Joint# JointOffset JointAngle LinkLength TwistAngle init

1 2.974 0.385 90

2 0 2.92 180

3 0 0 -90 -90

4 1.4 0 90

5 0 0.9

6 0 -90 -90

40.5+4+6+38.94+4+x=93.44 joint4

X+Y=90 Joint5

Joint# JointOffset(b) JointAngle LinkLength（a） TwistAngle(alph) init

1 0.6 0.3 90 0

2 0 0.6 180 0

3 0 0 -90 0

4 0.6 0 90 0

5 0 0 -90 0

6 0.2 0 0 0