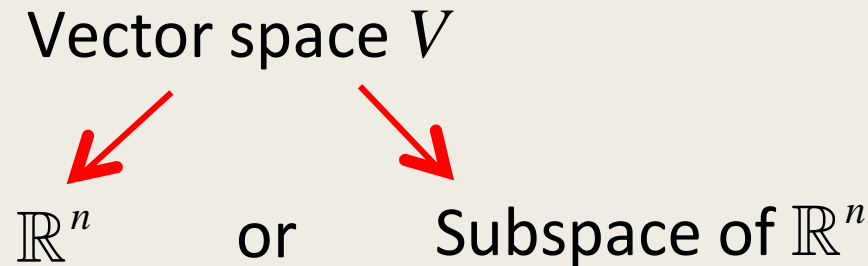


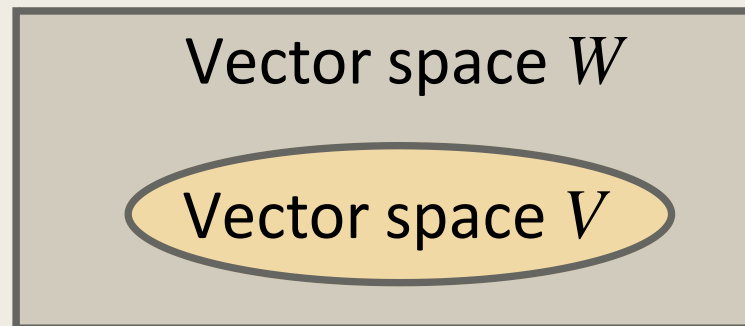
BASES I

Vector spaces

- 1) A set V is called a **vector space** if either $V = \mathbb{R}^n$ or V is a **subspace** of \mathbb{R}^n for some positive integer n .

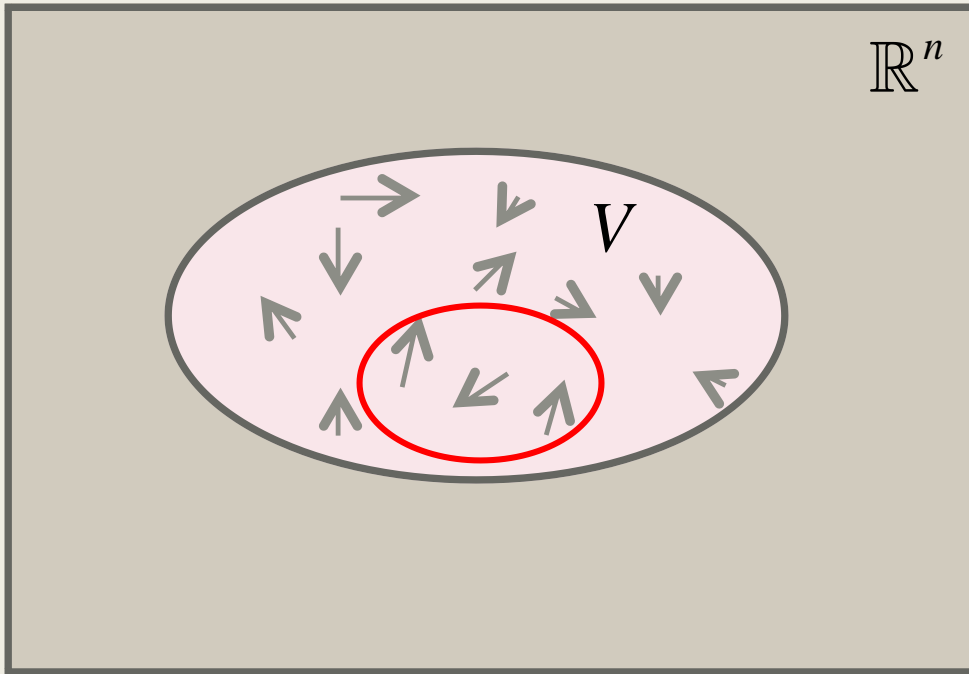


- 2) Let W be a vector space. A set V is called a **subspace** of W if V is a vector space contained in W .



Finding a small set

Consider a vector space V .



Question:

Find a subset S of V , containing as few vectors as possible, so that every vector in V is a linear combination of the vectors in S (that is, $\text{span}(S) = V$).

Such a set can then be used to build a 'coordinate system' for V .

Definition

Let $S = \{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k\}$ be a subset of a vector space V .

Then S is called a basis (plural bases) for V if

1. S is linearly independent and
2. S spans V .

Example

Show that $S = \{(2,4), (1,0)\}$ is a basis for \mathbb{R}^2 . **DONE!**

1) S contains only two vectors, which are not multiples of each other, so S is a **linearly independent** set.

2) Does S **span** \mathbb{R}^2 ? **YES!**

Is $a(2,4) + b(1,0) = (x, y)$ always consistent for all (x, y) ?

$$\left(\begin{array}{cc|c} 2 & 1 & x \\ 4 & 0 & y \end{array} \right) \xrightarrow{\text{red arrow}} \left(\begin{array}{cc|c} 2 & 1 & x \\ 0 & -2 & y - 2x \end{array} \right)$$

Example

Show that $S = \{(1, 2, 1), (2, 9, 0), (3, 3, 4)\}$ is a basis for \mathbb{R}^3 .

