## A3SR Math Review

## Properties of Logarithms

#### **Relevant Courses:**

- -Quantitative Methods
- -Generalized Linear Models

#### Notes

#### Definition

Logarithms are defined such that  $log_b(A) = X$  is equivalent to  $b^X = A$ 

#### **Properties**

Using properties of exponents and the definition above, we can derive the following:

- a. The Product Rule:  $log_b(MN) = log_b(M) + log_b(N)$
- b. The Quotient Rule:  $log_b(\frac{M}{N}) = log_b(M) log_b(N)$
- c. The Power Rule:  $log_b(M^p) = plog_b(M)$
- d.  $log_b(b^X) = X$
- e.  $b^{log_b(X)} = X$
- f.  $log_b b = 1$
- g.  $log_b 1 = 0$

#### Example 1: Expanding logarithms

$$log_{e}(\frac{2x^{3}}{y})$$
=  $log_{e}(2x^{3}) - log_{e}(y)$   
=  $log_{e}(2) + log_{e}(x^{3}) - log_{e}(y)$   
=  $log_{e}(2) + 3log_{e}(x) - log_{e}(y)$ 

#### Example 2: Condensing logarithms

$$2log_3(x) + log_3(5) - log_3(2)$$

$$= log_3(x^2) + log_3(5) - log_3(2)$$

$$= log_3(5x^2) - log_3(2)$$

$$= log_3(\frac{5x^2}{2})$$

#### **Practice Problems**

- 1. Solve the following:
  - a.  $log_e(e^x)$
  - b.  $log_{10}(100)$
  - c.  $log_{10}(\frac{1}{10})$ d.  $log_{10}(0)$
- 2. Expand the following:

  - a.  $log_{10}(\frac{5y^3}{x})$ b.  $log_2(\frac{4y^2}{3x})$ c.  $log_e(2x^2y^3)$
- 3. Condense the following:
  - a.  $4log_3(x) 2log_3(y)$
  - b.  $log_2(x) + 5log_2(y) log_2(5)$
  - c.  $log_{10}(5) + log_{10}(2)$

#### Answers

- 1. Solve:
  - a. *x*
  - b. 2

  - d. There is no solution because there is no power of 10 that would equal 0
- 2. Expand:
  - a.  $log_{10}(5) + 3log_{10}(y) log_{10}(x)$
  - b.  $2 + 2log_2(y) log_2(3) log_2(x)$
  - c.  $log_e(2) + 2log_e(x) + 3log_e(y)$
- 3. Condense
  - a.  $log_3(\frac{x^4}{y^2})$
  - b.  $log_2(\frac{xy^5}{5})$  c. 1

### Matrix Algebra

#### **Relevant Courses:**

-Quantitative Methods

#### Notes

Note that these notes are a summary of relevant information from https://www.math.psu.edu/bressan/PSPDF/M441-linalgebra\_review.pdf

#### **Definitions**

An  $m \times n$  matrix A has m rows, n columns, and can be written as:

$$A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \dots & \dots & \dots & \dots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix}$$

The transpose of an  $m \times n$  matrix, A is the  $n \times m$  matrix (denoted  $A^T$ ) such that every element  $a_{ij}$  in matrix A is moved to row j and column i. For example, if:

$$A = \begin{bmatrix} 1 & 2 & 5 \\ 3 & 4 & 7 \end{bmatrix}$$

then,

$$A^T = \begin{bmatrix} 1 & 3 \\ 2 & 4 \\ 5 & 7 \end{bmatrix}$$

The  $n \times n$  identity matrix  $I_n$  is a matrix with 1s on the diagonal and 0s everywhere else:

$$I_n = \begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ & & \ddots & & \dots \\ 0 & 0 & \dots & 1 \end{bmatrix}$$

An  $n \times n$  matrix is called "diagonal" if all elements not on the diagonal are zeros. For example:

