Définition du style : Exi\_trace

# **LLR DOC**

**OVSP - MODES** 

SOFTWARE DETAILED DESIGN DESCRIPTION

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# 1. MODES REQUIREMENTS SPECIFICATION

# 1.1. COMMON DESIGN AND PHYSICAL CONSTRAINTS

The Modes component doesn't contain any requirement or constraint which concern several or al functionalities simultaneously. This paragraph gathers requirements and constraints, which concern several or all functionalities simultaneously.

### 1.2. MODES\_GET\_SW\_MODE

# 1.2.1. Modes\_Get\_SW\_Mode

This function provides the  $\underline{s} \mathbb{S} \text{oftware mode}.$ 

### 1.2.1.1. Parameters and Return Value

#### **Parameters**

• Function return: The OVSP-software mode (V\_Modes\_SW\_Mode) (TE\_Modes\_SW\_Mode)

#### Pre-conditions on parameters

None

### 1.2.1.2. Called Functions

None

# 1.2.1.3. Input/Output Data

#### Data

• IN: {V\_Modes\_SW\_Mode}

# Pre-conditions on data

None

a mis en forme : Anglais (États-Unis)

a mis en forme : Anglais (États-Unis)

### 1.2.1.4. Requirements

### REQ-SDDD\_Modes\_Get\_SW\_Mode\_0001-01

Modes\_Get\_SW\_Mode

	Causes	Causes
	<u>ALWAYS</u> <u>Always</u>	ALWAYS <u>Always</u>
Effects	Return {V_Modes_SW_Mode}	{V_Modes_SW_Mode}
Traceal Rationa		nine the Software mode to apply and provides it

allowing them to adapt their behaviour. This function is needed to provide the Software mode. Test

Verification Method

[END\_REQ]

# 1.3. MODES\_INITIALIZE

# 1.3.1. Modes\_Initialize

This function initializes the Modes CSC.

#### 1.3.1.1. Parameters and Return Value

#### **Parameters**

• Function return: Not used.

Pre-conditions on parameters

None

### 1.3.1.2. Called Functions

None

# 1.3.1.3. Input/Output Data

#### Data

• OUT: {V\_Modes\_SW\_Mode}

Pre-conditions on data

None

# 1.3.1.4. Requirements

# REQ-SDDD\_Modes\_Initialize\_0001-01

[COV.REQ\_OVSP\_SRD-00001]

a mis en forme : Retrait : Gauche : 1 cm, Suspendu : 3,4 cm

### Modes\_Initialize

			Causes	
Effects			<u>Always</u> ALWAYS	
Effects			Set {V_Modes_SW_Mode} to E_Modes_Init	
Traceal		Refined		
Rationa	ıle	-		
Verifica	tion Method	Test		

[END\_REQ]

# 1.4. MODES\_MANAGE\_DEGRADED\_TR

# 1.4.1. Modes\_Manage\_Degraded\_Tr

This function manages the SW-software mM-ode transition in dD-egraded mode.

#### 1.4.1.1. Parameters and Return Value

#### **Parameters**

• Function return: Not usedused.

# Pre-conditions on parameters

None

### 1.4.1.2. Called Functions

# Calls

- CBIT\_Get\_Test\_Result
- Config\_Get\_Integrity\_Status
- DrvFTM\_Start\_NxOSy\_Acq

# Post-conditions

None

# 1.4.1.3. Input/Output Data

• <u>IN/</u>OUT: {V\_Modes\_SW\_Mode}

# Pre-conditions on data

None

a mis en forme le tableau

#### 1.4.1.4. Requirements

# REQ-SDDD\_Modes\_Manage\_Degraded\_Tr\_0001-01

[COV.REQ\_OVSP\_SRD-00004COV.REQ\_OVSP\_SRD-00007; COV.REQ\_OVSP\_SRD-00004; COV. REQ\_OVSP\_SRD-00021]

