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Hook Diagram > For diliterent imputs Lecture – 14



The Processor: Datapath and Control

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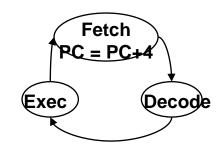
Instruction Execution

For every instruction the first two steps are:

- Send the program counter (PC) to the memory that contains the code and fetch the instruction from that memory.
- Read one or two registers, using the fields of the instruction to select the registers to read.

The Processor: Datapath & Control

- Our implementation of the MIPS is simplified
 - □ memory-reference instructions: lw, sw
 - □ arithmetic-logical instructions: add, sub, and, or, slt
 - □ control flow / branch instructions: beq, j
- Generic implementation
 - use the program counter (PC) to supply the instruction address and fetch the instruction from memory (and update the PC)



- decode the instruction (and read registers)
- execute the instruction
- All instructions (except j) use the ALU after reading the registers

How? memory-reference? arithmetic? control flow?



Instruction Execution

- All instruction classes, except jump, use the ALU after reading the registers.
- The memory-reference instructions use the ALU for an address calculation.
- The arithmetic-logical instructions use the ALU for operation execution.
- Branch instructions use the ALU for comparison.

Instruction Execution

After using the ALU, the actions required to complete various instruction classes differ.

- A memory reference instruction will need to access the memory either to write data for a store or read data for a load.
- Arithmetic-logical instruction must write the data from the ALU back into a register.
- A branch instruction may change the next instruction address based on the comparison, otherwise the PC should be incremented by 4 to get the address of the next instruction.

MIPS Instruction Format

• All instructions are 32 bits with a 6-bit primary opcode.

I-type instruction (Transfer, branch, imm. format)

Opcode	5 rs rt	16 Immediate
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Example: ADDI Rs, Rt,

IMM

R-type instruction (Arithmetic instruction format)

	5	5	5	5	66
Opcode	rs	rt	rd	shamt	funct

Example: ADD Rd, Rs, Rt

SLL Rd, Rt,

Shamt

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MIPS Instruction Format

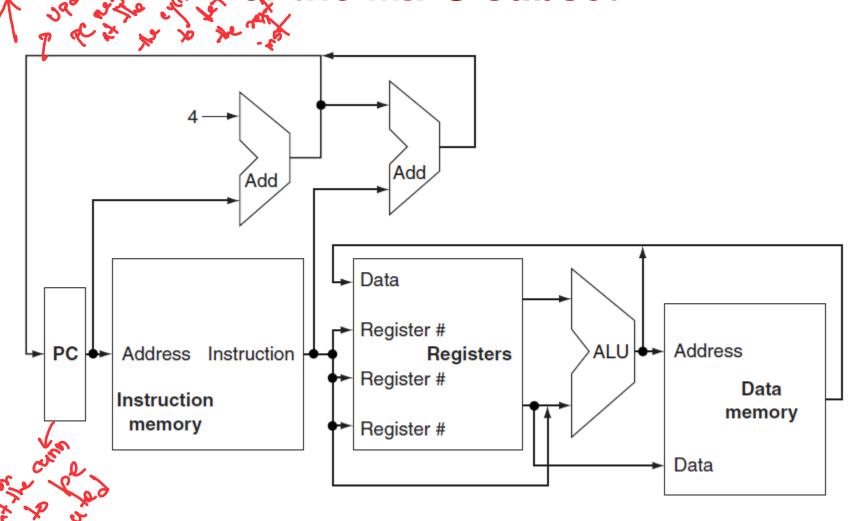
J-type instruction (Jump instruction format)