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 5 \end{bmatrix}$$

An  $n \times n$  matrix is called "upper triangular" if all elements below the diagonal are zeros. For example:

$$\begin{bmatrix}
1 & 0 & 1 \\
0 & 4 & 2 \\
0 & 0 & 4
\end{bmatrix}$$

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An  $n \times n$  matrix is called "lower triangular" if all elements above the diagonal are zeros. For example:

$$\begin{bmatrix} 1 & 0 & 0 \\ 1 & 4 & 0 \\ 0 & 4 & 4 \end{bmatrix}$$

Suppose that an we have  $2 n \times n$  matrices, A and B, such that  $AB = I_n$  (note: this also implies  $BA = I_n$ ). Then we say that B is the inverse of A (and vice versa) and we can write,  $B = A^{-1}$ . A matrix A has an inverse if and only if its determinant is not equal to zero. Note that the determinant of a  $2 \times 2$  matrix can be calculated as follows (it is not important that you are able to calculate the determinant of a higher dimensional matrix by hand):

$$det(\begin{bmatrix} a & b \\ c & d \end{bmatrix}) = ad - bc$$

#### Operations with matrices

- a. Adding matrices (A + B = C): If we add  $2 m \times n$  matrices, A and B, we get another  $m \times n$  matrix C such that  $c_{ij} = a_{ij} + b_{ij}$
- b. Subtracting matrices (A B = C): If we subtract the  $m \times n$  matrix B from the  $m \times n$  matrix A, we get another  $m \times n$  matrix C such that  $c_{ij} = a_{ij} b_{ij}$
- c. Multiplying a matrix by a scalar (cA = B): If we multiply the  $m \times n$  matrix A by a scalar, c, then we get another  $m \times n$  matrix B such that  $b_{ij} = c * a_{ij}$
- d. Matrix multiplication (AB = C): Note that it is only possible to compute AB if the number of columns in matrix A equals the number of rows in matrix B. If this is the case, then when we multiply an  $m \times n$  matrix A by an  $n \times k$  matrix B, we get an  $m \times k$  matrix, C, such that  $c_{ik} = a_{i1}b_{1k} + a_{i2}b_{2k} + \cdots + a_{in}b_{nk}$

#### **Example 1: Matrix Multiplication**

$$\begin{bmatrix} 3 & 4 \\ 2 & 5 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 7 & 2 & 1 \\ 3 & 5 & 2 \end{bmatrix} = \begin{bmatrix} (3*7+4*3) & (3*2+4*5) & (3*1+4*2) \\ (2*7+5*3) & (2*2+5*5) & (2*1+5*2) \\ (1*7+2*3) & (1*2+2*5) & (1*1+2*2) \end{bmatrix} = \begin{bmatrix} 33 & 26 & 11 \\ 29 & 29 & 12 \\ 13 & 12 & 5 \end{bmatrix}$$

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#### Properties of matrix operations

a. 
$$A + B = B + A$$

b. 
$$(A+B) + C = A + (B+C)$$

c. 
$$(AB)C = A(BC)$$

d. 
$$(A+B)C = AC + BC$$

e. If A is an  $m \times n$  matrix, then  $I_m A = A$  and  $AI_n = A$ 

Note that, in general  $AB \neq BA$ 

#### Writing a system of equations using matrix notation

Note that, if we have a system of equations:

$$y_1 = a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n$$
  
 $y_2 = a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n$ 

. . .

$$y_m = a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n$$

We can re-write these equations much more simply as:

Y = AX where Y is a  $1 \times m$  matrix, A is an  $m \times n$  matrix, and X is a  $1 \times n$  matrix:

$$\begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \dots & \dots & \dots & \dots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$

### **Practice Problems**

- 1. Solve the following:
  - a. Prob1
  - b. Prob2
  - c. Prob3
  - d. Prob4
- 2. Show that A and B are inverses:
  - a. Prob1
  - b. Prob2
  - c. Prob3

#### Answers

- 1. Solve:
  - a. Ans1
  - b. Ans2
  - c. Ans3
  - d. Ans4
- 2. Show that A and B are inverses:
  - a. Ans1
  - b. Ans2
  - c. Ans3

## Derivatives

- -Probability -Quantitative Methods

# Integrals

- -Probability -Quantitative Methods

# **Summary Statistics**

- -Probability -Quantitative Methods -Statistical Computing

# P-Values and T-Tests

- -Quantitative Methods -Statistical Computing
- -Causal Inference

## Correlation and Covariance

- -Quantitative Methods -Probability

# Ordinary Least Squares Regression

## Relevant Courses:

-Quantitative Methods

# Probability Density/Mass Functions

- -Quantitative Methods -Probability
- -Causal Inference

# Expectation

## Relevant Courses:

-Probability