# Modes\_Manage\_Degraded\_Tr

	Causes							
	<u>Always</u> ALWAYS							
	Get the CBIT Test Result][Provide the CBIT tTest rResult]							
	"CBIT Test Resultv_CBIT_Result" (V_CBIT_Test_Result) is equal to E_CBIT_Fatal_Error	All-the other cases						
		[Get the OVSP Config table Integrity Status]						
Effects	Set {V Modes SW Mode} to E Modes Fail	"OVSP Config table Integrity Statusv_OVSP_Config_Validity" {V_Config_OVSP_Cfg_Integrity} is equal to E_Config_Integrity_OK	All-the other cases					
		Set {V_Modes_SW_Mode} to E_Modes_Operational <u>CALL_CallCALL</u> DrvFTM_Start_NxOSy_Acq	No effect					
[Get the C	CBIT Test Result] [Provide the CBIT tTest rRes	ult]: corresponds to the following CALL:						
• (	CALL CBIT_Get_Test_Result with the following	g parameters:						
_	- RETURN Function return: "CBIT Test Resultv CBIT Result" (V_CBIT_Test_Result)							
[Get the OVSP Config table Integrity Status] [Provide the OVSP config table iIntegrity status]: corresponds to the following CALL:								
• -	CALL Config_Get_Integrity_Status with the following parameters:							
	RETURN Function return: usv_OVSP_Config_Validity"(V_Config_OVSP_	-"OVSP Config table Cfg_Integrity}	Integrity					

Causes

a mis en forme : Retrait : Gauche : 0,4 cm, Sans numérotation ni puces

a mis en forme le tableau

a mis en forme : Police :Non Gras

a mis en forme : Police :Non Gras

a mis en forme : Retrait : Gauche : 0,8 cm, Sans numérotation ni puces

a mis en forme : Retrait : Gauche : 0,4 cm, Sans numérotation ni puces

a mis en forme : Retrait : Gauche : 0,8 cm, Sans numérotation ni puces

[END\_REQ]

# 1.5. MODES\_MANAGE\_INIT\_TR

Refined Test

# 1.5.1. Modes\_Manage\_Init\_Tr

This function manages the SW-software m-Mode transition in  $\underline{H}$ -nit mode.

# 1.5.1.1. Parameters and Return Value

#### **Parameters**

Traceability Rationale Verification Method

• Function return: Not used.

#### Pre-conditions on parameters

None

#### 1.5.1.2. Called Functions

#### Calls

- Boot\_Get\_Side\_Id
- PBIT\_Get\_Test\_Result
- Config\_Get\_Integrity\_Status
- DrvFTM\_Start\_NxOSy\_Acq

#### **Post-conditions**

None

### 1.5.1.3. Input/Output Data

#### Data

• OUT: {V\_Modes\_SW\_Mode}

#### Pre-conditions on data

None

### 1.5.1.4. Requirements

# REQ-SDDD\_Modes\_Manage\_Init\_Tr\_000<u>1</u>5-01

[COV.REQ\_OVSP\_SRD-0000011; COV.REQ\_OVSP\_SRD-00002; COV.REQ\_OVSP\_SRD-00004; COV.REQ\_OVSP\_SRD-00021]

Modes\_Manage\_Init\_Tr

Causes <u>Always</u> [Get the OVSP side identification] [Get the PBIT test result] "OVSP Side Identification" is equal to BOOT SIDE ID INVALID OR "PBIT test Result" is equal to E\_PBIT\_Failed All-the other cases **Effects** [Get the OVSP config table integrity status] "OVSP Config table Integrity Status" is Set {V Modes SW Mode} to E Modes Fail All\_the\_other cases equal to E Config Integrity <u>KO</u> Set {V Modes SW Mod Set {V\_Modes\_SW\_Mode} to E\_Modes\_Operational

