



Week 05

MA1508E LINEAR ALGEBRA FOR ENGINEERING

Week 3

IVLE Quiz Discussion

Week 4

IVLE Quiz Discussion

Review of Week 03 (Units 013-017) content

- Block multiplication: entry by entry, row by row, column by column, block by block.
- What is an inverse of a matrix? Invertible and singular matrices.
- Checking if a given 'candidate' \mathbf{B} is an inverse of \mathbf{A}
- Uniqueness of inverse
- Checking $\mathbf{BA}=\mathbf{I}$ and $\mathbf{AB}=\mathbf{I}$
- Cancellation law for invertible matrices
- Definition of the transpose of a matrix; symmetric matrices in terms of transpose
- Some results on transpose
- Some results on inverse

Review of Week 03 (Units 013-017) content

- Powers of an invertible matrix
- Linear system and matrix equation
- What happens when we apply an ERO on an identity matrix?
- A square matrix is an elementary matrix if it can be obtained from an identity matrix by performing a single elementary row operation.
- All elementary matrices are invertible and their inverse is also an elementary matrix.
- If an elementary matrix represents a single elementary row operation X , then the inverse represents the elementary row operation that does the opposite of X .

Review of Week 04 (Units 018-022) content

- A set of four equivalent statements (on the invertibility of a matrix)
- Building on one part of the proof of the preceding theorem, we develop a method to find the inverse of an invertible matrix.
- This method also allows us to know when a matrix is invertible.
- If \mathbf{A} and \mathbf{B} are both square matrices of the same size, then to check whether \mathbf{B} is the inverse of \mathbf{A} , we only need to check $\mathbf{AB}=\mathbf{I}$ or $\mathbf{BA}=\mathbf{I}$ (and not both)
- If \mathbf{A} and \mathbf{B} are both square matrices of the same size and one of them is singular, then both \mathbf{AB} and \mathbf{BA} will be singular.
- The term $ad-bc$ we saw in the 2×2 matrix example – is there a general expression for bigger matrices?
- Determinant of a matrix. How can we compute this efficiently?
- Determinant of some special groups of matrices.

Review of Week 04 (Units 018-022) content

- Since the determinant of a triangular matrix is easy to compute, can we use ERO to help us?
- What does the determinant of a matrix tell us about the invertibility?
- What properties does determinants have?
- Establishing an “if and only if” statement for a 2×2 matrix to be invertible.
- Definition of the determinant of a square matrix (cofactor expansion).
- Special formula to remember the determinant of a 3×3 matrix.
- Computing determinant via cofactor expansion along any row or column.
- Determinant of special matrices
 - Triangular matrices
 - A square matrix and its transpose
 - Square matrices with identical rows or columns

Week 05 (units 023-028) overview

023 Determinants and elementary row operations

- How the 3 types of elementary row operations change the determinant of a square matrix
- Computing the determinant of a matrix using elementary row operations

024 Equivalent statements Part II

- \mathbf{A} is invertible if and only if $\det(\mathbf{A})$ is not zero

025 Properties of determinants

- $\det(c\mathbf{A})$; $\det(\mathbf{AB})$; $\det(\mathbf{A}^{-1})$

026 Euclidean vectors

- A vector and the components of a vector
- Addition and subtraction of vectors; and multiplying a scalar to a vector
- Identifying a vector with a matrix. Some vector operation laws
- Definition of the Euclidean n -space, \mathbf{R}^n ; subsets of \mathbf{R}^n

Week 05 (units 023-028) overview

027 More on Euclidean vectors

- Definition of norm of a vector; distance between two vectors; angle between two vectors; dot product between two vectors
- Dot product and matrix product

028 Orthogonality

- Some results on length and dot product for Euclidean vectors
- When are two vectors orthogonal?
- When is a set of vectors orthogonal?
- Orthonormal sets; normalising an orthogonal set

Cramer's Rule

Suppose $A\mathbf{x} = \mathbf{b}$ is a linear system where A is an invertible square matrix of order n . For $i = 1, 2, \dots, n$, let A_i be the square matrix of order n where the i th column of A is replaced by \mathbf{b} .

