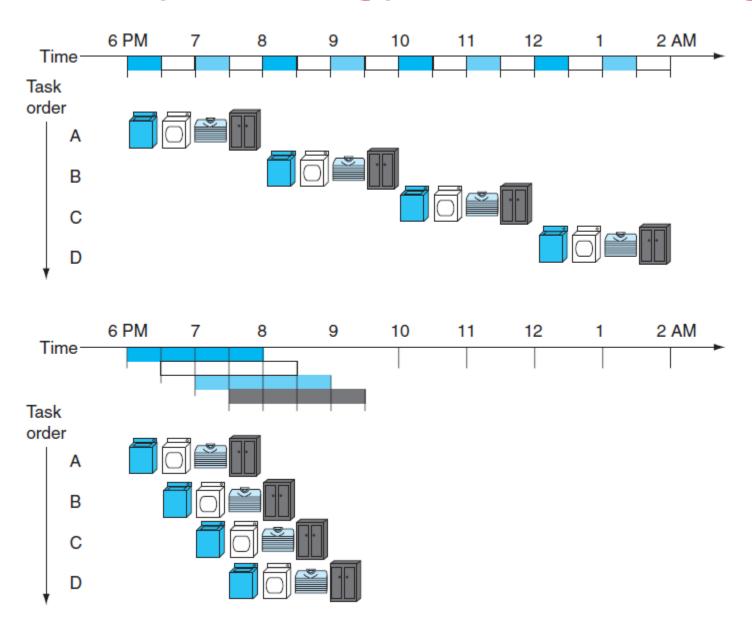
### Lecture – 17



## **Pipelining**

- An implementation technique in which multiple instructions are overlapped in execution.
- It is used to make the processor fast.
- Pipelining does not reduce the time to complete a single task but increases the throughput and the improvement in the throughput decreases the total time to complete the task.
- The speed up due to pipelining is equal to the number of stages in the pipeline if
  - 1. All the stages take about the same amount of time.
  - 2. The number of tasks is large compared to the number of stages.

## **Laundry Analogy for Pipelining**



## M

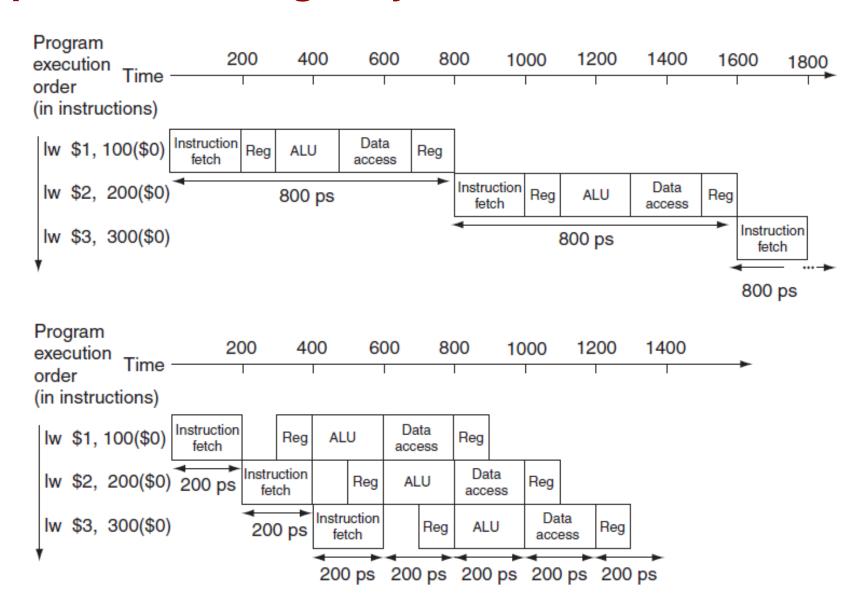
### **MIPS Pipeline**

- Fetch instruction from the memory.
- Read register while decoding the instruction.
- Execute the operation or calculate an address.
- Access an operand in data memory.
- Write the result into a register.

## Pipelined vs. Single-Cycle Instruction Execution

Instruction Class	Instruction Fetch	Register Read	ALU Operation	Data Access	Register Write	Total Time	
Load Word (LW)	200 ps 100 ps		200 ps	200 ps	100 ps	800 ps	
Store Word (SW)	200 ps	100 ps	200 ps	200 ps		700 ps	
R-format	200 ps	100 ps	200 ps		100 ps	600 ps	
Branch (Beq)	200 ps	100 ps	200 ps			500 ps	

#### Pipelined vs. Single-Cycle Instruction Execution



## **Speed Up of Pipelining**

 $Time between instructions_{pipelined} = \frac{Time between instructions_{nonpipelined}}{Number of pipe stages}$ 

- Time between the instruction must be 160 ps. We get 200 ps due to imperfectly balanced stage.
- With respect to total execution time, we get 2400 ps / 1400 ps = 1.7. This is due to small number of instruction.
- Suppose, we have 1,0000,003 instructions. So, speed up =  $1,0000,000 \times 200 + 1400 / 1,0000,000 \times 800 + 2400 \approx 4.00$



### **Pipelining MIPS**

- all instructions are same length
  - -so fetch and decode stages are similar for all instructions
- just a few instruction formats
  - -simplifies instruction decode and makes it possible in one stage
- memory operands appear only in load/stores
  - -so memory access can be deferred to exactly one later stage
- operands are aligned in memory
  - -one data transfer instruction requires one memory access stage

## 1

### **Pipeline Hazards**

There are situations in pipelining when the next instruction cannot execute in the following clock cycle. These events are called **hazards**.

