



Singleton

Static func. can be called ~~after~~ before obj. formation.

A class with a single obj.

~~class SO { }~~

~~bool checkObj() { }~~

~~class SO {
static bool flag;
SO() { if (flag == 0)
flag = 1;
};~~

~~SO::static flag = 0~~

class Main {
private:

Main() { }

static Main* obj; ~~static~~

public:

static Main* getIns() {

if (obj == null)

obj = new Main();

return obj; }

} ; static Main* Main::obj = null; (Initialize out of class)

void foo() { Main* p1 = Main::getIns();

void bar() { Main* p2 = Main::getIns(); }

State Design Offline

```
class Book {
    int state;
    bool issue (Mem * m)
    { if (state == AVA) {
      -----

```

```
      (A) state = ISS;
           return true;
    }

```

```
      (B) else return false;
    }

```

Book

Multiple books
obj. * 1 state obj

State

Abstract class

```
bool ret() {
    if (state == ISS)
    { state = AVA
      (C) return true;
    }
    else
    (D) return false;
}

```

issue(---) = 0
ret() = 0

These classes are singleton classes.
So no need to create & delete obj.

(B) ISS

B issue(...)
ret(...)
(C)

(A) AVA

A issue(...)
ret(...)
(D)

(B) RBL

B issue(...)
ret(...)
(D)

Reference Book

```
int main() {

```

```
    Book bl(---);

```

```
    bl.setState(new AVA());

```

```
    bl.setState(new ISS());
}

```

Refactor:

```
struct File{  
    char * name;  
    int size;  
}  
int comsiz ( File *f ) {  
    return f->size; }  
}
```

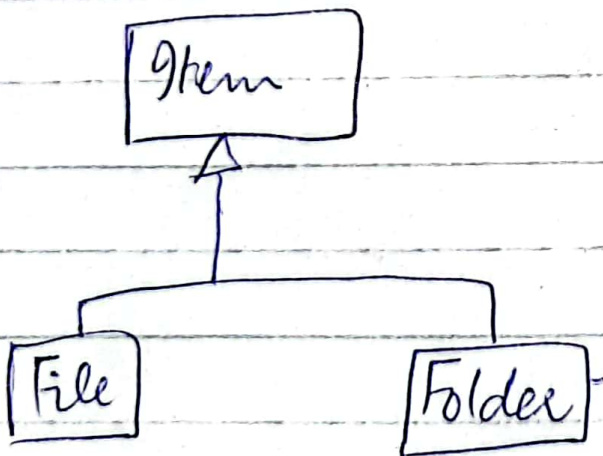
```
struct Folder {  
    char * name;  
    File * a[m];  
    Folder * b[n];  
}  
int comsize ( Folder *f ) {  
    int sum=0;  
    for ( i=1 ; i<m ; i++ ) {  
        sum += comsiz ( f->a[i] );  
    }  
    for ( j=1 ; j<n ; j++ ) {  
        sum += comsiz ( f->b[j] );  
    }  
    return sum;  
}
```


login

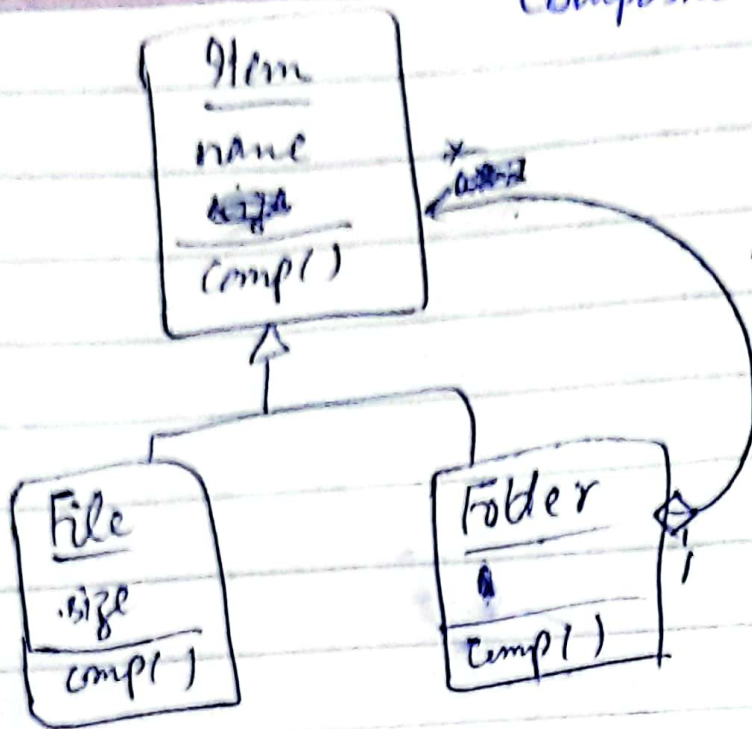
OOP used:

