

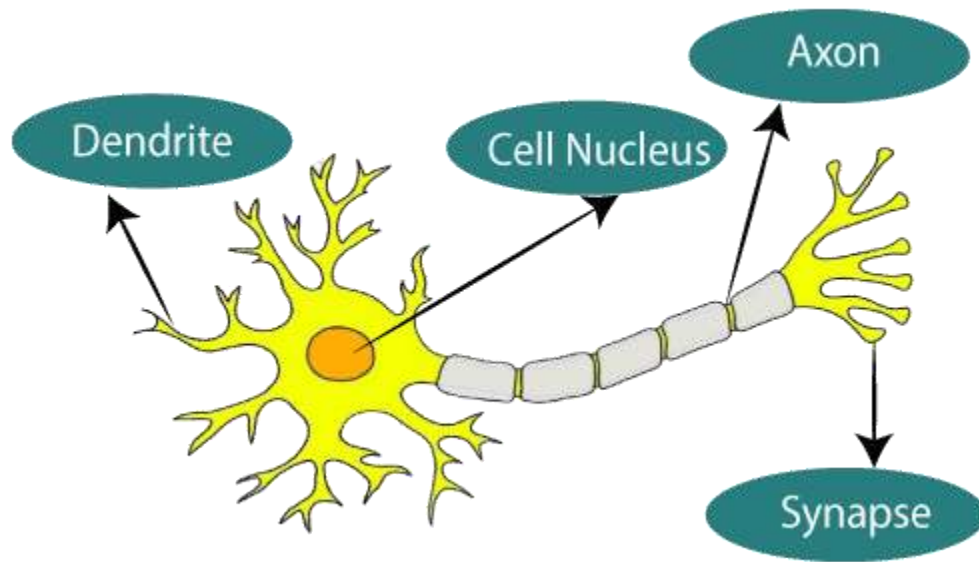
# HAIMLC701 AI & ML in Healthcare

<b>2.0</b>		<b>AI, ML, Deep Learning and Data Mining Methods for Healthcare</b>	<b>10</b>
	2.1	Knowledge discovery and Data Mining, ML, Multi classifier Decision Fusion, Ensemble Learning, Meta-Learning and other Abstract Methods.	
	2.2	Evolutionary Algorithms, Illustrative Medical Application-Multiagent Infectious Disease Propagation and Outbreak Prediction, Automated Amblyopia Screening System etc.	
	2.3	Computational Intelligence Techniques, Deep Learning, Unsupervised learning, dimensionality reduction algorithms.	

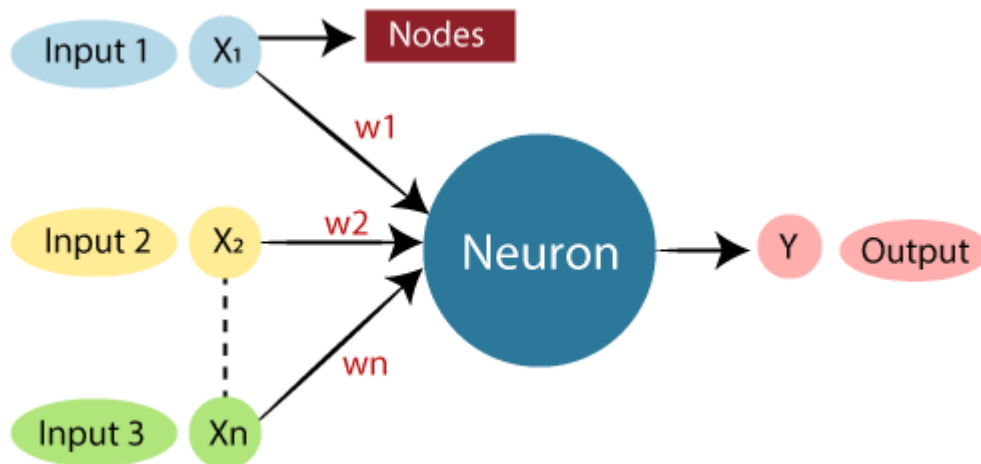
# What is Deep learning?

- Subfield of machine learning focuses on learning data representations as successive layers of increasingly meaningful representations
- **What are Neural Networks?**
- Used to mimic the basic functioning of the human brain and are inspired by how the human brain interprets information
- Used to solve various real-time tasks because of its ability to perform computations quickly and its fast responses

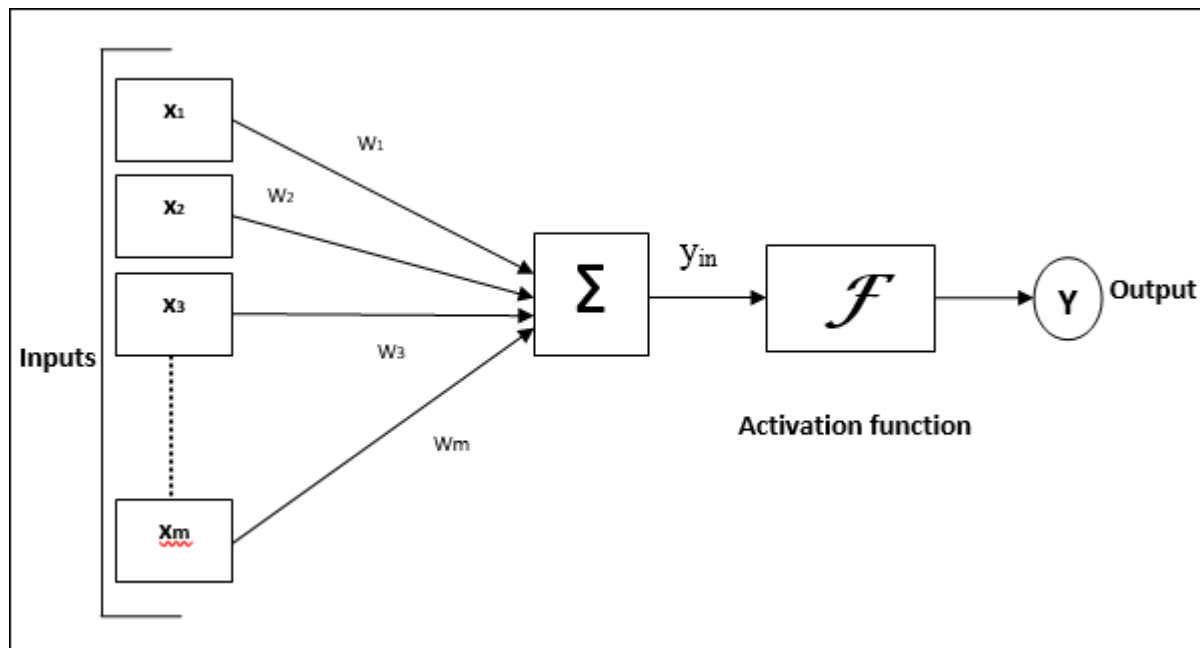
# Biological Neuron vs Artificial Neuron



Dendrites –Inputs  
cell nucleus – Nodes  
synapse –Weights  
Axon -Output



# ANN



- For the above general model of ANN, the net input can be calculated as

$$y_{in} = x_1 \cdot w_1 + x_2 \cdot w_2 + x_3 \cdot w_3 \dots x_m \cdot w_m$$

$$\text{i.e., Net input } y_{in} = \sum_i^m x_i \cdot w_i$$

The output can be calculated by applying the activation function over the net input.

$$Y = F(y_{in})$$

# Types of Neural Networks

- **ANN-** Artificial neural network
  - It is a feed-forward neural network because the inputs are sent in the forward direction
  - It can also contain hidden layers which can make the model even denser
  - They have a fixed length as specified by the programmer
  - It is used for Textual Data or Tabular Data
  - A widely used real-life application is Facial Recognition
  - It is comparatively less powerful than CNN and RNN

# Types of Neural Networks

- **CNN**– Convolutional Neural Networks
  - Mainly used for Image Data in Computer Vision
  - Some of the real-life applications are object detection in autonomous vehicles
  - Contains a combination of convolutional layers and neurons
  - More powerful than both ANN and RNN

# Types of Neural Networks

- **RNN**—Recurrent Neural Networks
  - It is used to process and interpret time series data
  - In this type of model, the output from a processing node is fed back into nodes in the same or previous layers
  - The most known types of RNN are **LSTM** (Long Short Term Memory) Networks

