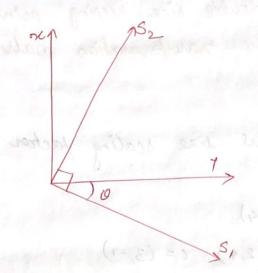
## General Scaling Direction



· Parameter sa à sy scale the object along x ày directions. We can scale an object in other directions by rotating the object to align the desired scaling direction with the co-ordinate ares before applying the scaling transformation.

· Suppose we apply scaling factor Sià Sz is direction shown in figure then we will apply following transformations.

for si & se coincide with re à y axes.

2. scale sue object with specified scale factor.

3. Perform opposite rotation to return points to their original orientations (i.e. inverse of step-1) . The matrix representation is:  $p' : R^{-1}(o) \subseteq S(s_1, s_2) \cdot \{R(o) \cdot P_j\}$   $= \{R^{-1}(o) \cdot S(s_1, s_2) \cdot R(o)\} \cdot P$   $= \begin{bmatrix} coso \\ -sinto \\ 0 \end{bmatrix} \cdot \begin{bmatrix} s_1 coso \\ s_2 \\ s_3 \end{bmatrix} \cdot \begin{bmatrix} s_2 coso \\ s_3 \\ s_4 \end{bmatrix} \cdot \begin{bmatrix} s_3 coso \\ s_3 \\ s_4 \end{bmatrix} \cdot \begin{bmatrix} s_3 coso \\ s_3 \\ s_4 \end{bmatrix} \cdot \begin{bmatrix} s_3 coso \\ s_3 \\ s_4 \end{bmatrix} \cdot \begin{bmatrix} s_3 coso \\ s_3 \\ s_4 \end{bmatrix} \cdot \begin{bmatrix} s_3 coso \\ s_3 \\ s_4 \end{bmatrix} \cdot \begin{bmatrix} s_3 coso \\ s_3 \\ s_4 \end{bmatrix} \cdot \begin{bmatrix} s_3 coso \\ s_4 \\ s_4 \end{bmatrix} \cdot \begin{bmatrix} s_4 coso \\ s_4 \\ s_4 \end{bmatrix} \cdot \begin{bmatrix} s_4$ 

Here P'& P are column vector of final & initial point co-ordinate respectively and o is the angle between actual scaling direction and our standard co-ordinate ares.

his transferration

but flips of value

1000