6 26

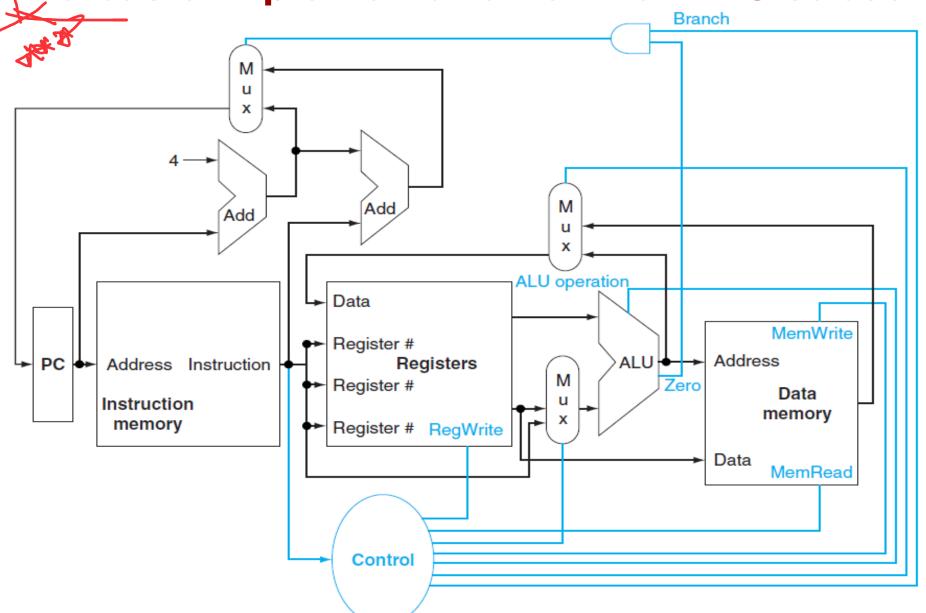
Opcode Offset added to PC

Example: J ADR

An abstract view of the implementation of the MIPS subset



The basic implementation of the MIPS subset



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The Single Cycle Datapath

- Takes a single long clock cycle for every instruction.
- Every instruction begins execution on one clock edge and completes execution on the next clock edge.

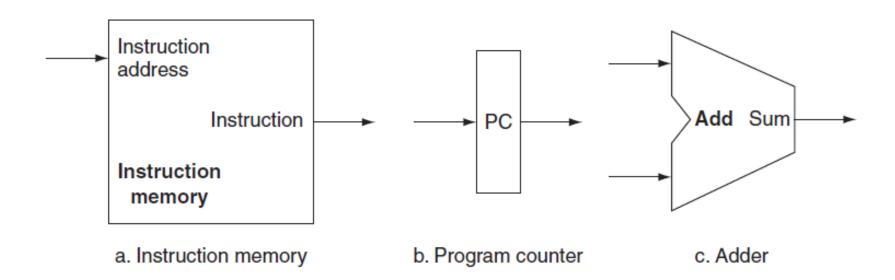
Reasons for separate Memory and Data Unit:

- The format of data and instruction is different in MIPS.
- Less Expensive.
- The processor operates in one clock cycle and cannot use a single-ported memory for two different accesses within that cycle.

Logic Design Conventions

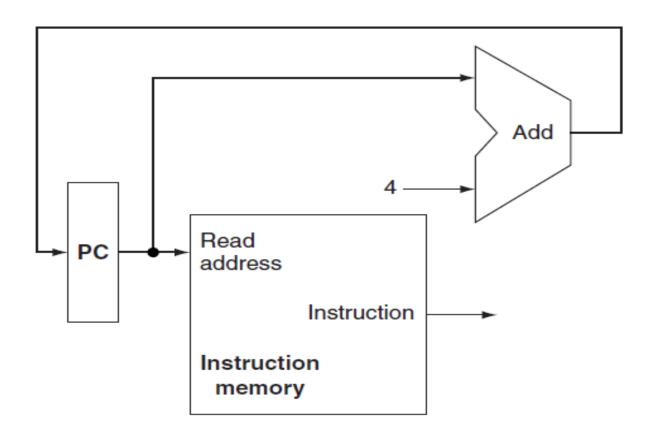
Read Yourself

Building a Datapath



- Two state elements (instruction memory and program counter) are needed to store and access instructions.
- An adder is needed to compute the next instruction address.

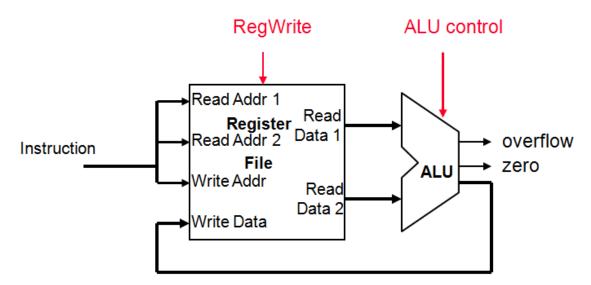
Building a Datapath



It fetches instructions and increments the PC to obtain the address of the next sequential instruction.

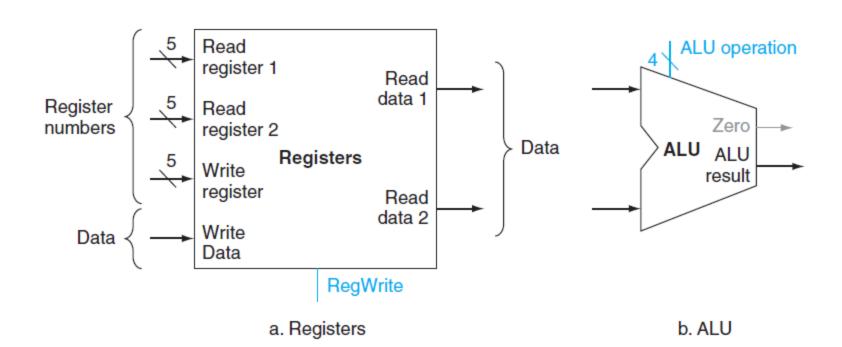
R format operations (add, sub, slt, and, or)

