W06-05

Slide 01: In this unit, we continue our discussion on the column space of a matrix and also its rank.

Slide 02: Consider the following linear system.

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We have seen in earlier units that one way of representing a linear system is to use a matrix equation Ax = b where A is the coefficient matrix, x is the variable matrix while b represents the right hand side constant matrix.

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The linear system can also be written in the form of a vector equation as shown here. On the left side of the equation, we have

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the first variable x multiplied to the first column of \boldsymbol{A} plus

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the second variable y multiplied to the second column of \boldsymbol{A} plus

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the third variable z multiplied to the third column of \boldsymbol{A} .

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The right hand side of the vector equation is the constant matrix \boldsymbol{b} . The expression on the left side of the equation is essentially a linear combination of the columns of \boldsymbol{A} .

Slide 03: Now that we see that the linear system $\mathbf{A}\mathbf{x} = \mathbf{b}$ can be expressed as a vector equation (*),

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 $\mathbf{A}\mathbf{x} = \mathbf{b}$ is consistent would mean that vector equation (*) can be satisfied by some x, y and z.

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The values of x, y an z that satisfies equation (*) would be how the constant matrix \boldsymbol{b} can be written as a linear combination of the columns of \boldsymbol{A} .

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By definition, since the column space of \boldsymbol{A} contains all the possible linear combinations of the columns of \boldsymbol{A} , since \boldsymbol{b} is a linear combination of the columns of \boldsymbol{A} , this would mean that \boldsymbol{b} belongs to the column space of \boldsymbol{A} .

Slide 04: Conversely, if we start off with the knowledge that b belongs to the column space of A,

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this would imply that b is a linear combination of the columns of A.

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By writing **b** as a linear combination of the columns of **A**, the coefficients x, y and z would be the solutions to vector equation (*),

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which means that, equivalently, $\mathbf{A}\mathbf{x} = \mathbf{b}$ is consistent. Although this argument arises from a numerical example, the same idea can be applied to prove the following theorem.

Slide 05: Let A be a $m \times n$ matrix. From the previous discussion, we observe that any vector in the column space of A can be represented by Au for some vector u in \mathbb{R}^n with n components. Thus the column space of A is the set of all Au where u takes on all possible vectors in \mathbb{R}^n . We also saw that a linear system Ax = b will be consistent if and only if b is a vector in the column space of A.

Slide 06: In this example, the linear system with 4 equations and 3 unknowns is first rewritten as a matrix equation Ax = b.

Slide 07: We then solve the linear system by Gaussian elimination.

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The conclusion we obtain is that Ax = b is inconsistent since the last column of a row-echelon form of the augemented matrix is a pivot column.

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If we only look at the left hand side of the vertical line, the portion of the matrix in green is in fact a row-echelon form of A. Since it has three leading entries, we see that the rank of A is 3.

Slide 08: If we look at the entire augmented matrix as a whole, the rank of the augmented matrix is 4, which is 1 more than the rank of A.

Slide 09: Thus, we now have another way of chracterising consistent linear systems. Basically, a linear system Ax = b is consistent if and only if the coefficient matrix A and the augmented matrix $(A \mid b)$ have the same rank.

Slide 10: To summarise this unit,

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we presented a theorem that gave an equivalent statement to the statement that Ax = b is consistent. The equivalent statement was stated in terms of the right hand side b, thought of as a vector, belonging to the column space of the coefficient matrix A.

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Another way of characterising a consistent linear system was in terms of the ranks of \mathbf{A} and the augmented matrix $(\mathbf{A} \mid \mathbf{b})$.