There are three different types of hazards:

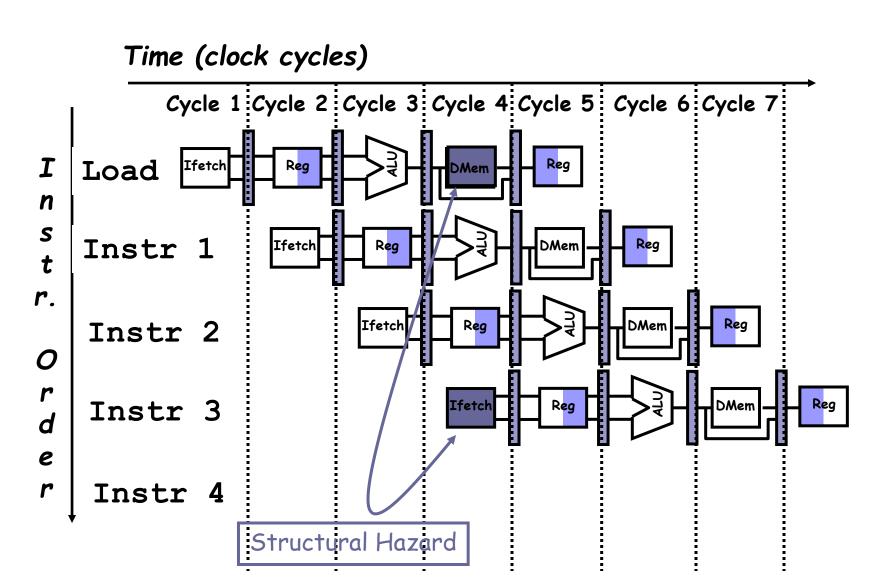
- 1. Structural Hazards
- 2. Data Hazards
- 3. Control Hazards



#### **Structural Hazards**

- An occurrence in which a planned instruction cannot execute in the proper clock cycle because the hardwire cannot support the combination of instruction that are set to execute in the given clock cycle.
- E.g., suppose single not separate instruction and data memory in pipeline below with one read port
  - then a structural hazard between first and fourth lw instructions

#### **Structural Hazard**

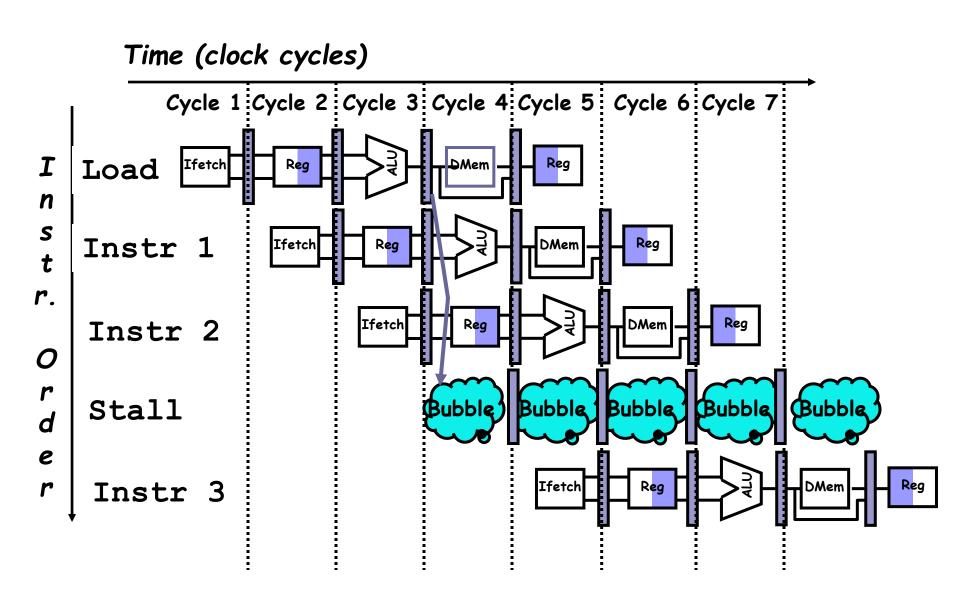




### **Resolving Structural Hazards**

- Solution 1: Wait
  - Must detect the hazard
  - Must detect the mechanism to stall
- Solution 2: Throw more hardware at the problem

#### **Detecting and Resolving Structural Hazard**



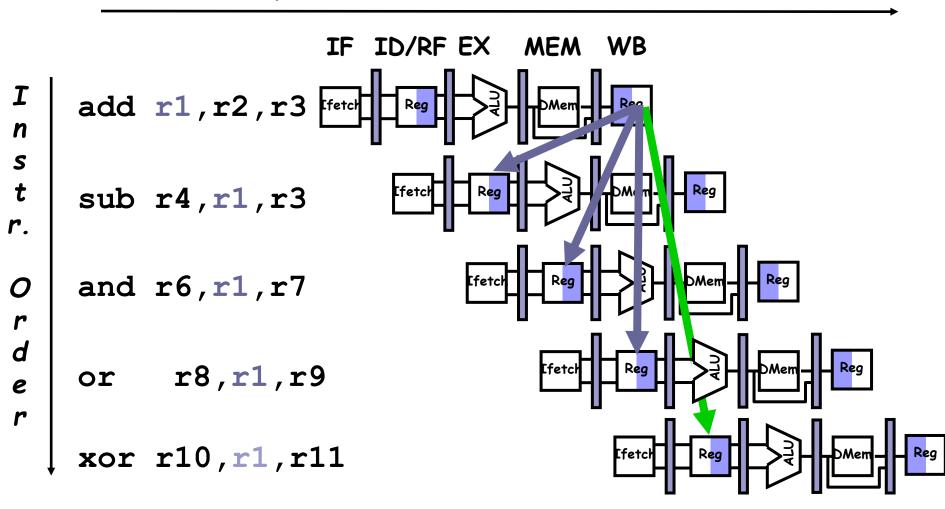


#### **Data Hazards**

- An occurrence in which a planned instruction cannot execute in the proper clock cycle because data that is needed to execute the instruction is not yet available.
- Instruction needs data from the result of a previous instruction still executing in pipeline

