

Department of Inter Disciplinary Studies, Faculty of Engineering,

University of Jaffna, Sri Lanka MC 2020 : Linear Algebra

Tutorial-04 October 2023

- 1. Given that $T: \begin{pmatrix} x \\ y \\ z \end{pmatrix} \to \begin{pmatrix} x-y \\ y+z \\ 2x-3z \end{pmatrix}$ and $U: \begin{pmatrix} x \\ y \\ z \end{pmatrix} \to \begin{pmatrix} 2x-3y-z \\ 2y+3z \\ 5z \end{pmatrix}$, find matrices representing
 - (a) T (b) U (c) TU
- 2. The transformation $T: \mathbb{R}^3 \to \mathbb{R}^3$ is represented by the matrix T.
 - The vector $\begin{pmatrix} 2 \\ 0 \\ 0 \end{pmatrix}$ is transformed by T to the vector $\begin{pmatrix} 6 \\ 2 \\ 4 \end{pmatrix}$.

 The vector $\begin{pmatrix} 3 \\ 0 \\ -1 \end{pmatrix}$ is transformed by T to the vector $\begin{pmatrix} -2 \\ 3 \\ 5 \end{pmatrix}$.

 The vector $\begin{pmatrix} 0 \\ 1 \\ -1 \end{pmatrix}$ is transformed by T to the vector $\begin{pmatrix} 2 \\ -1 \\ -2 \end{pmatrix}$.

 Find T.
- 3. The transformation $T: \mathbb{R}^3 \to \mathbb{R}^3$ is represented by the matrix T where $T = \begin{pmatrix} 0 & -1 & 2 \\ 2 & 5 & -4 \\ 3 & 2 & 1 \end{pmatrix}$. The line l_1 is transformed by the line l_2 . The line l_1 has the vector equation $r = \begin{pmatrix} 2 \\ 4 \\ 1 \end{pmatrix} + t \begin{pmatrix} -1 \\ -2 \\ 3 \end{pmatrix}$, where t is a real parameter. Find a vector equation of l_2 .
- 4. The point A and B have position vector $\begin{pmatrix} 2\\1\\0 \end{pmatrix}$ and $\begin{pmatrix} -2\\3\\4 \end{pmatrix}$ respectively. The points A and B are transformed by the linear transformation T to the point A' and B' respectively. The transformation T is represented by the matrix T, where $T = \begin{pmatrix} 1 & -3 & 4\\2 & 3 & -2\\0 & 2 & 5 \end{pmatrix}$.
 - (a) Find the position vectors of A' and B'.
 - (b) Hence find a vector equation of the line A'B'.
- 5. The transformation $T: \mathbb{R}^3 \to \mathbb{R}^3$ is represented by the matrix T where $T = \begin{pmatrix} 3 & -2 & -2 \\ -2 & -8 & 4 \\ -2 & 4 & 0 \end{pmatrix}$. The plane π_1 is transformed by T to the plane π_2 . The plane π_1 has Cartesian equation x 2y + z = 0. Find a Cartesian equation of π_2 .