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Tarea 3

1.

Sea $L = L(\ddot{q}_i, \dot{q}_i, q_i; t)$

$$J = \int_{t_1}^{t_2} L(\ddot{q}_i, \dot{q}_i, q_i; t) dt$$

$$\frac{\partial J}{\partial x} = \frac{\partial}{\partial x} \int_{t_1}^{t_2} \left(\frac{\partial L}{\partial \ddot{q}_i} \frac{\partial \ddot{q}_i}{\partial x} + \frac{\partial L}{\partial \dot{q}_i} \frac{\partial \dot{q}_i}{\partial x} + \frac{\partial L}{\partial q_i} \frac{\partial q_i}{\partial x} \right) dt$$

$$\frac{\partial q_i}{\partial x} = n(t), \quad \frac{\partial \dot{q}_i}{\partial x} = \frac{dn}{dt}, \quad \frac{\partial \ddot{q}_i}{\partial x} = \frac{d^2 n}{dt^2}$$

$$\frac{\partial J}{\partial x} = \frac{\partial J}{\partial x} \left[\int_{t_1}^{t_2} \frac{\partial L}{\partial \ddot{q}_i} \frac{d^2 n}{dt^2} dt + \int_{t_1}^{t_2} \left(\frac{\partial L}{\partial \dot{q}_i} \frac{dn}{dt} \right) dt + \int_{t_1}^{t_2} \left(\frac{\partial L}{\partial q_i} n \right) dt \right]$$

Integrando por partes el segundo término:

$$\int_{t_1}^{t_2} \left(\frac{\partial L}{\partial \dot{q}_i} \frac{dn}{dt} \right) dt = \frac{\partial L}{\partial \dot{q}_i} n \Big|_{t_1}^{t_2} - \int_{t_1}^{t_2} \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}_i} \right) n(t) dt$$

$$u = \frac{\partial L}{\partial \dot{q}_i}, \quad dv = \frac{dn}{dt} dt, \quad y \quad du = \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}_i} \right) dt, \quad v = n$$

Integrando el tercer término por Partes:

$$\begin{aligned} \int_{t_1}^{t_2} \frac{\partial L}{\partial q_i} n dt &= \frac{\partial L}{\partial q_i} n \Big|_{t_1}^{t_2} - \int_{t_1}^{t_2} \frac{d}{dt} \left(\frac{\partial L}{\partial q_i} \right) n dt \\ &= - \int_{t_1}^{t_2} \frac{d}{dt} \left(\frac{\partial L}{\partial q_i} \right) n dt \end{aligned}$$

Repetiendo el proceso se tiene que:

$$\frac{\partial J}{\partial x} = \int_{t_1}^{t_2} \left[\frac{\partial L}{\partial \ddot{q}_i} - \frac{d}{dt} \frac{\partial L}{\partial \dot{q}_i} + \frac{d^2}{dt^2} \frac{\partial L}{\partial q_i} \right] n(t) dt = 0$$

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$$\frac{\partial L}{\partial q_i} - \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}_i} \right) + \frac{d^2}{dt^2} \left(\frac{\partial L}{\partial \ddot{q}_i} \right) = 0$$

2.

$$L(\dot{q}, q; t) = \frac{1}{2} g_{ab}(q^c) \dot{q}^a \dot{q}^b$$

Recordando las condiciones

i) $g_{ab} = g_{ba}$

ii) g_{ab} es simétrica

$$\frac{\partial L}{\partial q^c} = \frac{1}{2} \frac{d}{dq^c} g_{ab} \dot{q}^a \dot{q}^b$$

$$\frac{\partial L}{\partial \dot{q}^c} = \frac{1}{2} g_{cb} \dot{q}^b + \frac{1}{2} g_{ac} \dot{q}^a$$

$$\frac{d}{dt} \left[\frac{1}{2} g_{cb} \dot{q}^b + \frac{1}{2} g_{ac} \dot{q}^a \right] = \frac{1}{2} g_{cb} \ddot{q}^b + \frac{1}{2} g_{ac} \ddot{q}^a + \frac{1}{2} \frac{\partial}{\partial q^a} (g_{cb}) \dot{q}^a \dot{q}^b + \frac{1}{2} \frac{\partial}{\partial q^b} (g_{ca}) \dot{q}^a \dot{q}^b$$

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$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}^c} \right) = g_{ac} \ddot{q}^a + \frac{1}{2} \dot{q}^a \dot{q}^b \left(\frac{\partial}{\partial q^a} (g_{cb}) + \frac{\partial}{\partial q^b} (g_{ac}) \right)$$

