# 程序验证方法 研究生课程 Chapter 12 (12.1-12.6) Fairness

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## Outline

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- 12.2 Transformational Semantics
- 12.3 Well-Founded Structures
- 12.4 Random Assignment
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## 12.1 The Concept of Fairness

Fairness models the idea of "true parallelism", where every component of a parallel program progresses with unknown, but positive speed.

In other words, every component eventually executes its next enabled atomic instruction.

```
PU1 \equiv signal := \mathbf{false};
\mathbf{do} \neg signal \rightarrow \text{"print next line"}
\Box \neg signal \rightarrow signal := \mathbf{true}
\mathbf{od}.
```

Assuming that the signal := true is eventually executed, the program PU1 terminates.

To enforce termination one has to assume fairness.

#### Two variants of fairness

- Weak fairness: requires that every guarded command of a do loop, which is from some moment on continuously enabled, is activated infinitely often.
- Strong fairness: requires that every guarded command that is enabled infinitely often is also activated infinitely often.

```
PU2 \equiv signal := \mathbf{false}; \ full-page := \mathbf{false}; \ \ell := 0; \mathbf{do} \ \neg signal \rightarrow \text{ "print next line"}; \ell := (\ell + 1) \ \mathbf{mod} \ 30; full-page := \ell = 0 \square \ \neg signal \land full-page \rightarrow signal := \mathbf{true} \mathbf{od}.
```

In this book, we understand by fairness the notion of strong fairness.

### **Selections and Runs**

- A selection (of n components) is a pair (E, i)
- $\triangleright E \subseteq \{1, ..., n\}$  of enabled components
- $\succ$ an activated component  $i \in E$
- A run (of n components) is a finite or infinite sequence of selections.

$$(E_0, i_0)...(E_j, i_j).$$

## Example

```
PU1 \equiv signal := \mathbf{false};
\mathbf{do} \neg signal \rightarrow \text{"print next line"}
\Box \neg signal \rightarrow signal := \mathbf{true}
\mathbf{od}.
```

A computation of PU1 that exclusively activates the first component yields the run:

$$(\{1,2\},1)(\{1,2\},1)...(\{1,2\},1)...$$

Since the index 2 is never activated, the run and hence the computation is not fair.

Every fair computation of PU1 is finite, yielding a run of the form:

$$(\{1,2\},1)...(\{1,2\},1)(\{1,2\},2).$$

### Fair Nondeterminism Semantics

```
\mathcal{M}_{fair}[S](\sigma) = \{\tau \mid \langle S, \sigma \rangle \to^* \langle E, \tau \rangle\} 
\cup \{\bot \mid S \text{ can diverge from } \sigma \text{ in a fair computation}\} 
\cup \{\text{fail } \mid S \text{ can fail from } \sigma\}.
```

```
\mathcal{M}_{tot}[S](\sigma) = \mathcal{M}[S](\sigma)
\cup \{ \bot \mid S \text{ can diverge from } \sigma \}
\cup \{ \mathbf{fail} \mid S \text{ can fail from } \sigma \}.
```

## Example

```
PU3 \equiv signal := \mathbf{false}; \ count := 0;

\mathbf{do} \neg signal \rightarrow \text{"print next line"};

count := count + 1

\Box \neg signal \rightarrow signal := \mathbf{true}

\mathbf{od}.
```

**count**: counts the number of lines printed. For  $i \geq 0$  ,  $\sigma_i(count) = i$ 

we obtain  $\mathcal{M}_{tot} \llbracket PU3 \rrbracket (\sigma) = \{ \sigma_i \mid i \geq 0 \} \cup \{ \bot \}$  but  $\mathcal{M}_{fair} \llbracket PU3 \rrbracket (\sigma) = \{ \sigma_i \mid i \geq 0 \}.$ 

Under the assumption of fairness, PU3 always terminates but still there are infinitely many final states possible:  $\sigma_i$  with  $i \geq 0$ . This differs from the bounded nondeterminism (Bounded Nondeterminism Lemma 10.1, P353), it is called unbounded nondeterminism.

#### 12.2 Transformational Semantics

• We are looking for a transformation  $T_{fair}$  which transforms each nondeterministic program S into another nondeterministic program  $T_{fair}(S)$  satisfying the semantic equation

$$\mathcal{M}_{fair}[S] = \mathcal{M}_{tot}[T_{fair}(S)]. \tag{12.1}$$

 $T_{fair}$  provides us with information on how to implement fairness.

```
Conclusion of (12.1) \models_{fair} \{p\} \ S \ \{q\} \ \text{iff} \ \models_{tot} \{p\} \ T_{fair}(S) \ \{q\}, (12.2)
```

A program S is correct in the sense of fair total correctness if and only if its transformed version  $T_{fair}(S)$  is correct in the sense of usual total correctness.

