0DBSCAN Algorithm:

DBSCAN Problem1:

- Apply the DBSCAN algorithm to the given data points and
- Create the clusters with
- minPts = 4 and
- epsilon (ε) = 1.9.

Data Points:

P1: (3, 7)	P2: (4, 6)
P3: (5, 5)	P4: (6, 4)
P5: (7, 3)	P6: (6, 2)
P7: (7, 2)	P8: (8, 4)
P9: (3, 3)	P10: (2, 6)
P11: (3, 5)	P12: (2, 4)

Similarity threshold is less than 1.9

minPts = 4 and epsilon (ε) = 1.9

	P1	P2	P3	P4	P5	P6	P7	P8	P9	P10	P11	P12
P1	0	1.41								1.41		
P2	1.41	0	1.41								1.41	
P3	2.83	1.41	0	1.41								
P4	4.24	2.83	1.41	0	1.41							
P5	5.66	4.24	2.83	1.41	0	1.41	1.0	1.41				
P6	5.83	4.47	3.16	2.00	1.41	0	1.0					
P7	6.40	5.00	3.61	2.24	1.00	1.00	0					
P8	5.83	4.47	3.16	2.00	1.41	2.83	2.24	0				
P9	4.00	3.16	2.83	3.16	4.00	3.16	4.12	5.10	0			1.41
P10	1.41	2.00	3.16	4.47	5.83	5.66	6.40	6.32	3.16	0	1.41	
P11	2.00	1.41	2.00	3.16	4.47	4.24	5.00	5.10	2.00	1.41	0	1.41
P12	3.16	2.83	3.16	4.00	5.10	4.47	5.39	6.00	1.41	2.00	1.41	0

P1: P2, P10
P2: P1, P3, P11
P3: P2, P4
P4: P3, P5
P5: P4, P6, P7, P8
P6: P5, P7
P7: P5, P6
P8: P5
P9: P12
P10: P1, P11
P11: P2, P10, P12
P12: P9, P11

P1: P2, P10

P2: P1, P3, P11

P3: P2, P4

P4: P3, P5

P5: P4, P6, P7, P8

P6: P5, P7

P7: P5, P6

P8: P5

P9: P12

P10: P1, P11

P11: P2, P10, P12

P12: P9, P11

minPts = 4 and epsilon (ε) = 1.9

Point	Status	
P1	Noise	Border
P2	Core	
P3	Noise	Border
P4	Noise	Border
P5	Core	
P6	Noise	Border
P7	Noise	Border
P8	Noise	Border
P9	Noise	
P10	Noise	Border
P11	Core	
P12	Noise	Border

P1: P2, P10

P2: P1, P3, P11

P3: P2, P4

P4: P3, P5

P5: P4, P6, P7, P8

P6: P5, P7

P7: P5, P6

P8: P5

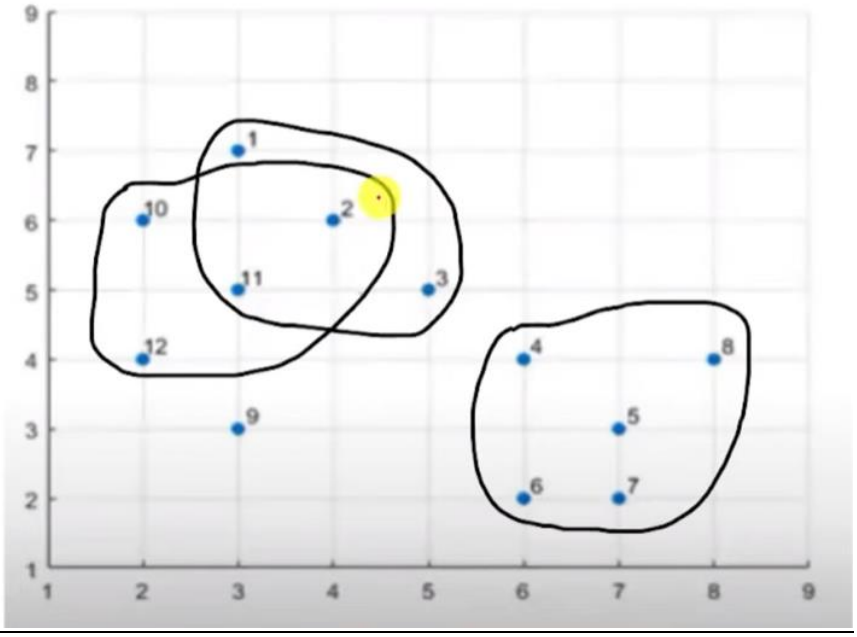
P9: P12

P10: P1, P11

P11: P2, P10, P12

P12: P9, P11

minPts = 4 and epsilon (ε) = 1.9



DBSCAN Problem 2:

Apply the DBSCAN algorithm with similarity threshold of 0.8 (using the similarity matrix) to the given data points and MinPts>=2 (Minimum required points in a cluster) what are core, border and noise (outliers) in the set of points given in table.

	P1	P2	P3	P4	P5
P1	1.00	0.10	0.41	0.55	0.35
P2	0.10	1.00	0.64	0.47	0.98
P3	0.41	0.64	1.00	0.44	0.85
P4	0.55	0.47	0.44	1.00	0.76
P5	0.35	0.98	0.85	0.76	1.00

minPts = 2 and Similarity Index = 0.8

	P1	P2	P3	P4	P5
P1	1.00	0.10	0.41	0.55	0.35
P2	0.10	1.00	0.64	0.47	0.98
P3	0.41	0.64	1.00	0.44	0.85
P4	0.55	0.47	0.44	1.00	0.76
P5	0.35	0.98	0.85	0.76	1.00

P1: -

P2: P5

P3: P5

P4: -

P5: P2, P3

Point	Status	
P1	Noise	
P2	Core	
P3	Core	
P4	Noise	
P5	Core	

No Border Points in the given dataset