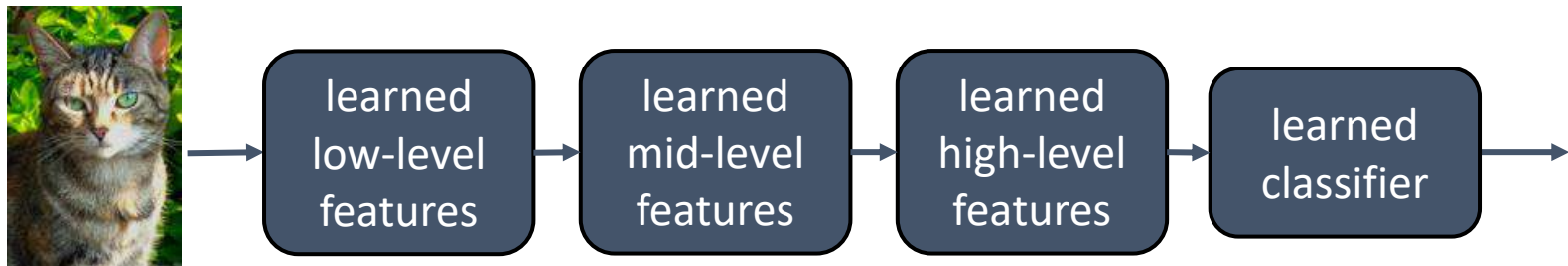
Learning in ANN can be classified into three categories namely supervised learning, unsupervised learning, and reinforcement learning.

# Machine Learning Vs Deep Learning

“Traditional” machine learning:



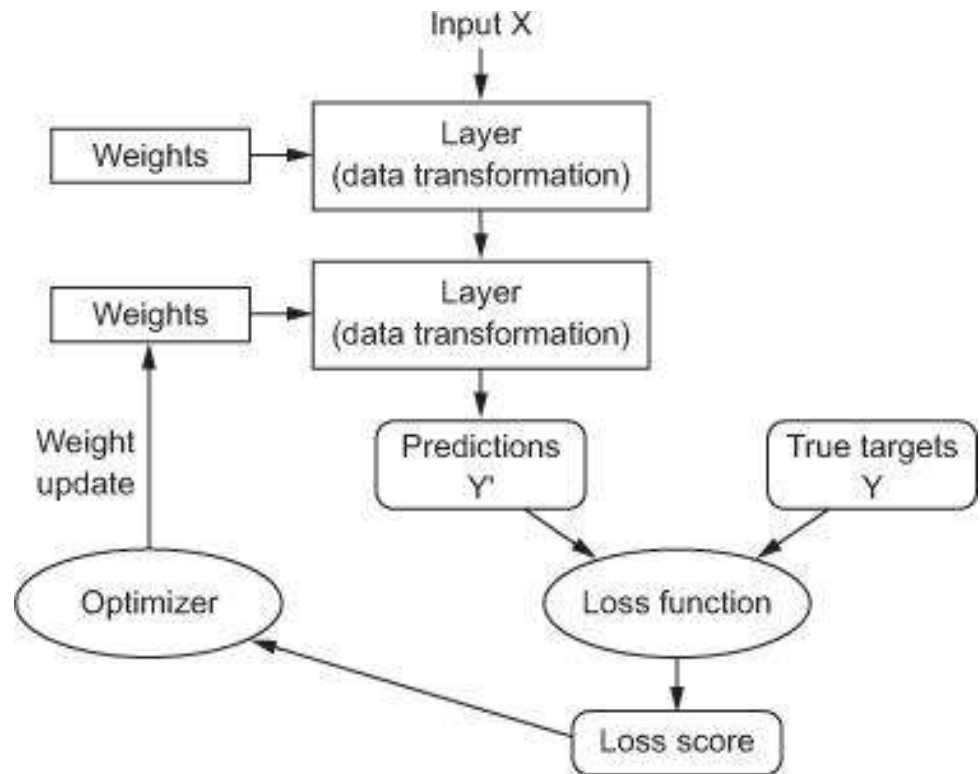
Deep, “end-to-end” learning:





# Anatomy of a deep neural network

- Layers
- Input data and targets
- Loss function
- Optimizer

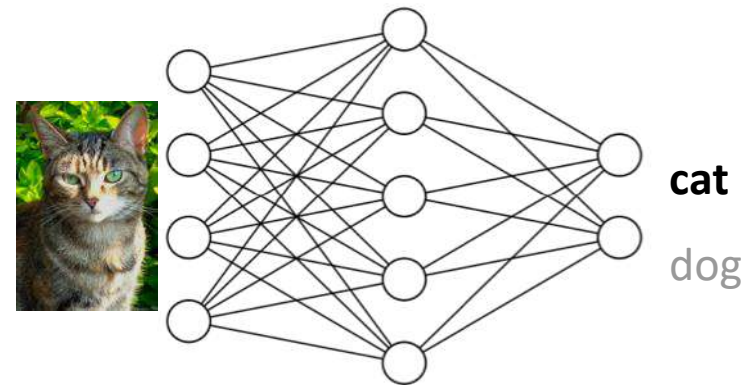
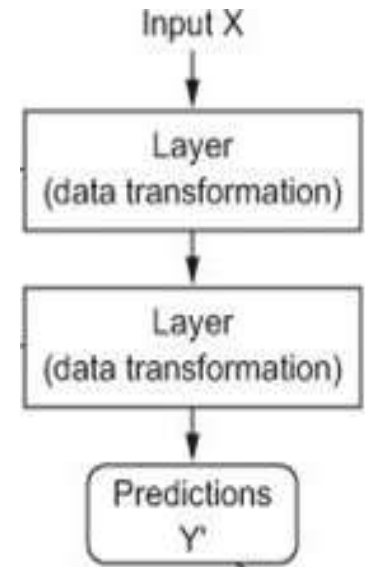


# Layers

- Data processing modules
- Many different kinds exist
  - densely connected
  - convolutional
  - recurrent
  - pooling, flattening, merging, normalization, etc.
- Input: one or more tensors  
output: one or more tensors
- Usually have a state, encoded as **weights**
  - learned, initially random
- When combined, form a **network** or a **model**

# Input data and targets

- The network maps the input data  $X$  to predictions  $Y'$
- During training, the predictions  $Y'$  are compared to true targets  $Y$  using the loss function

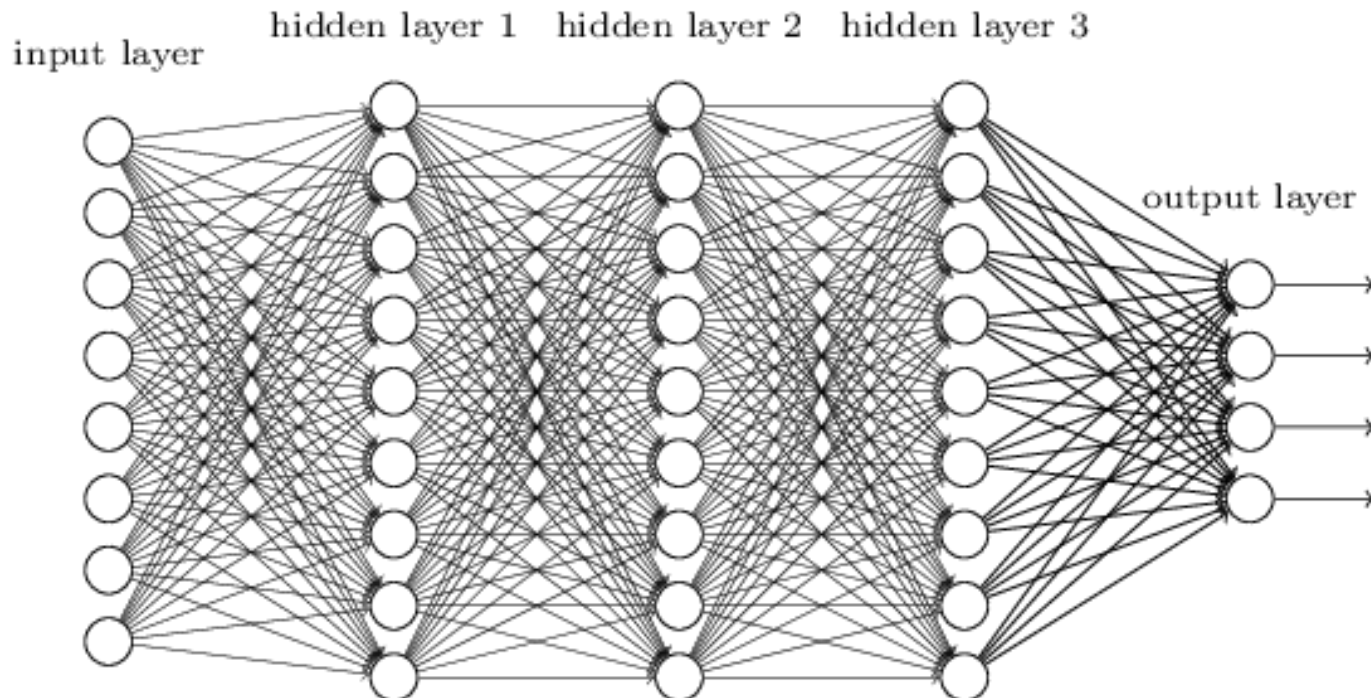


# Loss function

- The quantity to be minimized (optimized) during training
  - the only thing **the network** cares about
  - there might also be other metrics **you** care about
- Common tasks have “standard” loss functions:
  - *mean squared error* for regression
  - *binary cross-entropy* for two-class classification
  - *categorical cross-entropy* for multi-class classification
  - etc.

