



It is designed by Intel to transfer data at the fastest rate. It allows the device to transfer the data directly to/from memory without any interference of the CPU. Using a DMA controller, the device requests the CPU to hold its data, address and control bus, so the device is free to transfer data directly to/from the memory. The DMA data transfer is initiated only after receiving HLDA signal from the CPU.

The sequences of operations performed by a DMA are

- Initially, when any device has to send data to the memory, the device has to send DMA request (DRQ) to DMA controller.
- The DMA controller sends Hold request (HRQ) to the CPU and waits for the CPU to assert the HLDA signal.
- Then the microprocessor tri-states all the data bus, address bus, and control bus. The CPU will relinquish the bus and acknowledges the HOLD request through HLDA signal.
- Now the CPU is in HOLD state and the DMA controller has to manage the operations over buses between the memory interfaced with Microprocessor and I/O devices.

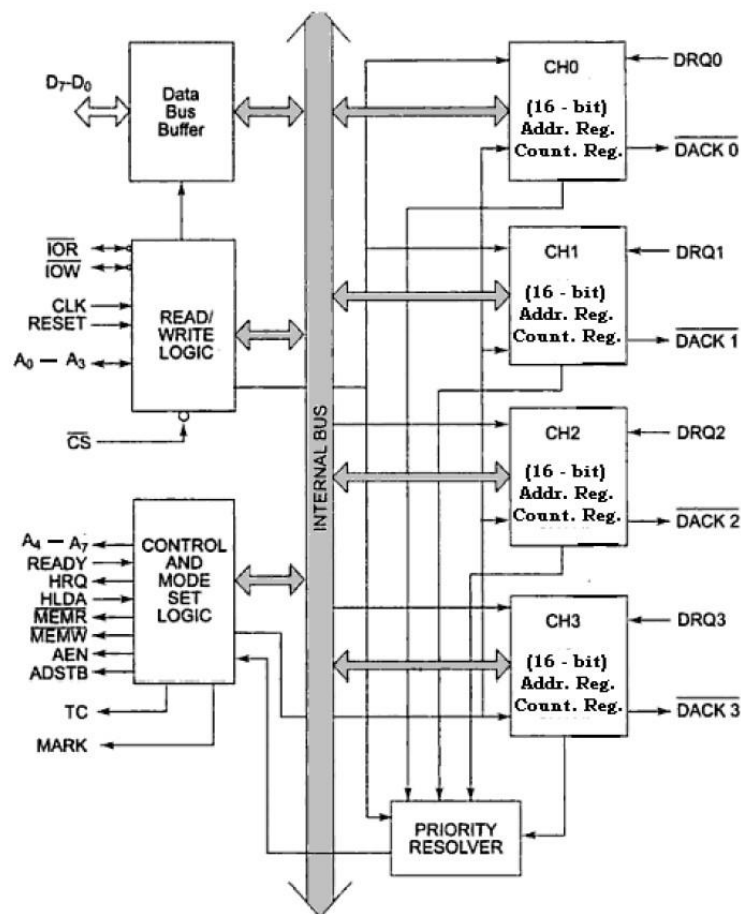
## **FEATURES OF 8257**

- It has four channels that can be used over four I/O devices.
- Each channel has 16-bit address and 14-bit counter.
- Each channel can transfer data up to 64kb.
- Each channel can be programmed independently.
- Each channel can perform read transfer, write transfer and verify transfer operations.
- It operates in 2 modes, i.e., **Master mode** and **Slave mode**.

**INTERNAL ARCHITECTURE OF 8257:**

The functional Block Diagram of DMA controller (8257) is shown in Figure 3.8.2 and the description are as follows: It consists of five functional blocks:

- a) Data bus buffer
- b) Control logic
- c) Read/write logic
- d) Priority Resolver
- e) DMA channels



**Figure 3.8.2 Functional Block Diagram of 8257**



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*[Source: Advanced Microprocessors and Microcontrollers by A.K Ray & K.M.Bhurchandi]*



### **Data Bus Buffer:**

8-bit Tristate, bidirectional buffer interfaces the internal bus of 8257 with the external system bus under the control of various control signals.

### **Read/Write Logic:**

In the slave mode, the read/write logic accepts the I/O Read or I/O Write signals, decodes the Ao-A3 lines and either writes the contents of the data bus to the addressed internal register or reads the selected register depending upon whether IOW or IOR signal is activated. In master mode, the read/write logic generates the IOR and IOW signals to control the dataflow to or from the selected peripheral.

### **Control Logic:**

The control logic controls the sequences of operations and generates the required control signals like AEN, ADSTB, MEMR, MEMW, TC and MARK along with the address lines A4-A7, in master mode.

### **Priority Resolver:**

The priority resolver resolves the priority of the four DMA channels depending upon whether normal priority or rotating priority is programmed.

### **Register Organisation of 8257:**

The 8257 performs DMA operation over four independent DMA channels with the following Registers.

