Chapter Goals

- Describe the two main responsibilities of an operating system
- Define memory and process management
- Explain how timesharing creates the virtual machine illusion
- Explain the relationship between logical and physical addresses
- Compare and contrast memory management techniques

Chapter Goals

- Distinguish between fixed and dynamic partitions
- Define and apply partition selection algorithms
- Explain the stages and transitions of the process life cycle
- Explain the processing of various CPU scheduling algorithms

Software Categories

Application software

Software written to address specific needs—to solve problems in the real world

System software

Software that manages a computer system at a fundamental level

Can you name examples of each?

Operating system

System software that

- manages computer resources, such as CPU, memory and input/output devices
- provides an interface through which a human can interact with the computer
- allows an application program to interact with these other system resources

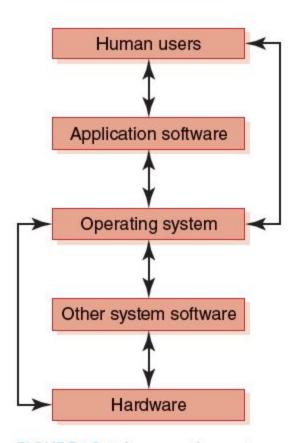


FIGURE 10.1 An operating system interacts with many aspects of a computer system.

What operating systems have you used?

Booting

Hardware is wired to initially load a small set of system instructions stored in ROM

These instructions load a larger set of instructions from hard disk

Dual boot – Multiboot

The various roles of an operating system generally revolve around the idea of "sharing nicely"

An operating system manages resources, and these resources are often shared in one way or another among programs that want to use them

Resource Management

Multiprogramming

The technique of keeping multiple programs that compete for access to the CPU in main memory at the same time so that they can execute

Memory management

The process of keeping track of what programs are in memory and where in memory they reside

Resource Management

Process

A program in execution

Process management

The act of carefully tracking the progress of a process and all of its intermediate states

CPU scheduling

Determining which process in memory is executed by the CPU at any given point

Batch Processing

The first operating system was a human operator, who organized various jobs from multiple users into *batches* of jobs that needed the same resources

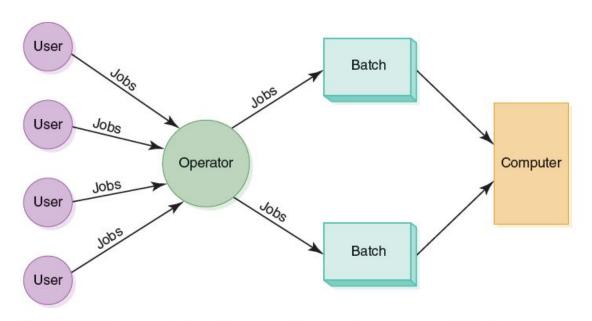


FIGURE 10.3 In early systems, human operators would organize jobs into batches

Timesharing

Timesharing system

A system that allows multiple users to interact with a computer at the same time

Virtualization

Virtualization is the process of running a virtual instance of a computer system in a layer abstracted from the actual hardware. Most commonly, it refers to running operating systems being run in a virtual environment.

Other Factors

Real-time System

A system in which response time is crucial given the nature of the application

Response time

The time delay between receiving a stimulus and producing a response

Device driver

A small program that "knows" the way a particular device expects to receive and deliver information

Memory Management

Operating systems must employ techniques to

- Track where and how a program resides in memory
- Convert logical addresses into actual addresses

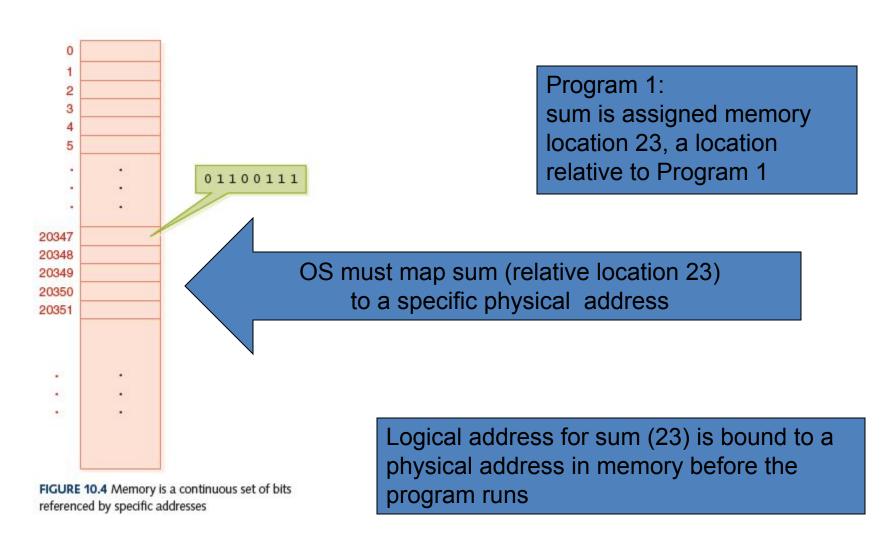
Logical address

Reference to a stored value relative to the program making the reference

Physical address

Actual address in main memory

Memory Management



Single Contiguous MM

Operating system

Application program

FIGURE 10.5 Main memory divided into two sections There are only two programs in memory