# CNN-Convolutional Neural Network

- Class of ANN most commonly applied to analyze visual imagery
- CNNs use a mathematical operation called convolution in place of general matrix multiplication in at least one of their layers



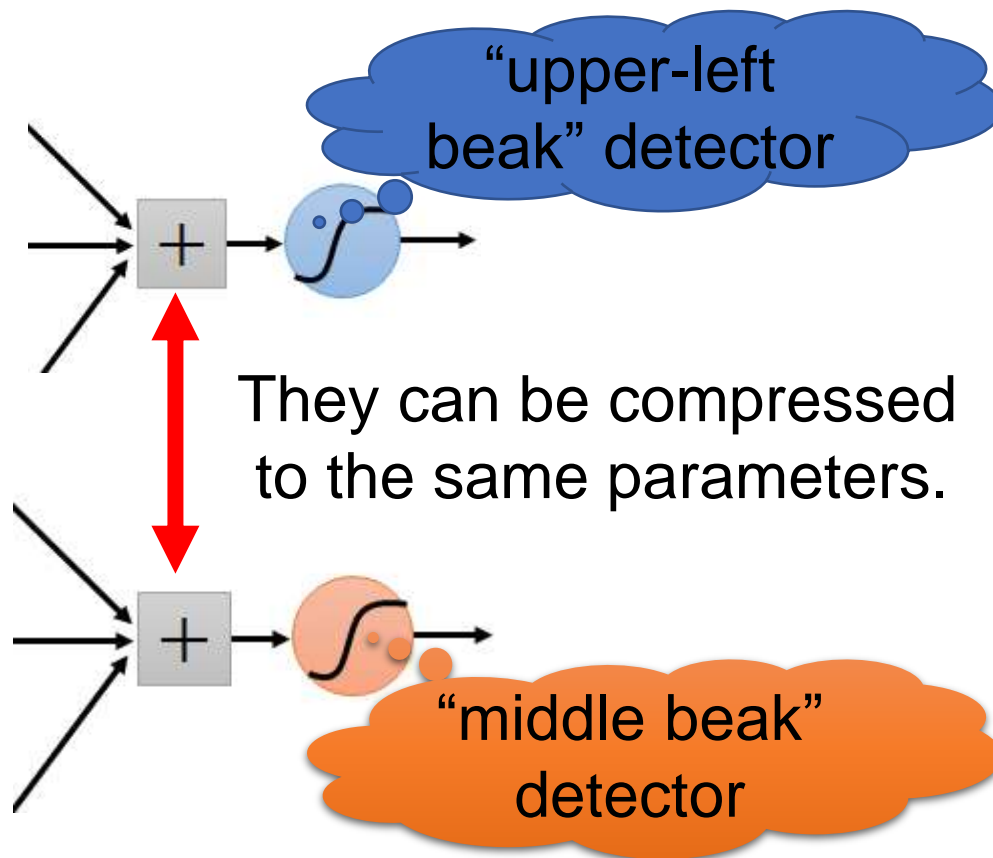
# Consider learning an image:

- Some patterns are much smaller than the whole image

Can represent a small region with fewer parameters

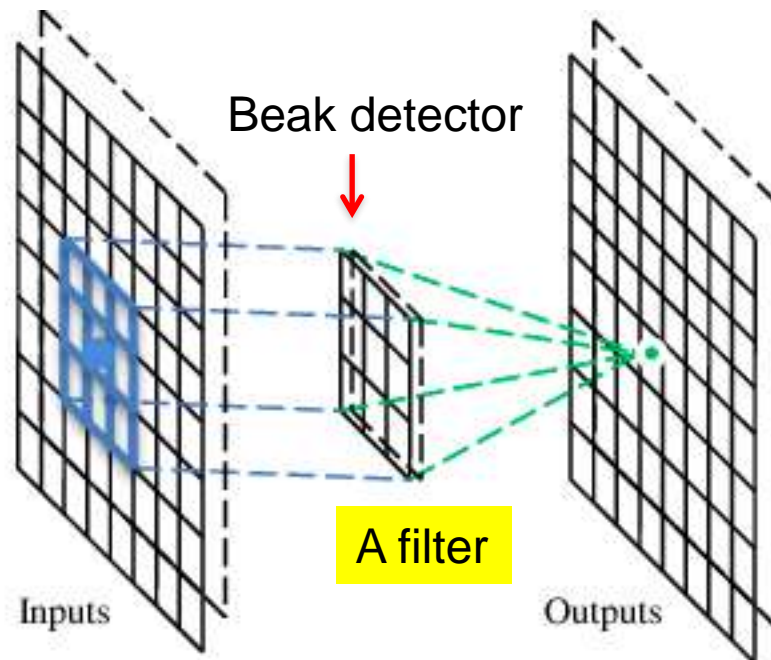


Same pattern appears in different places:  
They can be compressed!  
What about training a lot of such “small” detectors  
and each detector must “move around”.



# A convolutional layer

A CNN is a neural network with some convolutional layers (and some other layers). A convolutional layer has a number of filters that does convolutional operation





# Convolution

**These are the network parameters to be learned.**

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

6 x 6 image

1	-1	-1
-1	1	-1
-1	-1	1

Filter 1

-1	1	-1
-1	1	-1
-1	1	-1

Filter 2

⋮ ⋮

Each filter detects a small pattern (3 x 3).