#### 12.3 Well-Founded Structures

Definition 12.1. Let (P, <) be an *irreflexive partial order*; that is, let P be a set and < an irreflexive transitive relation on P. We say that < is *well-founded on a subset* W  $\subseteq$  P if there is no infinite descending chain

$$\dots < w_2 < w_1 < w_0$$

of elements  $w_i \in W$ . The pair (W, <) is then called a well-founded structure. If w < w' for some  $w, w' \in W$  we say that w is less than w' or w' is greater than w.

Of course, the natural numbers form a well-founded structure (N,<) under the usual relation <. But also the extension (N  $\cup$  { $\omega$ },<), with  $\omega$  denoting an "unbounded value" satisfying

for all  $n \in N$ , is well-founded.

## 12.4 Random Assignment

- $M_{tot}$  yields bounded nondeterminism (Lemma 10.1),  $M_{fair}$  yields unbounded nondeterminism (Example 12.2).
- The transformed program  $T_{fair}(S)$  uses an additional language construct : the random assignment.

It assigns an arbitrary nonnegative integer to the integer variable x.

The random assignment is an explicit form of unbounded nondeterminism.

The random assignments will enable us to reason about programs under fairness assumptions.

## Random Assignment: Semantics

(xxvi) 
$$\langle x :=?, \sigma \rangle \rightarrow \langle E, \sigma[x := d] \rangle$$
  
for every natural number  $d \ge 0$ .

The random assignment terminates for any initial state, but there are infinitely many possibilities for the final state.

$$\triangleright$$
N[[x :=?]](σ) = {σ[x := d] | d ≥ 0}  
for a proper state σ and N =M or N =M<sub>tot</sub>.

## Random Assignment: Verification

**AXIOM 37: RANDOM ASSIGNMENT** 

$$\{\forall x \ge 0 : p\} \ x := ? \{p\}$$

#### PROOF SYSTEM PNR:

This system consists of the proof system PN augmented with axiom 37.

## Random Assignment---Verification

#### **RULE 38: REPETITIVE COMMAND III**

$$\{p \land B_i\} \ S_i \ \{p\}, i \in \{1, ..., n\}, 
 \{p \land B_i \land t = \alpha\} \ S_i \ \{t < \alpha\}, i \in \{1, ..., n\}, 
 \underbrace{p \to t \in W} 
 \{p\} \ \mathbf{do} \ \Box_{i=1}^n \ B_i \to S_i \ \mathbf{od} \ \{p \land \bigwedge_{i=1}^n \ \neg B_i\}$$

Guarantees the termination of the whole repetitive command

#### where

- (i) t is an expression which takes values in an irreflexive partial order (P,<) that is well-founded on the subset  $W \subseteq P$ ,
- (ii)  $\alpha$  is a simple variable ranging over P that does not occur in p, t,  $B_i$  or  $S_i$  for  $i \in \{1, ..., n\}$ .

#### **PROOF SYSTEM TNR:**

This system is obtained from the proof system *TN* by adding axiom 37 and replacing rule 33 by rule 38.

#### **RULE 33: REPETITIVE COMMAND II**

where t is an integer expression and z is an integer variable not occurring in p, t,  $B_i$  or  $S_i$  for  $i \in \{1, ..., n\}$ .

#### 12.5 Scheduler

- Schedulers explain how to implement fairness.
- Develop a transformation  $T_{fair}$
- The development of a scheduler that enforces fairness in runs,
- The embedding of the schedulers into nondeterministic programs.

### The Scheduler FAIR

For n components it is defined as follows:

• The scheduler state is given by n integer variables  $z_1, \ldots, z_n$ 

Represent priorities assigned to the n components.

A component i has higher priority than a component j if  $z_i < z_j$ 

This state is initialized nondeterministically by the random assignments

INIT 
$$\equiv z_1 := ?; ...; z_n := ?$$

## The Scheduler FAIR

• this state is initialized nondeterministically by the random assignments

INIT 
$$\equiv z_1 := ?; ...; z_n := ?;$$

- the scheduling relation  $sch(\sigma, (E, i), \sigma')$  holds iff  $\sigma, E, i, \sigma'$  are as follows:
  - (i)  $\sigma$  is given by the current values of  $z_1, / \ldots, z_n$
  - (ii) E and i satisfy the condition

$$SCH_i \equiv z_i = \min \{z_k \mid k \in E\}, -$$

(iii)  $\sigma'$  is obtained from  $\sigma$  by executing

If during a run FAIR is presented with a set E of enabled components, it selects a component  $i \in E$  that has maximal priority

 $\begin{aligned} \text{UPDATE}_i &\equiv z_i :=?; \longrightarrow \text{Reset the priority of the selected component } i \\ \text{for all } j &\in \{1, \dots, n\} - \{i\} \text{ do} \\ &\text{if } j &\in \text{E then } z_j := z_j - 1 \text{ fi} \\ &\text{od,} \end{aligned} \qquad \begin{aligned} &\text{Guarantees that to but not selected of the selected component } i \end{aligned}$ 

Guarantees that the priorities of all enabled but not selected components j get increased.

