NATIONAL UNIVERSITY OF SINGAPORE

Department of Mathematics

SEMESTER II, 2018/2019 MA1508E MID-TERM TEST

Full Name :	_
Matric/Student Number :	
Tutorial Group :	

INSTRUCTIONS

PLEASE READ CAREFULLY

- Write your full name, matric number and tutorial group clearly above on this cover page.
- There are 3 questions printed on 2 pages. Answer all questions.
- You must show all your working clearly, failure to do so will result in marks deducted.
- Use pen for this test.
- All answers and working have to be written on the answer book provided.
- Start on a new page for each question.
- Tie this cover page (and question paper) together with your answer book before submission.

Question 1

(a) Consider the following linear system where k is a constant.

$$\begin{cases} x - 3y & = 6 \\ x + 3z & = -3 \\ 2x + ky + (3-k)z & = 1 \end{cases}$$

Find all values of k such that the linear system

- (i) has exactly one solution.
- (ii) has infinitely many solutions.
- (iii) has no solution.

$$\begin{pmatrix} 1 & -3 & 0 & | & 6 \\ 1 & 0 & 3 & | & -3 \\ 2 & k & 3 - k & | & 1 \end{pmatrix} \xrightarrow{R_2 - R_1} \begin{pmatrix} 1 & -3 & 0 & | & 6 \\ 0 & 3 & 3 & | & -9 \\ 0 & k + 6 & 3 - k & | & -11 \end{pmatrix}$$

$$\xrightarrow{\frac{1}{3}R_2} \begin{pmatrix} 1 & -3 & 0 & | & 6 \\ 0 & 1 & 1 & | & -3 \\ 0 & k + 6 & 3 - k & | & -11 \end{pmatrix} \xrightarrow{R_3 - (k+6)R_2} \begin{pmatrix} 1 & -3 & 0 & | & 6 \\ 0 & 1 & 1 & | & -3 \\ 0 & 0 & -2k - 3 & | & 3k + 7 \end{pmatrix}$$

So the linear system

- (i) exactly one solution when $k \neq -\frac{3}{2}$.
- (ii) will not have infinitely many solutions for any value of k.
- (iii) has no solution when $k = -\frac{3}{2}$.
- (b) Let \boldsymbol{A} and \boldsymbol{B} be a 4×4 matrices such that $\det(\boldsymbol{A}) = 1508$ and $\det(\boldsymbol{B}) = -1508$. Determine if the following statements are true. If a statement is true, provide a proof. If a statement is false, provide an example of \boldsymbol{A} and/or \boldsymbol{B} (with the desired determinant) and \boldsymbol{c} such that the statement is violated.
 - (i) For any 4×1 matrix c, the equation (A + B)x = c has exactly one solution.
 - (ii) The homogeneous linear system (A B)x = 0 always has infinitely many solutions.
 - (iii) For any 4×1 matrix c, the equation (AB)x = c is always consistent.

2

(i) The statement is false. For example, we may let

$$\mathbf{A} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1508 \end{pmatrix} \quad \mathbf{B} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & -1508 \end{pmatrix} \quad \mathbf{c} = \begin{pmatrix} 2 \\ 2 \\ 2 \\ 0 \end{pmatrix}.$$

Then the linear system (A + B)x = c,

$$\begin{pmatrix} 2 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 2 \\ 2 \\ 2 \\ 0 \end{pmatrix}$$

has infinitely many solutions $x_1 = 1, x_2 = 1, x_3 = 1, x_4 = t, t \in \mathbb{R}$.

(ii) The statement is false. For example, we may let

$$\mathbf{A} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1508 \end{pmatrix} \quad \mathbf{B} = \begin{pmatrix} -1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & -754 \end{pmatrix}.$$

In this case, the linear system (A - B)x = 0,

$$\begin{pmatrix} 2 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & 2262 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$

has only the trivial solution.

