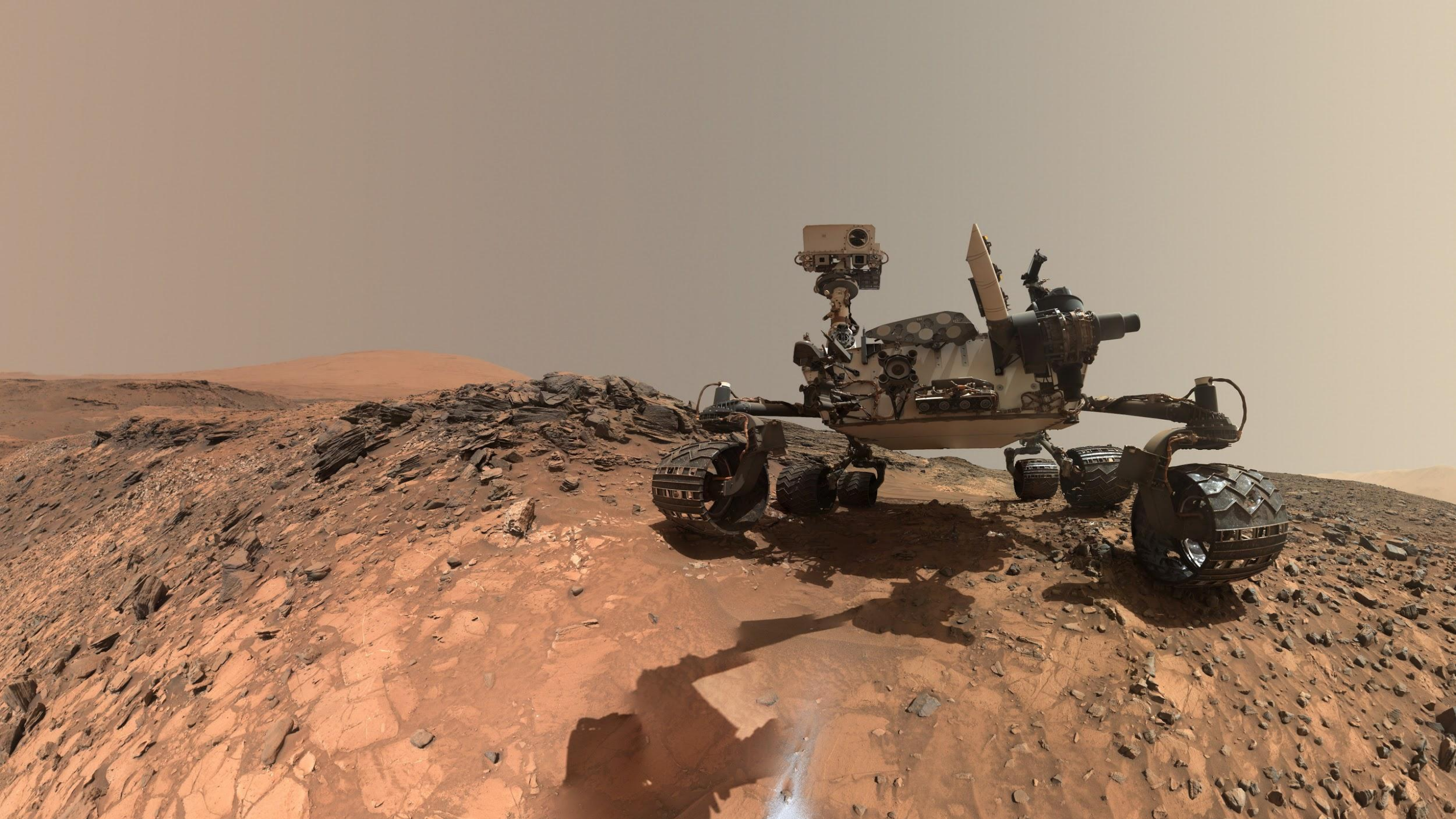


# Robo Challenge

## STARThack St. Gallen





# The Challenge

We sent a rover to Mars to prepare for its colonization. Sadly, one of the supply rockets crashed, leaving the rover without resupplies.

