


DIMENSIONS PART I

Theorem

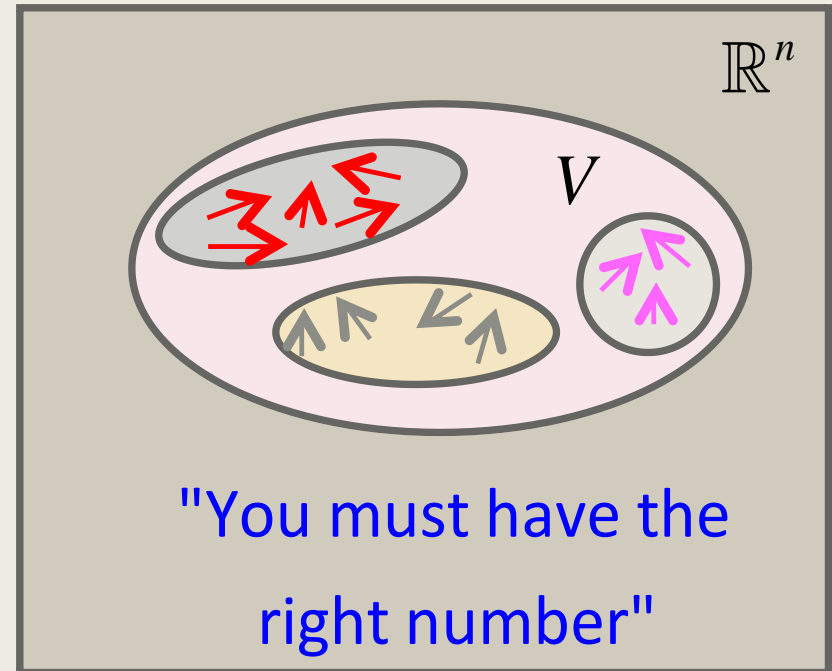
Let V be a vector space which has a basis with k vectors.

 = basis for V

Then

(1) any subset of V with more than k vectors is always linearly dependent (so cannot be a basis);

(2) any subset of V with less than k vectors cannot span V (so also cannot be a basis);



Definition

The **dimension** of a vector space V denoted by $\dim(V)$, is defined to be the number of vectors in a basis for V .

The dimension of the zero space is defined to be zero.

Example

1) $\dim(\mathbb{R}^n) = n$

(recall a basis for \mathbb{R}^n can be $\{e_1, e_2, \dots, e_n\}$).

2) Subspaces of \mathbb{R}^2 : $\rightarrow \{0\}$: dimension 0

\mathbb{R}^2 : dimension 2

lines through the origin: dimension 1

3) Subspaces of \mathbb{R}^3 : $\rightarrow \{0\}$: dimension 0

\mathbb{R}^3 : dimension 3

lines through the origin: dimension 1

planes containing the origin: dimension 2

Example

Find a basis for and determine the dimension of the subspace $W = \{(x, y, z) \mid y = 2z\}$.

$$= \{(x, 2z, z) \mid x, z \in \mathbb{R}\}$$

$$= \{x(1, 0, 0) + z(0, 2, 1) \mid x, z \in \mathbb{R}\}$$

$$= \text{span}\{(1, 0, 0), (0, 2, 1)\}$$

$\{(1, 0, 0), (0, 2, 1)\}$ spans W

$\{(1, 0, 0), (0, 2, 1)\}$ is linearly independent (**why?**)

$\{(1, 0, 0), (0, 2, 1)\}$ is a basis for W and $\dim(W) = 2$.

Example

Find a basis for and determine the dimension of the solution space of the homogeneous system

$$\begin{cases} 2v + 2w - x + z = 0 \\ -v - w + 2x - 3y + z = 0 \\ x + y + z = 0 \\ v + w - 2x - z = 0 \end{cases}$$

Example

$$\left(\begin{array}{ccccc|c} 2 & 2 & -1 & 0 & 1 & 0 \\ -1 & -1 & 2 & -3 & 1 & 0 \\ 0 & 0 & 1 & 1 & 1 & 0 \\ 1 & 1 & -2 & 0 & -1 & 0 \end{array} \right) \xrightarrow{\quad} \left(\begin{array}{ccccc|c} 1 & 1 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right)$$

$$\begin{cases} v = -s - t \\ w = s \\ x = -t \\ y = 0 \\ z = t, \end{cases} \quad s, t \in \mathbb{R} \qquad \begin{pmatrix} v \\ w \\ x \\ y \\ z \end{pmatrix} = \begin{pmatrix} -s - t \\ s \\ -t \\ 0 \\ t \end{pmatrix} = s \begin{pmatrix} -1 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} + t \begin{pmatrix} -1 \\ 0 \\ -1 \\ 0 \\ 1 \end{pmatrix}$$

Example

$$\begin{pmatrix} v \\ w \\ x \\ y \\ z \end{pmatrix} \text{ belongs to the solution space } \Leftrightarrow \begin{pmatrix} v \\ w \\ x \\ y \\ z \end{pmatrix} = s \begin{pmatrix} -1 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} + t \begin{pmatrix} -1 \\ 0 \\ -1 \\ 0 \\ 1 \end{pmatrix}$$

$$\text{Solution space} = \text{span} \left\{ \begin{pmatrix} -1 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} -1 \\ 0 \\ -1 \\ 0 \\ 1 \end{pmatrix} \right\}$$

A basis for
the solution space

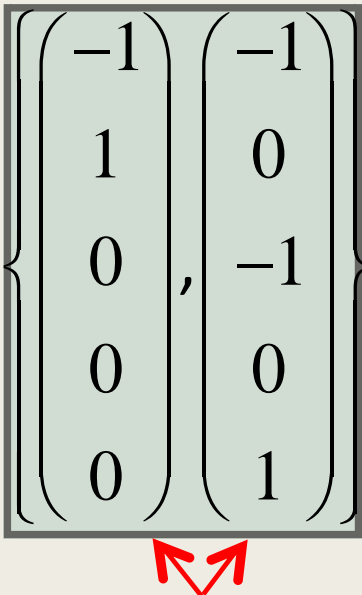
Dimension of the
solution space is 2.

Linearly independent

Remark

Solution space = span $\left\{ \begin{pmatrix} -1 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \begin{pmatrix} -1 \\ 0 \\ -1 \\ 0 \\ 1 \end{pmatrix} \right\}$ ← A basis for the solution space

Linearly independent



A set of vectors that spans the solution space for any homogeneous linear system found using the above method will always be linearly independent.

Summary

- 1) All bases for the same vector space have the same number of vectors.
- 2) Definition of dimension (of a vector space).
- 3) Finding a basis for the solution space of a homogeneous linear system.