Cause Clue Clauses:

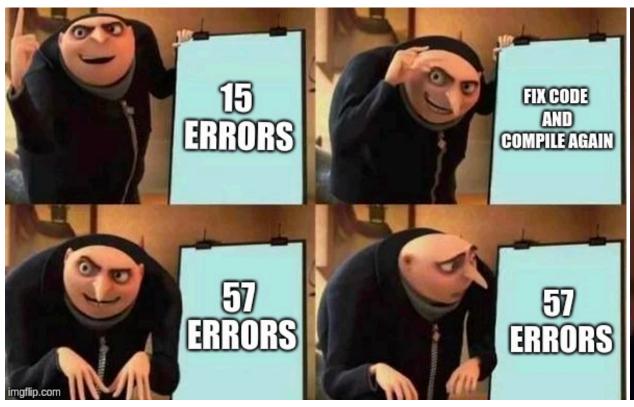
Error Localization using Maximum Satisfiability

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2020.10.14 Wed @ IS893-2020-fall



Debugging is hard









Debugging is HARD!!!

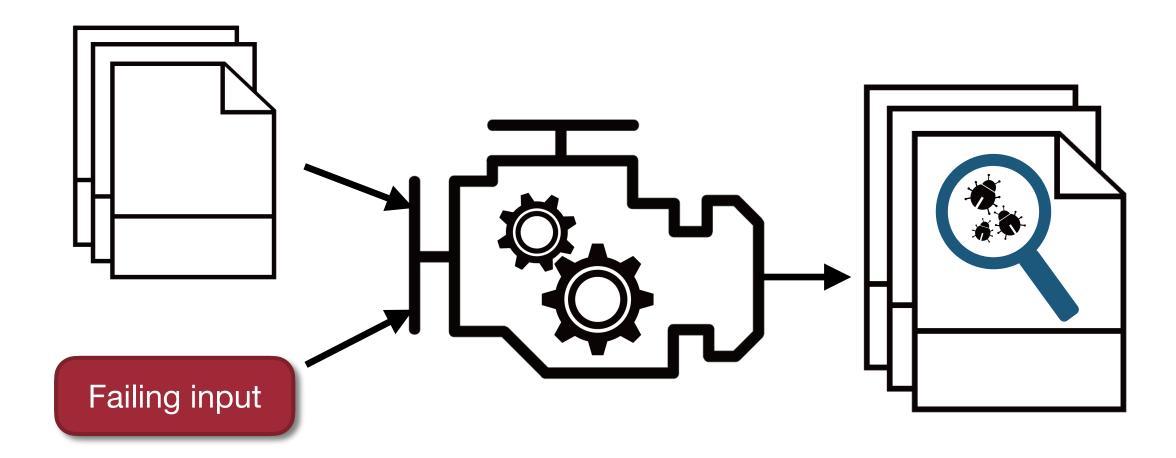
```
    int* a = 0;  Root cause
    . ~~~
    var = &a;
```



Null dereference at line 5.



What CCC is about





Some background knowledges

Max SAT

partial Max SAT

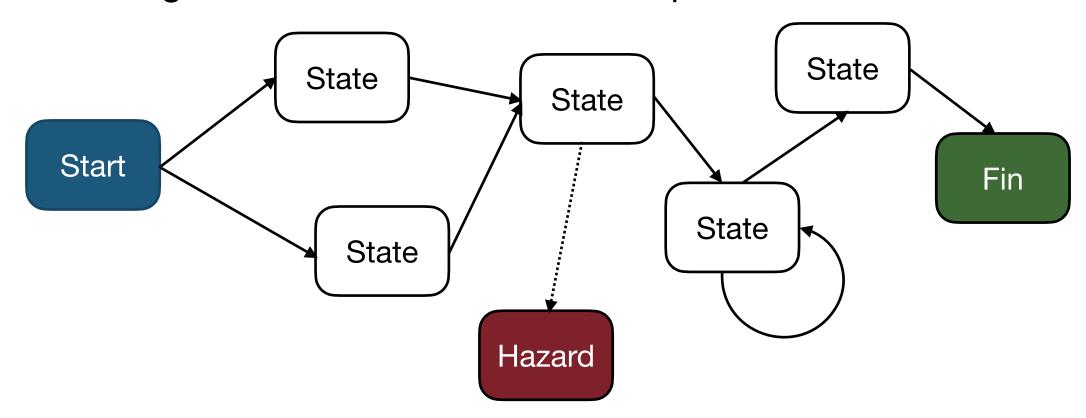
 $A \wedge B \wedge C \wedge D \wedge E$