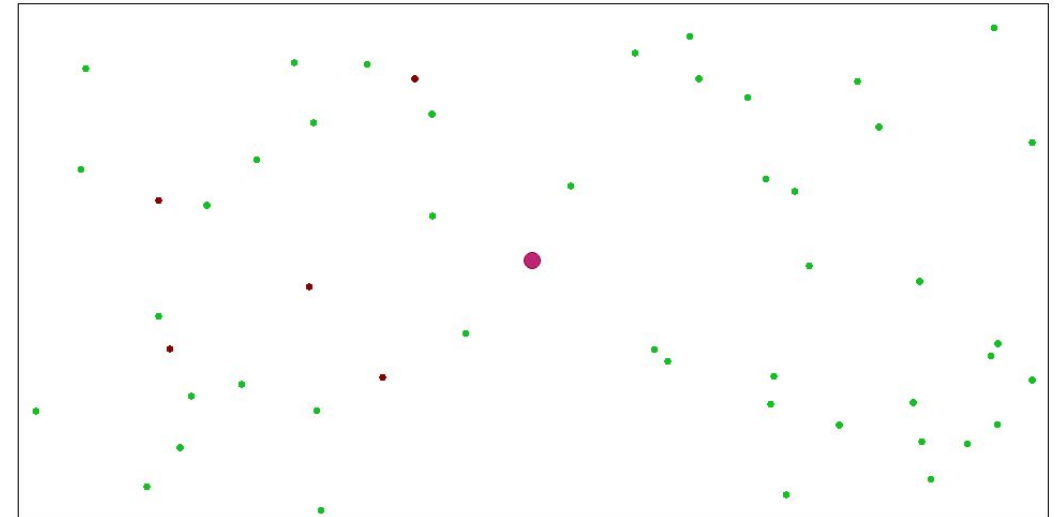
Thankfully, you are the engineer on call during the crash happened and immediately answered the emergency call.



# The Challenge

Collect as much supplies as possible

- You have 2 minutes
- Collect as many supply items as possible
- Beware of the craters!
- No manual intervention is allowed
- Be creative!
  - Clever simplicity or Machine Learning





# The Challenge

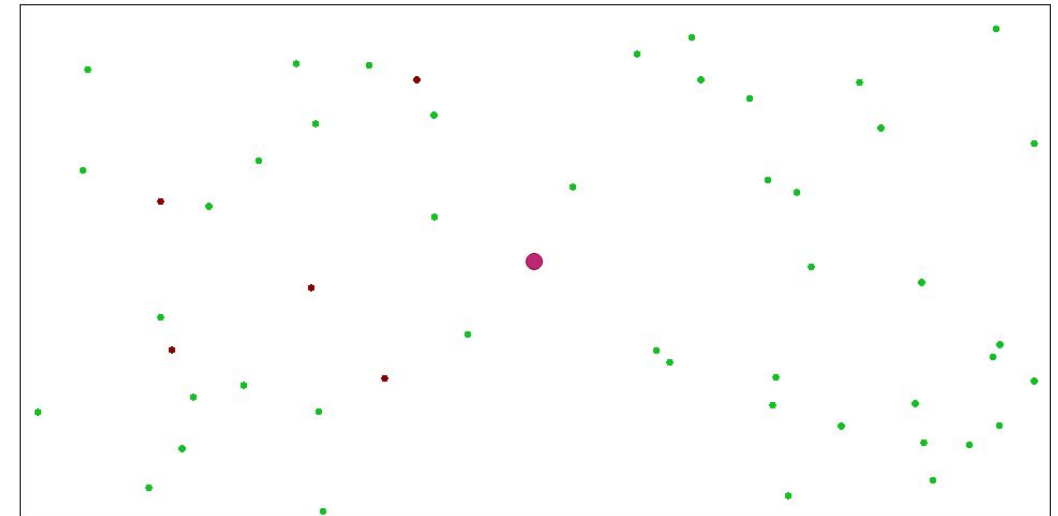
Control the robot

## Control the robot

- You can control the robot by sending him commands
- The robot answers if he completed the commands

## Get infos about environment

- The Robot Positioning System provides you with the position of the robot



# GitHub

You will find more information, links and examples in our GitHub repo.