Por la condición i) $\nabla g_{ab} = g_{ba}$

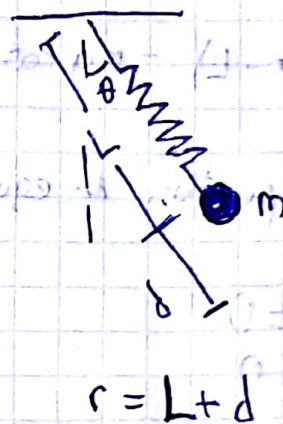
$$\begin{aligned} \frac{\partial L}{\partial q^c} + \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}^c} \right) &= g_{ac} \ddot{q}^a + \frac{1}{2} \dot{q}^a \dot{q}^b \left(\frac{\partial}{\partial q^a} (g_{cb}) + \frac{\partial}{\partial q^b} (g_{ac}) \right) - \frac{1}{2} g_{ab} \ddot{q}^a \dot{q}^b \\ &= g_{ac} \ddot{q}^a + \frac{1}{2} \left(\frac{\partial}{\partial q^a} g_{cb} + \frac{\partial}{\partial q^b} g_{ac} - \frac{\partial}{\partial q^c} g_{ab} \right) \dot{q}^a \dot{q}^b \end{aligned}$$

$$\Gamma_{bc}^a = \frac{1}{2} \left(\frac{\partial g_{cb}}{\partial q^a} + \frac{\partial g_{ac}}{\partial q^b} - \frac{\partial g_{ab}}{\partial q^c} \right)$$

$$\frac{\partial L}{\partial q^c} + \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}^c} \right) = g_{ac} \ddot{q}^a + \Gamma_{bc}^a \dot{q}^a \dot{q}^b$$

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3.



$$L = T - V$$

$$T = \frac{1}{2} m (\dot{x}^2 + \dot{y}^2) = \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\theta}^2)$$

$$V = \frac{1}{2} k (r - L)^2 - mgr \cos \theta$$

$$L = \frac{1}{2} m (\dot{r}^2 + r^2 \dot{\theta}^2) + \frac{1}{2} k (r - L)^2 - mgr \cos \theta$$

Luego,

$$\frac{\partial L}{\partial \theta} = mgr \sin \theta$$

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\theta}} \right) = \frac{d}{dt} (r^2 \dot{\theta}) = 2r\dot{\theta} + r^2 \ddot{\theta} \quad (\text{Para } \theta)$$

Y las ecuaciones de Euler-Lagrange se escriben:

$$\frac{\partial L}{\partial \theta} - \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{\theta}} \right) = mgr \sin \theta - 2r\dot{\theta} - r^2 \ddot{\theta} = 0 \quad (\text{Para } \theta)$$

$$\frac{\partial L}{\partial r} = k(r - L) - mg \cos \theta$$

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{r}} \right) = m\dot{r} \quad \text{y} \quad \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{r}} \right) = m\ddot{r} \quad (\text{Para } r)$$

$$\frac{\partial L}{\partial r} = k(r - L) - mg \cos \theta \quad \text{y} \quad \frac{d}{dt} \left(\frac{\partial L}{\partial \dot{r}} \right) = m\ddot{r}$$

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Y las ecuaciones de E-L

$$k(r-L) - mg \cos \theta - m\ddot{r} = 0$$

Los puntos de equilibrio:

$$\dot{r} = 0$$

$$r = 0$$

$$\begin{cases} mg \sin \theta - 2\theta - r\ddot{\theta} = 0 \\ k(r-L) - mg \cos \theta - m\ddot{r} = 0 \end{cases}$$

$$k(r-L) - mg \cos \theta - m\ddot{r} = 0$$

4.

$$a) L = e^{bt} \left(\frac{1}{2} m \dot{q}^2 - \frac{1}{2} k^2 q^2 \right)$$

$$\frac{\partial L}{\partial q} = -e^{bt} k^2 q$$

$$\frac{\partial L}{\partial \dot{q}} = e^{bt} m \dot{q}$$

$$\frac{d}{dt} \left(\frac{\partial L}{\partial \dot{q}} \right) = b m e^{bt} \dot{q} + e^{bt} [(\ddot{q})^2 + \dot{q} \ddot{q}]$$

$$e^{bt} m \ddot{q} - b m e^{bt} \dot{q} + e^{bt} (\ddot{q})^2 + e^{bt} \dot{q} \ddot{q} = 0 //$$

$$b) q = e^{bt/2} \tilde{q}, \quad \tilde{q} = Q e^{-bt/2} \quad \dot{\tilde{q}} = \dot{Q} e^{-bt/2} + \left(-\frac{b}{2}\right) Q e^{-bt/2}$$

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$$L = \left(e^{bt} \left(\frac{1}{2} m e^{-bt} \left(\dot{Q} - \frac{b}{2} Q \right)^2 \right) - \frac{1}{2} e^{bt} k^2 Q^2 e^{-bt} \right)$$

$$L = \frac{1}{2} \left[m \left(\dot{Q} - \frac{b}{2} Q \right)^2 - k^2 Q^2 \right] //$$