W03-04

Slide 01: In this unit we will learn how to compute the inverse of an invertible square matrix. Through the same process, we will also learn how to conclude that a square matrix is singular.

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Slide 02: Recall the following discussion from a previous unit.

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We saw that for any matrix A, performing a series of elementary row operations on A, can be represented by pre-multiplying a series of elementary matrices to A. Such a series of elementary matrices $E_1, E_2, ..., E_k$ can be chosen such that $E_k E_{k-1} ... E_1 A$ is the unique reduced row-echelon form of A.

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We also know now that if \boldsymbol{A} is invertible, this reduced row-echelon form of \boldsymbol{A} will be the identity matrix.

Slide 03: Also in an earlier unit when we introduced the concept of invertible matrices, we stated that given a square matrix B of the same size as A, in order to check whether B is the inverse of A, it is sufficient to just check whether AB or BA is equal to I and once this has been established to be true, then the two matrices will be inverses of each other.

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Thus, from the matrix equation highlighted in blue, since A and the product of elementary matrices $E_k E_{k-1} ... E_1$ are both square matrices of the same size, the matrix equation would imply that A^{-1} must be the product of these elementary matrices.

Slide 04: We now put what we already know at the top of this slide.

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Suppose \mathbf{A} is a square matrix of order n. Consider the following $n \times 2n$ matrix with the left hand side being \mathbf{A} and the right hand side being the identity matrix of order n.

Slide 05: We will now pre-multiply the entire sequence of elementary matrices $E_k E_{k-1} ... E_1$

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to this $n \times 2n$ matrix.

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Note that pre-multiplying the sequence of elementary matrices to the $n \times 2n$ matrix can be considered as pre-multiplying to each of the $n \times n$ matrix on either side of the vertical line.

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We now use the first fact that pre-multiplying the sequence of elementary matrices to \boldsymbol{A} , which is equivalent to performing the sequence of elementary row operations on \boldsymbol{A} would reduce the matrix \boldsymbol{A} to the identity matrix. This is of course, assuming that \boldsymbol{A} is an invertible matrix.

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Next, we recognise that the product of these elementary matrices is actually the inverse of A, which is what you would observe on the right side of the vertical line at this point.

Slide 06: The above discussion clearly provides us with a way to find the inverse of an invertible matrix A. To recap, to find A^{-1} , we will construct a $n \times 2n$ matrix with A on the left side and I on the right side. Proceed to perform elementary row operations on this matrix until the left side of the matrix is reduced from A to I. What results on the right side of the matrix is our desired A^{-1} .

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A natural question that one may ask is, what happens if the matrix \boldsymbol{A} that we are investigating turns out to be singular?

Slide 07: Well, we already know that \boldsymbol{A} is invertible is equivalent to the fact that the reduced row-echelon form of \boldsymbol{A} will be the identity matrix. Therefore, if \boldsymbol{A} turns out to be singular, after we have pre-multiplied the sequence of elementary matrices to the $n \times 2n$ matrix, the left side of the matrix will result in the reduced row-echelon form of \boldsymbol{A} which is not the identity matrix. This will then indicate to us that \boldsymbol{A} is indeed singular.

Slide 08: Let us go through an example. Determine if the following matrix A is invertible, and if so, find its inverse.

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As discussed previously, we start by constructing a 3×6 matrix with \boldsymbol{A} on the left and $\boldsymbol{I_3}$ on the right.

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We will proceed with performing elementary row operations on this matrix with the intention of reducing the matrix \boldsymbol{A} on the left side of the vertical line to its reduced row-echelon form. In accordance to the Gauss-Jordan elimination, the first two elementary row operations performed are shown here.

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The current state of the 3×6 matrix is shown and we will continue with the elimination steps.

Slide 09: The next elementary row operation performed will be $R_3 + 2R_2$. (#)

And at this point you will observe that the left hand side is already in row-echelon form. At this point, we should be able to conclude that because a row-echelon form of the 3×3 matrix \boldsymbol{A} has 3 leading entries, it is certain that \boldsymbol{A} will have the identity matrix $\boldsymbol{I_3}$ as its reduced row-echelon form, meaning that it is indeed invertible. Since we would need to find \boldsymbol{A}^{-1} anyway, we will need to proceed with more elimination steps.

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We first multiply row 3 by -1,

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resulting in this matrix.

Slide 10: Following three more elementary row operations, we arrive at the following and it is observed now that the matrix A on the left has been successfully reduced to the identity matrix I_3 .

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In accordance to our earlier discussion, we can conclude that \boldsymbol{A} is invertible,

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and the 3×3 matrix found on the right hand side of the final matrix is precisely our \mathbf{A}^{-1} .

Slide 11: We will go through the same procedure to show that this 4×4 matrix is singular.

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As usual, we set up a 4×8 matrix as shown. While I will not show the details of the elimination performed on the matrix, I would urge you to try and perform Gaussian elimination to see the outcome.

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For this matrix, you should observe that after some elementary row operations, the left hand side is reduced to the reduced row-echelon form of A,

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denoted by \mathbf{R} ,

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which is not the identity matrix of order 4. Thus we are able to conclude that \boldsymbol{A} is singular.

Slide 12: In summary,

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we have derived a method to find the inverse of an invertible matrix.

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Using the same method, we have also a way to show that a matrix is singular.