S → B
B → bdsx

```
class Item {  
    char * name;  
    virtual int compsize() = 0;  
};  
class File: public Item {  
    int size;  
    int compsize() { return size; }  
};  
class Folder: public FileItem {  
    Item * a[N];  
    int compsize() {  
        int sum = 0;  
        for (int i = 0; i < N; i++)  
            sum += a[i] → compsize();  
        return sum; }  
}
```

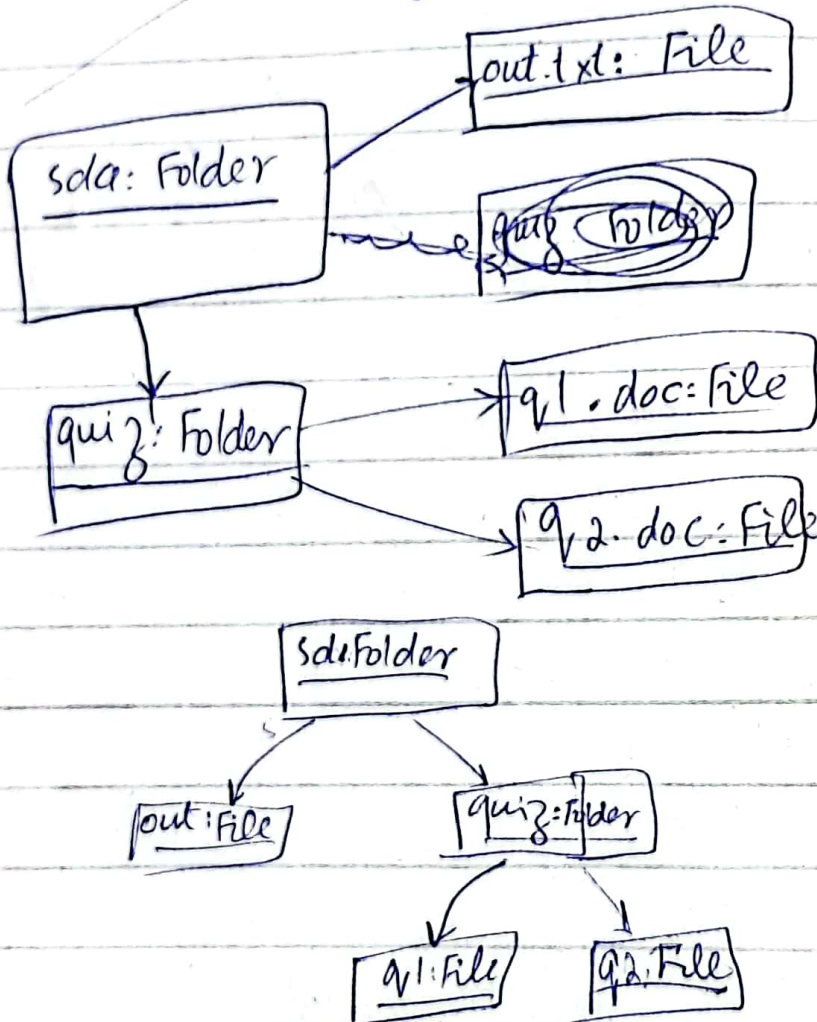


Composite Pattern



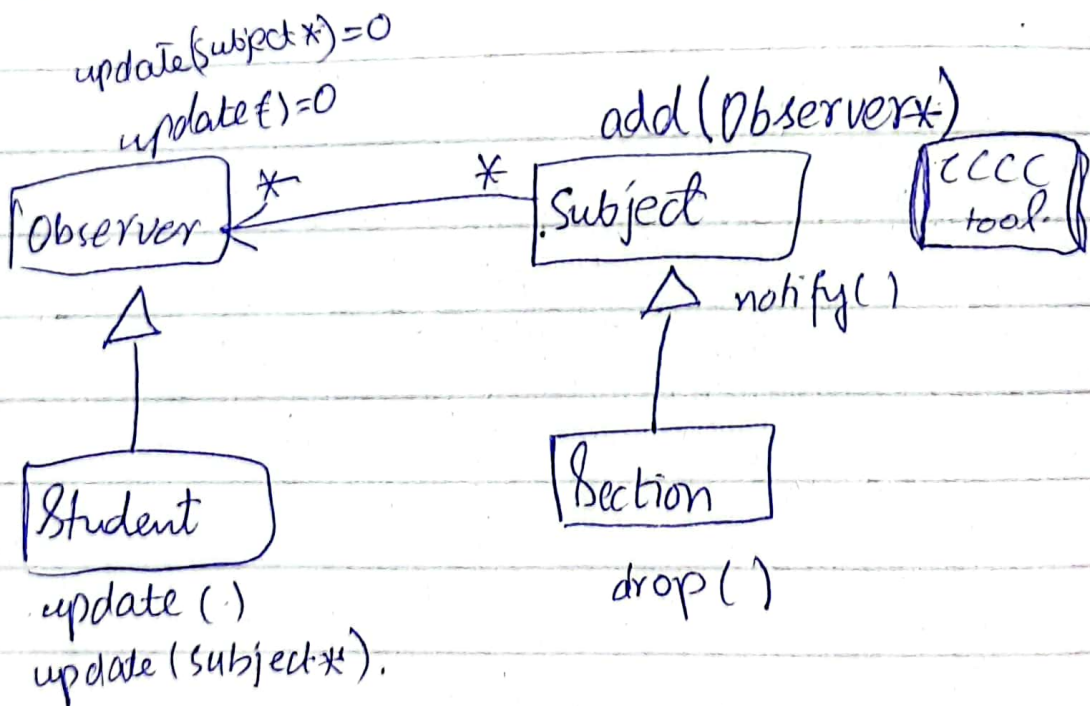
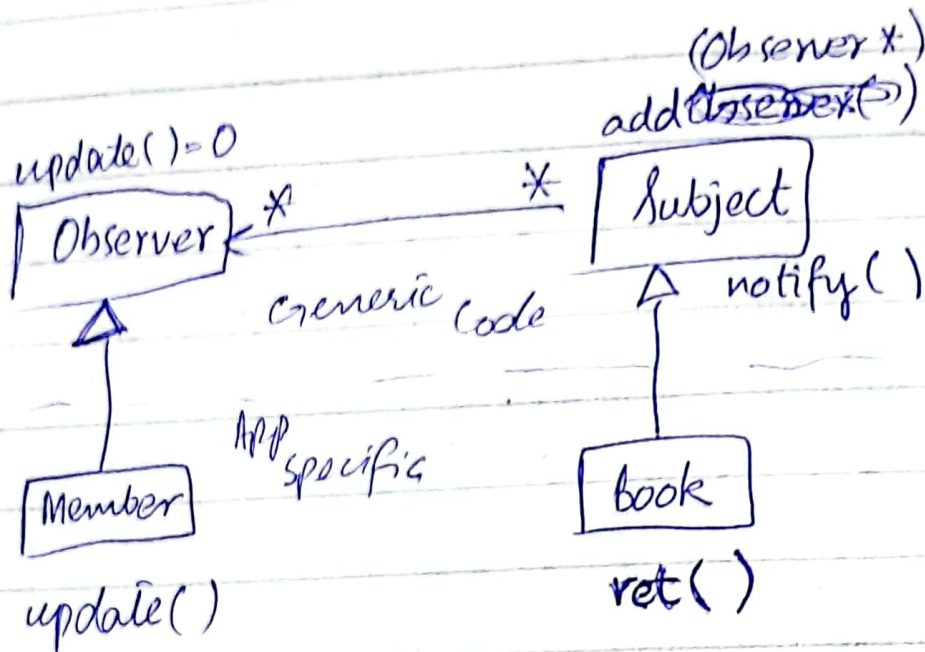
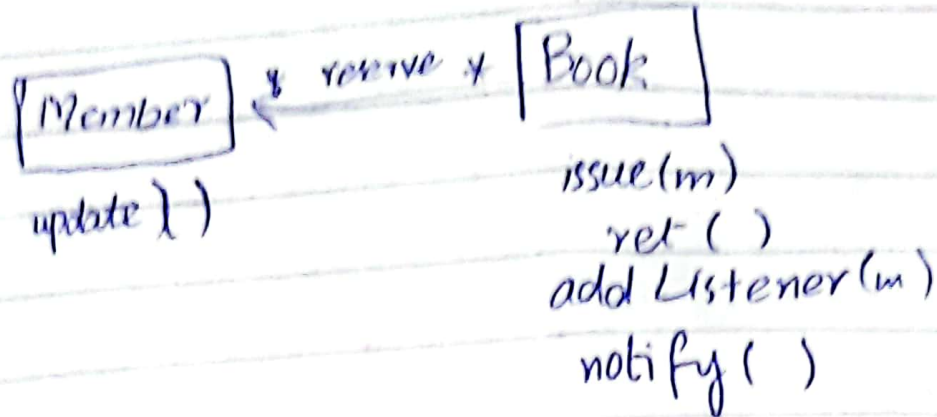
Showing recursion that can see in previous code without COP