- perform the (op and funct) operation on values in rs and rt
- store the result back into the Register File (into location rd)

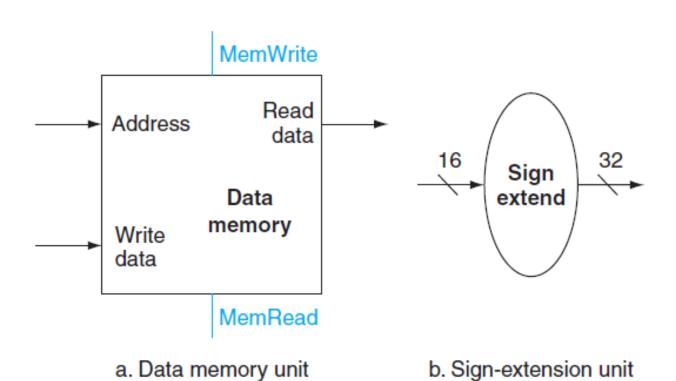


The Register File is not written every cycle (e.g. sw), so we need an explicit write control signal for the Register File

Data elements needed to implement R-type instructions

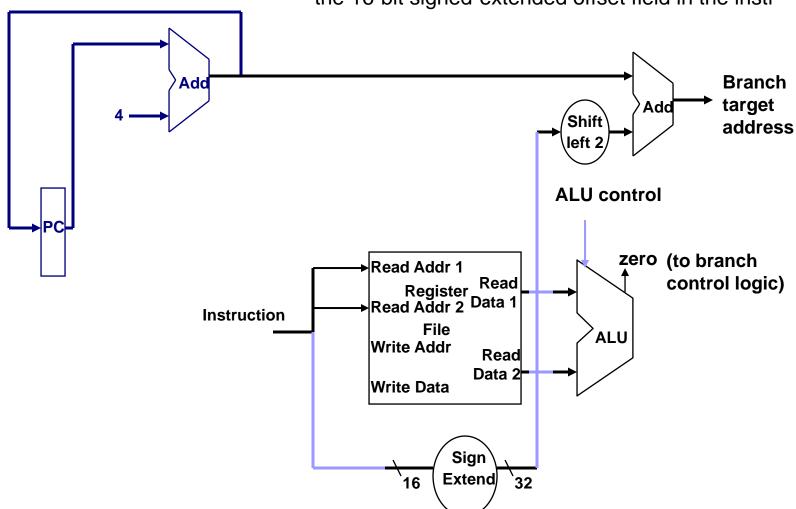


Data elements needed to implement Load and Store

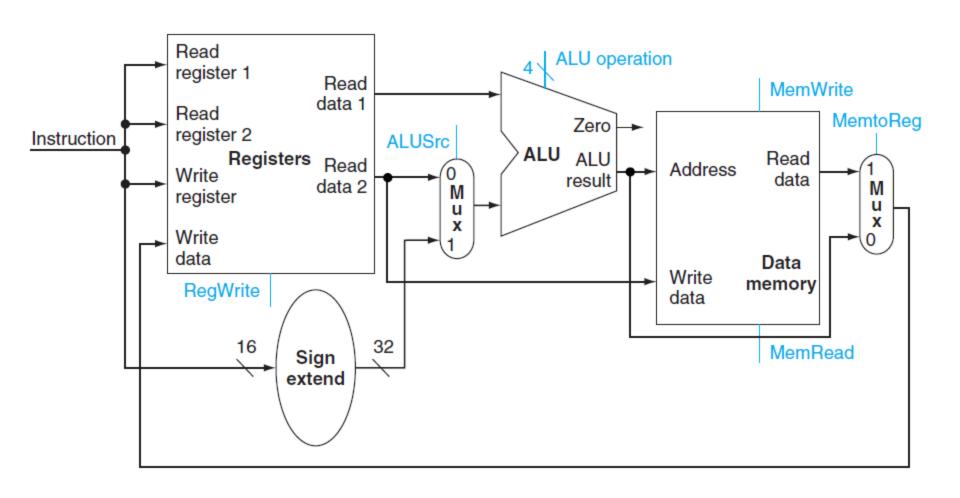


Executing Branch Operations

- Branch operations involves
 - compare the operands read from the Register File during decode for equality (zero ALU output)
 - compute the branch target address by adding the updated PC to
 the 16-bit signed-extended offset field in the instr



Datapath for the Memory Instruction and R-type instruction



A Simple Datapath for the MIPS Architecture