## 12.6 Transformation

Given a nondeterministic program

$$S \equiv S_0$$
; do  $\square_{i=1}^n B_i \to S_i$  od,

 $\mathit{SCH}_i \equiv z_i = \min \ \{z_k \mid k \in E\}$ 

• The transformed program  $T_{fair}(S)$  is obtained by embedding the scheduler *FAIR* into S:

The guard of the ith component can be passed

The guard of the ith component can be passed only if it is enabled and selected by FAIR

$$T_{fair}(S) \equiv S_0; \; INIT;$$
 do  $\square_{i=1}^n \mid B_i \wedge SCH_i \mid \rightarrow UPDATE_i; \; S_i \; od,$ 

where we interpret E as the set of indices  $k \in \{1, ..., n\}$  for which  $B_k$  holds:  $E = \{k \mid 1 \le k \le n \land B_k\}$ .

### Transformation

• Expanding the abbreviations INIT,  $SCH_i$ ,  $UPDATE_i$  from FAIR yields:

```
T_{fair}(S) \equiv S_0; \ z_1 :=?; \ldots; \ z_n :=?;
\operatorname{do} \square_{i=1}^n B_i \wedge z_i = \min \left\{ z_k \mid 1 \leq k \leq n \wedge B_k \right\} \rightarrow z_i :=?;
\operatorname{for all} \ j \in \{1, \ldots, n\} - \{i\} \ \operatorname{do} 
\operatorname{if} \ B_j \ \operatorname{then} \ z_j := z_j - 1 \ \operatorname{fi} 
\operatorname{od};
S_i
\operatorname{od}.
```

• In case of identical guards  $B_1 \equiv \cdots \equiv B_n$ , the transformation simplifies to

```
T_{fair}(S) \equiv S_0; \ z_1 :=?; \ldots; \ z_n :=?; do \square_{i=1}^n \ B_i \wedge z_i = min \ \{z_1, \ldots, z_n\} \rightarrow z_i :=?; for all j \in \{1, \ldots, n\} - \{i\} do z_j := z_j - 1 od; S_i od.
```

## Example

Example 12.4. The printer-user program

```
PU1 \equiv signal := \mathbf{false};
\mathbf{do} \neg signal \rightarrow \text{"print next line"}
\Box \neg signal \rightarrow signal := \mathbf{true}
\mathbf{od}
```

discussed in Section 12.1 is transformed into

With the help of the scheduling variables  $z_1$  and  $z_2$ , the transformed program  $T_{fair}(PU1)$  generates exactly the fair computations of the original program PU1

$$T_{fair}(PU1) \equiv signal := \mathbf{false}; \ z_1 :=?; \ z_2 :=?;$$
  $\mathbf{do} \neg signal \land z_1 \leq z_2 \rightarrow z_1 :=?; \ z_2 := z_2 - 1;$  "print next line"  $\square \neg signal \land z_2 \leq z_1 \rightarrow z_2 :=?; \ z_1 := z_1 - 1;$   $signal := \mathbf{true}$   $\mathbf{od}.$ 

## **Transformation**

Theorem 12.3. (Embedding) For every one-level nondeterministic program S and every proper state  $\sigma$ 

$$\mathcal{M}_{fair}[S](\sigma) = \mathcal{M}_{tot}[T_{fair}(S)](\sigma) \mod Z,$$

where Z is the set of scheduling variables  $z_i$  used in  $T_{fair}$ .

Due to the presence of the scheduling variables  $z_1, ..., z_n$  in  $T_{fair}(S)$ , the best we can prove is that the semantics  $\mathcal{M}_{fair}[S]$  and  $\mathcal{M}_{tot}[T_{fair}(S)]$  agree modulo  $z_1, ..., z_n$ ; that is, the final states agree on all variables except  $z_1, ..., z_n$ . To express this we use the **mod** notation introduced in Section 2.3.

We say that two sets of states X and Y agree modulo Z, and write

$$X = Y \mod Z$$

if

$$\{\sigma[Var-Z] \mid \sigma \in X\} = \{\sigma[Var-Z] \mid \sigma \in Y\}.$$

# Thank You