What is Muller's Method?

Muller's Method is a numerical method used to find the roots of a polynomial or a nonlinear equation, especially when:

- The function is not easily solvable using other methods like bisection or Newton-Raphson.
- The root is complex (imaginary).

It **uses a quadratic interpolation** technique to approximate the function and then find the root of that quadratic equation.

Given three initial guesses:

$$x_0, x_1, x_2$$

We:

1. Fit a quadratic polynomial through those points:

$$f(x_0), f(x_1), f(x_2)$$

- 2. Find the root of that quadratic polynomial (just like solving $ax^2 + bx + c = 0$).
- 3. Use the root as a new approximation x_3 , and repeat the process until convergence.

Mathematical Formulas

Step 1: Define three initial points

$$x_0, x_1, x_2$$
 (initial guesses)

Step 2: Compute differences

Let:

$$h_1=x_1-x_0,\quad h_2=x_2-x_1 \ \delta_1=rac{f(x_1)-f(x_0)}{x_1-x_0},\quad \delta_2=rac{f(x_2)-f(x_1)}{x_2-x_1} \ d=rac{\delta_2-\delta_1}{h_2+h_1}$$

Step 3: Form the quadratic polynomial

The quadratic is of the form:

$$f(x)pprox a(x-x_2)^2+b(x-x_2)+c$$

Step 4: Solve the quadratic for root

$$x=x_2+rac{-2c}{b\pm\sqrt{b^2-4ac}}$$

Choose the denominator with larger magnitude (to avoid division by a small number):

Use sign of b: Denominator $= b + \mathrm{sign}(b) \cdot \sqrt{b^2 - 4ac}$

Step 5: Update the guess

$$x_3=x_2+rac{-2c}{b\pm\sqrt{b^2-4ac}}$$

Step 6: Repeat the steps

Continue the iteration until:

$$|x_{n+1}-x_n|<\epsilon \quad ext{(some small tolerance)}$$

Problem-01:

Find a root of an equation $f(x)=2x^3-2x-5$ using Muller Method

We need 3 initial guesses, say:

$$x_0 = 1, \quad x_1 = 2, \quad x_2 = 3$$

Let's calculate their function values:

$$f(x)=2x^3-2x-5$$
 $f(x_0)=f(1)=2(1)^3-2(1)-5=2-2-5=-5$ $f(x_1)=f(2)=2(8)-4-5=16-4-5=7$ $f(x_2)=f(3)=2(27)-6-5=54-6-5=43$

Let:

$$h_1 = x_1 - x_0 = 2 - 1 = 1$$
 $h_2 = x_2 - x_1 = 3 - 2 = 1$
 $\delta_1 = \frac{f(x_1) - f(x_0)}{x_1 - x_0} = \frac{7 - (-5)}{1} = 12$
 $\delta_2 = \frac{f(x_2) - f(x_1)}{x_2 - x_1} = \frac{43 - 7}{1} = 36$
 $d = \frac{\delta_2 - \delta_1}{h_2 + h_1} = \frac{36 - 12}{2} = \frac{24}{2} = 12$

We now use point $x_2 = 3$ as our base point.

$$a = d = 12$$
 $b = \delta_2 + h_2 \cdot d = 36 + 1 \cdot 12 = 48$ $c = f(x_2) = f(3) = 43$

$$x = x_2 + \frac{-2c}{b \pm \sqrt{b^2 - 4ac}}$$

First calculate:

$$\sqrt{b^2 - 4ac} = \sqrt{48^2 - 4(12)(43)} = \sqrt{2304 - 2064} = \sqrt{240} \approx 15.49$$

We now calculate two possible denominators:

•
$$b + \sqrt{...} = 48 + 15.49 = 63.49$$

•
$$b - \sqrt{...} = 48 - 15.49 = 32.51$$

We choose the one with the larger magnitude (to avoid division by small number): So, denominator = 63.49

Now compute:

$$x_3 = 3 + rac{-2(43)}{63.49} = 3 - rac{86}{63.49} pprox 3 - 1.3545 = 1.6455$$

Now use new three points:

•
$$x_0 = 2$$

•
$$x_1 = 3$$

•
$$x_2 = 1.6455$$

Then repeat Steps 2–4 with updated values.

After repeating the steps, the **root converges to** approximately:

x≈1.6006

(Accurate up to 4 decimal places)

Definition:

Muller's Method is an **iterative root-finding technique** that uses a **quadratic interpolant** through three points to approximate a root of the equation:

$$f(x)=0$$

At each iteration, a quadratic polynomial is constructed using three previous approximations, and the root of this polynomial (closest to the last approximation) is taken as the next estimate.