Then the unique solution is $\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$ where

Cramer's
Rule

$$x_i = \frac{\det(A_i)}{\det(A)}, \quad i = 1, 2, \dots, n.$$

Example

Solve the following linear system by Cramer's Rule.

$$\begin{cases} x & + & y & + & z & = & -1 \\ 2x & - & y & - & z & = & 4 \\ x & + & 2y & - & 3z & = & 7 \end{cases}$$

$$\mathbf{A} = \begin{pmatrix} 1 & 1 & 1 \\ 2 & -1 & -1 \\ 1 & 2 & -3 \end{pmatrix} \quad \mathbf{A}_1 = \begin{pmatrix} -1 & 1 & 1 \\ 4 & -1 & -1 \\ 7 & 2 & -3 \end{pmatrix} \quad \mathbf{A}_2 = \begin{pmatrix} 1 & -1 & 1 \\ 2 & 4 & -1 \\ 1 & 7 & -3 \end{pmatrix} \quad \mathbf{A}_3 = \begin{pmatrix} 1 & 1 & -1 \\ 2 & -1 & 4 \\ 1 & 2 & 7 \end{pmatrix}$$

Example

$$\det(A) = 15 \quad \det(A_1) = 15 \quad \det(A_2) = 0 \quad \det(A_3) = -30$$

$$x = \frac{15}{15} = 1$$

$$y = \frac{0}{15} = 0$$

$$z = \frac{-30}{15} = -2$$

$$A = \begin{pmatrix} 1 & 1 & 1 \\ 2 & -1 & -1 \\ 1 & 2 & -3 \end{pmatrix} \quad A_1 = \begin{pmatrix} -1 & 1 & 1 \\ 4 & -1 & -1 \\ 7 & 2 & -3 \end{pmatrix} \quad A_2 = \begin{pmatrix} 1 & -1 & 1 \\ 2 & 4 & -1 \\ 1 & 7 & -3 \end{pmatrix} \quad A_3 = \begin{pmatrix} 1 & 1 & -1 \\ 2 & -1 & 4 \\ 1 & 2 & 7 \end{pmatrix}$$

Example 4.1

Let

$$\mathbf{A} = \begin{pmatrix} 1 & 0 & 2 & 0 \\ 0 & 1 & 3 & -1 \\ -2 & 1 & 0 & -2 \\ 0 & 0 & 2 & 1 \end{pmatrix}, \quad \mathbf{C} = \begin{pmatrix} -1 & 3 & 4 & -2 \\ 0 & 10 & 1 & 1 \\ 0 & 0 & 0 & 5 \\ 0 & 0 & 0 & 1 \end{pmatrix}, \quad \mathbf{x} = \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix}$$

- (a) Find $\det(\mathbf{C})$.
- (b) Without computing the matrix \mathbf{AC} , explain why the homogeneous linear system $\mathbf{ACx} = \mathbf{0}$ has infinitely many solutions.

Example 4.2

Show that $\begin{vmatrix} 1 & a & a^2 \\ 1 & b & b^2 \\ 1 & c & c^2 \end{vmatrix} = (b-a)(c-a)(c-b)$

Example 4.3

Let A be a 4×4 matrix such that $\det(A) = 9$. Find

- (a) $\det(3A)$ (b) $\det(A^{-1})$ (c) $\det(3A^{-1})$ (d) $\det((3A)^{-1})$

Example 4.4

Let A, B and C be matrices such that both A and B can be obtained from C by elementary row operations:

$$C \xrightarrow{3R_2} \xrightarrow{R_3 + 2R_1} A$$

$$C \xrightarrow{R_1 + R_2} \xrightarrow{R_2 \leftrightarrow R_3} \xrightarrow{R_4 - R_2} B$$

(a) Describe how A can be obtained from B by elementary row operations.

(b) Let $A = \begin{pmatrix} 1 & -1 & 7 & \frac{1}{11} \\ 0 & 2 & 1 & 1 \\ 0 & 0 & 3 & 1 \\ 0 & 0 & 0 & -1 \end{pmatrix}$. Find $\det(B)$.

Finally...

THE END