(iii) The statement is true. Since $\det(\mathbf{A}\mathbf{B}) = \det(\mathbf{A})\det(\mathbf{B}) \neq 0$, the matrix $\mathbf{A}\mathbf{B}$ is invertible. Thus for any \mathbf{c} , $\mathbf{A}\mathbf{B}\mathbf{x} = \mathbf{c}$ has a (unique) solution $\mathbf{x} = (\mathbf{A}\mathbf{B})^{-1}\mathbf{c}$.

3

Question 2

(a) Let
$$\mathbf{A} = \begin{pmatrix} 1 & -1 & 0 \\ 2 & 0 & 3 \\ 1 & -1 & 2 \end{pmatrix}$$
 and $\mathbf{B} = \begin{pmatrix} 1 & -1 & 0 \\ 0 & 2 & 3 \\ 0 & 0 & 1 \end{pmatrix}$.

(i) Find elementary matrices E_1, E_2, E_3 such that

$$E_2E_1A=E_3B.$$

- (ii) Using the equation $E_2E_1A = E_3B$, compute the determinant of A. (You are not allowed to use other methods.) Explain why A is invertible.
- (iii) Express A^{-1} as a product of **exactly six** elementary matrices. (**Hint:** B is a row-echelon form of A.)

(i)
$$\boldsymbol{A} \overset{R_2-2R_1}{\longrightarrow} \begin{pmatrix} 1 & -1 & 0 \\ 0 & 2 & 3 \\ 0 & 0 & 2 \end{pmatrix} \overset{\frac{1}{2}}{\longrightarrow} \boldsymbol{B}.$$

So the three elementary matrices are

$$\boldsymbol{E_1} = \begin{pmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad \boldsymbol{E_2} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -1 & 0 & 1 \end{pmatrix} \quad \boldsymbol{E_3} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{pmatrix}$$

(ii) Since $\det(\boldsymbol{B})=2,$ $\frac{1}{2}\cdot 1\cdot 1\cdot \det(\boldsymbol{A})=\det(\boldsymbol{B})=2.$

Thus $\det(\mathbf{A}) = 4$.

(iii) We perform 3 more elementary row operations on B:

$$\mathbf{B} \xrightarrow{\frac{1}{2}R_2} R_2 - \frac{3}{2}R_3 R_1 + R_2 \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}.$$

So $A^{-1} = E_6 E_5 E_4 E_3^{-1} E_2 E_1$ where E_1, E_2, E_3 are given in part (i) and

$$\boldsymbol{E_3}^{-1} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & \frac{1}{2} \end{pmatrix} \quad \boldsymbol{E_4} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \frac{1}{2} & 0 \\ 0 & 0 & 1 \end{pmatrix} \quad \boldsymbol{E_5} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & -\frac{3}{2} \\ 0 & 0 & 1 \end{pmatrix} \quad \boldsymbol{E_6} = \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}.$$

(b) Let A be a 3×3 matrix where the columns of A are a_1, a_2 and a_3 respectively. That is,

$$oldsymbol{A} = egin{pmatrix} oldsymbol{a_1} & oldsymbol{a_2} & oldsymbol{a_3} \end{pmatrix}$$
 .

Let B be another 3×3 matrix whose second and third column are the same as the second and third column of A, that is

$$oldsymbol{B} = egin{pmatrix} oldsymbol{b_1} & oldsymbol{a_2} & oldsymbol{a_3} \end{pmatrix}.$$

Let C be the following 3×3 matrix:

$$C = \begin{pmatrix} ma_1 + nb_1 & a_2 & a_3 \end{pmatrix}, \quad m, n \in \mathbb{R}.$$

That is, the first column of C is $ma_1 + nb_1$ and the second and third columns are a_2 and a_3 respectively. Prove that

$$\det(\mathbf{C}) = m\det(\mathbf{A}) + n\det(\mathbf{B}).$$

First, note that A, B and C differ only in the first column. So when we compute the determinant of these 3 matrices by cofactor expansion (along the first column), the first column cofactors of A, B and C are all equal, denoted by A_{11} , A_{21} and A_{31} . Let a_{11} , a_{21} and a_{31} be the first column entries of A. So