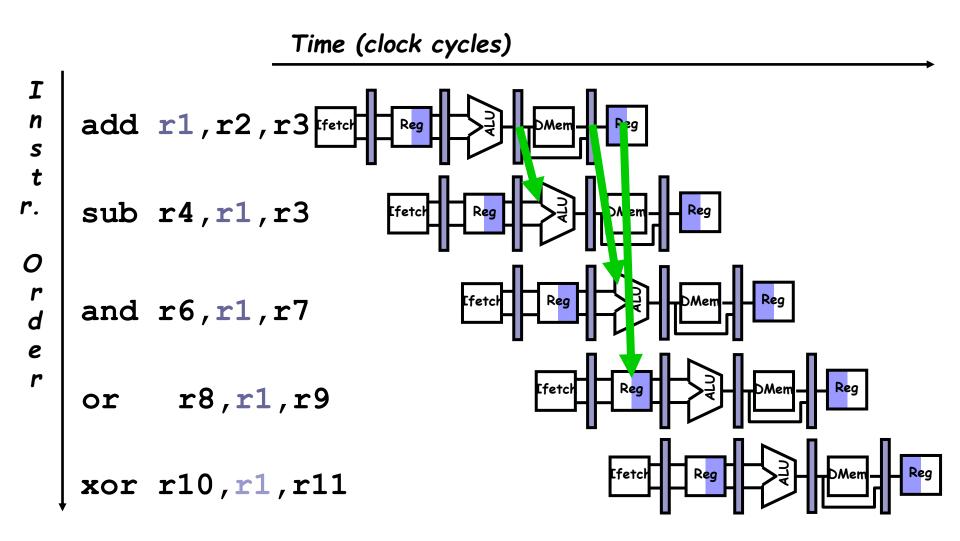
## Data Hazards

Time (clock cycles)



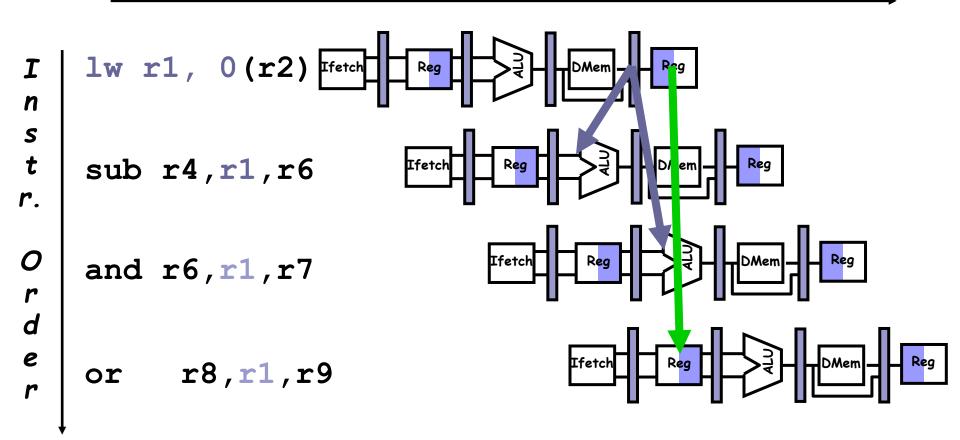
## w

### Forwarding to Avoid Data Hazard



## Data Hazard Even with Forwarding (Load Data Hazard)

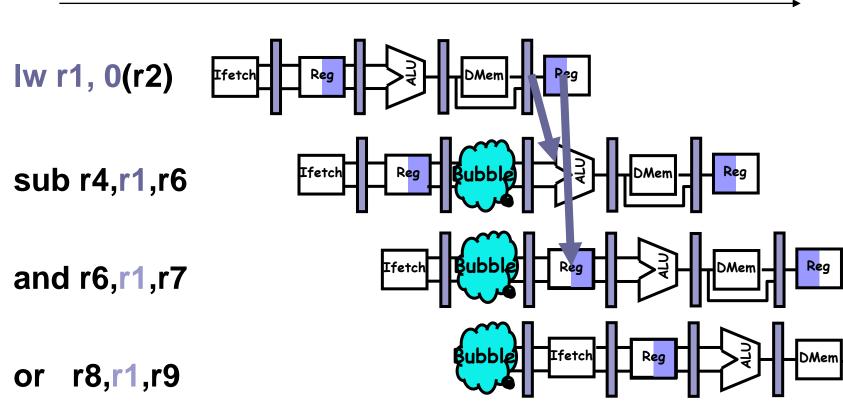
Time (clock cycles)



r

### Resolving the Load Data Hazard





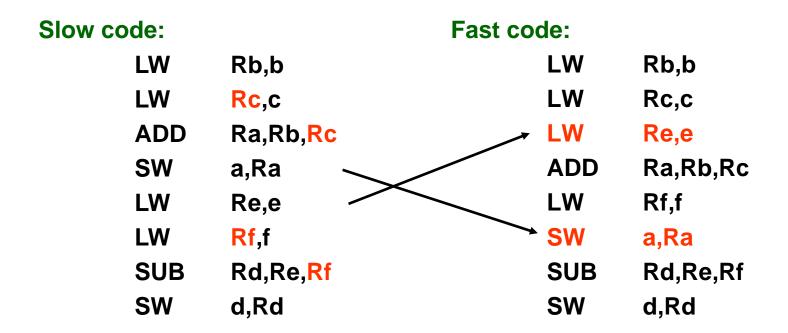
## м

## Software Scheduling to Avoid Load Hazards

Try producing fast code for

$$a = b + c;$$
  
 $d = e - f;$ 

assuming a, b, c, d ,e, and f in memory.