**a mis en forme :** Pas de saut de page avant, Pas de paragraphes solidaires, Pas de lignes solidaires

a mis en forme : Pas de paragraphes solidaires

**a mis en forme :** Pas de paragraphes solidaires

		e} to E_Modes_Degraded	CALL DrvFTM_Start_NxOSy_Acq		
		Causes		4	a mis en forme : Pas de paragraphes solidaires
	AlwaysALWAYS				
	IGetProvide the OVSP-side identification]				
		he PBIT tTest rResult]	<del>''']</del>		a mis en forme : Police :Non Gras
	"OVSP Side  Identificationy OVSP Side Id{V_Boot_OV  SP_Side_Id}" is equal to  BOOT_SIDE_ID_INVALID OR "PBIT test  Resulty_PBIT_Result{V_PBIT_Test_Result}  "is equal to E_PBIT_Failed		<del>e other cases</del>		
ffects		-	VSP <u>c</u> Config table <u>i</u> Integrity		a mis en forme : Police :Non Gras
			<u>sStatus</u>		a mis en forme : Pas de paragraphes solidaires
	Set {V_Modes_SW_Mode} to E_Modes_Fail	"OVSP Config table Integrity Status" is equal to E Config Integrity KO	All the other cases		
		Set  {V_Modes_SW_Mod e} te  E_Modes_Degraded	Set {V_Modes_SW_Mode} to E_Modes_Operational CALL DrvFTM_Start_NxOSy_Acq		
ovide (	Get the OVSP side identification - corresponds	s to the following CALL		•	a mis en forme : Police :Non Gras
• (	CALL <b>Boot_Get_Side_Id</b> with the following pa	arameters:			a mis en forme : Police :Non Gras
	RETURN Function retu		"OVSP Side		<b>a mis en forme :</b> Pas de paragraphes solidaires, Lignes solidaires
	Get the PBIT tTest rResult: corresponds to the				a mis en forme: Retrait: Gauche: 0,4 cm, Sans numérotation ni puces, Éviter veuves et orphelines, Ligne solidaires
_	RETURN Function return: "PBIT test Res	ultv_PBIT_Result" (V_l	PBIT_Test_Result}	•	a mis en forme : Retrait : Gauche : 0,8 cm, Sans numérotation ni puces
	<u>Get</u> the OVSP <u>c</u> Config table <u>i</u> l⊦ntegrity <u>s</u> Status]		llowing CALL:	\\\\	a mis en forme : Police :Non Gras
	CALL Config_Get_Integrity_Status with the following parameters:				a mis en forme : Police :Non Gras
Stat	RETURN Function return: usv_OVSP_Config_Validity"{V_Config_OVSP	<pre>- "OVSP Config - Cfg_Integrity}</pre>	g table Integrit		<b>a mis en forme :</b> Pas de paragraphes solidaires, Lignes solidaires
Rat	ceability Refined ionale - iffication Method Test				a mis en forme: Retrait: Gauche: 0,4 cm, Sans numérotation ni puces, Éviter veuves et orphelines, Ligne solidaires
ND_REQ	1				a mis en forme : Retrait : Gauche : 0,8 cm, Sans numérotation ni puces
.6. M	ODES_MANAGE_OPERATIONAL	\\	a mis en forme : Police :Non Gras		
					a mis en forme : Police :Non Gras
.6.1.	Modes_Manage_Operational_Tr			\	a mis en forme : Retrait : Gauche : 0,4 cm, Sans numérotation ni puces
					Y

This function manages the SW-software mMode transition in oOperational mode.

a mis en forme : Retrait : Gauche : 0,8 cm, Sans numérotation ni puces

#### 1.6.1.1. Parameters and Return Value

#### **Parameters**

• Function return: Not usedused.

### Pre-conditions on parameters

None

### 1.6.1.2. Called Functions

#### Calls

- CBIT\_Get\_Test\_Result
- Config\_Get\_Integrity\_Status
- DrvFTM\_Stop\_NxOSy\_Acq
- CAN\_Get\_TriggTest\_Cmd
- OVSP\_Get\_Engine\_SpeedLevel
- CAN\_Get\_Test\_Speed
- DrvFTM\_Stop\_NxOSy\_Acq
- DrvFTM\_Manage\_TSpeed