Let the current approximations be:

$$x_1, x_2, x_3$$

With corresponding function values:

$$f_1 = f(x_1), \quad f_2 = f(x_2), \quad f_3 = f(x_3)$$

Define the differences:

$$h_1 = x_1 - x_3, \quad h_2 = x_2 - x_3$$

$$d_1 = f_1 - f_3, \quad d_2 = f_2 - f_3$$

Let the denominator for the interpolation be:

$$D = h_1 \cdot h_2 \cdot (h_1 - h_2)$$

The coefficients of the quadratic polynomial:

$$P(x) = a_0 + a_1(x - x_3) + a_2(x - x_3)^2$$

Are given by:

$$a_0 = f_3$$
 $a_1 = rac{d_2 h_1^2 - d_1 h_2^2}{D}$ $a_2 = rac{d_1 h_2 - d_2 h_1}{D}$

Since $P(x_4) = 0$, we solve:

$$a_0 + a_1(x_4 - x_3) + a_2(x_4 - x_3)^2 = 0$$

Let $\Delta=x_4-x_3$, then:

$$\Delta = rac{-2a_0}{a_1 \pm \sqrt{a_1^2 - 4a_0a_2}}$$

Choose the sign in the denominator so that the absolute value of the denominator is maximized (to improve numerical stability).

Thus, the next approximation is:

$$x_4 = x_3 + \Delta = x_3 + rac{-2a_0}{a_1 \pm \sqrt{a_1^2 - 4a_0a_2}}$$

Iterative Algorithm Steps:

1. Choose initial guesses:

 x_1, x_2, x_3 close to the desired root.

- 2. Compute f_1, f_2, f_3
- 3. Form h_1, h_2, d_1, d_2, D
- 4. Compute coefficients a_0, a_1, a_2
- 5. Evaluate:

$$x_4 = x_3 + rac{-2a_0}{a_1 + ext{sgn}(a_1) \cdot \sqrt{a_1^2 - 4a_0a_2}}$$

6. Update:

$$(x_1,x_2,x_3) \leftarrow (x_2,x_3,x_4)$$

7. Repeat until:

$$|f(x_4)| < \text{tolerance}$$

$$f(x) = x^3 + 2x^2 + 10x - 20 = 0$$

Iteration 1:

Let:

$$x_1 = 0, \quad x_2 = 1, \quad x_3 = 2$$
 $f_1 = -20, \quad f_2 = -7, \quad f_3 = 16$
 $h_1 = -2, \quad h_2 = -1$
 $d_1 = -36, \quad d_2 = -23$
 $D = (-2)(-1)((-2) - (-1)) = -2$
 $a_0 = 16$
 $a_1 = \frac{-23 \cdot (-2)^2 - (-36) \cdot (-1)^2}{-2} = \frac{-92 - 36}{-2} = \frac{-128}{-2} = 64$
 $a_2 = \frac{-36 \cdot (-1) - (-23) \cdot (-2)}{-2} = \frac{36 - 46}{-2} = \frac{-10}{-2} = 5$

Discriminant:

$$\sqrt{a_1^2 - 4a_0a_2} = \sqrt{64^2 - 4\cdot 16\cdot 5} = \sqrt{4096 - 320} = \sqrt{3776} pprox 61.43$$

Denominator choice (larger magnitude):

$$64+61.43pprox125.43$$
 $x_4=2-rac{2\cdot 16}{125\cdot 43}pprox2-0.2559=1.7441$

Repeat using:

$$x_1 = 1, \quad x_2 = 2, \quad x_3 = x_4$$

Eventually, you will converge to the root:

$$x \approx 1.36808$$

Feature	Version 1 (Earlier Given)	Version 2 (Later, Textbook Style)
Reference Points	x_0,x_1,x_2	x_1,x_2,x_3
Formula Style	Based on finite difference + Newton form	Based on quadratic interpolation through 3 points
Root Formula	$x_3=x_2+rac{-2c}{b\pm\sqrt{b^2-4ac}}$	$x_4=x_3+rac{-2a_0}{a_1\pm\sqrt{a_1^2-4a_0a_2}}$
Coefficients	$a=d, b=\delta_2+h_2d, c=f(x_2)$	Interpolated a_0, a_1, a_2 from divided differences
Use of Notation	Simple polynomial-fitting	General interpolation form using D,h_1,h_2,d_1,d_2

1. Solve
$$x^3 - x - 2 = 0$$
 with $x_1 = 1$, $x_2 = 1.2$, $x_3 = 1.4$.

2. Solve
$$g(x) = 1 + 2x - \tan x = 0$$
 with $x_1 = 1.5$, $x_2 = 1.4$, $x_3 = 1.3$.