55	13	25	19

4	13	0

Example of a Convolved Feature

- ▶ We then repeat the same process for the other two channels.
- ▶ We can add more filters by defining additional weight matrices.
- ▶ Three set of parameters control the output volume.
 - ▶ The depth (number of filters)
 - ▶ If we assume this is the initial layer, we can represent the filter(weight) matrix of the first channel as $w_0[:, :, :, 0]_{4 \times 3 \times 1}$.
 - ▶ Similarly, the weight matrix of the 2nd and 3rd channel will be $w_0[:, :, :, 1]_{4 \times 3 \times 1}$ & $w_0[:, :, :, 2]_{4 \times 3 \times 1}$.
 - ▶ The weight matrix of the entire first layer W_0 will be of size $4 \times 3 \times 3$.
 - ▶ The stride
 - ▶ The zero-padding

Summary of the Convolution Layer

- ▶ Accept an input of size $W_i \times H_i \times D_i$, width, height, and dimension.
- ▶ Requires 4 hyperparameters:
 - ▶ Filter size K
 - ▶ The receptive field F (size of the local region covered at each stride).
 - ▶ Stride size (S).
 - ▶ The amount of zero padding (P).
- ▶ Produce an output volume of size $W_{i+1} \times H_{i+1} \times D_{i+1}$.
 - ▶ $W_{i+1} = (W_i - F + 2P)/S + 1$
 - ▶ $H_{i+1} = (H_i - F + 2P)/S + 1$
 - ▶ $D_{i+1} = K$

The Activation Layer

- ▶ This is basically used to improve the non-linearity of the network without affecting the receptive fields.
- ▶ ReLU⁴ (and its improved version Leaky ReLU) is often used.
- ▶ What exactly is the neuron that is been activated?
 - ▶ Anytime you take a dot product of a filter and a local region to produce a 3D volume (in this instance) is a neuron.

⁴Results in faster training

The Pooling Layer

- ▶ The feature output from the convolution layer are sensitive to the location of the region in the image. Shifts, change in resolution could lead to different feature mapping.
- ▶ A common approach to dealing with this is down sampling (DS).
- ▶ DS can be achieved by changing the stride size across the image.
- ▶ A more robust⁵ method is "pooling".

⁵Does not require retraining of the initial input

The Pooling Layer

- ▶ How does pooling work?
 1. Select a feature map, which simply an output from a neuron.
 2. Map a lower dimensional representation of that feature space.
 3. Apply a pooling method to the mapped-out feature space.
- ▶ Two common pooling methods:
 - ▶ Average Pooling: Simply calculate the average if each feature map.
 - ▶ Maximum Pooling: You take the maximum within each feature map.

Fully Connected Layer

- ▶ This is where classification takes place.
- ▶ At this layer, you apply regular neural network architecture to the flatten representation of the learned 33D features.
- ▶ Classification works the same as in normal neural networks!

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Regularization in CNN and Sample Implementation

- ▶ (Next week - 03/04)

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References

References

1. Pattern Recognition and Machine Learning ~ M. Bishop
 - ▶ Chapter 5.5
2. A Gentle Introduction to Backpropagation ~ S. Shashi
 - ▶ [Click to Access](#)