#### Post-conditions

None

# 1.6.1.3. Input/Output Data

#### Data

• <u>IN/</u>OUT: {V\_Modes\_SW\_Mode}

# Pre-conditions on data

None

### 1.6.1.4. Requirements

# REQ-SDDD\_Modes\_Manage\_Operational\_Tr\_0001-01

[COV.REQ\_OVSP\_SRD-00007; COV.REQ\_OVSP\_SRD-000021; COV.REQ\_OVSP\_SRD-00005]
[COV.REQ\_OVSP\_SRD-00007; COV.REQ\_OVSP\_SRD-00021; COV.REQ\_OVSP\_SRD-00005]
00005[COV.REQ\_OVSP\_SRD-00003; COV.REQ\_OVSP\_SRD-00007; COV.REQ\_OVSP\_SRD-000069; COV.REQ\_OVSP\_SRD-00007]

# Modes\_Manage\_Operational\_Tr

		Caus	es	•		a mis en forme le tableau
		<u>Always</u> AL				
	[Get	et the CBIT Test Result][Provide the CBIT tTest rResult]			a mis en forme : Police :Non Gras	
	"CBIT Test Resulty CBIT Result{ V_CBIT_Test_Result} "is equal to E_CBIT_Fatal_Error		All-the other cases			
		Provide Get the	OVSP <u>c</u> Config table <u>i</u> Integrity <u>s</u> Status]			a mis en forme : Police :Non Gras
		"OVSP Config table Integrity Statusv OVSP Config Validity" (V_Config_OVS P_Cfg_Integrity) is equal to E_Config_Integrity_KO	All- <del>the</del> other cases			a mis en forme : Police :Non Gras
		Set {V_Modes_SW_Mode} to E_Modes_Degraded	[Provide Get the CAN taringgered tarest command] [Provide Get the employed [Level]]			a mis en forme : Police :Non Gras
	Set {V_Modes_SW_Mode} to E_Modes_Fail					a mis en forme : Police :Non Gras
Effects						a mis en forme : Police :Non Gras
			"CAN Triggered Test commandy-TriggTest_Cmd{V_CAN_T riggTest_cmd}" is equal to E_CAN_TriggTest_On AND "Engine Speed Levely-Engine_SpeedLevel" {V_OVSP_Context_Out.V_Engine_Sp eedLevel}-is equal to E_OVSP_SW_Low_Speed	All the other cases		
			Set {V_Modes_SW_Mode} to			a mis en forme : Police :Non Gras
			E_Modes_TriggeredTest			
			<u>[Provide Get the CAN t∓riggered t∓est speed]</u>			a mis en forme : Police :Non Gras
			<u>CallALLCALL</u>	No		a mis en forme : Police :Non Gras
			DrvFTM_Stop_NxOSy_Acq CallALLCALL DrvFTM_Manage_TSpeed with IN "CAN Triggered Test speedv_TriggTest_Speed"[Manage the Test Speed]	effect		a mis en forme : Police :Non Gras
Get the C	CBIT Test Result] [Provid	e the CBIT tTest rResult): (	corresponds to the following CALL:			
		esult with the following pa		•		a mis en forme : Retrait : Gauche : 0,4 cm, Sans numérotation ni puces

