

1. **[Primer on Strong Convexity]** Let f be a strongly-convex continuously differentiable function with modulus $\mu > 0$. Show that

$$f(y) \leq f(x) + \nabla f(x)^\top (y - x) + \frac{1}{2\mu} \|\nabla f(y) - \nabla f(x)\|^2, \quad \forall x, y$$

[Hint: Consider the function $\phi_x(z) := f(z) - \nabla f(x)^\top z$. Show that $\phi_x(\cdot)$ is strongly convex with same modulus μ , and then apply PL-inequality.]

2. **[AGD vs HB]:** Consider the function $f(x) := \log(x + \sqrt{1 + x^2}) + x^2$, for $x \in \mathbb{R}$. Is the function strongly-convex? Does the function admit Lipschitz-gradient? Implement the accelerated gradient method (AGD) and heavy-ball (HB) methods in Python, and compare their performances for this test functions in terms of iterations required for convergence. Share your implementations.
3. **[Contraction Coefficient]:** Consider the simplest first-order gradient descent scheme

$$x_{k+1} = x_k - \alpha \nabla f(x_k).$$

We consider gradient descent as a fixed-point iteration:

$$x_{k+1} \leftarrow G_\alpha(x_k).$$

The gradient step G_α is a *contraction* if:

$$\|G_\alpha(x) - G_\alpha(y)\|_2 \leq L_G \|x - y\|_2 \quad \text{for some } L_G < 1.$$

The idea is that since the optimum x^* is a fixed-point of G_α , we would want the fixed-point iteration $x_{k+1} \leftarrow G_\alpha(x_k)$ to converge to x^* . Below, we need to show three key results that let us analyze Polyak's Heavy Ball method or the Accelerated Gradient Descent method.

- (a) If the gradient step $G_\alpha(x)$ is a contraction, then the Gradient Descent converges linearly to x^* .
- (b) Let f be twice continuously differentiable, L -smooth and μ -strongly convex, then the contraction coefficient L_G is at most $\max\{|1 - \alpha\mu|, |1 - \alpha L|\}$. [Hint: You may need to use Mean-Value Theorem]
- (c) For steepest descent, we need to choose the step-size in order to minimize the contraction coefficient L_G . Find the optimal step size and show that

$$\|x_{k+1} - x^*\|_2 \leq \left(\frac{\kappa - 1}{\kappa + 1} \right)^{k+1} \|x_0 - x^*\|_2,$$

where $\kappa := \frac{L}{\mu}$ is the condition number of the problem.

4. **[Kernel SVMs]** We briefly discussed kernel-SVMs in class. This particular problem requires some hands-on experience with Python (scikit-learn). You are required to submit a Jupyter notebook that consists of following features:
- (a) Generate $n = 100$ points uniformly inside a unit circle. Assign them labels $y = +1$
 - (b) Randomly generate $n = 100$ points uniformly inside a disc bounded between $x_1^2 + x_2^2 = 4$ and $x_1^2 + x_2^2 = 6$. Assign them labels $y = -1$.
 - (c) Run a simple linear SVM and report the performance (Show decision boundaries).
 - (d) Run a kernel-SVM and report the performance (Show decision boundaries). A 'poly' (polynomial) kernel should suffice. You may try other kernels, such as 'rbf' (radial basis functions).

5. **[Linear Convergence]** Consider the following optimization problem,

$$\arg \min_{x \in \mathbb{R}^d} F(x) = f(x) + g(x),$$

where ∇f is L -Lipschitz but g may be non-smooth. $F(\cdot)$ is said to satisfy the proximal-PL inequality if

$$\mathcal{D}_g(x, L) \geq 2\mu(F(x) - F^*),$$

where $\mathcal{D}_g(x, \alpha) := -2\alpha \min_y \{ \langle \nabla f(x), y - x \rangle + \alpha \|y - x\|^2 + g(y) - g(x) \}$. Show that F converges linearly, and find the corresponding contraction coefficient.

6. **[Necessity and Sufficiency of KKT Conditions]** Show that for a convex optimization problem with strong duality, x^* and (λ^*, ν^*) are primal and dual optimal solutions, respectively *if and only if* $x^*, (\lambda^*, \nu^*)$ satisfy KKT conditions.
7. **[KKT conditions in action]** Solve the following optimization problem:

$$\begin{aligned} & \text{maximize} && xy \\ & \text{subject to,} && x + y^2 \leq 2 \\ & && x, y \geq 0. \end{aligned}$$

8. **[Condition for Convexity]** Let $f : \mathbb{R}^n \rightarrow \mathbb{R}$ be a differentiable function such that $\text{dom } f$ is convex and for all $x, y \in \text{dom } f$, $f(y) \geq f(x) + \nabla f(x)^\top (y - x)$. Show that f is a convex function.