Object Diagram



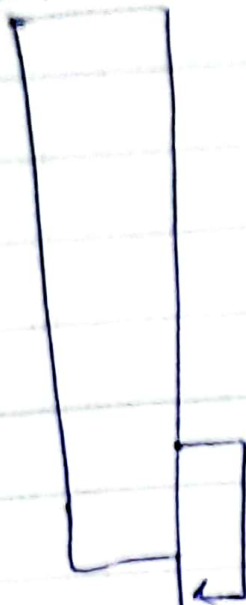
Observer Design Pattern

Notify all members when book return



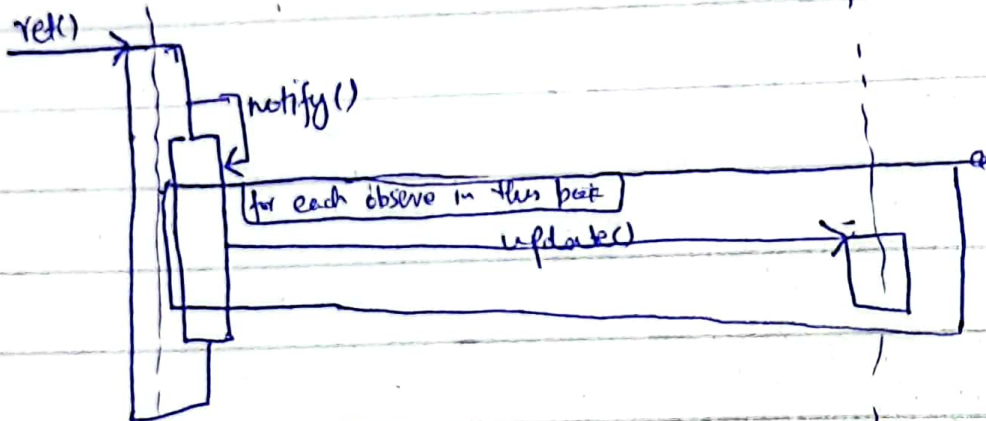
b: Book

m: Member



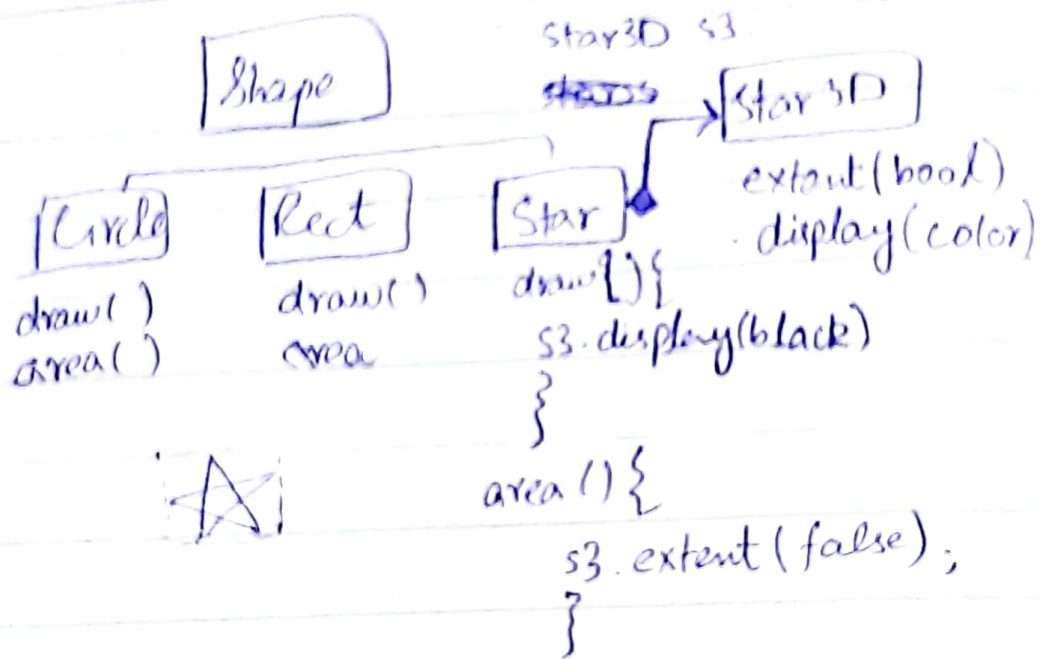
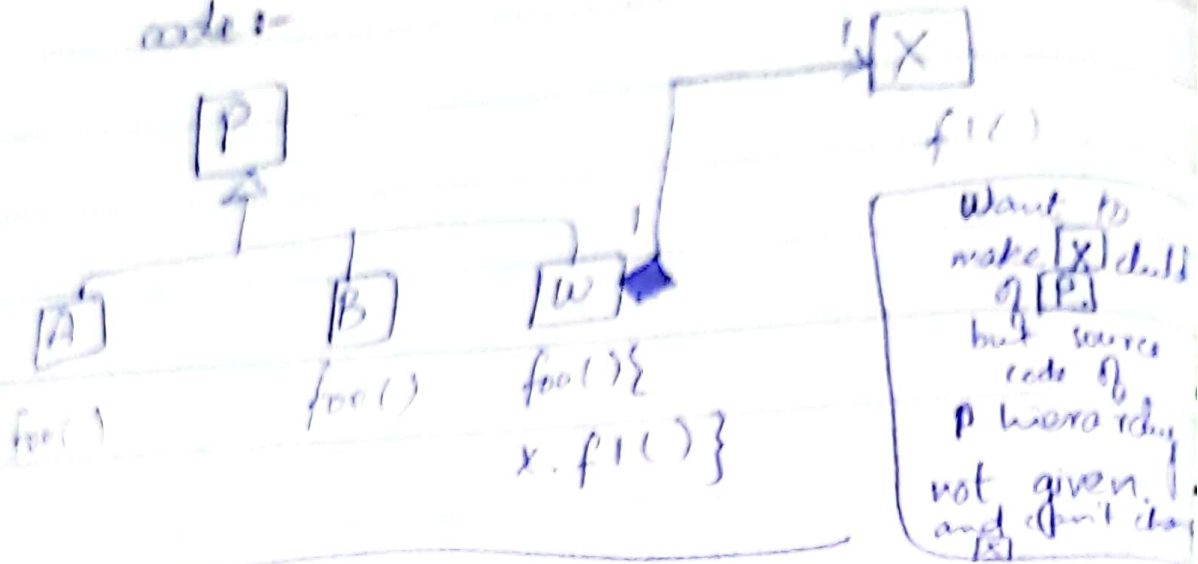
b: book

m: weber



Adapter Pattern / Wrapper Pattern

How to plug a class into an inheritance hierarchy without changing code:-



Vector []

Friend class Iterator {
int data;

has next() = 0
next() = 0

Iterator



VectIt

hasnext()
next()

ListIt

hasnext()
next()

class VectIt {

next() {

class ListIt {

next() {

this -> data;

}

hasnext() {

class Vector {

int * a[N];

int max;

int no;

friend VectInt;

28/11

SDA

```
int sum(Vector *vec)
{
    int s=0;
    for (int i=0; i<vec->n; i++) {
        s = s + (vec->a[i]);
    }
    return s;
}
```

For every data structure we ~~should~~ have to write separate sum func.

} write code sum that works for each data structure

```
int sum(Iterator* it) {
    int s=0;
    while (it->hasNext()) {
        s = s + it->next();
    }
    return s;
}
```

~~class Iterator {~~
~~int data;~~
~~Iterator() {~~
~~data = 0;~~
~~next() {~~
~~return data;~~
~~}~~
~~}~~

→ data value

```
class VecIt : public Iterator {
```

```
    Vector * vec;
```

```
    int i;
```

```
    VecIt ( Vector * v ) {
```

```
        vec = v;
```

```
        i = 0; }
    bool hasNext() {
```

```
        return ( i < vec->no );
```

```
    }
    int {next() {
```

```
        vec->a[i++];
```

```
    }
```

```
};
```

```
List {
```

```
    Node * head;
```

```
    friend ListIt;
```

```
ListIt {
```

```
    Node * next;
```

```
    int data;
```

