

Week 09 F2F Example Solutions

1. Example 8.1

- (a) Put the vectors as rows of a matrix and then perform Gaussian Elimination to find a row-echelon form.

$$\mathbf{A} = \begin{pmatrix} 1 & -2 & 0 & 0 & 3 \\ 2 & -5 & -3 & -2 & 6 \\ 0 & 5 & 15 & -10 & 0 \\ 2 & 1 & 15 & 8 & 6 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & -2 & 0 & 0 & 3 \\ 0 & -1 & -3 & -2 & 0 \\ 0 & 0 & 0 & -2 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}.$$

So a basis for W is $\{(1, -2, 0, 0, 3), (0, -1, -3, -2), (0, 0, 0, -2, 0)\}$.

- (b) The dimension of W is 3.
(d) Since a row-echelon form of \mathbf{A} has no leading entries in columns 3 and 5, we add two vectors $(0, 0, 1, 0, 0)$ and $(0, 0, 0, 0, 5)$ to extend the basis found in (a) to get a basis for \mathbb{R}^5 .

2. Example 8.2

- (a)

$$\begin{pmatrix} 1 & 0 & -2 & -1 & 1 \\ 1 & 1 & -1 & 2 & 0 \\ 3 & 1 & 0 & 0 & -1 \end{pmatrix} \longrightarrow \begin{pmatrix} 1 & 0 & 0 & -1 & -1 \\ 0 & 1 & 0 & 3 & 2 \\ 0 & 0 & 1 & 0 & 1 \end{pmatrix}$$

So a basis for the row space of \mathbf{A} is $\{(1, 0, 0, -1, -1), (0, 1, 0, 3, 2), (0, 0, 1, 0, 1)\}$.

- (b) A basis for the nullspace of \mathbf{A} is $\{(1, -3, 0, 1, 0), (1, -2, -1, 0, 1)\}$.
(c) It is easy to check that $\mathbf{A}\mathbf{x} = \mathbf{b}$.
(d) A general solution is

$$\mathbf{x} = \begin{pmatrix} 1 \\ 3 \\ -1 \\ 2 \\ 2 \end{pmatrix} + \begin{pmatrix} 1 \\ -3 \\ 0 \\ 1 \\ 0 \end{pmatrix} + t \begin{pmatrix} 1 \\ -2 \\ -1 \\ 0 \\ 1 \end{pmatrix} \quad \text{where } s, t \in \mathbb{R}.$$

3. Example 8.3

- (a) Easy to check that $\mathbf{u}_1 \cdot \mathbf{u}_2 = \mathbf{u}_1 \cdot \mathbf{u}_3 = \mathbf{u}_2 \cdot \mathbf{u}_3 = 0$. So S is a linearly independent set of 3 vectors in \mathbb{R}^3 , thus S is an orthogonal basis for \mathbb{R}^3 .
(b) $\mathbf{w} = c_1\mathbf{u}_1 + c_2\mathbf{u}_2 + c_3\mathbf{u}_3$ where

$$c_1 = \frac{\mathbf{w} \cdot \mathbf{u}_1}{\mathbf{u}_1 \cdot \mathbf{u}_1} = -\frac{2}{7}, c_2 = \frac{\mathbf{w} \cdot \mathbf{u}_2}{\mathbf{u}_2 \cdot \mathbf{u}_2} = \frac{1}{7}, c_3 = \frac{\mathbf{w} \cdot \mathbf{u}_3}{\mathbf{u}_3 \cdot \mathbf{u}_3} = 0.$$