 $A \wedge B \wedge C \wedge D \wedge E$



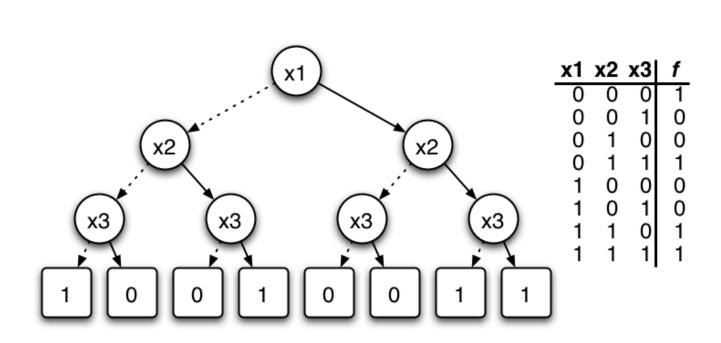
Model checking

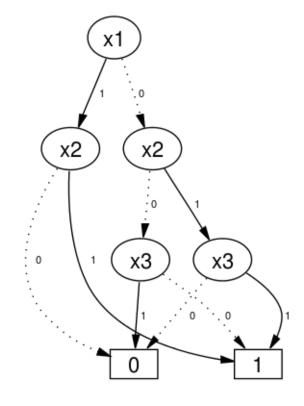
Checking finite-state model for some spec.





Binary decision diagram

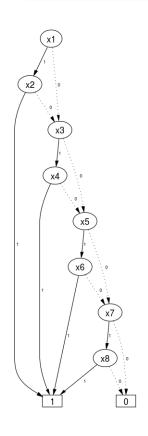


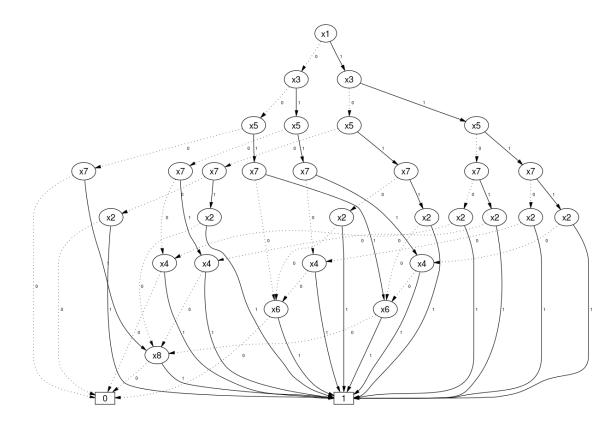




BDD (cont')

$$f(X_1, ..., X_8) = X_1X_2 + X_3X_4 + X_5X_6 + X_7X_8$$





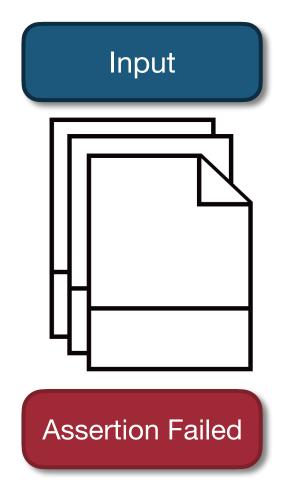


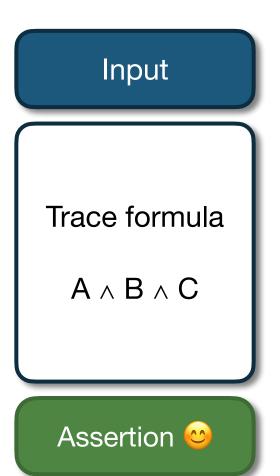
Bounded model checking

- Checks k-depth paths with SAT solver
- Unroll loops
- Gives up some extent of completeness
- Special thanks to SAT researchers!
- Each one has its own pros and cons (BDD)