The operating system

The application program

This approach is called single contiguous memory management

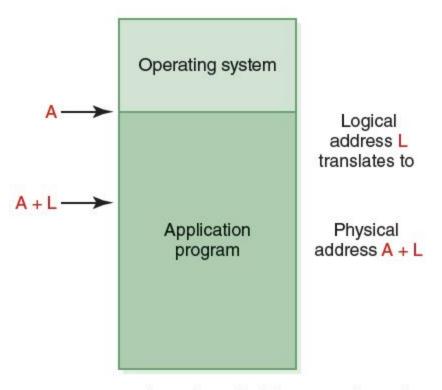
Single Contiguous MM

In concrete terms:

A logical address is simply an integer value relative to the starting point of the program A physical address is a logical address added to the starting location of the program in main memory

Advantages – Disadvantages ? - Flexibility

Single Contiguous MM



If A is location 100, and the application program is Program 1, then sum is stored at location 123.

FIGURE 10.6 Binding a logical address to a physical address

Partition Memory Management

Single contiguous MM has only the OS and one other program in memory at one time

Partition MM has the OS and any number of other programs in memory at one time

There are two schemes for dividing up memory for programs:

- Fixed partitions Main memory is divided into a fixed number of partitions into which programs can be loaded
- Dynamic partitions Partitions are created as needed to fit the programs waiting to be loaded

Partition Memory Management

Memory is divided into a set of partitions, some empty and some allocated to programs

Base register

A register that holds the beginning address of the current partition (the one that is running)

Limit register

A register that holds the length of the current partition

Partition Memory Management

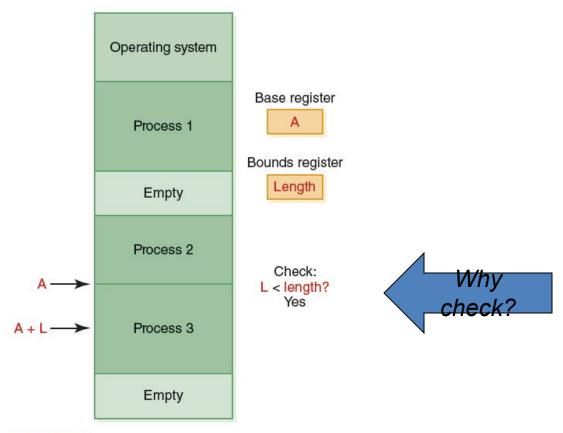
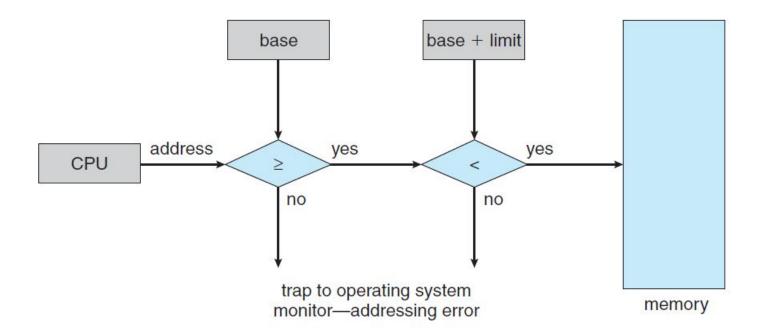


FIGURE 10.7 Address resolution in partition memory management



Partition Selection Algorithms

Which partition should we allocate to a new program?

- First fit Allocate program to the first partition big enough to hold it
- Best fit Allocated program to the smallest partition big enough to hold it
- Worst fit Allocate program to the largest partition big enough to hold it

Can you give a rationale for each?

