



Week 08

MA1508E LINEAR ALGEBRA FOR ENGINEERING

Week 7

IVLE Quiz Discussion

Review of Week 07 (Units 035-039) content

- Recall the notion of redundancy → linear independence
- Notion of linear independence → solutions to a vector equation
- Set with only one vector → when is it a linearly independent set?
- Set with only two vectors → when is it a linearly independent set?
- Linear independence defined in terms of redundancy
- Guaranteed dependence (more than n vectors in \mathbb{R}^n)
- Linear (in)dependence in \mathbb{R}^2 (two or more vectors)
- Linear (in)dependence in \mathbb{R}^3 (two or more vectors)
- Intuitively, more vectors means more likely to be linearly dependent. When can we add vectors to a linearly independent set and preserve independent property? When will we no longer be able to do this?

Review of Week 07 (Units 035-039) content

- What is a vector space?
- Finding a ‘small’ set that is able to span a vector space.
- Definition of a basis
- Uniqueness of expression when writing a vector in a vector space in terms of a set of basis vectors.
- Definition of coordinate vectors (with respect to a basis)
- Different ‘representations’ of the same vector.
- What is a standard basis for \mathbb{R}^n ?

Week 08 (units 040-044) overview

040 Dimensions Part I

- All bases for the same vector space have the same number of vectors
- Definition of dimension (of a vector space)
- Finding a basis for the solution space of a homogeneous linear system.

041 Dimensions Part II

- Knowing the dimension of a vector space V helps in determining whether a set S can be a basis for V
- The dimension of all subspaces of a vector space V does not exceed the dimension of V
- The only subspace of a vector space V that has the same dimension as V is V itself.

042 Equivalent statements Part III

- \mathbf{A} is an invertible matrix of order n if and only if the rows (columns) of \mathbf{A} forms a basis for \mathbb{R}^n

Week 08 (units 040-044) overview

043 Row space and column space

- Definition of the row space and column space of a matrix
- If the rows of \mathbf{A} are linearly independent, then they form a basis for the row space of \mathbf{A}
- If \mathbf{R} is a matrix in row-echelon form, then the non-zero rows of \mathbf{R} form a basis for the row space of \mathbf{R}

044 Finding a basis for the row space

- Row equivalent matrices have the same row space
- A method to find a basis for the row space of a matrix.

Discussion

Question: To find a basis for and determine the dimension of the solution space of a homogeneous linear system.

$$\left(\begin{array}{cccc|c} \dots & \dots & \dots & \dots & \dots & 0 \\ \dots & \dots & \dots & \dots & \dots & 0 \\ & \vdots & & & & \vdots \\ \dots & \dots & \dots & \dots & \dots & 0 \end{array} \right) \xrightarrow{\text{GJE}} \left(\begin{array}{ccccc|c} * & \dots & 0 & \dots & 0 & 0 \\ 0 & \dots & * & \dots & 0 & 0 \\ & & 0 & & \vdots & \vdots \\ 0 & \dots & 0 & \dots & * & 0 \end{array} \right)$$

How do we write out
a general solution?

↑
pivot columns

Discussion

Assign variables corresponding to non pivot columns arbitrary parameters.

Let's say there are a total of 3 arbitrary parameters s, t, u (it does not matter how many) assigned to variables x_i, x_j, x_k .

$$\left(\begin{array}{cccc|c} * & |x_i| & 0 & |x_j| & 0 & |x_k| \\ 0 & |...| & * & |...| & 0 & |0 \\ 0 & |...| & 0 & |...| & \vdots & | \vdots \\ 0 & |...| & 0 & |...| & * & |0 \end{array} \right)$$

How do we write out a general solution?

Discussion

3 arbitrary parameters s, t, u

(it does not matter how many)

assigned to variables x_i, x_j, x_k .

$$\left(\begin{array}{cc|c} x_i & x_j & x_k \\ * & 0 & 0 \\ \dots & \dots & \dots \\ 0 & * & 0 \\ \dots & \dots & \dots \\ 0 & 0 & 0 \\ \dots & \dots & * \\ 0 & 0 & 0 \end{array} \right)$$

$$\left\{ \begin{array}{lcl} : & = & : \\ x_i & = & s \\ : & = & : \\ x_j & = & t \\ : & = & : \\ x_k & = & u \\ : & = & : \end{array} \right.$$

$$\left(\begin{array}{c} x_i \\ x_j \\ x_k \\ \vdots \end{array} \right) = s \left(\begin{array}{c} 1 \\ 0 \\ 0 \\ \vdots \end{array} \right) + t \left(\begin{array}{c} 0 \\ 1 \\ 0 \\ \vdots \end{array} \right) + u \left(\begin{array}{c} 0 \\ 0 \\ 1 \\ \vdots \end{array} \right)$$

Discussion

These 3 vectors will span the solution space.

$$\begin{pmatrix} \vdots \\ x_i \\ \vdots \\ x_j \\ \vdots \\ x_k \\ \vdots \end{pmatrix} = s \begin{pmatrix} \vdots \\ 1 \\ \vdots \\ 0 \\ \vdots \\ 0 \\ \vdots \end{pmatrix} + t \begin{pmatrix} \vdots \\ 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \\ \vdots \end{pmatrix} + u \begin{pmatrix} \vdots \\ 0 \\ \vdots \\ 0 \\ \vdots \\ 1 \\ \vdots \end{pmatrix}$$

$$\left(\begin{array}{cccc|c} * & \cdots & 0 & \cdots & 0 \\ 0 & \cdots & * & \cdots & 0 \\ 0 & \cdots & 0 & \cdots & * \\ 0 & \cdots & 0 & \cdots & 0 \end{array} \right)$$

Are they always linearly independent?