# Convolution

stride=1

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

6 x 6 image

1	-1	-1
-1	1	-1
-1	-1	1

Filter 1

Dot  
product



3

-1

# Convolution

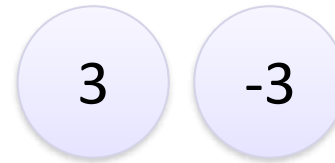
If stride=2

1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

6 x 6 image

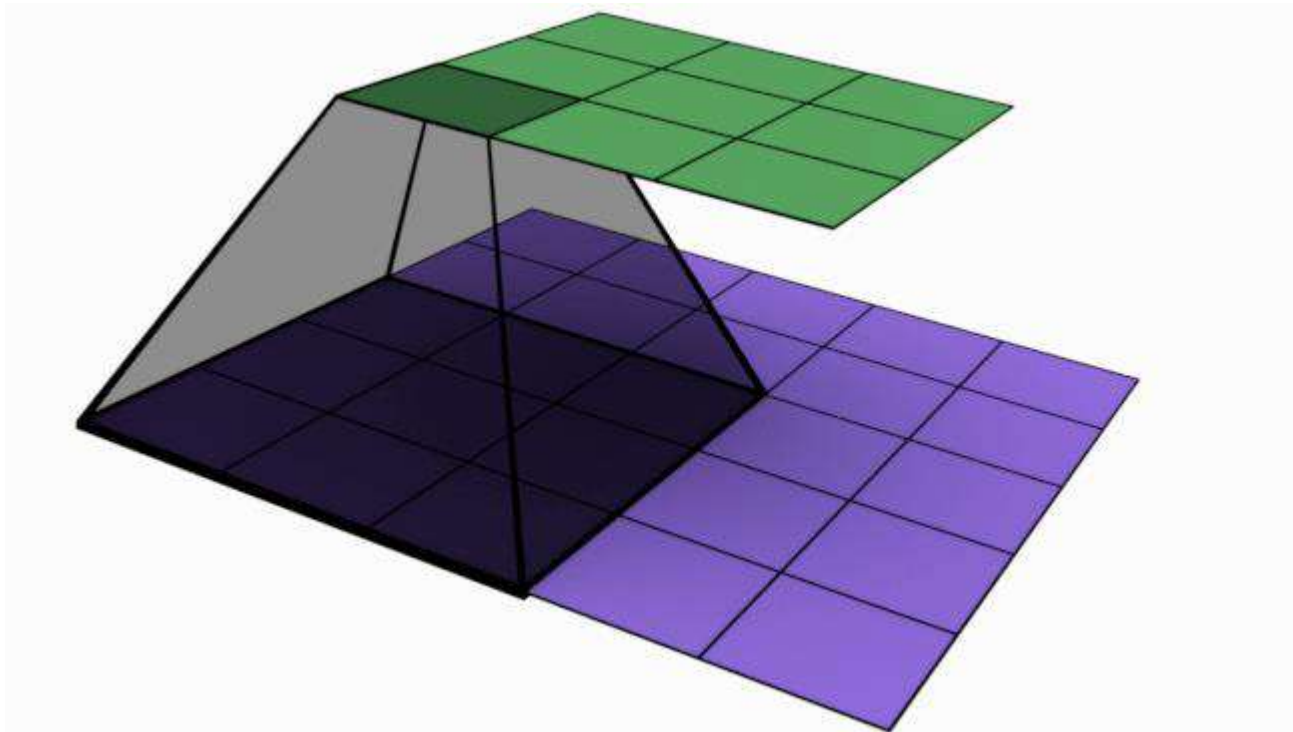
1	-1	-1
-1	1	-1
-1	-1	1

Filter 1



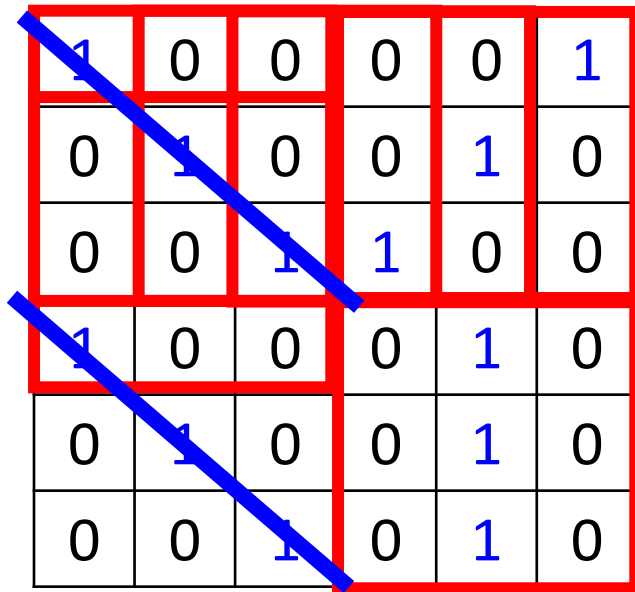
$3_0$	$3_1$	$2_2$	1	0
$0_2$	$0_2$	$1_0$	3	1
$3_0$	$1_1$	$2_2$	2	3
2	0	0	2	2
2	0	0	0	1

12.0	12.0	17.0
10.0	17.0	19.0
9.0	6.0	14.0



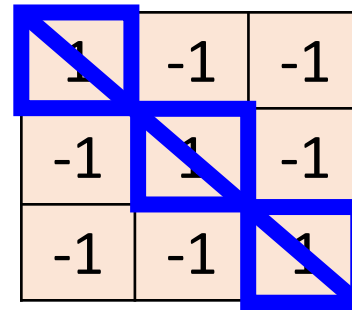
# Convolution

stride=1



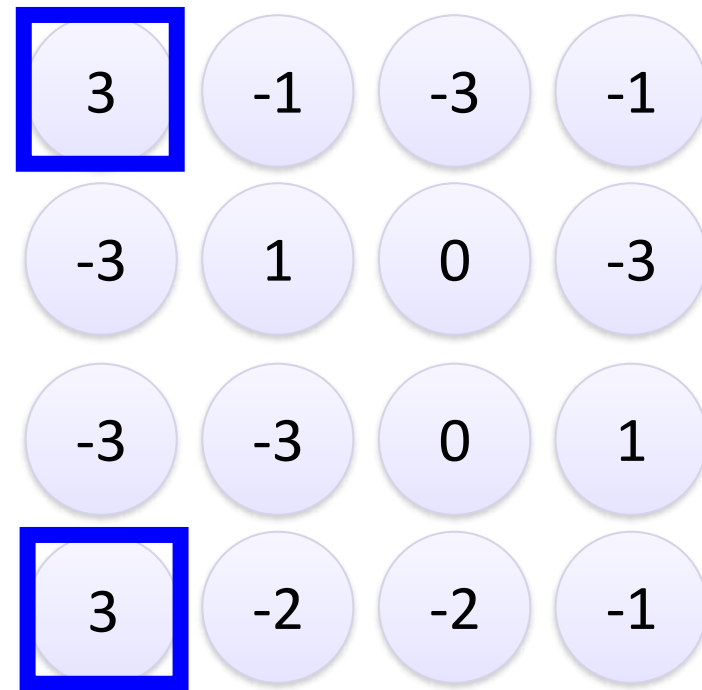
1	0	0	0	0	1
0	1	0	0	1	0
0	0	1	1	0	0
1	0	0	0	1	0
0	1	0	0	1	0
0	0	1	0	1	0

