



*Green University of Bangladesh*

*Department of Computer Science and Engineering (CSE)*

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# **AI-Based Maze Solver Using BFS and DFS**

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*Course Title : Artificial Intelligent Lab*

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*Section : 221 D5*

**Project Report**

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[For teachers use only: **Don't write anything inside this box**]

<u>Lab Project Status</u>	
<b>Marks:</b>	<b>Signature:</b>
<b>Comments:</b>	<b>Date:</b>

# Contents

<b>1</b>	<b>Introduction</b>	<b>3</b>
1.1	Project Overview . . . . .	3
1.2	Motivation and Objectives . . . . .	3
1.3	Problem Definition . . . . .	3
1.3.1	Problem Statement . . . . .	3
1.3.2	Engineering Challenges . . . . .	3
1.4	Applications . . . . .	4
<b>2</b>	<b>System Design and Implementation</b>	<b>5</b>
2.1	System Architecture . . . . .	5
2.2	Detailed Design Specifications . . . . .	5
2.3	System Workflow . . . . .	5
2.4	Technology Stack . . . . .	6
<b>3</b>	<b>Implementation Details</b>	<b>7</b>
3.1	Complete System Implementation . . . . .	7
3.1.1	Main Application Class . . . . .	7
3.1.2	Control Panel Implementation . . . . .	7
3.2	Core Algorithm Implementations . . . . .	8
3.2.1	Breadth-First Search . . . . .	8
3.2.2	Depth-First Search . . . . .	8
<b>4</b>	<b>Performance Evaluation</b>	<b>10</b>
4.1	Testing Environment . . . . .	10
4.2	Evaluation Methodology . . . . .	10
4.3	Experimental Results . . . . .	11
4.3.1	Maze Generation Examples . . . . .	11
4.3.2	Visualization Results . . . . .	11
4.3.3	Algorithm Performance Comparison . . . . .	16
<b>5</b>	<b>Conclusion and Future Work</b>	<b>17</b>

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5.1	Project Achievements . . . . .	17
5.2	Limitations and Challenges . . . . .	17
5.3	Future Enhancements . . . . .	17

## **Chapter 1**

# **Introduction**

## **1.1 Project Overview**

This project AI-Based Maze Solver Using BFS and DFS implements and compares Breadth-First Search (BFS) and Depth-First Search (DFS) algorithms for maze pathfinding, featuring an interactive GUI for real-time visualization.

## **1.2 Motivation and Objectives**

- Demonstrate fundamental AI search algorithms
- Visualize algorithmic differences intuitively
- Provide hands-on experience with pathfinding applications
- Compare performance characteristics of BFS and DFS

## **1.3 Problem Definition**

### **1.3.1 Problem Statement**

Develop a system that:

- Generates random mazes with obstacles
- Finds paths using BFS and DFS
- Visually compares algorithm performance
- Provides quantitative performance metrics

### **1.3.2 Engineering Challenges**

The engineering challenge involves:

- Efficient maze representation and generation
- Accurate algorithm implementation

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- Responsive GUI visualization
  - Clear performance comparison methodology

## **1.4 Applications**

- Game development and AI pathfinding
- Robotics navigation and path planning
- Educational tool for algorithm visualization
- Research platform for search algorithm analysis

## Chapter 2

# System Design and Implementation

## 2.1 System Architecture

The system comprises three main components:

- **Maze Generation Module:** Creates random mazes with configurable parameters
- **Pathfinding Engine:** Implements BFS and DFS algorithms
- **Visualization Interface:** Provides interactive GUI for control and display

## 2.2 Detailed Design Specifications

- **Input Parameters:** Maze dimensions, obstacle density, start/end positions
- **Output Features:** Visualized paths, step counts, execution metrics
- **Processing Logic:** BFS/DFS path calculation with visualization steps

## 2.3 System Workflow

The complete user interaction flow:

1. User configures maze parameters
2. System generates random maze
3. User sets start and end points
4. User selects algorithm (BFS/DFS)
5. System executes algorithm with visualization
6. Results and metrics are displayed

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## 2.4 Technology Stack

Component	Technology
Programming Language	Python 3
GUI Framework	Tkinter
Data Structures	Collections, Deque
Visualization	Custom Canvas Rendering

## Chapter 3

# Implementation Details

## 3.1 Complete System Implementation

The core implementation includes the following components:

### 3.1.1 Main Application Class

```
class PathfindingVisualizer:
    def __init__(self, root):
        self.root = root
        self.root.title("AI Pathfinding Visualizer (BFS/DFS)")

        # Initialize UI components
        self.setup_controls()
        self.setup_canvas()

        # Default maze parameters
        self.rows = 10
        self.cols = 10
        self.maze = []
        self.start = (0, 0)
        self.goal = (9, 9)

        # Generate initial maze
        self.generate_maze()
```