GitHub Repo

<https://github.com/Zuehlke/robo-challenge>



# Workshop - Technical Overview



# Workshop - Step 1

Checkout our repo



**Checkout the repo**

<https://github.com/Zuehlke/robo-challenge>



# Workshop - Step 2

## Install Docker



We provide a complete simulated Environment using docker images. Therefore you need to install docker on your machine.

### Windows

Install Docker Tools: <https://www.docker.com/products/docker-toolbox>

### Mac

<https://docs.docker.com/docker-for-mac/install/>

### Linux

<https://docs.docker.com/engine/installation/>

# Workshop - Step 3

Install docker-compose



To ease your setup, we provide a docker compose file. So install docker compose:

<https://docs.docker.com/compose/install/#alternative-install-options>

After the successful installation run:

```
$ docker-compose -f docker-compose-simulator.yml up
```

# Workshop - Step 4

Check the environment

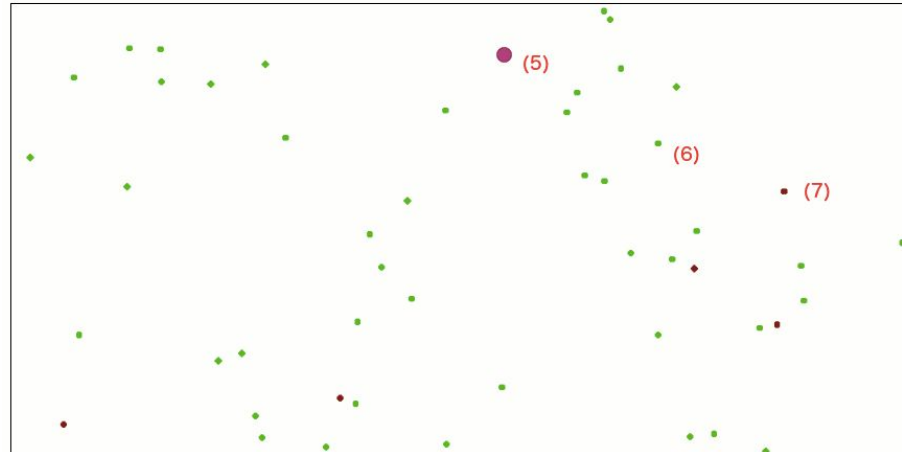
Navigate to: <http://localhost:8080>

You should see something like this:

## RoboChallenge - Autonomous Mars Rover

Map

robot angle: 90, left motor: 700, right motor: 1140, x: 1050, y: 850, r: 15, max x: 1920, max y: 960  
score: 0 from 45



Control

(1)

Zoom	<input type="text" value="0.5"/>
F B	<input type="text" value="1000"/>
L R	<input type="text" value="90"/>
STOP	RESET

Current Game

State: RUNNING (2)  
Player: mru  
Time: 26.49971652030945

Leaderboard

Player	Points	(3)
mru2	5	Prepare Game
mru	4	Prepare Game
test	1	Prepare Game

# Workshop - Step 5

Start developing!

Use one of your examples or your language of choice.

Connect to your local MQTT broker and try to start a game: `tcp://127.0.0.1:1883`

To start a game:

- Send the registration message
- Click on “Prepare game” on UI
- Send the start message

# Workshop

# Have Fun!

We are here for questions.