6 x 6 image



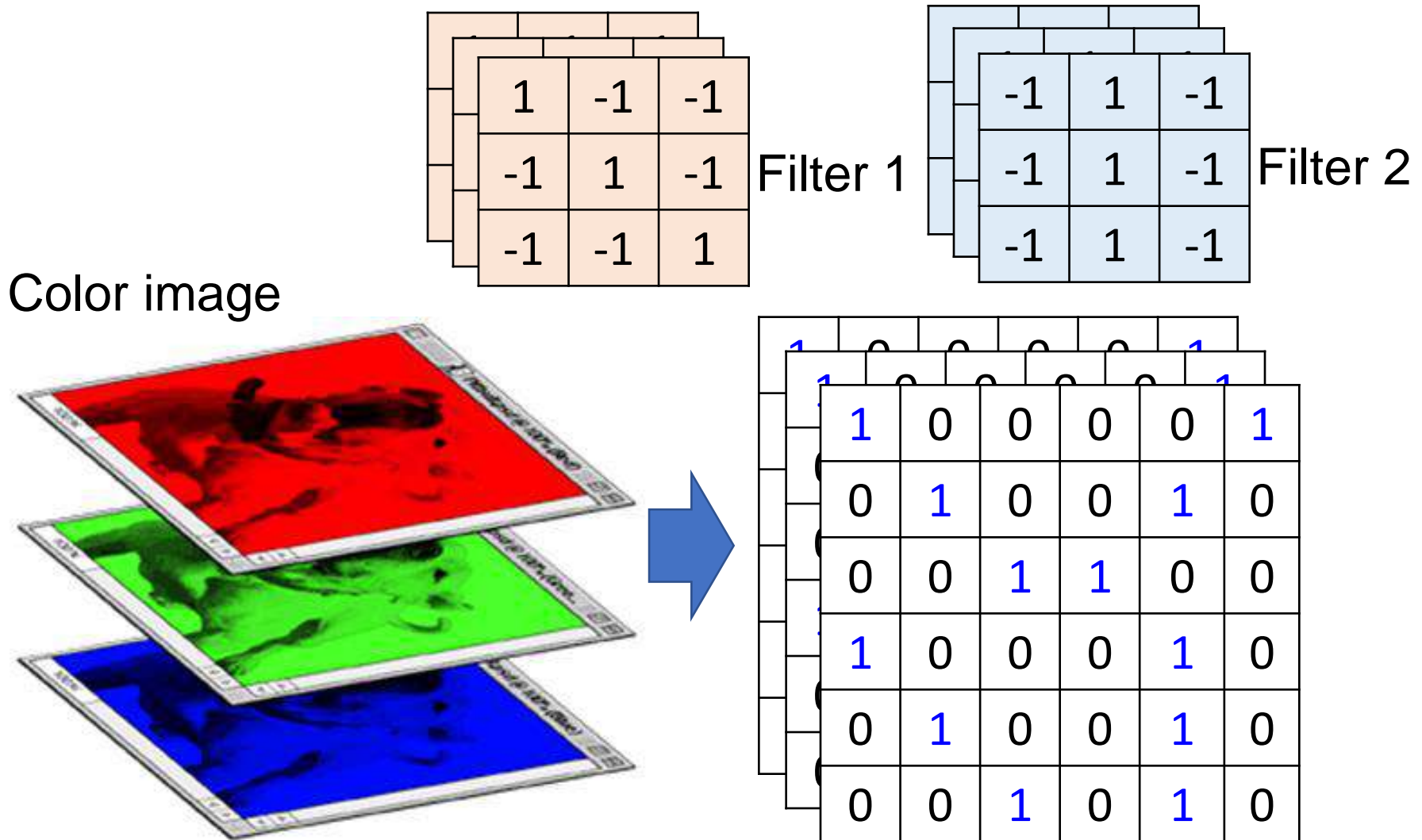
1	-1	-1
-1	1	-1
-1	-1	1

Filter 1

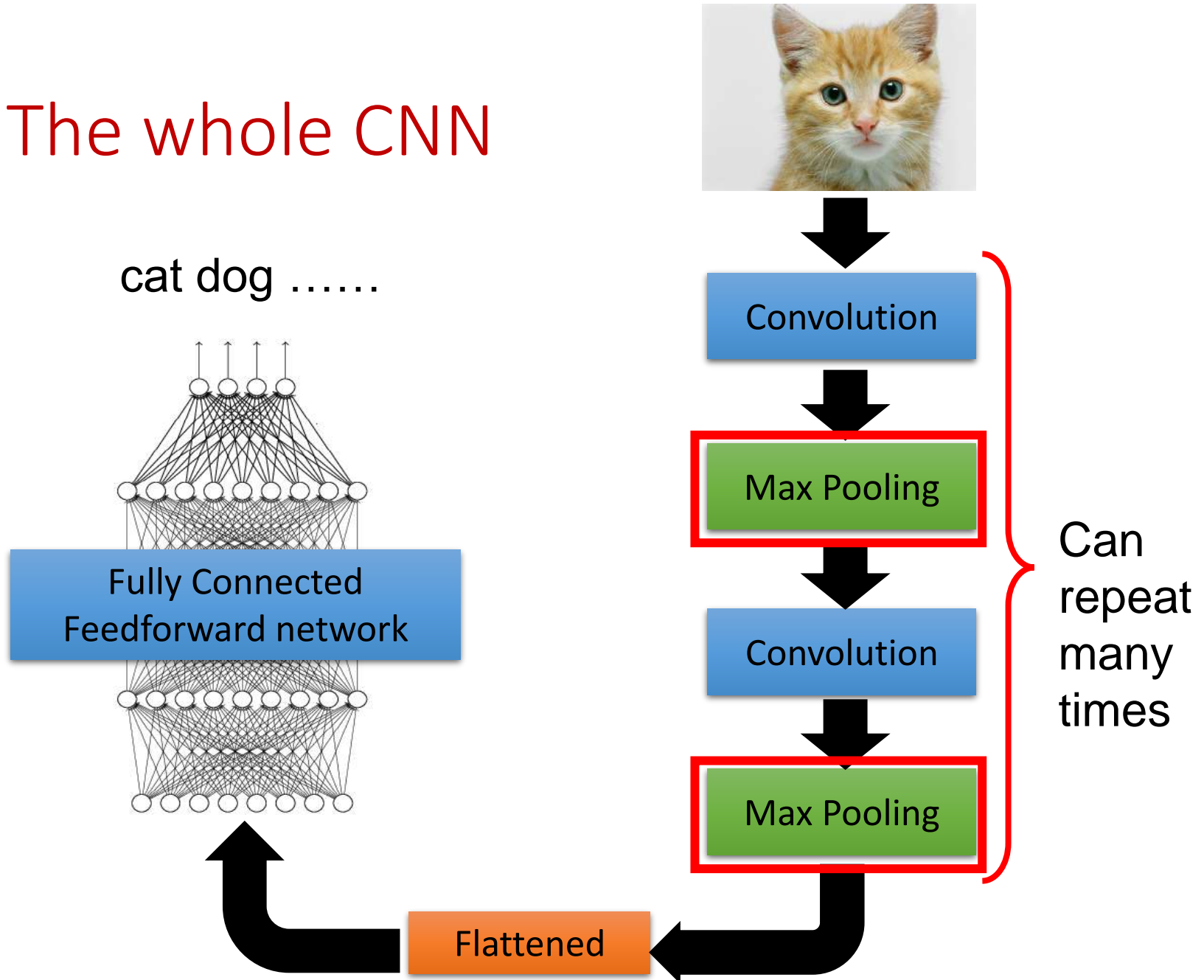


3	-1	-3	-1
-3	1	0	-3
-3	-3	0	1
3	-2	-2	-1

# Color image: RGB 3 channels



# The whole CNN



# Max Pooling

Size reduces after Max Pooling

1	-1	-1
-1	1	-1
-1	-1	1

Filter 1

-1	1	-1
-1	1	-1
-1	1	-1

Filter 2

3	-1	-3	-1
-3	1	0	-3
-3	-3	0	1
3	-2	-2	-1

-1	-1	-1	-1
-1	-1	-2	1
-1	-1	-2	1
-1	0	-4	3



# Why Pooling

- Subsampling pixels will not change the object

bird



Subsampling

bird

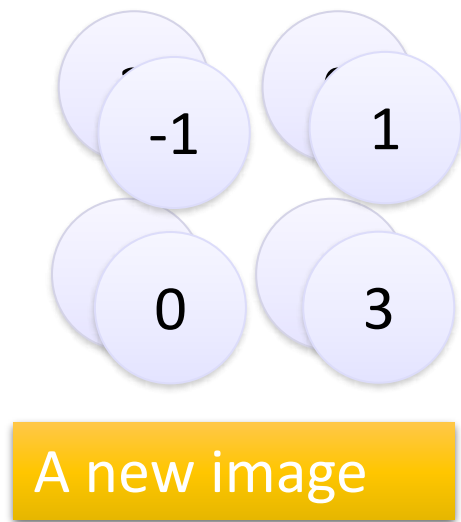


- We can subsample the pixels to make image smaller
- fewer parameters to characterize the image

# A CNN compresses a fully connected network in two ways:

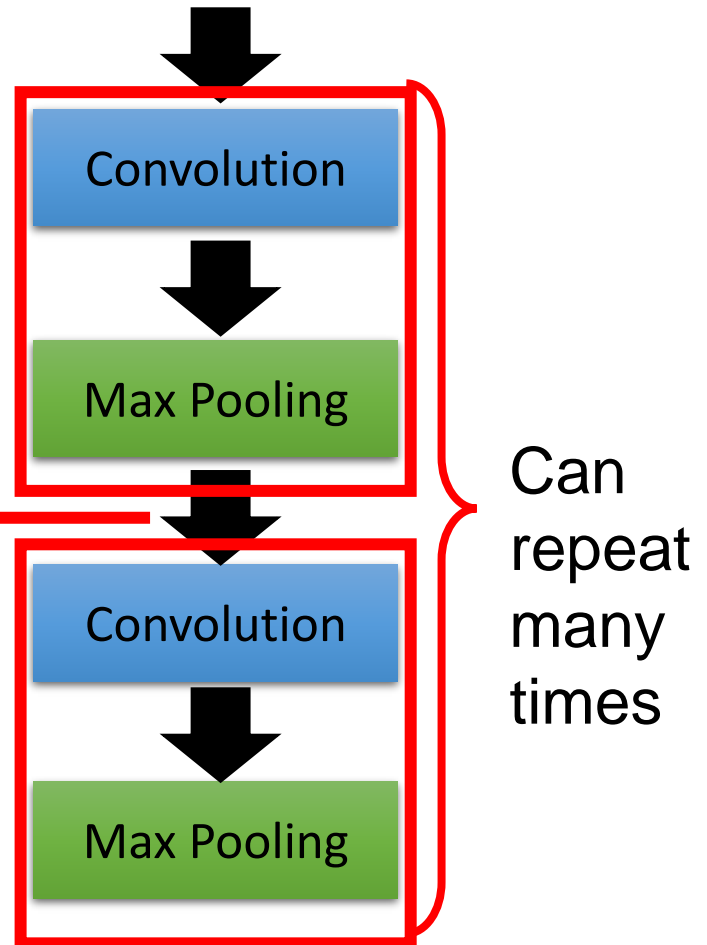
- Reducing number of connections
- Shared weights on the edges
- Max pooling further reduces the complexity