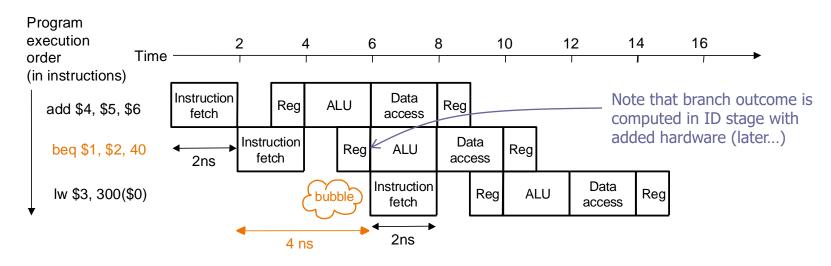
#### **Control Hazards/ Branch Hazards**

- An occurrence in which the proper instruction cannot execute in the proper clock cycle because the instruction that was fetched is not the one that is needed.
- Arises from the need to make a decision based on the result of one instruction while others are executing.

## r

#### **Control Hazards**

- Control hazard: need to make a decision based on the result of a previous instruction still executing in pipeline
- Solution 1 Stall the pipeline



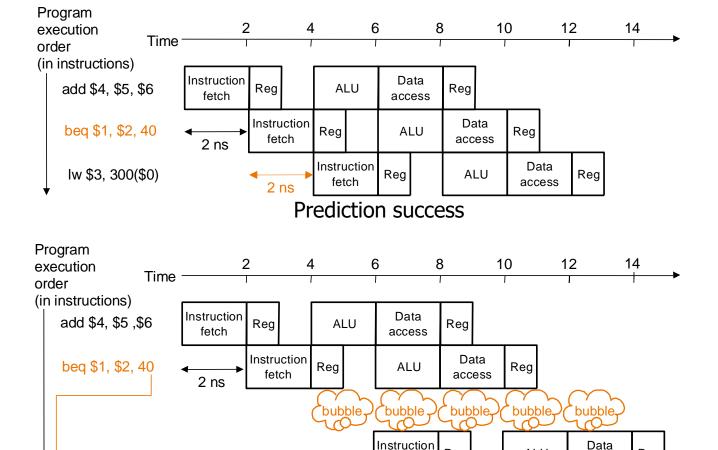
Pipeline stall

#### **Control Hazards**

#### Solution 2 Predict branch outcome

e.g., predict *branch-not-taken*:

or \$7, \$8, \$9



Reg

fetch

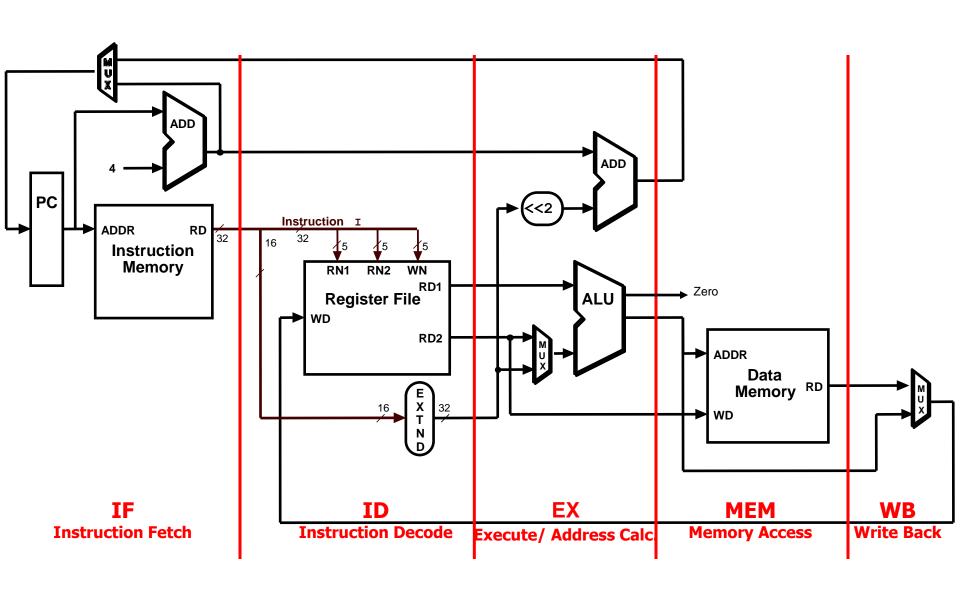
Prediction failure: undo (=flush)