#### **1. DMA Address Register**

Each DMA channel has one DMA address register. The function of this register is to store the address of the starting memory location, which will be accessed by the



DMA channel. The device that wants to transfer data over a DMA channel, will access the block of the memory with the starting address stored in the DMA Address Register.

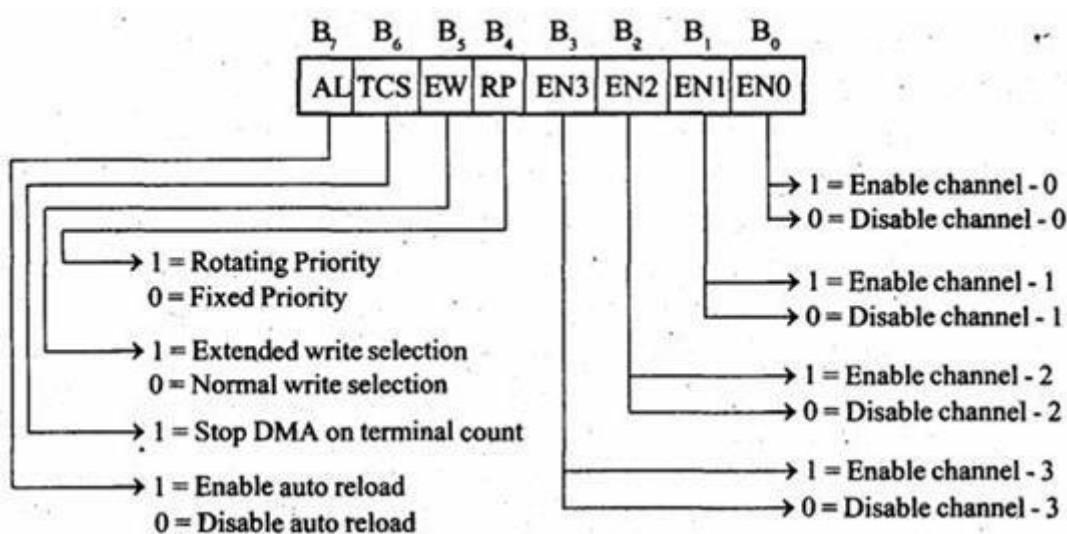
## 2. Terminal Count Registers

Each of the four DMA channels of 8257 has one terminal count register (TC). This 16-bit register is used for ascertaining that the data transfer through a DMA channel ceases or stops after the required number of DMA cycles.

After each DMA cycle, the terminal count register content will be decremented by one and finally it becomes zero after the required number of DMA cycles are over. The bits 14 and 15 of this register indicate the type of the DMA operation (transfer).

## 3. Mode Set Register

The mode set register is used for programming the 8257 as per the requirements of the system. The function of the mode set register is to enable the DMA channels individually and also to set the various modes of operation as shown in Figure 3.8.3.



**Figure 3.8.3 Mode Set Register**

[Source: Advanced Microprocessors and Microcontrollers by A.K Ray & K.M.Bhurchandi]



The bits Do-D3 enable one of the four DMA channels of 8257. If the TC STOP bit is set, the selected channel is disabled after the terminal count condition is reached, and it further prevents any DMA cycle on the channel. If the TC STOP bit is programmed to be zero, the channel is not disabled, even after the count reaches zero and further requests are allowed on the same channel. The auto load bit, if set, enables channel 2 for the repeat block chaining operations, without immediate software intervention between the two successive blocks. The extended write bit, if set to '1', extends the duration of MEMW and IOW signals by activating them earlier, which is useful in interfacing the peripherals with different access times.

#### **4. Status register**

The lower order 4-bits of this register contain the terminal count status for the four individual channels. If any of these bits is set, it indicates that the specific channel has reached the terminal count condition. The update flag is not affected by the read operation. This flag can only be cleared by resetting 8257. The update flag is set every time the channel 2 registers are loaded with contents of the channel 3 registers. It is cleared by the completion of the first DMA cycle of the new block. This register can only be read.

### **DMA TRANSFER & OPERATIONS**

The 8257 is able to accomplish three types of operations such as

1. DMA operation
2. Write Operation
3. Read Operation

Operational sequence of 8257 is as follows

- The 8257 requests any one of the 8257 DRQ inputs to transfer single byte.
- In response to the request, the 8257 sends HRQ signal to CPU at its



HLD input and waits for acknowledgement at the HLDA input.

- If the DMA controller receives the HLDA signal it indicates that the bus is available for the transfer.
- The DMA controller generates the read and write commands to transfer the byte from/to the I/O Device.
- The DACK line of the used channel is pulled down by the DMA controller to I/O device that requested for DMA transfers.
- The HRQ line is lowered by the DMA controller to indicate the CPU that it may regain the control of the bus.
- The DRQ must be high until acknowledged.
- In each state, the DRQ lines are sampled and highest priority request is recognized during next transfer. The HRQ line is maintained active till all the DRQ lines go low.