$$\det(\mathbf{A}) = a_{11}A_{11} + a_{21}A_{21} + a_{31}A_{31}.$$

Similarly, if b_{11} , b_{21} and b_{31} are the first column entries of \boldsymbol{B} , we have

$$\det(\mathbf{B}) = b_{11}A_{11} + b_{21}A_{21} + b_{31}A_{31}.$$

Now the first column entries of C are $ma_{11} + nb_{11}$, $ma_{21} + nb_{21}$ and $ma_{31} + nb_{31}$. So

$$\det(\mathbf{C}) = (ma_{11} + nb_{11})A_{11} + (ma_{21} + nb_{21})A_{21} + (ma_{31} + nb_{31})A_{31}$$

$$= m(a_{11}A_{11} + a_{21}A_{21} + a_{31}A_{31}) + n(b_{11}A_{11} + b_{21}A_{21} + b_{31}A_{31})$$

$$= m\det(\mathbf{A}) + n\det(\mathbf{B})$$

Question 3

Let $S = \{\boldsymbol{u_1}, \boldsymbol{u_2}, \boldsymbol{u_3}\}$ where

$$\boldsymbol{u_1} = \begin{pmatrix} \frac{1}{\sqrt{2}} \\ 0 \\ -\frac{1}{\sqrt{2}} \\ 0 \end{pmatrix}, \quad \boldsymbol{u_2} = \begin{pmatrix} a \\ a \\ b \\ b \end{pmatrix}, \quad \boldsymbol{u_3} = \begin{pmatrix} 0 \\ -\frac{1}{\sqrt{2}} \\ 0 \\ \frac{1}{\sqrt{2}} \end{pmatrix},$$

where a, b are real numbers.

- (i) If a = 1, b = -1, compute $\cos(\theta)$ where θ is the angle between u_1 and u_2 .
- (ii) If $a = -\frac{1}{\sqrt{2}}$, $b = \frac{1}{\sqrt{2}}$, compute the distance between u_2 and u_3 .
- (iii) Find all values of a and b such that S is an orthonormal set.
- (i) When a = 1, b = -1,

$$\mathbf{u_2} = \begin{pmatrix} 1 \\ 1 \\ -1 \\ -1 \end{pmatrix} \Rightarrow cos(\theta) = \frac{\mathbf{u_1} \cdot \mathbf{u_2}}{||\mathbf{u_1}|| ||\mathbf{u_2}||} = \frac{\frac{1}{\sqrt{2}} + \frac{1}{\sqrt{2}}}{1 \cdot 2} = \frac{1}{\sqrt{2}}.$$

(ii) When $a = -\frac{1}{\sqrt{2}}$, $b = \frac{1}{\sqrt{2}}$,

$$u_{2} = \begin{pmatrix} -\frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} \Rightarrow u_{2} - u_{3} = \begin{pmatrix} -\frac{1}{\sqrt{2}} \\ 0 \\ \frac{1}{\sqrt{2}} \\ 0 \end{pmatrix}$$

$$\Rightarrow d(u_{2}, u_{3}) = ||u_{2} - u_{3}|| = \sqrt{\frac{1}{2} + \frac{1}{2}} = 1.$$

(iii) For S to be an orthogonal set,

$$\mathbf{u_2} \cdot \mathbf{u_1} = 0 \Rightarrow \frac{a}{\sqrt{2}} - \frac{b}{\sqrt{2}} = 0 \Rightarrow a = b.$$

It should be noted that $u_2 \cdot u_3 = 0$ would yield the same a = b and $u_1 \cdot u_3 = 0$. For S to be an orthonormal set, the length of u_2 must be 1.

$$||u_2|| = 1 \Rightarrow \sqrt{a^2 + a^2 + b^2 + b^2} = 1 \Rightarrow \sqrt{a^2 + a^2 + a^2 + a^2} = 1 \Rightarrow \pm 2a = 1 \Rightarrow a = \pm \frac{1}{2}.$$

So the values of a, b such that S is an orthonormal set is $(a, b) = (\frac{1}{2}, \frac{1}{2})$ and $(a, b) = (-\frac{1}{2}, -\frac{1}{2})$.

END OF TEST