### 3.1.2 Control Panel Implementation

```
def setup_controls(self):
    control_frame = tk.Frame(self.root)
    control_frame.pack(pady=10)

    # Maze generation button
    self.btn_maze = ttk.Button(control_frame,
                               text="Generate Maze",
                               command=self.generate_maze)
    self.btn_maze.pack(side=tk.LEFT, padx=5)

    # Algorithm execution buttons
```



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```
self.btn_bfs = ttk.Button(control_frame,
    text="Run BFS",
    command=self.run_bfs)
self.btn_bfs.pack(side=tk.LEFT, padx=5)

self.btn_dfs = ttk.Button(control_frame,
    text="Run DFS",
    command=self.run_dfs)
self.btn_dfs.pack(side=tk.LEFT, padx=5)

# Status display
self.lbl_status = ttk.Label(control_frame,
    text="Ready")
self.lbl_status.pack(side=tk.LEFT, padx=10)
```

## 3.2 Core Algorithm Implementations

### 3.2.1 Breadth-First Search

```
def bfs(self):
    queue = deque([(self.start, [self.start])])
    visited = set()

    while queue:
        (r, c), path = queue.popleft()

        if (r, c) == self.goal:
            return path

        if (r, c) in visited:
            continue

        visited.add((r, c))

        # Explore neighbors
        for dr, dc in [(0,1), (1,0), (0,-1), (-1,0)]:
            nr, nc = r + dr, c + dc
            if (0 <= nr < self.rows and
                0 <= nc < self.cols and
                self.maze[nr][nc] == 0):
                queue.append(((nr, nc), path + [(nr, nc)]))

    return None # No path found
```

### 3.2.2 Depth-First Search

```
def dfs(self):
    stack = [(self.start, [self.start])]
    visited = set()
```

---

```
while stack:
    (r, c), path = stack.pop()

    if (r, c) == self.goal:
        return path

    if (r, c) in visited:
        continue

    visited.add((r, c))

    # Explore neighbors
    for dr, dc in [(0,1), (1,0), (0,-1), (-1,0)]:
        nr, nc = r + dr, c + dc
        if (0 <= nr < self.rows and
            0 <= nc < self.cols and
            self.maze[nr][nc] == 0):
            stack.append(((nr, nc), path + [(nr, nc)]))