1) Does S span \mathbb{R}^3 ? **YES!**

Is $a(1, 2, 1) + b(2, 9, 0) + c(3, 3, 4) = (x, y, z)$ always consistent for all (x, y, z) ?

$$\left(\begin{array}{ccc|c} 1 & 2 & 3 & x \\ 2 & 9 & 3 & y \\ 1 & 0 & 3 & z \end{array} \right) \xrightarrow{\text{red arrow}} \left(\begin{array}{ccc|c} 1 & 2 & 3 & * \\ 0 & 5 & -3 & * \\ 0 & 0 & -\frac{1}{5} & * \end{array} \right)$$

Some expression involving x, y, z

Example

Show that $S = \{(1,2,1), (2,9,0), (3,3,4)\}$ is a basis for \mathbb{R}^3 .

2) Is S a linearly independent set?

YES!

DONE!

Does $a(1,2,1) + b(2,9,0) + c(3,3,4) = (0,0,0)$ have only the trivial solution?

$$\begin{pmatrix} 1 & 2 & 3 & | & x \\ 2 & 9 & 3 & | & y \\ 1 & 0 & 3 & | & z \end{pmatrix} \xrightarrow{\text{red arrow}} \begin{pmatrix} 1 & 2 & 3 & | & * \\ 0 & 5 & -3 & | & * \\ 0 & 0 & -\frac{1}{5} & | & * \end{pmatrix} \begin{matrix} \swarrow \\ \rightarrow \\ \searrow \end{matrix} \begin{matrix} \text{Some expression} \\ \text{involving } x, y, z \end{matrix}$$
$$\begin{pmatrix} 1 & 2 & 3 & | & 0 \\ 2 & 9 & 3 & | & 0 \\ 1 & 0 & 3 & | & 0 \end{pmatrix} \xrightarrow{\text{red arrow}} \begin{pmatrix} 1 & 2 & 3 & | & 0 \\ 0 & 5 & -3 & | & 0 \\ 0 & 0 & -\frac{1}{5} & | & 0 \end{pmatrix}$$

Example

Is $S = \{(1,1,0,1), (2,1,0,3), (3,-1,0,3)\}$ a basis for \mathbb{R}^4 ?

No. We know (from a previous unit) that 3 vectors cannot span \mathbb{R}^4 .

Is $S = \{(1,0,1,1), (0,0,1,2), (-1,0,0,1), (2,0,3,3)\}$ a basis for \mathbb{R}^4 ?

No. $(0,1,0,0)$ is not a linear combination of vectors in S .

Remarks

- 1) A basis for a vector space V contains the smallest possible number of vectors that can span V .
- 2) For convenience, we say that the empty set \emptyset is the basis for the zero space.
- 3) Except the zero space, any vector space has infinitely many different bases.

Theorem

If $S = \{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k\}$ is a basis for a vector space V , then every vector $\mathbf{v} \in V$ can be expressed in the form (as a linear combination of $\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k$)

$$\mathbf{v} = c_1\mathbf{u}_1 + c_2\mathbf{u}_2 + \dots + c_k\mathbf{u}_k$$

in exactly one way, where $c_1, c_2, \dots, c_k \in \mathbb{R}$.

Proof: Suppose it can be done in two ways.

$$\mathbf{v} = a_1\mathbf{u}_1 + a_2\mathbf{u}_2 + \dots + a_k\mathbf{u}_k \quad (1)$$

$$\mathbf{v} = b_1\mathbf{u}_1 + b_2\mathbf{u}_2 + \dots + b_k\mathbf{u}_k \quad (2)$$

Theorem

Proof: Suppose it can be done in two ways.

It's actually
just ONE way!

$$\mathbf{v} = a_1\mathbf{u}_1 + a_2\mathbf{u}_2 + \dots + a_k\mathbf{u}_k \quad (1)$$

$$\mathbf{v} = b_1\mathbf{u}_1 + b_2\mathbf{u}_2 + \dots + b_k\mathbf{u}_k \quad (2)$$

$$(1) - (2) \Rightarrow$$

$$\mathbf{0} = (a_1 - b_1)\mathbf{u}_1 + (a_2 - b_2)\mathbf{u}_2 + \dots + (a_k - b_k)\mathbf{u}_k \quad (*)$$

But S is a basis means it is a linearly independent set.

$\Rightarrow (*)$ has only the trivial solution.

$$\Rightarrow a_1 - b_1 = 0, a_2 - b_2 = 0, \dots, a_k - b_k = 0$$

$$\Rightarrow a_1 = b_1, a_2 = b_2, \dots, a_k = b_k$$

Summary

- 1) What is a vector space? A subspace of a vector space.
- 2) Definition of a basis (for a vector space).
- 3) Uniqueness in representing a vector in terms of a set of basis vectors.