DETURN Function action (CRIT Tool Book) ORIT Tool Book (CRIT Tool Book)	a mis en forme : Retrait : Gauche : 0,8 cm, Sans
- RETURN Function return: "CBIT Test Resultv_CBIT_Result" (V_CBIT_Test_Result)	numérotation ni puces
[Get the OVSP config table integrity status] [Provide the OVSP config table integrity status]: corresponds to the following CALL:	
• CALL Config_Get_Integrity_Status with the following parameters:	a mis en forme : Retrait : Gauche : 0,4 cm, Sans numérotation ni puces
- RETURN Function return: "OVSP Config table Integrity Statusy OVSP Config Validity" (V_Config_OVSP_Cfg_Integrity)	a mis en forme: Retrait: Gauche: 0,8 cm, Sans numérotation ni puces
[Get the CAN triggered test command] [Provide the CAN triggered test command]: corresponds to the following CALL:	a mis en forme : Police :Non Gras
CALL CAN_Get_TriggTest_Cmd with the following parameters:	a mis en forme : Retrait : Gauche : 0,4 cm, Sans numérotation ni puces
- RETURN Function return: "CAN Triggered Test" commandv_TriggTest_Cmd"(V_CAN_TriggTest_cmd)	a mis en forme : Retrait : Gauche : 0,8 cm, Sans numérotation ni puces
[Get the engine speed level] [Provide the eEngine sSpeed Level]: corresponds to the following CALL:	
CALL OVSP_Get_Engine_SpeedLevel with the following parameters:      RETURN Function return: "Engine Speed"	<b>a mis en forme :</b> Retrait : Gauche : 0,4 cm, Sans numérotation ni puces
Levelv Engine SpeedLevel" (V_OVSP_Context_Out.V_Engine_SpeedLevel)	a mis en forme : Retrait : Gauche : 0,8 cm, Sans numérotation ni puces
[Get the CAN triggered test speed] [Provide the CAN triggered test speed]: corresponds to the following CALL:	a mis en forme : Police :Non Gras
CALL CAN_Get_Test_Speed with the following parameters:	a mis en forme : Retrait : Gauche : 0,4 cm, Sans numérotation ni puces
	a mis en forme : Retrait : Gauche : 0,8 cm, Sans numérotation ni puces
[Manage the Test Speed]: corresponds to the following CALL	
CALL DrvFTM_Manage_TSpeed with the following parameters:	a mis en forme : Exi_texte
- IN: {V_CAN_Test_Speed.U_Value_32BitFloat} Traceability Retined	a mis en forme : Retrait : Gauche : 0,8 cm, Sans numérotation ni puces
Rationale - Verification Method Test	
[END_REQ]	
1.7 MODES MANAGE TRIGGTEST TR	

#### 1.7. MODES\_MANAGE\_TRIGGTEST\_TR

# 1.7.1. Modes\_Manage\_TriggTest\_Tr

This function manages the SW-software mMode transition in  $\underline{\mathtt{Tt}}$ -riggered  $\underline{\mathtt{Tt}}$ -est mode.

# 1.7.1.1. Parameters and Return Value

#### **Parameters**

• Function return: Not <u>used\_used.</u>

Pre-conditions on parameters

None

# 1.7.1.2. Called Functions

Calls

- CBIT\_Get\_Test\_Result
- CAN\_Get\_TriggTest\_Cmd
- Boot\_Get\_Side\_Id
- DrvGPIO\_Write
- DrvFTM\_Stop\_CAM\_Generation
- \_\_DrvFTM\_Stop\_Tspeed
- <u>DrvFTM\_Init\_TSpeedOut\_Values</u>
- \_\_DrvFTM\_Start\_NxOSy\_Acq
- CAN\_Reset\_TestDiscrete\_Cmd
- CAN\_Get\_Test\_Speed
- DrvFTM\_Manage\_TSpeed

#### **Post-conditions**

None

# 1.7.1.3. Input/Output Data

#### Data

• <u>IN/</u>OUT: {V\_Modes\_SW\_Mode}

#### Pre-conditions on data

None

# 1.7.1.4. Requirements

REQ-SDDD\_Modes\_Manage\_TriggTest\_Tr\_0001-01

[COV.REQ OVSP SRD-00007; COV.REQ OVSP SRD-00021; COV.REQ OVSP SRD-00006; COV.REQ OVSP SRD-00069COV.REQ\_OVSP\_SRD-00006; COV.REQ\_OVSP\_SRD-00007]