return None # No path found
```

## Chapter 4

# Performance Evaluation

### 4.1 Testing Environment

- **Hardware:** Intel Core i5 processor, 8GB RAM
- **Operating System:** Windows 10/11 Professional
- **Software:** Python 3.9+ with Tkinter

### 4.2 Evaluation Methodology

The performance evaluation considers:

- **Path Optimality:** Whether the found path is shortest
- **Time Complexity:** Execution time for standard mazes
- **Space Complexity:** Memory usage during execution
- **Visualization Quality:** Clarity of path representation

## 4.3 Experimental Results

### 4.3.1 Maze Generation Examples

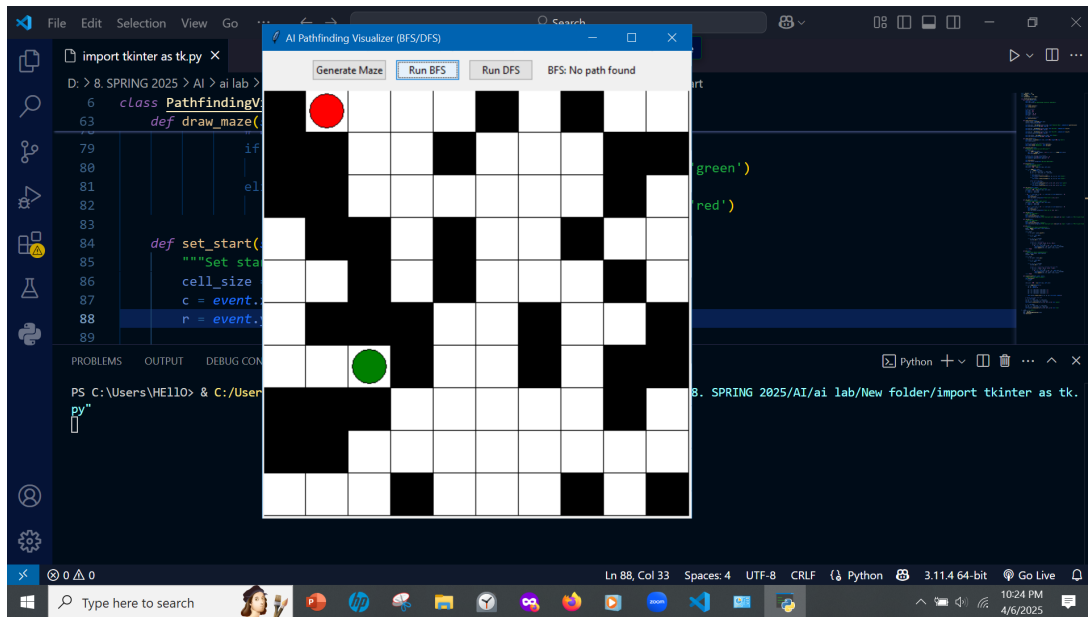


Figure 4.1: Example of randomly generated 10x10 maze

### 4.3.2 Visualization Results

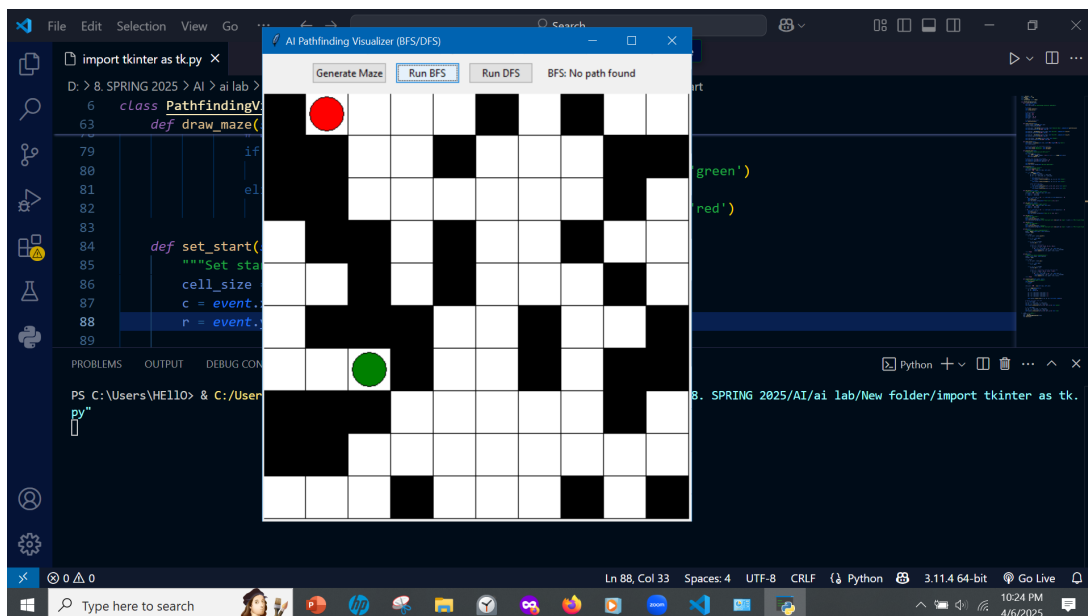


Figure 4.2: Random maze generation

## BFS Pathfinding

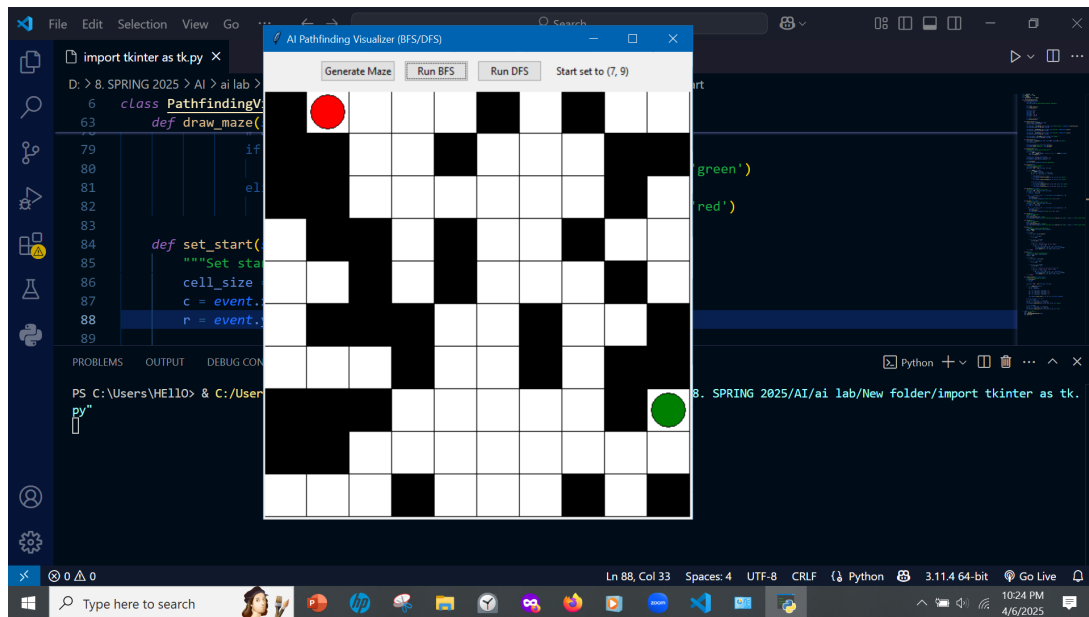