# The whole CNN



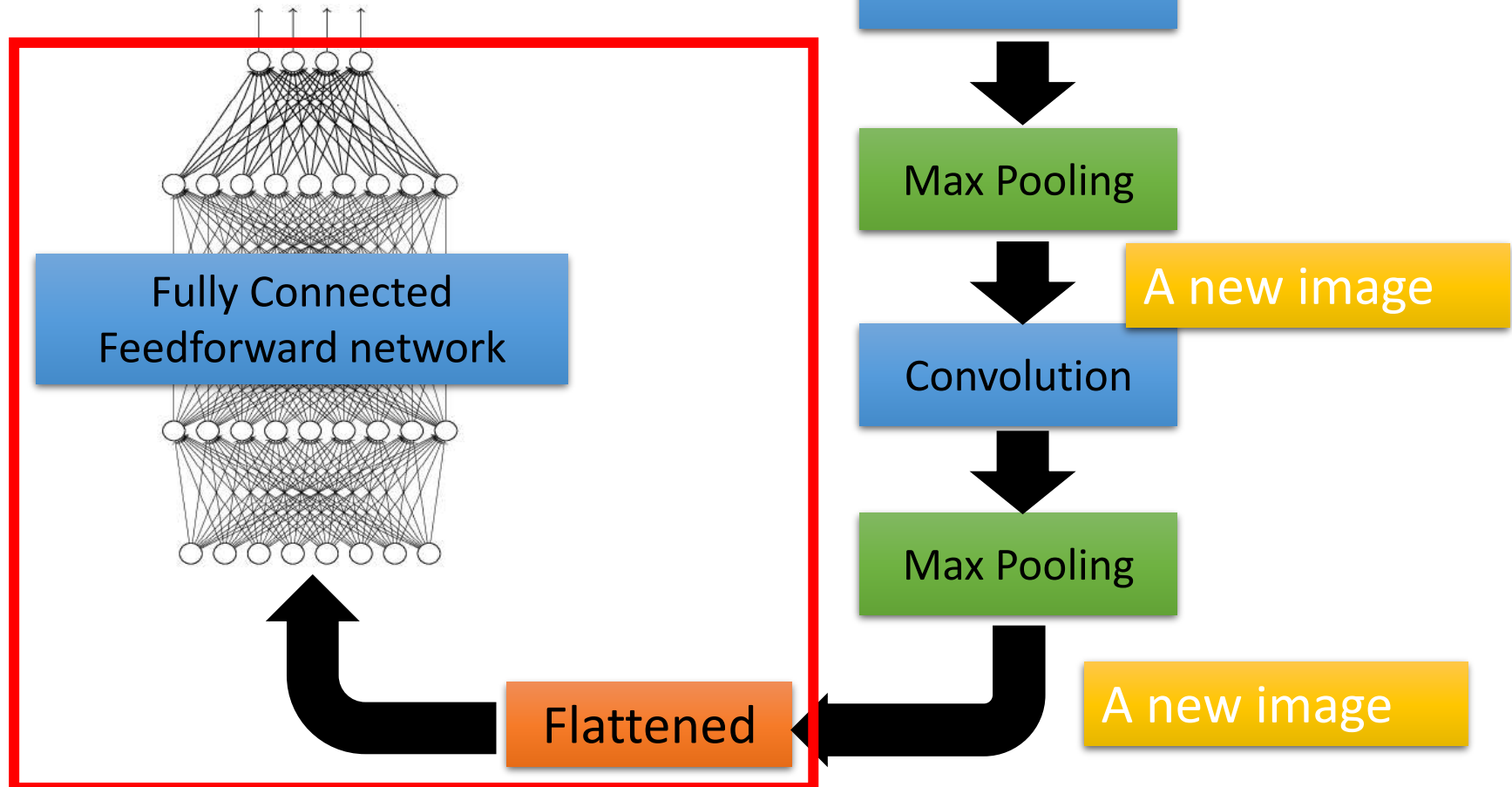
Smaller than the original image

The number of channels is the number of filters

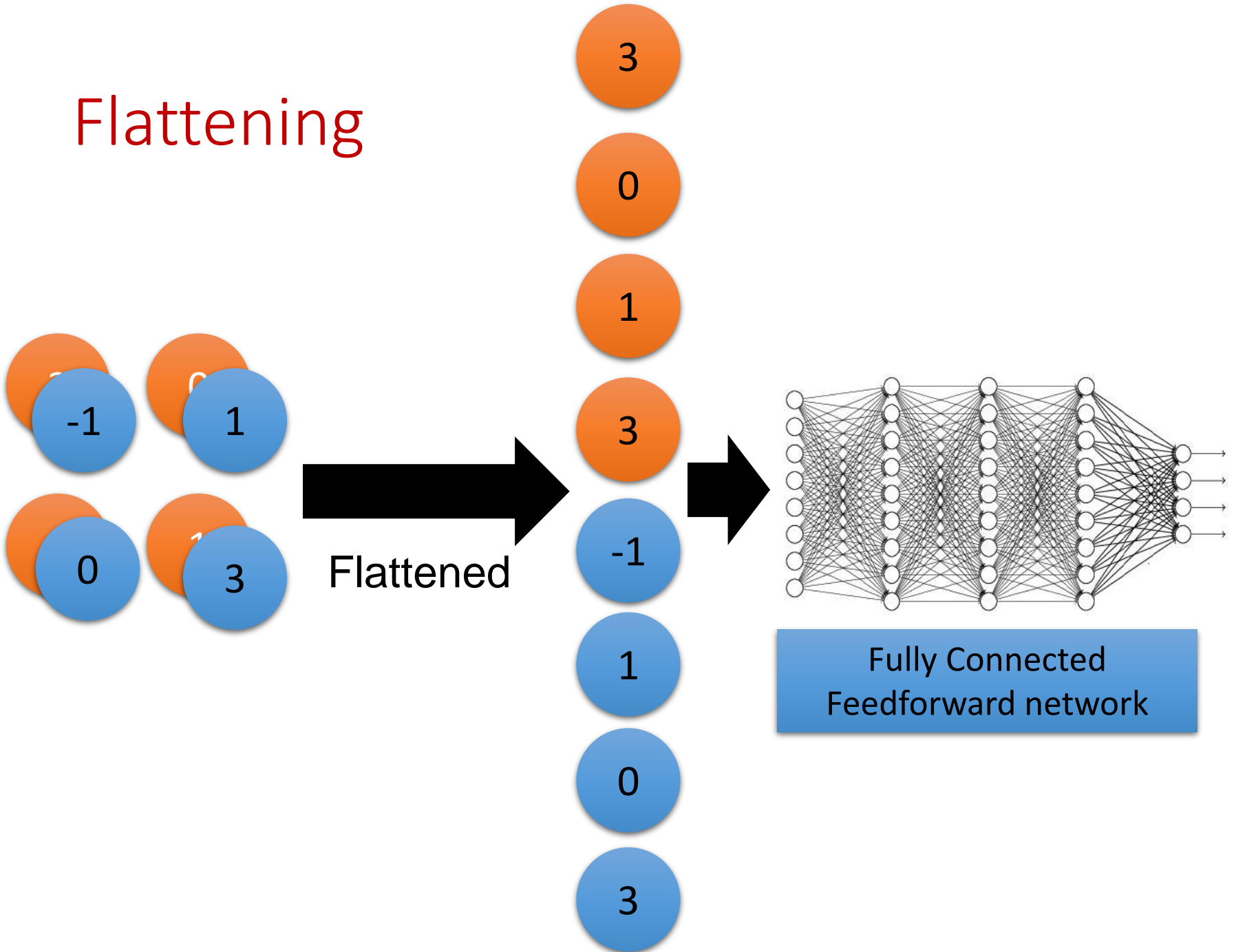


# The whole CNN

cat dog .....