a mis en forme : Lignes solidaires

Modes_N	Manage_TriggTest_Tr				•	a mis en forme : Lignes solidaires
		Causes				
	AlwaysALWAYS					
		Provide Get the CBIT tT	est rkesuiti			a mis en forme : Police :Non Gras
	"CBIT Test Resulty CBIT Result (V CBIT Test Resul	Δ    +			a mis en forme : Police :Non Gras	
	th_"is equal to E_CBIT_Fatal_Error	All ti	ne other cases			
		Provide Get the CA	N <u>t</u> ∓riggered <u>t</u> ∓est comi	nand]		a mis en forme : Police :Non Gras
		"CAN Triggere	d Test			a mis en forme : Police :Non Gras
		commandv TriggTest Cmd{V_ is equal to E_CAN_T	CAN_TriggTest_cmd} <u>"</u>	All the other cases		
		Set {V_Modes_SW_Mode} to B	_Modes_Operational			
		Provide Get the OVSP si	de identification]			a mis en forme : Police :Non Gras
		<u>"OVSP side</u>				a mis en forme : Police :Non Gras
	Set {V_Modes_SW_Mod	identificationv_OVSP_Side_Id{ V_Boot_OVSP_Side_Id}_"is equal to BOOT_SIDE_ID_LS	All-the other cases			
=		CALL <b>DrvGPIO Write</b> with <b>JN</b>				a mis en forme : Police :Gras
Effects		DRVGPIO_OUT_CAM_CMD1	<del>Call-</del> CALL <del>ALL</del>			a mis en forme : Police :Gras
		and E OVSP SW Cmd Off[Write the CAM first command on the	DrvFTM_Stop_CAM_ Generation	Provide Get the		a mis en forme : Lignes solidaires
				CAN <u>t</u> ∓riggered		a mis en forme : Police :Non Gras
		<u>dDiscrete output</u> ]		<u>t</u> ∓est speed]	- \	a mis en forme : Police :Non Gras
	e} to E_Modes_Fail	<u>CallALLCALL</u> DrvFTM_	Stop_Tspeed	<u>CALLallCALL</u> DrvFTM Manag		a mis en forme : Police :Non Gras
		CALL DrvFTM Init TSpeedOut Values		e TSpeed with  JN "CAN  Triggered Test speedy TriggTes t_Speed"[Manag e the test speed]		a mis en forme : Police :Non Gras
		CALL Call CALL DrvFTM_S			a mis en forme : Police :Non Gras	
		CALL DrvGPIO_Wi	H////		a mis en forme : Police :Gras	
		DRVGPIO OUT CAM CMD2 and  E_OVSP_SW_Cmd_Off[Write the CAM second command on the dDiscrete output]				a mis en forme : Police :Gras
					1 1///	a mis en forme : Lignes solidaires
		CALL DrvGPIO_W				a mis en forme : Police :Gras
		DRVGPIO_OUT_DOUTINHIB and			\ \\	a mis en forme : Police :Non Gras
		E_OVSP_SW_Cmd_OfffWr command on the dDis			\\\\	a mis en forme : Police :Gras
		CALL <b>DrvGPIO</b> Wi	the state of the s			a mis en forme : Police :Gras
		DRVGPIO_OUT_OSAI			// //	a mis en forme : Police :Gras
		E OVSP SW Cmd Off[Write to				a mis en forme : Police :Gras
		on the dDiscrete output]				a mis en forme : Police :Gras
		CALL Call CALL CAN_Reset	_iestDiscrete_Cmd		1	a mis en forme : Police :Gras
[Get the C	CBIT test result] [Provid	e the CBIT tTest rResult]: corresp	oonds to the following C	ALL <u>:</u>		a mis en forme : Police :Non Gras
CALL (	CBIT_Get_Test_Result	t with the following parameters:				
-	RETURN Function	return: "CBIT Test Resultv_CBIT	_Result"{V_CBIT_Test_	Result}	•	a mis en forme : Retrait : Gauche : 0,8 cm, Sans numérotation ni puces

