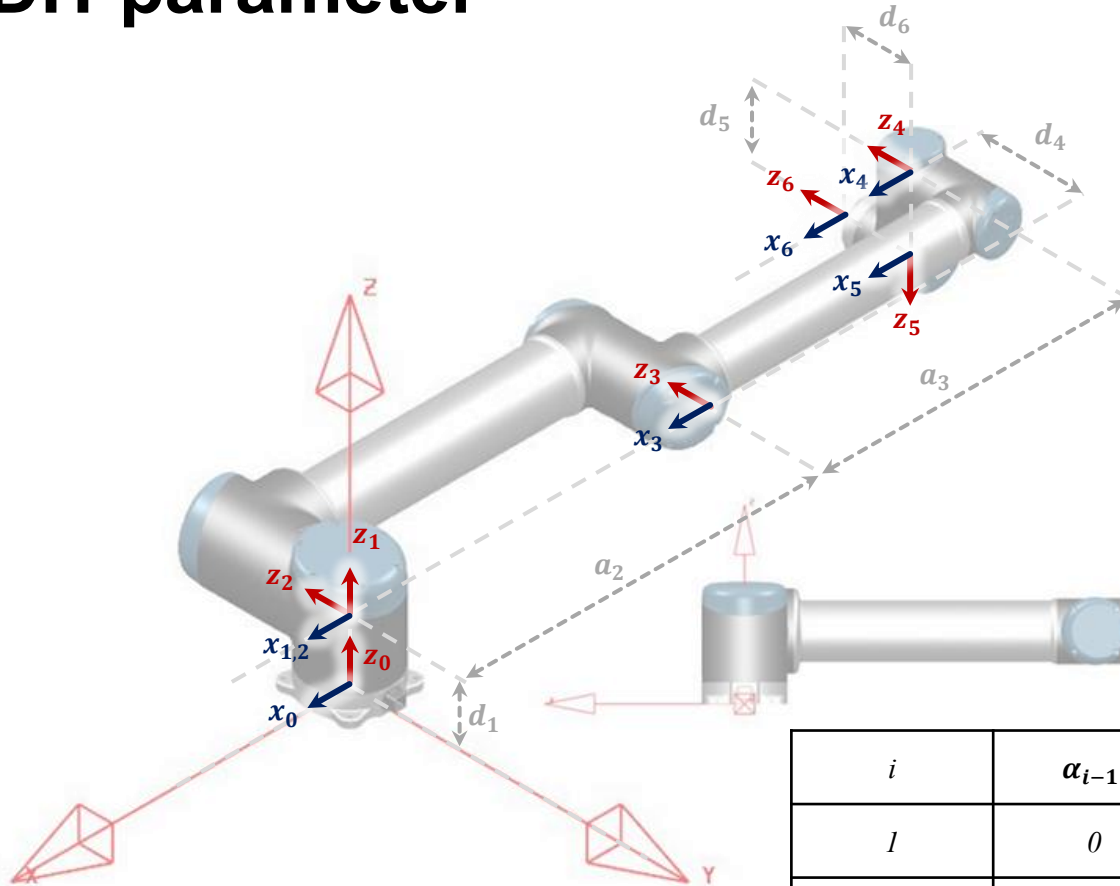# UR10 Kinematics – Craig's Ver.
DH-parameter

Zero Configuration

Link0(d_1) : 0.1273 m   Link3(d_4) : 0.163941 m

Link1(a_2) : 0.612 m   Link4(d_5) : 0.1157 m

Link2(a_3) : 0.5723 m   Link5(d_6) : 0.0922 m

i	α_{i-1}	a_{i-1}	d_i	θ_i
1	0	0	d_1	θ_1
2	$\frac{\pi}{2}$	0	0	θ_2
3	0	$-a_2$	0	θ_3
4	0	$-a_3$	d_4	θ_4
5	$\frac{\pi}{2}$	0	d_5	θ_5
6	$-\frac{\pi}{2}$	0	d_6	θ_6