

# Gate.in.21

EE22BTECH11008 - Annapureddy Siva Meenakshi\*

Q:A system has transfer function

$$\frac{Y(s)}{X(s)} = \frac{s - \pi}{s + \pi}$$

let  $u(t)$  be the unit step function. The input  $x(t)$  that results in a steady-state output  $y(t) = \sin(\pi t)$  is \_\_\_\_.

**Solution:**

Variable	Description	Value
$x(t)$	input function	none
$y(t)$	output function	$\sin(\pi t)$
$H(s)$	Transfer-function	$\frac{s-\pi}{s+\pi}$

TABLE 0: input parameters

$$H(s) = \frac{s - \pi}{s + \pi} \quad (1)$$

$$\frac{1}{H(s)} = \frac{s + \pi}{s - \pi} \quad (2)$$

Converting transfer function to frequency response, we get

$$\frac{1}{H(j\omega)} = \frac{j\omega + \pi}{j\omega - \pi} \quad (3)$$

Here ,  $\omega = \pi$

$$\frac{1}{H(j\pi)} = \frac{j + 1}{j - 1} = -j = e^{-j\frac{\pi}{2}} \quad (4)$$

$$\left| \frac{1}{H(j\pi)} \right| = 1 \quad (5)$$

$$\angle \frac{1}{H(j\pi)} = -90^\circ \quad (6)$$

$$y(t) = \sin(\pi t) \quad (7)$$

$$|X| \sin(\omega t + \phi) \xrightarrow{\frac{1}{H(j\omega)}} |X| \left| \frac{1}{H(j\omega)} \right| \sin\left(\omega t + \phi + \angle \frac{1}{H(j\omega)}\right) \quad (8)$$

$$\sin(\pi t) \xrightarrow{\frac{1}{H(j\omega)}} \left| \frac{1}{H(j\omega)} \right| \sin\left(\pi t + \angle \frac{1}{H(j\omega)}\right) \quad (9)$$

Therefore by (7) and (9) , we get

$$x(t) = \sin\left(\pi t - \frac{\pi}{2}\right) \quad (10)$$

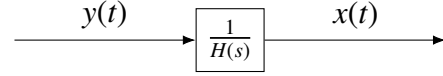


Fig. 0: Block diagram of inverse System

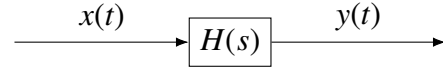


Fig. 0: Block diagram of the System

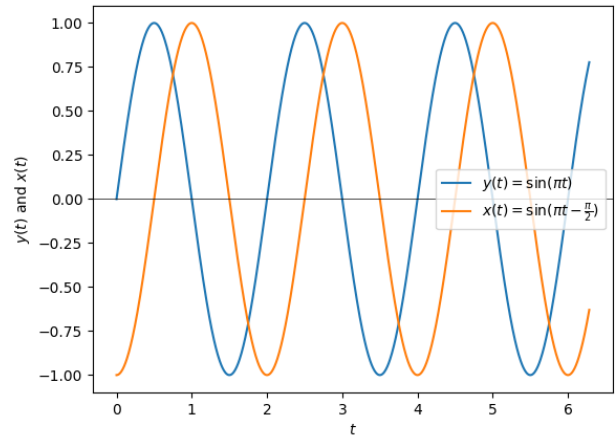


Fig. 0: Plot of  $x(t)$  and  $y(t)$  taken from Python

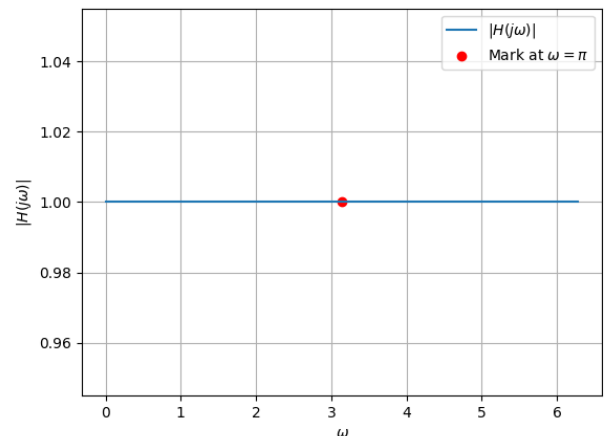


Fig. 0: Plot of  $|H(j\omega)|$  taken from Python