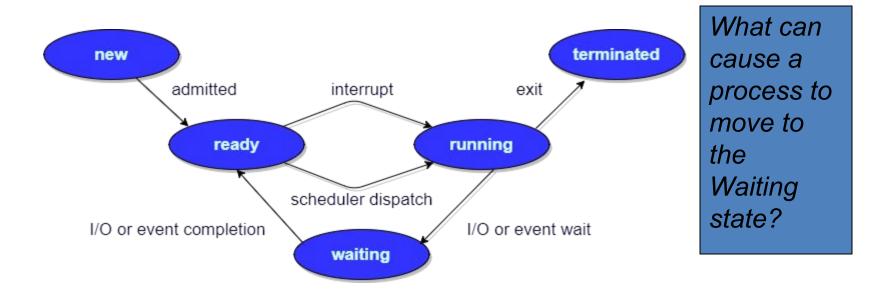
Process management

The act of managing the use of the CPU by individual processes

Recall that a process is a program in execution

What stages does a process go through?

The Process States



Process control block (PCB)

A data structure used by the OS to manage information about a process, including

- current value of the program counter
- values of all CPU registers for the process
- base and bound register values accounting information

Each *state* is represented by a list of PCBs, one for each process in that state

There is only one CPU and therefore only one set of CPU registers, which contain the values for the currently executing process

Each time a process is moved to the running state:

- Register values for the currently running process are stored into its PCB
- Its PCB is moved to the list of the state into which it goes
- Register values of the new process moving into the running state are loaded into the CPU
- This exchange of register information is called a context switch

CPU Scheduling

CPU Scheduling

The act of determining which process in the *ready* state should be moved to the *running* state

- Many processes may be in the ready state
- Only one process can be in the running state, making progress at any one time

Which one gets to move from ready to running?

CPU Scheduling

Nonpreemptive scheduling

The currently executing process gives up the CPU voluntarily

Preemptive scheduling

The operating system decides to favor another process, preempting the currently executing process

Turnaround time

The amount of time between when a process arrives in the ready state the first time and when it exits the running state for the last time (the total time spent between starting the process and ending the process)

CPU Scheduling Algorithms

First-Come, First-Served

Processes are moved to the CPU in the order in which they arrive in the running state

Shortest Job Next

Process with shortest estimated running time in the ready state is moved into the running state first

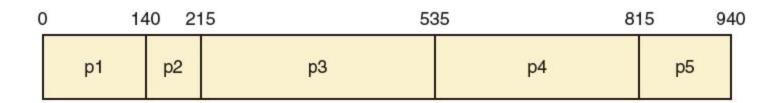
Round Robin

Each process runs for a specified time slice and moves from the running state to the ready state to await its next turn if not finished

First-Come, First-Served

Process	Service Time		
p1	140		
p2	75		
р3	320		
p4	280		
p5	125		

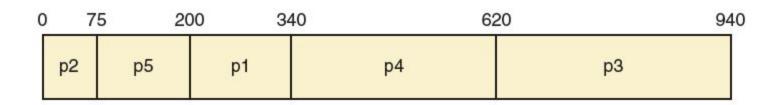
What is the average turn-around time?



Shortest Job Next

Process	Service Time		
p1	140		
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What is the average turn-around time?



Round Robin

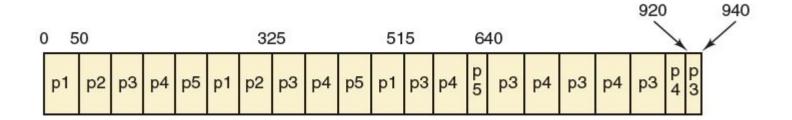
Every process is treated the same!

Time slice (quantum)

The amount of time each process receives before being preempted and returned to the ready state to allow another process its turn

Round Robin

Suppose the time slice is 50



What is the average turnaround time?

CPU Scheduling Algorithms

Are these scheduling algorithms preemptive or non-preemptive? Explain

First-Come, First-Served?

Shortest Job Next?

Round Robin?

Activity 1:

Use the following table of processes and service time. Draw Gantt charts that show turnaround time for each process using SJN (shortest job next) and RR (round robin) CPU Scheduling. Also find average turnaround time for each.

Process	P1	P2	P3	P4	P5
Service time	120	60	180	50	300

Activity 2:

Apply <u>First-Fit and Best-Fit</u> Algorithm on the following jobs given along the memory set available (fixed partitions). Fill Job Number column for your answer.

MEMORY MAP

	First-Fit	Best-Fit
	(Job No)	(Job No)
8 KB		
100 KB		
1024 KB		
56 KB		
2 KB		
48 KB		
2048 KB		
4 KB		
8 KB		
12 KB		
56 KB		

Jobs

J1	J2	J3	J4	J5	J6	J7	J8	J9	J10
4 KB	30 KB	6 KB	9 KB	10 KB	100 KB	200 KB	2 KB	5 KB	1 KB

Activity 5:

 Why shouldn't we use worst-fit partition selection in a fixed-partition memory management scheme?