# Flattening



# CNN in Keras

Only modified the *network structure* and *input format* (vector -> 3-D tensor)

```
model2.add( Convolution2D( 25, 3, 3,  
                           input_shape=(28, 28, 1)) )
```

1	-1	-1
-1	1	-1
-1	-1	-1

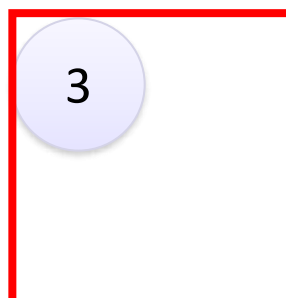
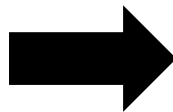
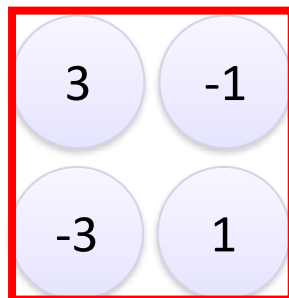
There are  
**25 3x3**  
filters.

Input\_shape = ( 28 , 28 , 1)

28 x 28 pixels

1: black/white, 3: RGB

```
model2.add(MaxPooling2D( (2, 2) ))
```



input

Convolution

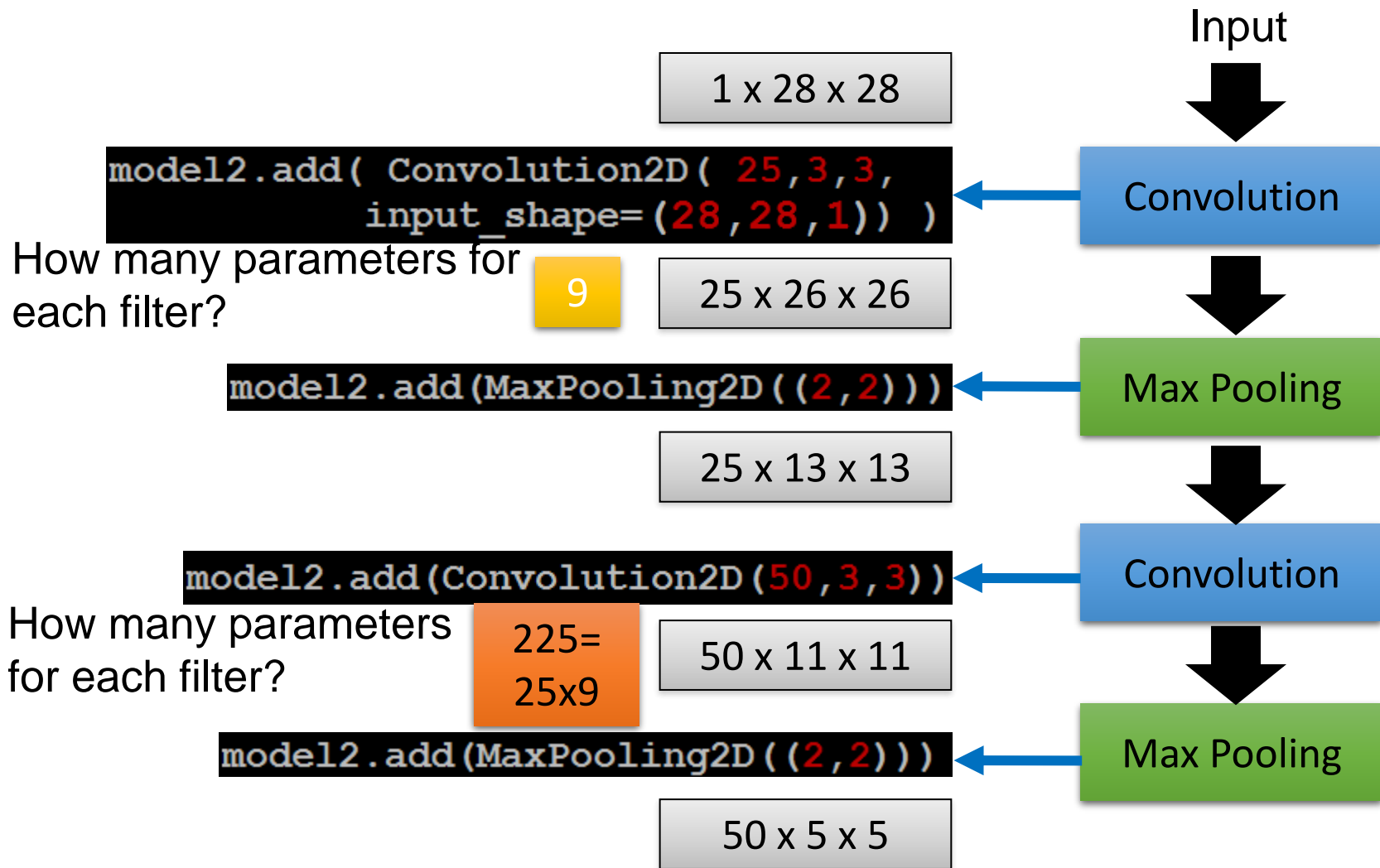
Max Pooling

Convolution

Max Pooling

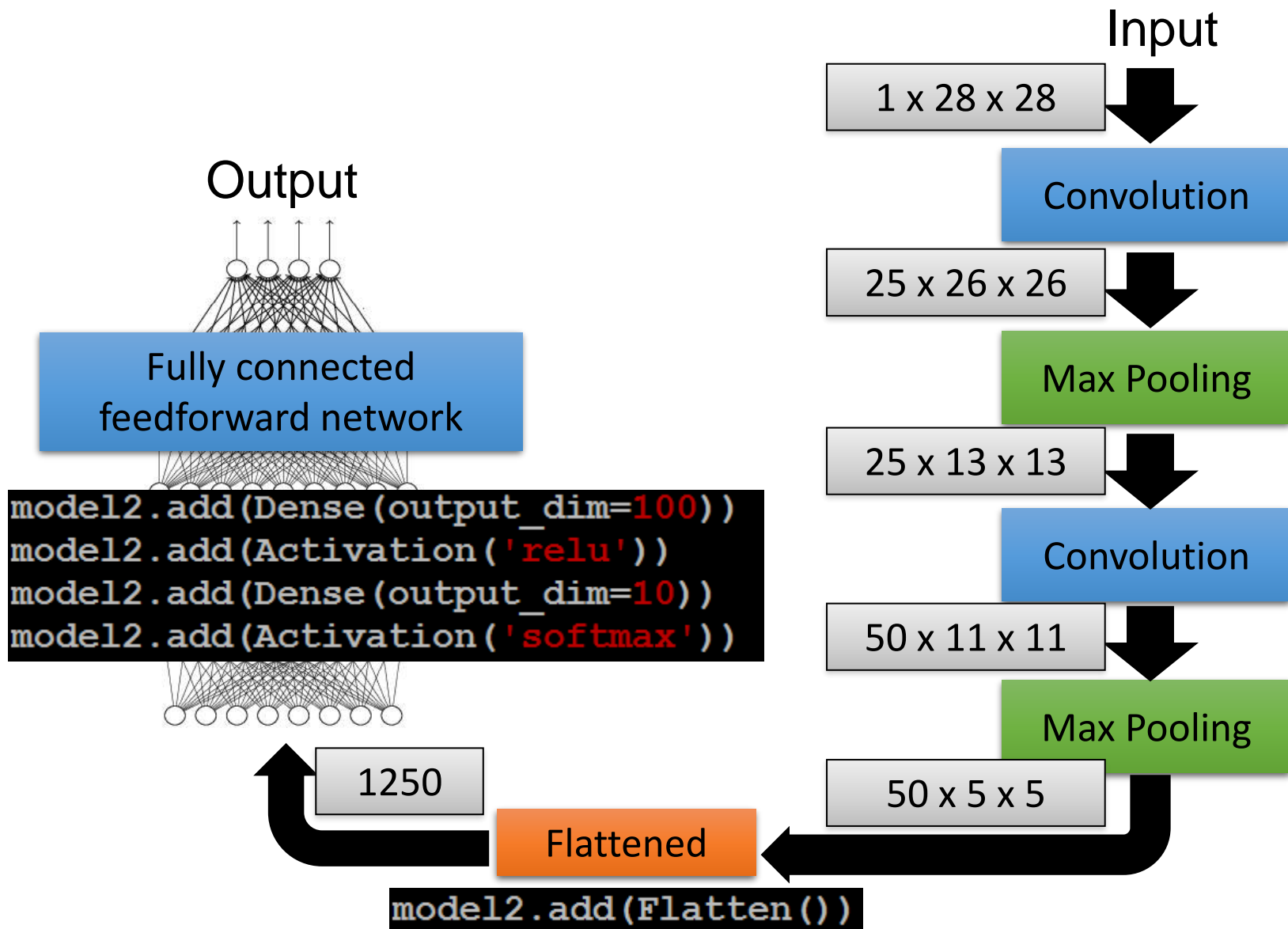
# CNN in Keras

Only modified the *network structure* and *input format (vector -> 3-D array)*



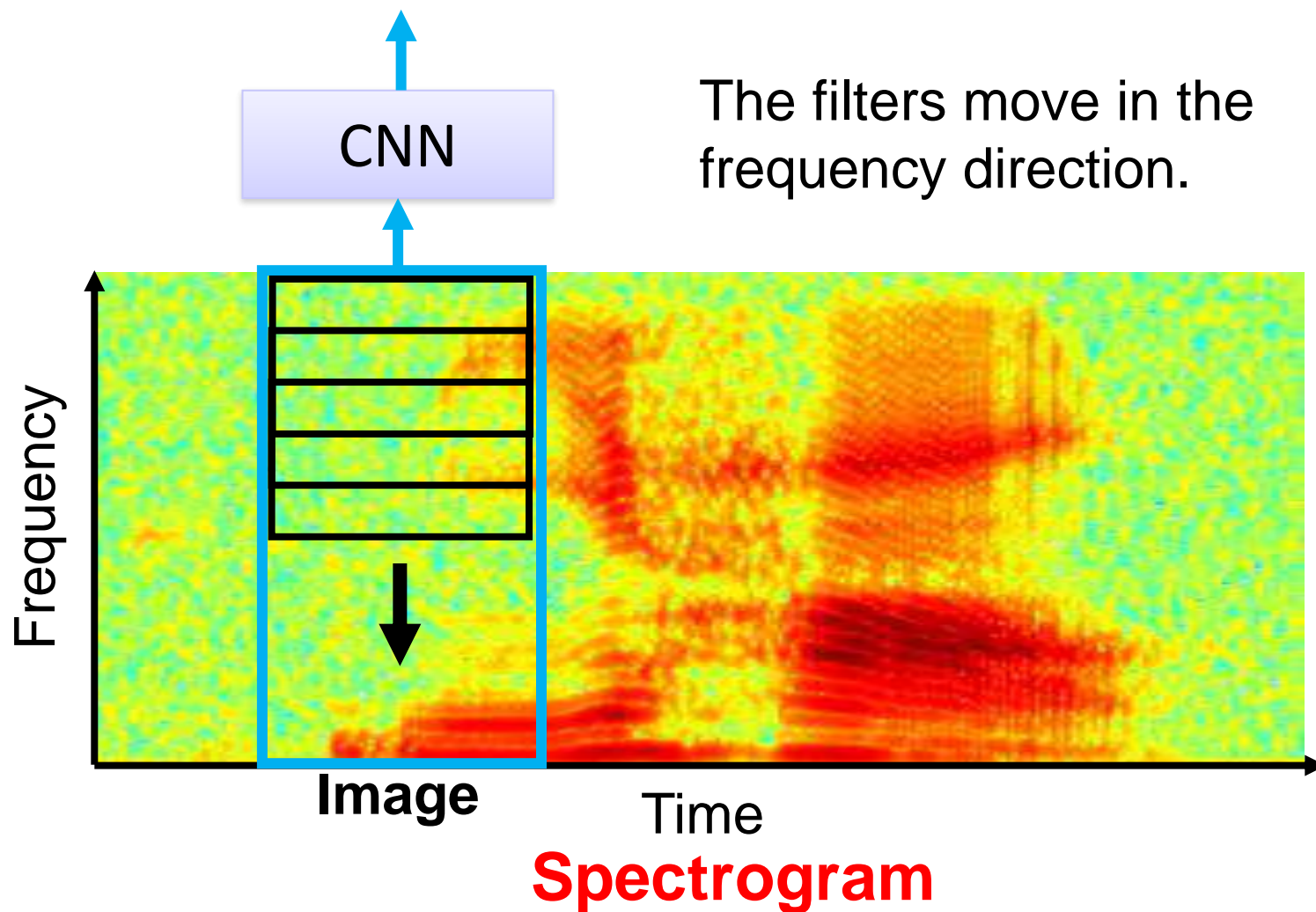
# CNN in Keras

Only modified the *network structure* and *input format (vector -> 3-D array)*

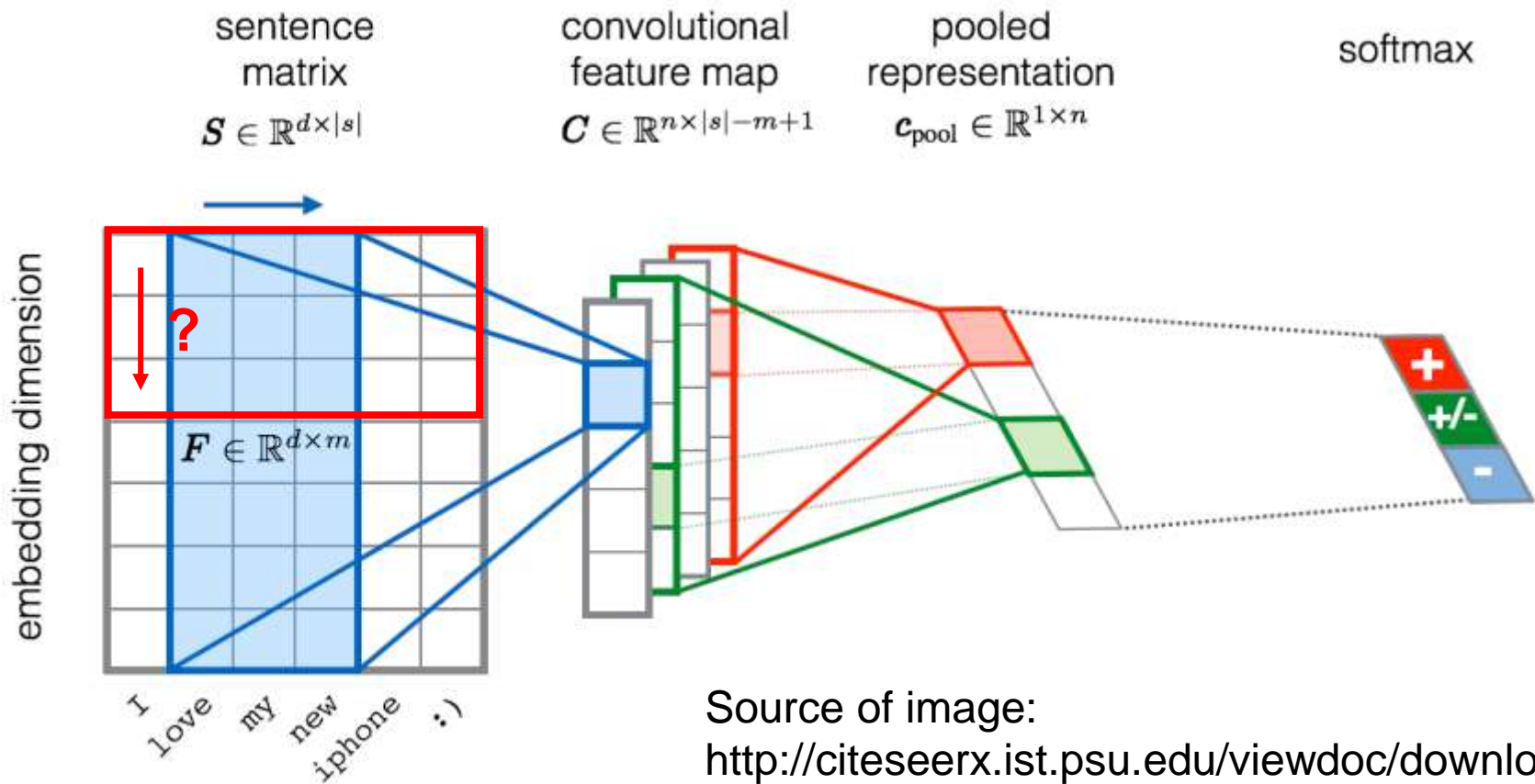




# CNN in speech recognition



# CNN in text classification



Source of image:

<http://citeseerx.ist.psu.edu/viewdoc/download?doi=10.1.1.703.6858&rep=rep1&type=pdf>