[Get the CAN triggered test command] [Provide the CAN triggered test command]: corresponds to the following CALL: CALL CAN\_Get\_TriggTest\_Cmd with the following parameters: RETURN Function return: "CAN Triggered a mis en forme: Retrait: Gauche: 0.8 cm., Sans Test commandv\_TriggTest\_Cmd" {V\_CAN\_TriggTest\_cmd} [Get the OVSP side identification] [Provide the OVSP side identification]: corresponds to the following CALL: CALL Boot\_Get\_Side\_Id with the following parameters: <u>RETURN</u> <u>Function return: "OVSP side identificationv\_OVSP\_Side\_Id"</u> (V\_Boot\_OVSP\_Side\_Id) • a mis en forme : Retrait : Gauche : 0,8 cm, Sans numérotation ni puces [Write the CAM first command on the dDiscrete output]: corresponds to the following CALL: a mis en forme : Police : Non Gras • CALL DrvGPIO\_Write with the following parameters: IN: (E OVSP SW Cmd Off) a mis en forme : Retrait : Gauche : 0,8 cm, Sans numérotation ni puces OUTIN: {DRVGPIO\_OUT\_CAM\_CMD1} IN E\_OVSP\_SW\_Cmd\_Off a mis en forme: Retrait: Gauche: 0,8 cm, Sans numérotation ni puces [Write the CAM second command on the dDiscrete output]: corresponds to the following CALL: a mis en forme : Police :Non Gras • CALL DrvGPIO\_Write with the following parameters: IN: {E\_OVSP\_SW\_Cmd\_Off} a mis en forme : Retrait : Gauche : 0,8 cm, Sans numérotation ni puces OUTIN: {DRVGPIO\_OUT\_CAM\_CMD2} - IN E\_OVSP\_SW\_Cmd\_Off a mis en forme: Retrait: Gauche: 0.8 cm. Sans [Write the DOUTINHIB command on the dDiscrete output]: corresponds to the following CALL: a mis en forme : Police : Non Gras • CALL DrvGPIO\_Write with the following parameters: a mis en forme : Retrait : Gauche : 0,8 cm, Sans IN: {E\_OVSP\_SW\_Cmd\_Off} numérotation ni puces **OUTIN:** {DRVGPIO\_OUT\_DOUTINHIB} - IN E\_OVSP\_SW\_Cmd\_Off a mis en forme: Retrait: Gauche: 0.8 cm., Sans numérotation ni puces [Write the OSARM command on the dDiscrete output]: corresponds to the following CALL: a mis en forme : Police :Non Gras • CALL DrvGPIO\_Write with the following parameters: IN: {E\_OVSP\_SW\_Cmd\_Off} a mis en forme: Retrait: Gauche: 0,8 cm, Sans OUTIN: {DRVGPIO\_OUT\_OSARM\_CMD} IN E\_OVSP\_SW\_Cmd\_Off a mis en forme: Retrait: Gauche: 0.8 cm., Sans numérotation ni puces <u>Provide-Get</u> the CAN <u>t</u>∓riggered <u>t</u>∓est speed]- corresponds to the following CALL: a mis en forme : Police : Non Gras CALL CAN\_Get\_Test\_Speed with the following parameters: a mis en forme : Police :Non Gras <u>RETURN</u>Function return: <u>"CAN</u> **Triggered** Test<sup>4</sup> a mis en forme : Police :Non Gras speedv\_TriggTest\_Speed"{V\_CAN\_Test\_Speed.U\_Value\_32BitFloat} a mis en forme: Retrait: Gauche: 0.8 cm., Sans [Manage the test speed]: corresponds to the following CALL numérotation ni puces • CALL DrvFTM\_Manage\_TSpeed with the following parameters: IN: {V\_CAN\_Test\_Speed.U\_Value\_32BitFloat} a mis en forme : Retrait : Gauche : 0,8 cm, Sans numérotation ni puces Traceability Refined Rationale Verification Method [END\_REQ]

# 1.8. MODES\_TREATMENTS

#### 1.8.1. Modes\_Treatments

This function performs the modes management treatments.

### 1.8.1.1. Parameters and Return Value

#### **Parameters**

• Function return: Not usedused.