Informal overview









Example

```
1. int array[3];
 2.
 3. int test_me(int index){
        if (index \neq 1) // Potential Bug 2
 5.
            index = 2;
      else
 7.
            index = index + 2; // Potential Bug 1
 8.
       i = index;
 9.
        return array[i]; // assert(i≥0 && i<3)
10.
11. \
```



Making trace formula

$$\begin{aligned} \mathsf{TF} &\equiv \mathsf{guard}_1 = (\mathsf{index}_1 \neq 1) \land \\ \mathsf{index}_2 &= 2 \land \mathsf{index}_3 = \mathsf{index}_1 + 2 \land \\ \mathsf{i} &= \mathsf{guard}_1? \mathsf{index}_2 : \mathsf{index}_3 \end{aligned}$$

$$\Phi \equiv \underbrace{\mathtt{index}_1 = 1}_{test\ input} \land \underbrace{\mathsf{TF}}_{trace\ formula} \land \underbrace{\mathtt{i} < 3}_{assertion}$$



Making trace formula

$$\begin{aligned} \mathsf{TF} &\equiv \mathsf{guard}_1 = (\mathsf{index}_1 \neq 1) \land \\ \mathsf{index}_2 &= 2 \land \mathsf{index}_3 = \mathsf{index}_1 + 2 \land \\ \mathsf{i} &= \mathsf{guard}_1? \mathsf{index}_2 : \mathsf{index}_3 \end{aligned}$$

$$\Phi \equiv \underbrace{\mathsf{index}_1 = 1}_{test\ input} \land \underbrace{\mathsf{TF}}_{trace\ formula} \land \underbrace{\mathsf{i} < 3}_{assertion}$$



Even accepts feedback!

$$\begin{aligned} \mathsf{TF} &\equiv \mathsf{guard}_1 = (\mathsf{index}_1 \neq 1) \land \\ \mathsf{index}_2 &= 2 \land \mathsf{index}_3 = \mathsf{index}_1 + 2 \land \\ \mathsf{i} &= \mathsf{guard}_1? \mathsf{index}_2 : \mathsf{index}_3 \end{aligned}$$

$$\Phi \equiv \underbrace{\mathsf{index}_1 = 1}_{test\ input} \land \underbrace{\mathsf{TF}}_{trace\ formula} \land \underbrace{\mathsf{i} < 3}_{assertion}$$



Loop unrolling

```
while(cond){
          stmt;
 4
     if(cond){
          stmt;
 6
          if(cond){
              stmt;
              if(cond){
 9
10
11
12
13
```

But limited steps!



One more step!

```
    int array[5];
    for (int i=0; i≤5; i++) { array[i]; }
```



Running BugAssist

| | Program | LOC# | Proc# | Reduc | assign# | | var# | | clause# | | Fault# | time |
|---|--------------|------|-------|-------|---------|-------|---------|--------|----------|---------|--------|-------|
| | | | | | Before | After | Before | After | Before | After | | |
| 1 | totinfo | 565 | 7 | S | 734 | 21 | 0.797m | 400 | 1.822m | 1225 | 2 | 0.19s |
| 2 | print_tokens | 726 | 18 | C | 65698 | 239 | 5.507m | 7439 | 53.483m | 22634 | 13 | 25s |
| 3 | schedule | 564 | 21 | DS | 5914 | 391 | 5.173m | 0.053m | 15.379m | 0.142m | 13 | 28s |
| 4 | schedule | 564 | 21 | DS | 41942 | 5412 | 78.982m | 4.517m | 239.385m | 13.788m | 25 | 11h |
| 5 | totinfo | 565 | 7 | CS | 865 | 454 | 0.862m | 0.734m | 4.156m | 3.728m | 3 | 225s |
| 6 | schedule2 | 374 | 16 | S | 398 | 275 | 0.021m | 0.015m | 0.062m | 0.048m | 9 | 20s |



Discussions

- Performance is much better than traditional way
- Limited scalability
- Can't detect omission fault
- Can be applied in different granularity



Questions?