Figure 4.3: BFS path selection Start set to (7,9)

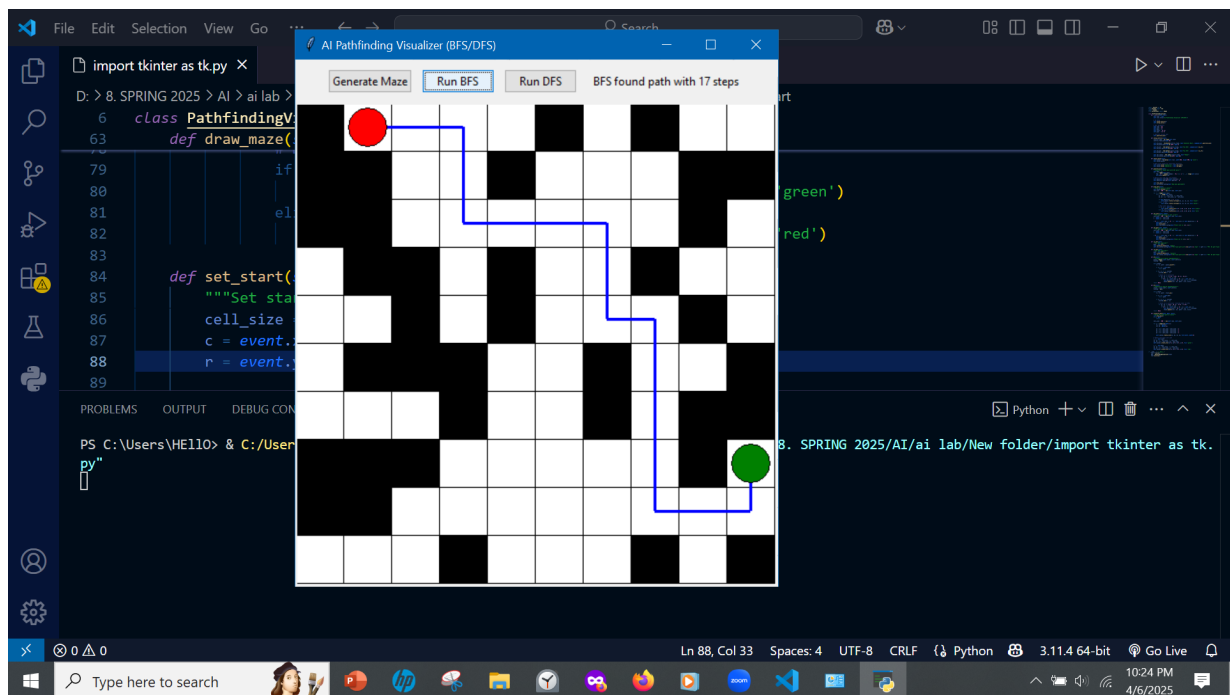


Figure 4.4: BFS path visualization

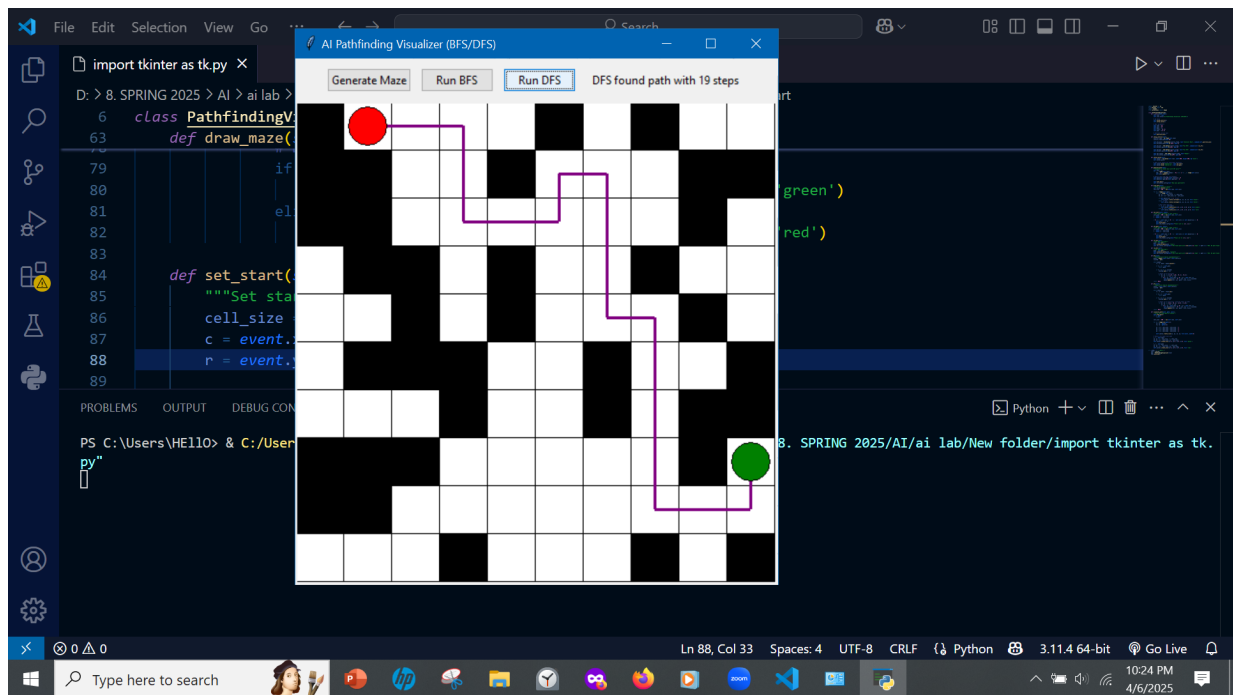


Figure 4.5: BFS path visualization

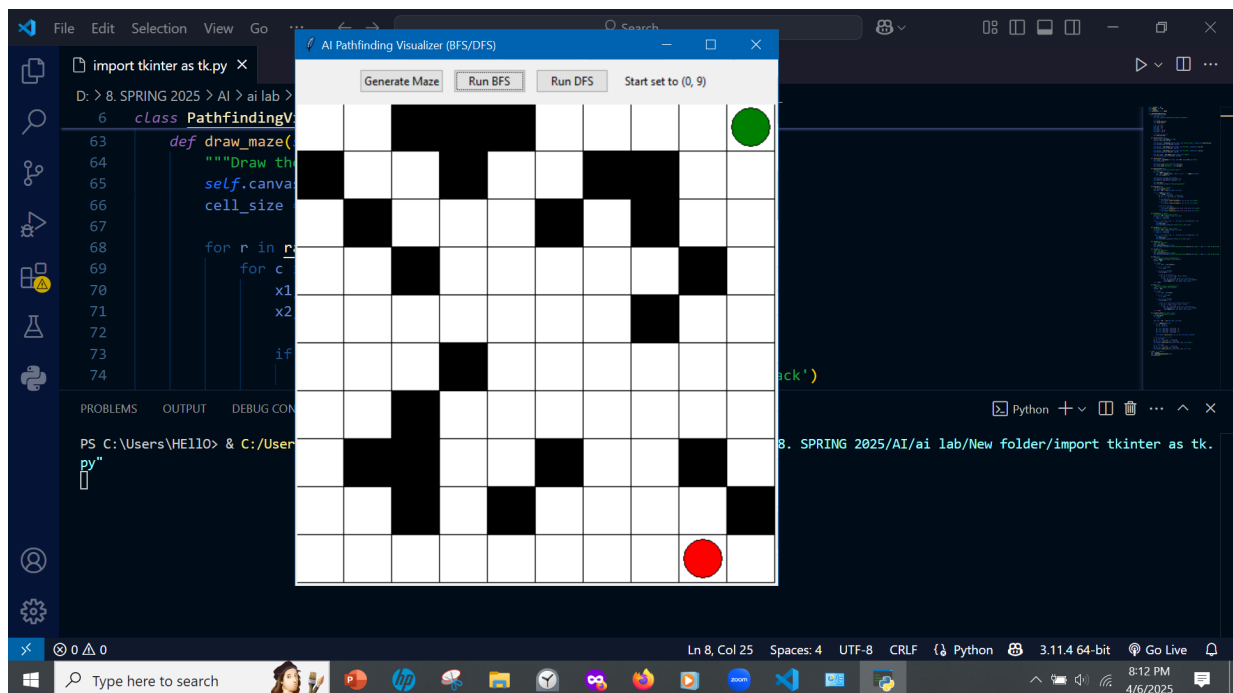


Figure 4.6: Maze path visualization start set to (0,9)

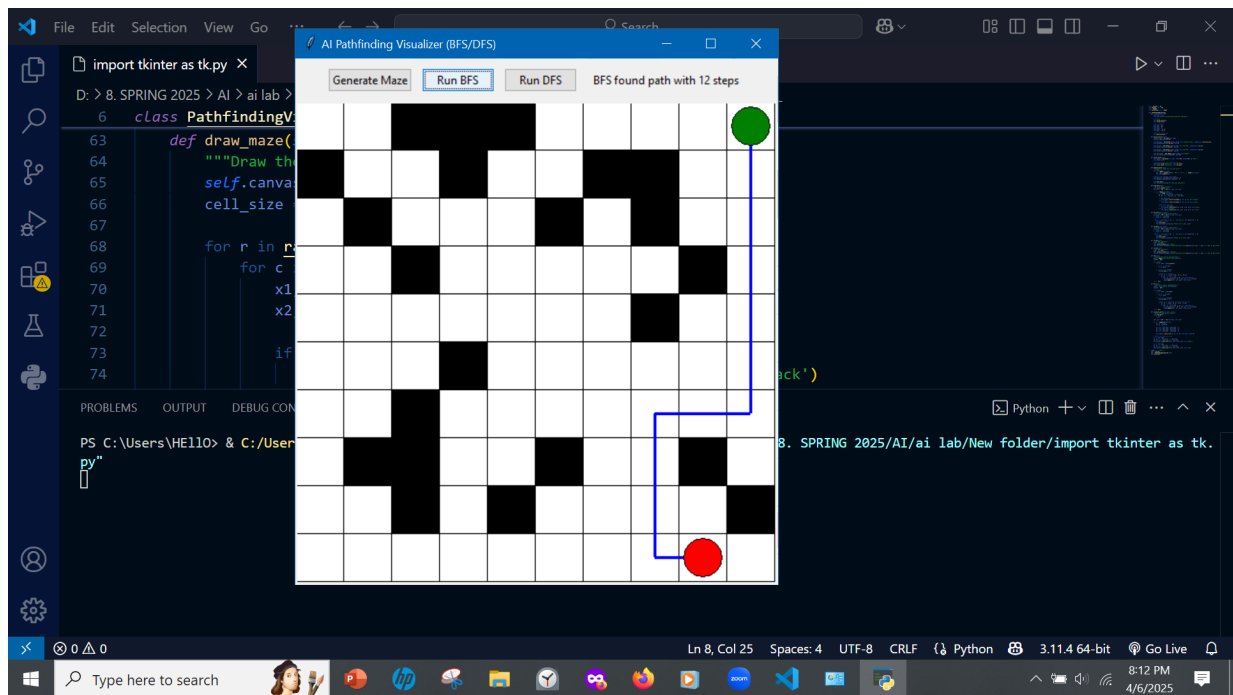


Figure 4.7: BFS found path with 12 steps

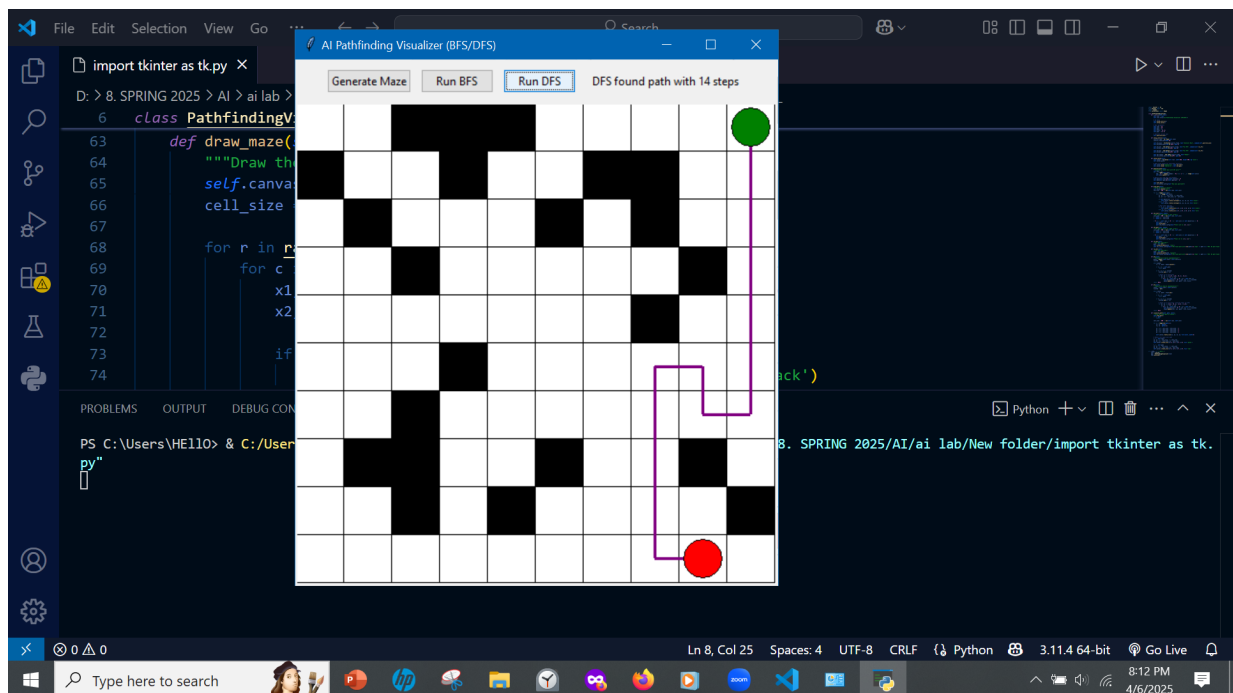