Discussion

$$\left(\begin{array}{c|ccccc} \vdots & & \vdots & \vdots & \vdots \\ 0 & 0 & 1 & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & =c_1 & 0 & +c_2 & 1 & +c_3 & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & 0 & 0 & 1 \\ \vdots & \vdots & \vdots & \vdots & \vdots \end{array} \right)$$

$$\Rightarrow c_1 = 0, c_2 = 0, c_3 = 0$$

$$\left(\begin{array}{c|cc|c} x_i & * & \dots & 0 \\ 0 & \dots & * & \dots & 0 \\ 0 & 0 & \dots & 0 & 0 \\ 0 & \dots & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & \dots & * & 0 \end{array} \right)$$

Are they always linearly independent?

YES!

So, this method always produces a basis for the solution space

Discussion

$$\begin{pmatrix} \vdots \\ 0 \\ \vdots \\ 0 \\ \vdots \\ 0 \\ \vdots \end{pmatrix} = c_1 \begin{pmatrix} \vdots \\ 1 \\ \vdots \\ 0 \\ \vdots \\ 0 \\ \vdots \end{pmatrix} + c_2 \begin{pmatrix} \vdots \\ 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \\ \vdots \end{pmatrix} + c_3 \begin{pmatrix} \vdots \\ 0 \\ \vdots \\ 0 \\ \vdots \\ 1 \\ \vdots \end{pmatrix}$$

$$\Rightarrow c_1 = 0, c_2 = 0, c_3 = 0 \quad \text{AND}$$

the dimension is always the number of non pivot columns in

$$\left(\begin{array}{c|c|c|c} * & x_i & x_j & x_k \\ 0 & \dots & \dots & \dots \\ \vdots & 0 & 0 & 0 \\ 0 & \dots & 0 & \dots \\ \vdots & 0 & \vdots & \vdots \\ 0 & \dots & \dots & 0 \end{array} \right)$$

Are they always linearly independent?

YES!

Example 7.1

Find a basis and determine the dimension of the solution space of the following homogeneous linear system:

$$\left\{ \begin{array}{rcl} x_1 + 3x_2 - x_3 + 2x_4 & = & 0 \\ -3x_2 + x_3 & = & 0 \\ x_1 & & - x_4 = 0 \end{array} \right.$$

Example 7.2



Let $\{u_1, u_2, u_3\}$ be a basis for a vector space V . Determine whether $\{v_1, v_2, v_3\}$ is a basis for V if

- (a) $v_1 = u_1, \quad v_2 = u_1 + u_2, \quad v_3 = u_1 + u_2 + u_3$
- (b) $v_1 = u_1 - u_2, \quad v_2 = u_2 - u_3, \quad v_3 = u_3 - u_1$

Example 7.3

Let $\mathbf{u}_1 = (1, 0, 1, 1)$, $\mathbf{u}_2 = (-3, 3, 7, 1)$, $\mathbf{u}_3 = (-1, 3, 9, 3)$, $\mathbf{u}_4 = (-5, 3, 5, -1)$ and let $S = \{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$ and $V = \text{span}(S)$.

(a) Find a non-trivial solution to the equation

$$a\mathbf{u}_1 + b\mathbf{u}_2 + c\mathbf{u}_3 + d\mathbf{u}_4 = \mathbf{0}$$

(b) Express \mathbf{u}_3 and \mathbf{u}_4 (separately) as linear combinations of \mathbf{u}_1 and \mathbf{u}_2 .

(c) Find a basis for and determine the dimension of V .

(d) Find a subspace W of \mathbb{R}^4 such that $\dim(W) = 3$ and $\dim(W \cap V) = 2$.

Justify your answer.

Example 7.4

Let $A = \begin{pmatrix} 1 & 0 & -1 & 1 & 1 \\ 1 & 1 & 2 & 0 & 3 \\ -1 & 0 & 2 & -1 & 0 \end{pmatrix}$ and $B = \begin{pmatrix} 1 & 0 & 0 & 1 & 2 \\ 0 & 1 & 0 & -1 & -1 \\ 0 & 0 & 1 & 0 & 1 \end{pmatrix}$.

- (a) Show that A and B has the same row space.
- (b) Without performing any further computation, write down a basis for the row space of A and state its dimension.

Finally...

THE END