ALU

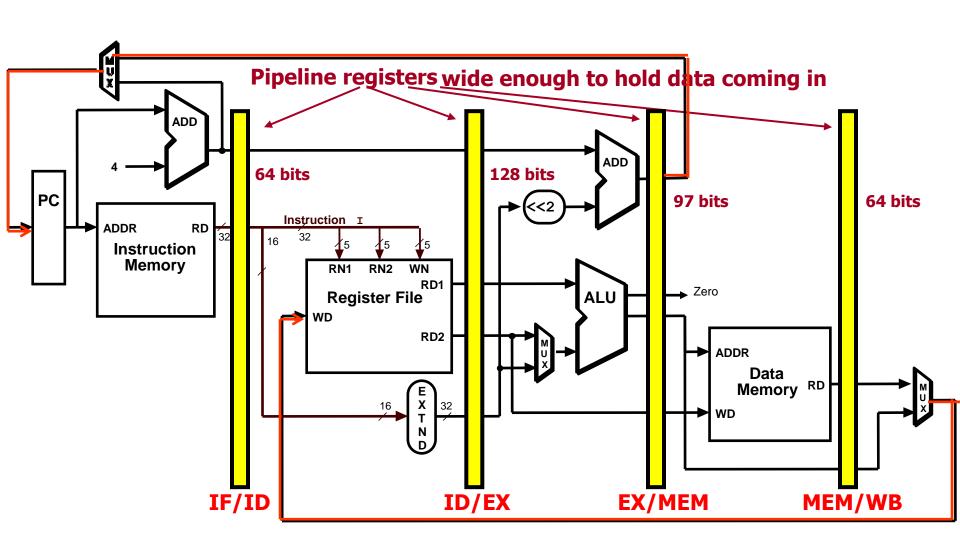
Reg

access

## Single-Cycle Datapath "Steps"



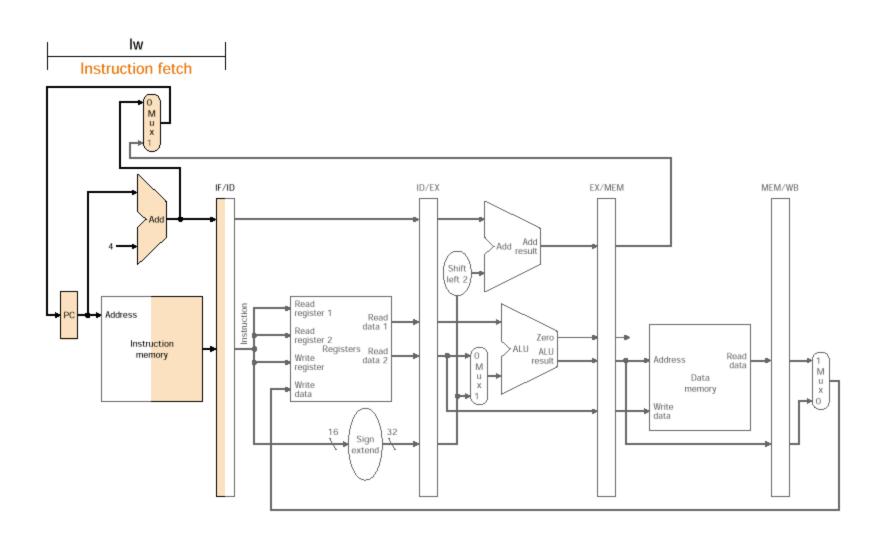
### **Pipelined Datapath**

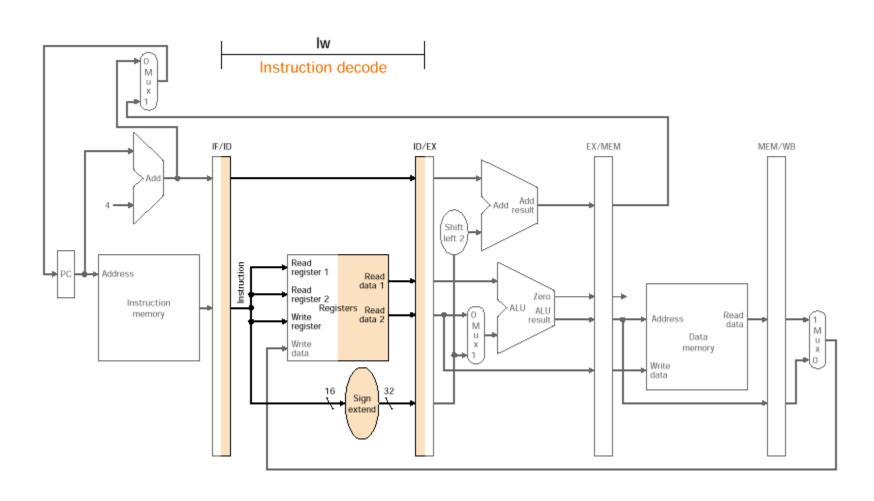


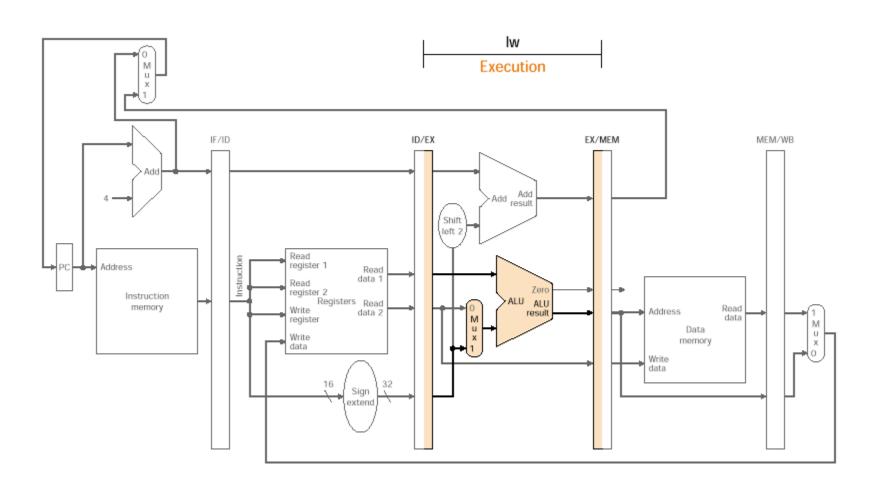


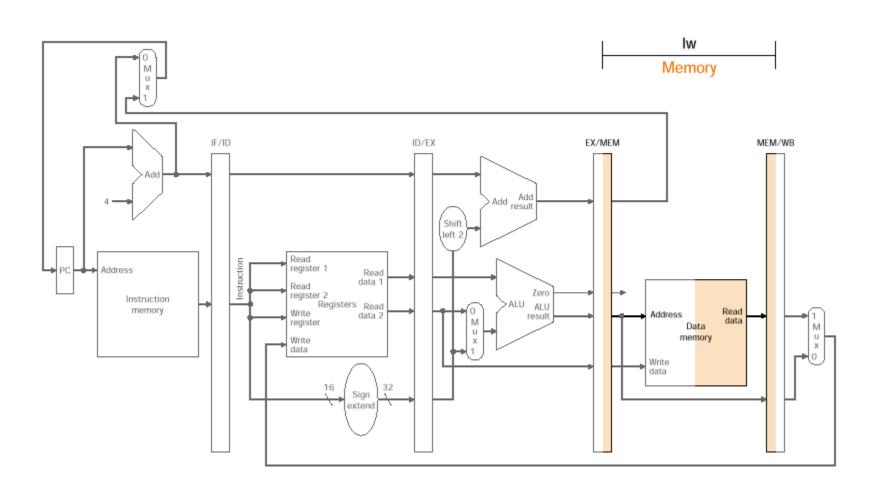
### **Pipelined Datapath**

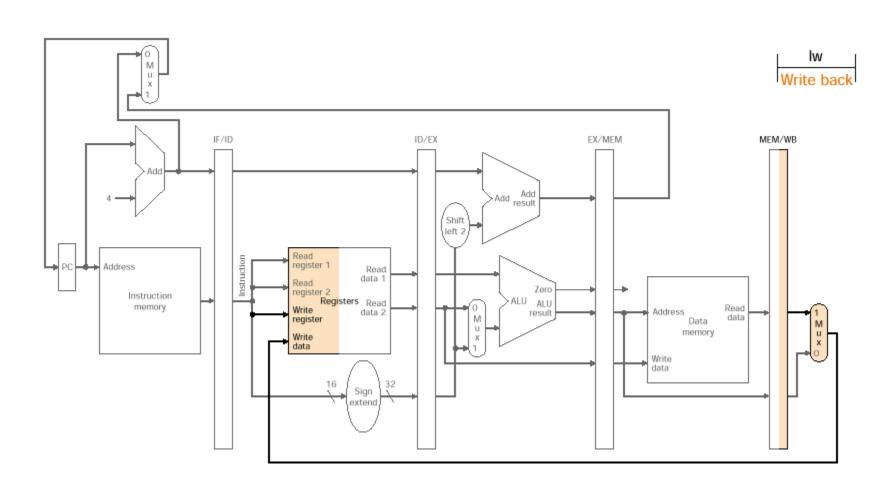
- No pipeline register at the end of write back stage. In this stage we write a register in the register file and any later instruction can get this data by reading this register. So no need for redundant register.
- Each component of the data path is associated with a single stage.
- Each register contains a portion of the instruction needed for that stage and later stages.