#### Pre-conditions on parameters

None

### 1.8.1.2. Called Functions

- Modes\_Manage\_Init\_Tr
- Modes\_Manage\_Operational\_Tr
- Modes\_Manage\_Degraded\_Tr
- Modes\_Manage\_TriggTest\_Tr
- DrvGPIO\_Write
- Logbook\_Is\_Failure\_to\_Write
- OVSP\_SW\_Return\_True

# Post-conditions

None

# 1.8.1.3. Input/Output Data

• IN/OUT: {V\_Modes\_SW\_Mode}

#### Pre-conditions on data

None

# 1.8.1.4. Requirements

REQ-SDDD\_Modes\_Treatments\_0001-01

[COV.REQ\_OVSP\_SRD-00001; COV.COV.REQ\_OVSP\_SRD-00008; REQ\_OVSP\_SRD-00003; COV.REQ\_OVSP\_SRD-000044; COV.REQ\_OVSP\_SRD-00006; COV.REQ\_OVSP\_SRD-00008; COV.REQ\_OVSP\_SRD-00001]

a mis en forme : Pas de saut de page avant

a mis en forme : Non Surlignage

#### Modes\_Treatments

			Causes					
	{V_Modes_SW_ Mode} is equal to E_Modes_Init	{V_Modes_SW_Mo de} is equal to E_Modes_Operatio nal	de} is equal to	{V_Modes_SW_ Mode} is equal to E_Modes_Trigg eredTest	All the other cases			
	CALL Call CALL Modes_Manage _Init_Tr	CALL Call CALL Modes_Manage_O perational_Tr	CALL Call CALL Modes_Manage_D egraded_Tr	CALL Call CALL Modes_Manage _TriggTest_Tr	11/ Mades 5/// M			
Effects	{V_	{V_Modes_SW_Mode} is equal to E_Modes_Fail						
	CALL <b>DrvG</b> I							
	" <u>v_Log_to_W</u> write"{V_Logbo	No effect						
		n external interrupt is alt the microcontroller	No	No effect				

[Provide-Get the flag indicating there is a failure to write in FlexNVM]: corresponds to the following CALL:

CALL **Logbook\_Is\_Failure\_to\_Write** with the following parameters:

<u>RETURN</u> <u>Function return:</u> {V\_Logbook\_Failure\_to\_Write} <u>"v\_Log\_to\_WriteLogbook\_failure\_to\_write"</u>

 $[Wait until an external interrupt is executed] \underline{\ corresponds \ to \ the \ following \ CALL: to \ a \ CALL \ of \ a \ function \ provided}$ in next version of OVSP software.

CALL OVSP\_SW\_Return\_True with the following parameters:

TRUE RETURN

[Halt the microcontroller]: Enter in an infinite loop.

Traceability Rationale

RefinedExtended
The transition to E\_Modes\_Fail in the default case is used to handle an incident that could lead to a corrupted value of (V\_Modes\_SW\_Mode). It is a functional case but not specified in SRD\_Test

Verification Method

[END\_REQ]

a mis en forme le tableau

a mis en forme : Police :Non Gras a mis en forme : Police :Non Gras a mis en forme : Police :Non Gras a mis en forme : Police :Non Gras

a mis en forme : Police :Non Gras a mis en forme : Police :Non Gras

a mis en forme : Police :Non Gras a mis en forme : Police :Non Gras

**a mis en forme :** Justifié, Retrait : Gauche : 1 cm, Suspendu : 3,41 cm

# **APPENDIX 1. DATA DICTIONNARY**

Refer to the FADEX OVSP SDDD The data dictionary is common for all the OVSP CSCs and it is attached in OVSP Software Detailed Design Description Erreur! Source du renvoi introuvable..

# **APPENDIX 2. CALL TREE**

Refer to the FADEX OVSP SDDD The call Tree is common for all the OVSP CSCs and it is attached in OVSP Software Detailed Description Erreur! Source du renvoi introuvable..

# **APPENDIX 3. DELETED REQUIREMENTS**

This Appendix provides all the I	dentifiers of requirements	deleted from the project start
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None.

# **APPENDIX 4. COVERAGE MATRIX**

The COVERAGE MATRIX is common for all the OVSP CSCs and it is attached in OVSP Software Detailed Design Description [R1]. Refer to the FADEX OVSP SDDD The COVERAGE MATRIX is common for all the OVSP CSCs and it is attached in OVSP Software Detailed Design Description Erreur! Source du renvoi introuvable..