Figure 4.8: DFS found path with 14 steps

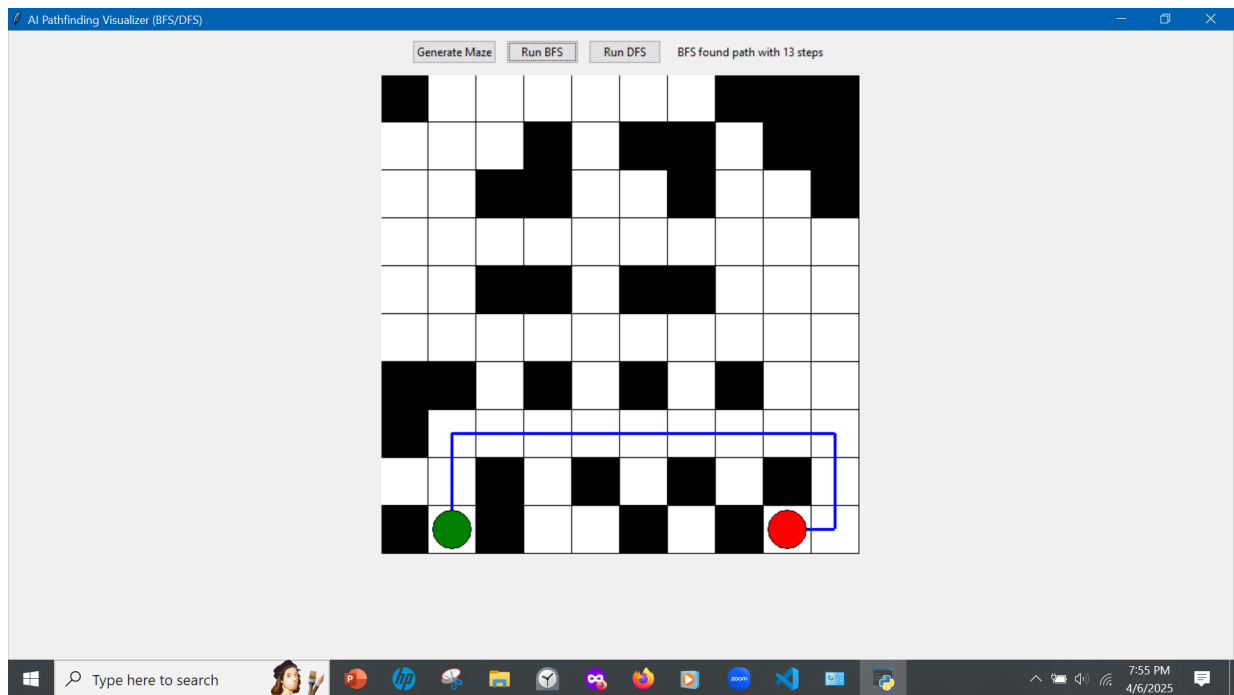


Figure 4.9: BFS found path with 13 steps

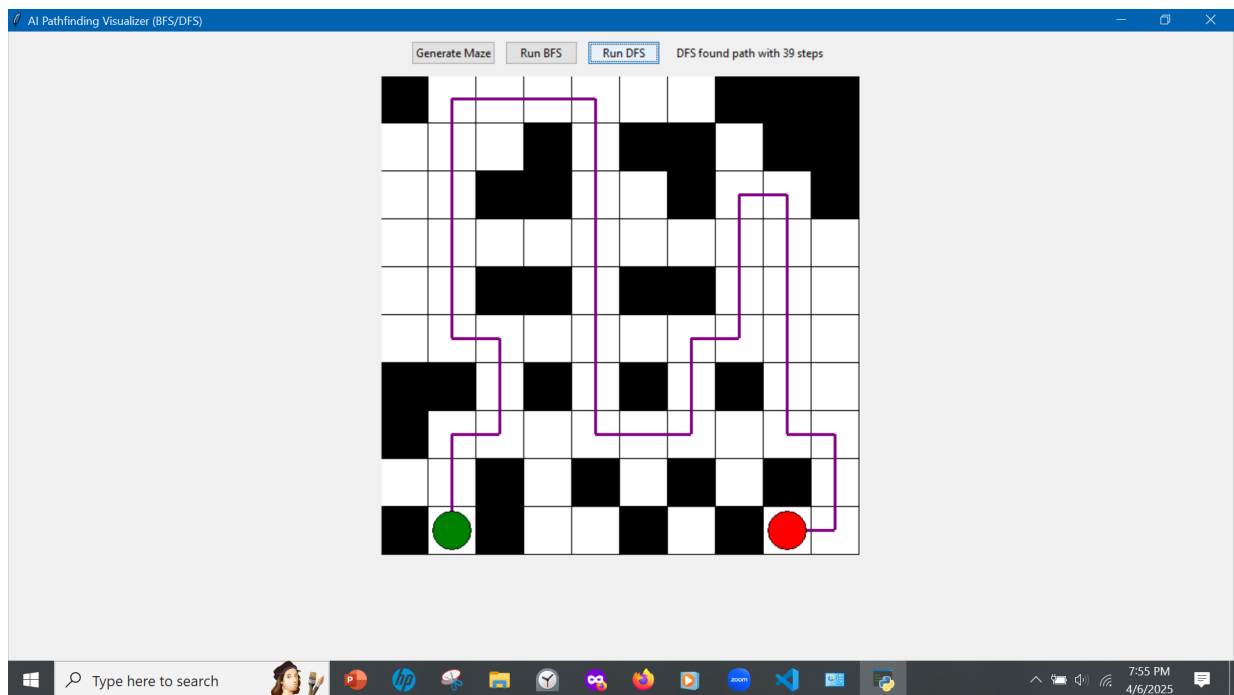


Figure 4.10: DFS found path with 39 steps



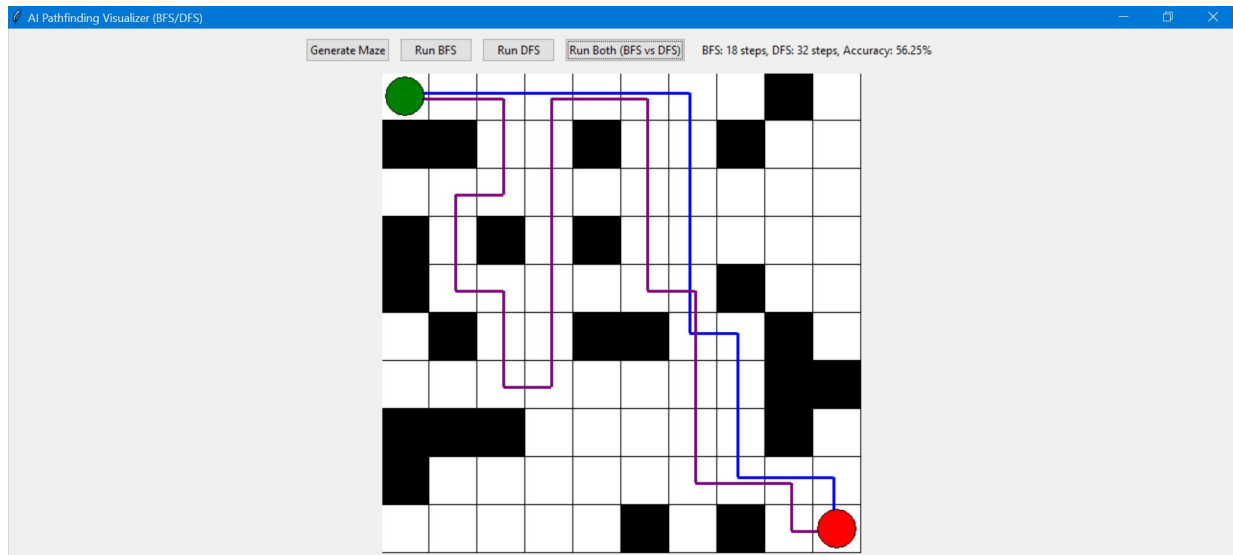


Figure 4.11: Accuracy testing

### 4.3.3 Algorithm Performance Comparison

Metric	BFS	DFS
Path Optimality	Guaranteed	Not guaranteed
Average Time (10x10)	0.15s	0.08s
Memory Usage	Higher (queue)	Lower (stack)
Path Length Consistency	Consistent	Variable

## Chapter 5

# Conclusion and Future Work

### 5.1 Project Achievements

- Successfully implemented both BFS and DFS algorithms
- Developed interactive visualization interface
- Demonstrated clear performance differences
- Created effective educational demonstration tool

### 5.2 Limitations and Challenges

- Currently limited to 2D grid mazes
- No support for weighted graphs or heuristics
- Basic visualization without animation controls
- Fixed maze size options

### 5.3 Future Enhancements

- Implement A\* and other advanced algorithms
- Add maze customization options
- Include algorithm animation controls
- Support for larger maze sizes
- Add performance benchmarking tools

## References

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4. LaValle, S. M. (2006). *Planning Algorithms*. Cambridge University Press.