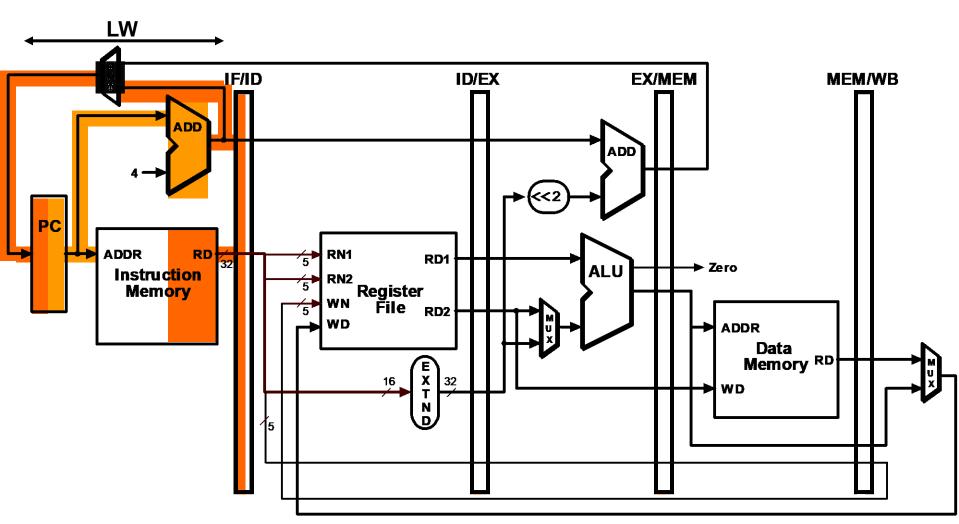


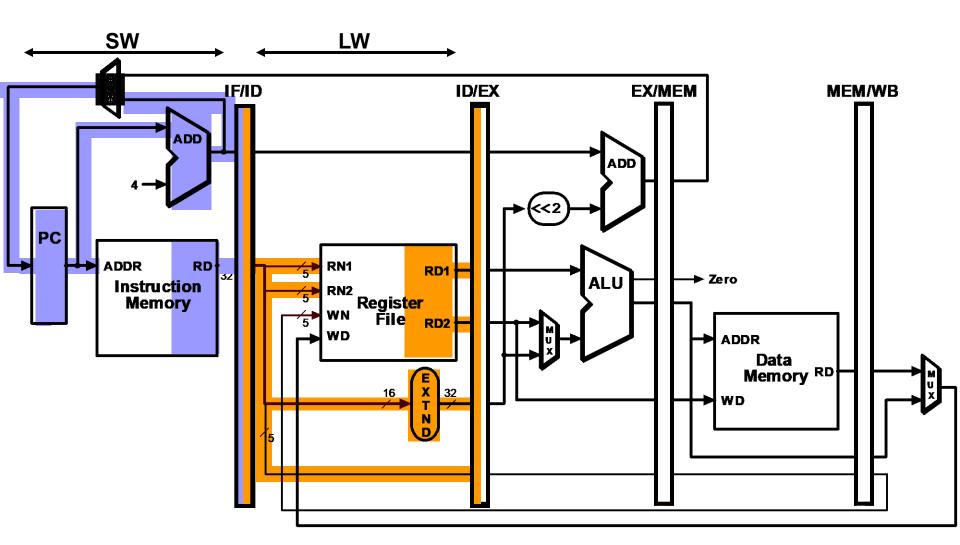


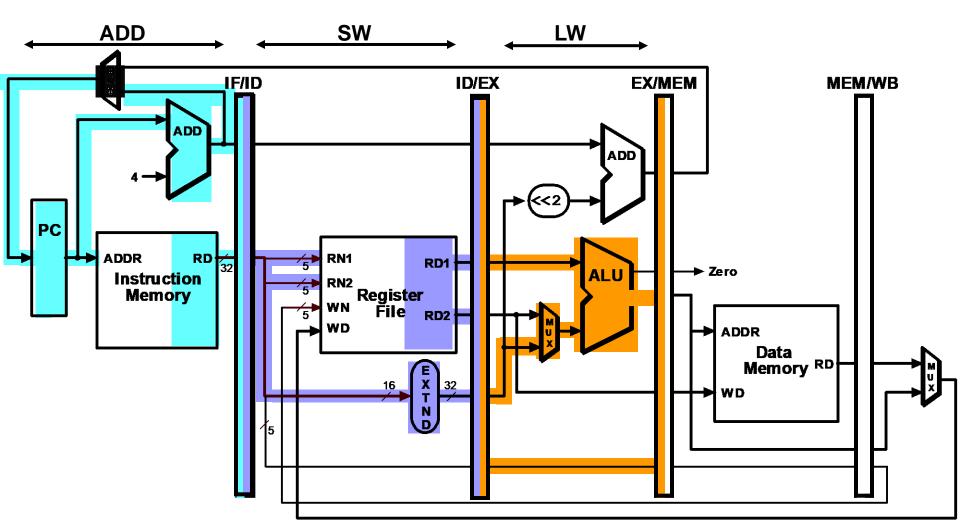
### Pipelined Example

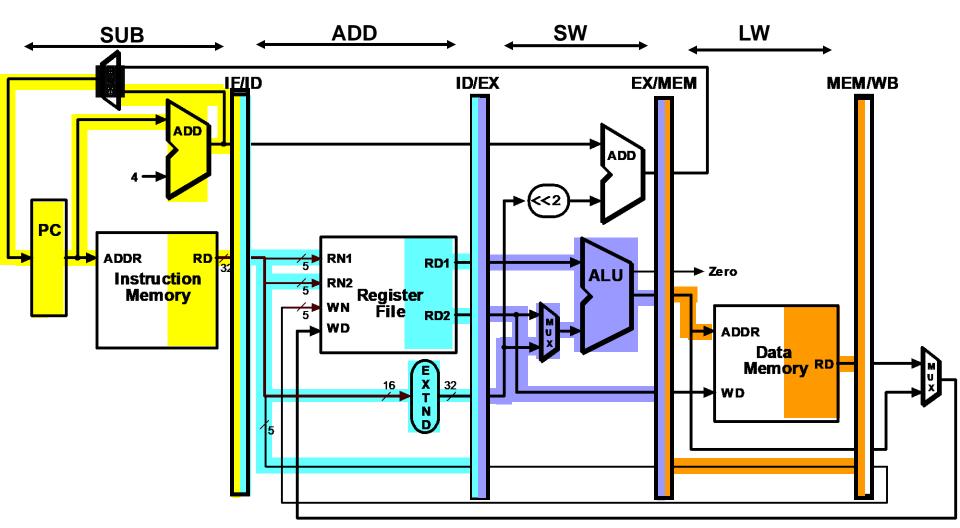
Consider the following instruction sequence:

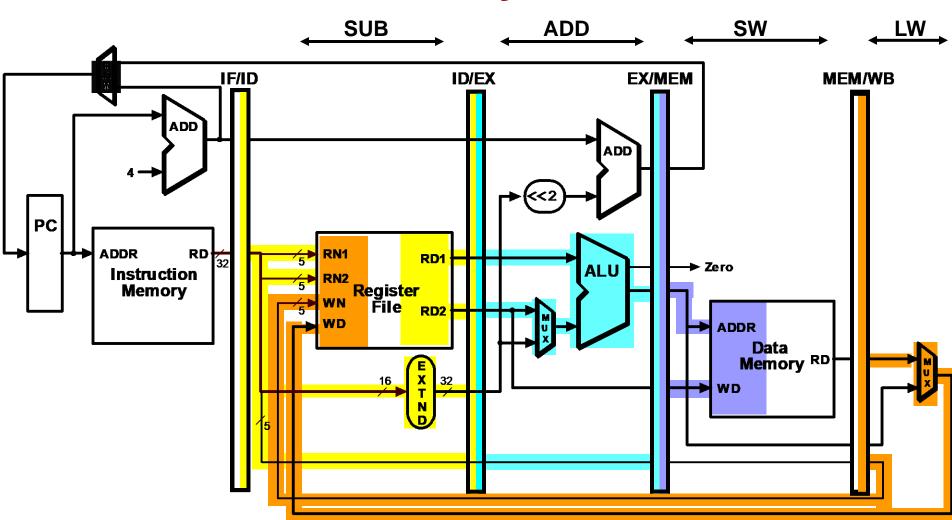
```
Iw $t0, 10($t1)
sw $t3, 20($t4)
add $t5, $t6, $t7
sub $t8, $t9, $t10
```

