Azmyin Md. Kamal

Baton Rouge, Louisiana - Portfolio: https://mechazo11.github.io/

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Skills

Programming C++, Python, PyTorch, MATLAB, LATEX

Software Development Git, Docker, Ruff

ROS 1 & 2, Gazebo Harmonic, ros2_control Frameworks & Platforms

Education.

Ph.D. in Mechanical Engineering (Ongoing)

LOUISIANA STATE UNIVERSITY (LSU)

Master of Science in Mechanical Engineering

THE UNIVERSITY OF LOUISIANA AT LAFAYETTE (UL LAFAYETTE)

Bachelor of Science (B.Sc) in Mechanical Engineering

AHSANULLAH UNIVERSITY OF SCIENCE AND TECHNOLOGY (AUST)

Baton Rouge, Louisiana, U.S.A Fall 21 - Present Lafayette, Louisiana, U.S.A

> Fall 19 - Fall 21 Dhaka, Bangladesh

Fall 11 - Spring 15

Work Experience

Graduate Research & Teaching Assistant

Louisiana State University

Baton Rouge, Louisiana, U.S.A Fall 21 - Present

• Developing a novel fault-tolerant, collaborative metric-semantic CSLAM framework in ROS 2 utilizing 3D object semantics and camera pose.

- Developing a new implementation of *Deep3D* bounding box regressor using EfficientNetV2. This work will also introduce a new pipeline for generating training data for training bounding box regressor.
- Developed a ROS 2 package to natively integrate ORB-SLAM3 into ROS 2 ecosystem.
- Responsible for the maintenance and upkeep of two RBKAIROS mobile manipulators, each valued at \$90K.
- Conducted laboratory sessions for Machine Design II and Control Engineering courses.

Graduate Research Assistant

Lafayette, Louisiana, U.S.A

Fall 19 - Summer 2021

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THE UNIVERSITY OF LOUISIANA AT LAFAYETTE • Developed a Python-based data analysis tool for COVID-19 infection phases, facilitating collaboration with computer scientists and contributing to publications in a Nature and a BMC journal papers.

• Developed a privacy-aware, multi-user indoor positioning system, deployed IoT occupancy monitoring systems and advised undergraduate RAs in IoT projects.

Projects (curated).

Solving Short-Term Relocalization Problems In MKVSLAM Using Spatial And Semantic Data | ROS 2, Python

- Developed a novel global pose recovery (relocalization) method for VSLAM frameworks using a new Keyframe descriptor and Keyframe place recognition method using object semantics and camera spatial data.
- About 2x speedup and 39% reduction in ATE in comparison to bag-of-words baseline method in ground and aerial vehicle datasets. Paper presented in IEEE/ASME AIM 2024. Code, Paper

ROS2 ORB-SLAM3 package | ROS 2, C++

• Developed a package that natively implements ORB-SLAM3 V1.0 in ROS 2 ecosystem. Code.

Clearpath Simulator comes to Gazebo Harmonic | ROS 2, C++, Python, Gazebo

Heavily modified fork of Clearpath Simulator that makes the simulator compatible with ROS 2 Jazzy and Gazebo Harmonic. Also introduces a number of new features. Code

Python-MPPI | Python, Numpy, Numba

• Developed a Numba-accelerated Model Predictive Path Integral controller for a 2D Differential Drive Robot Code

Mobile Robot Path Planning Using Genetic Algorithm | MATLAB

Wrote a N-dimensional Genetic Algorithm from scratch that can solve complex 2D path planning problem for robot navigation.Code

Anonymous Multi-User Tracking in Indoor Environment Using Computer Vision and Bluetooth | Python, PyTorch

- Master's thesis project where I developed a novel privacy-aware Multimodal Indoor Positioning System (MIPS) utilizing overhead RGB images and Bluetooth RSSI data. Manuscript available here.
- Project lead to a collaborative patent: US20240292188A1.

Deep Learning Projects | Python, PyTorch

- Developed a piano music generator using two Critic-Composer LSTMS. Code
- Implemented AlphaZero's Monte Carlo Tree Search algorithm in an 11x11 Gomoku game. Code

Honors & Awards

Jul 24	Attendance & Travel Grant, IEEE/ASME AIM 2024	Boston, U.S.A
Oct 23	Attendance Grant, ROSCon 2023	New Orleans, U.S.A
Jan 23	Graduate Teaching Assistantship (LSU), Dept. of MIE	Baton Rouge, U.S.A
Aug 21	Graduate Research Assistantship (LSU), NSF:NRI #2024795	Baton Rouge, U.S.A
Aug 21	Graduate Research Assistantship (ULL), NSF:RAPIDS #2027688	Lafayette, U.S.A
Nov 16	Dean's List of Honor, AUST	Dhaka, Bangladesh