

Azmyin Md. Kamal

ROBOTICIST · IEEE RAS STUDENT MEMBER · U.S PERMANENT RESIDENT

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Summary

Experienced Robotics researcher pursuing a Ph.D. in Mechanical Engineering, specializing in platform-agnostic, collaborative Visual SLAM frameworks, Robot Perception, 3D Object Detection, and Numerical Optimization. Additionally proficient in Deep Neural Networks with PyTorch, Data-Driven Control, ROS 1 & 2 ecosystems, CI/CD pipelines with Docker, Physics-based Robot Simulation, and upgrading legacy ROS packages. Expected to graduate in December 2025.

Skills

Programming	C++, Python, MATLAB, L ^A T _E X, Markdown
Software Development	Git, Docker, Ruff, Doxygen
Robotics & Applied Mathematics	Visual SLAM, Optimization, Koopman Operators, Robot Navigation
Frameworks & Platforms	ROS 1 & 2, PyTorch, Space ROS
Software libraries (selected)	SciPy, Numpy, Numba, Eigen, Matplotlib
Deep Learning Methods	YOLO, LSTM, CNN
Simulation & Visualization	Open 3D Engine (O3DE), RViz, Pangolin

Experience

Graduate Research & Teaching Assistant

Baton Rouge, Louisiana, U.S.A

LOUISIANA STATE UNIVERSITY

Fall 21 - Present

- Developing novel relocalization, metric-semantic mapping, and navigation algorithms for Keyframe VSLAM frameworks.
- In charge of the maintenance and upkeep for two RBKAIROS industrial-grade mobile manipulators, each valued at \$90K.
- Taught Machine Design and Control Engineering courses, and conducted relevant labs.

Graduate Research Assistant

Lafayette, Louisiana, U.S.A

THE UNIVERSITY OF LOUISIANA AT LAFAYETTE

Fall 19 - Summer 2021

- Developed a novel COVID-19 data analysis tool and a multimodal indoor positioning system.
- Mentored Undergraduate RAs in developing cyber-physical systems and applied machine learning.

Projects

Distributed, Collaborative Semantic-Mapping Module (Ongoing) | C++, Python, ROS 2, Rviz

- Developing a novel metric-semantic collaborative mapping framework for agents operating in GPS-denied environments.
- Modular and platform-agnostic design.

Solving Short-Term Relocalization Problems In MKVSLAM Using Spatial And Semantic Data | C++, Python, ROS 2, YOLOv5

- Developed a novel global pose recovery (relocalization) method for VSLAM frameworks using semantic and spatial data.
- The proposed method improved localization accuracy, extended operational lifetime, and demonstrated real-time performance.
- Paper presented in 2024 IEEE/ASME International Conference on Advanced Intelligent Mechatronics (AIM). [Code](#), [Paper](#)

ROS2 ORB-SLAM3 package | ROS 2, C++

- Developed a package that natively implements ORB-SLAM3 V1.0 in ROS 2 Humble. [Code](#)
- Repository has garnered over 30 stars and 5 forks, reflecting its usefulness and adoption within the community.

Integration of Open 3D Engine (O3DE) into Space ROS (Ongoing) | C++, ROS 2, Space ROS, O3DE, Docker

- Integrating this open-source engine to enable photorealistic, physics-based simulations within the Space ROS framework.

Niter2 Image-Space Triangulation Method | Python, Numpy, Numba

- Developed a Numba-accelerated python port of the "niter2" image-space two-view triangulation algorithm. [Code](#)

Anonymous Multi-User Tracking in Indoor Environment Using Computer Vision and Bluetooth | Python, PyTorch, Nvidia SBC

- Developed a novel multimodal indoor positioning system utilizing monocular images and Bluetooth RSSI data
- Master's Thesis. Manuscript available [here](#)

Multi-stage Logistic Growth Model for COVID 19 Infection Phase Analysis | Python, MATLAB, Data mining

- Developed a multi-stage logistic growth model based on a single-stage model written in MATLAB. [Code](#)
- Co-authored a Nature paper with this contribution. [Paper](#)

Deep Learning Projects | Python, PyTorch

- Developed a piano music generator using two Critic-Composer LSTMS. [Code](#)
- Implemented AlphaZero's Monte Carlo Tree Search algorithm in an 11x11 Gomoku game. [Code](#)

Education

Ph.D. in Mechanical Engineering (Ongoing)

Baton Rouge, Louisiana, U.S.A

LOUISIANA STATE UNIVERSITY (LSU)

Fall 21 - Present

Master of Science in Engineering (M.S), conc. Mechanical Engineering

Lafayette, Louisiana, U.S.A

THE UNIVERSITY OF LOUISIANA AT LAFAYETTE (UL LAFAYETTE)

Fall 19 - Fall 21

Bachelor of Science (B.Sc) in Mechanical Engineering

Dhaka, Bangladesh

AHSANULLAH UNIVERSITY OF SCIENCE AND TECHNOLOGY (AUST)

Fall 11 - Spring 15

Honors & Awards

Graduate Teaching & Research Assistantship: NSF:NRI #2024795, August 21 - December 24

Graduate Teaching & Research Assistantship: UL Lafayette & NSF:RAPIDS #2027688, January 20 - July 21

Dean's List of Honor with Valedictorian Distinction: Ahsanullah University of Science & Technology (AUST), November 16