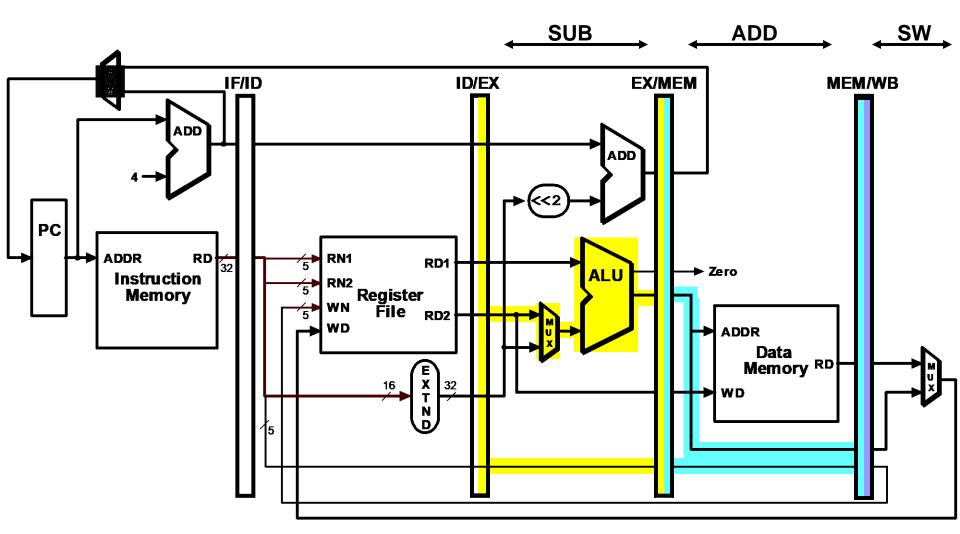


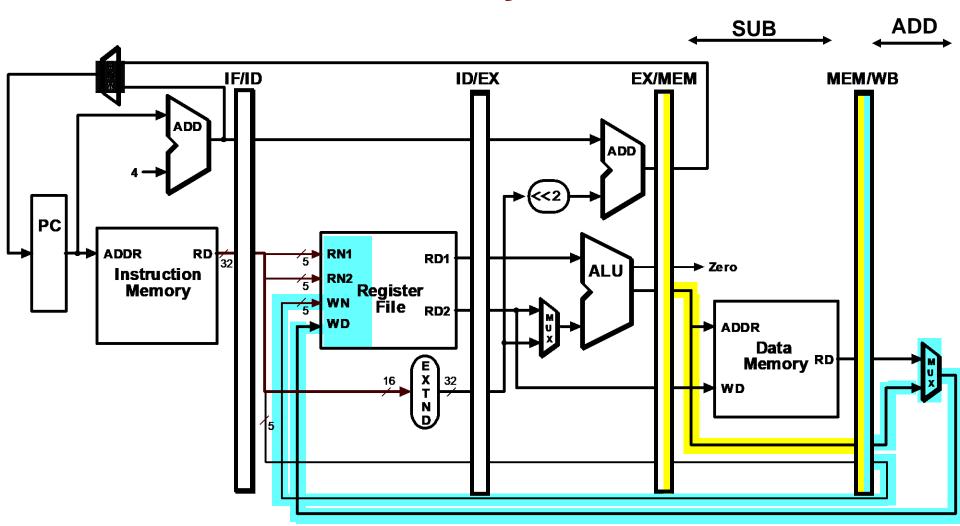


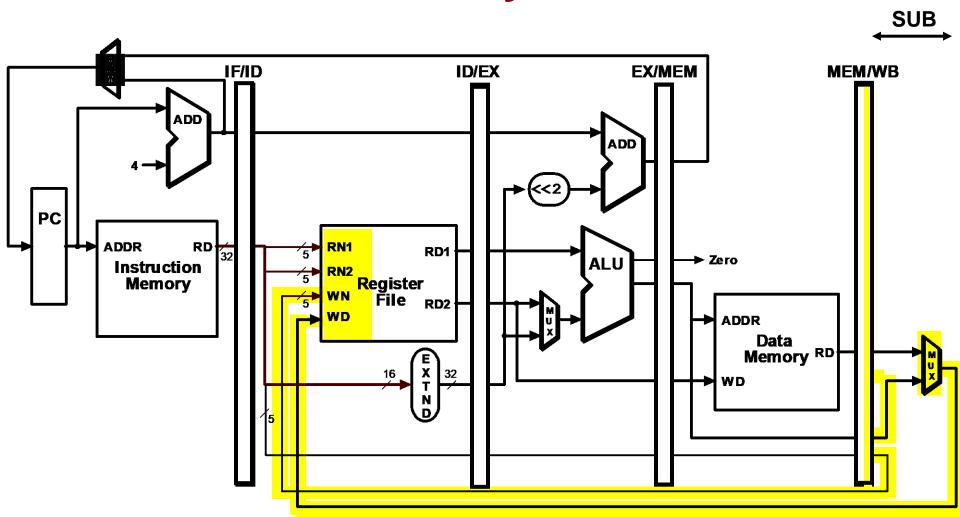




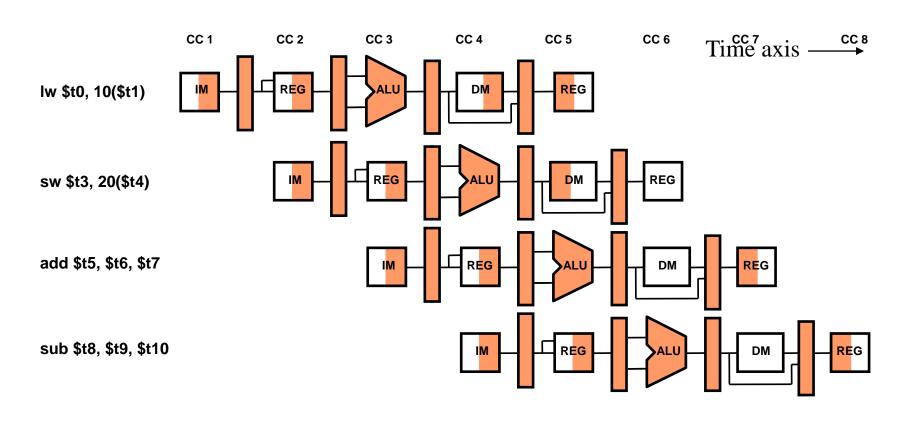








## Alternative View – Multiple-Clock-Cycle Diagram



## Another View – Multiple-Clock-Cycle Diagram

Program execution order (in instructions)

lw \$10, 20(\$1)	Instruction fetch	Instruction decode	Execution	Data access	Write back				
sub \$11, \$2, \$3		Instruction fetch	Instruction decode	Execution	Data access	Write back			
add \$12, \$3, \$4			Instruction fetch	Instruction decode	Execution	Data access	Write back		
lw \$13, 24(\$1)				Instruction fetch	Instruction decode	Execution	Data access	Write back	
add \$14, \$5, \$6					Instruction fetch	Instruction decode	Execution	Data access	Write back