Roll no: 14

Batch: S11

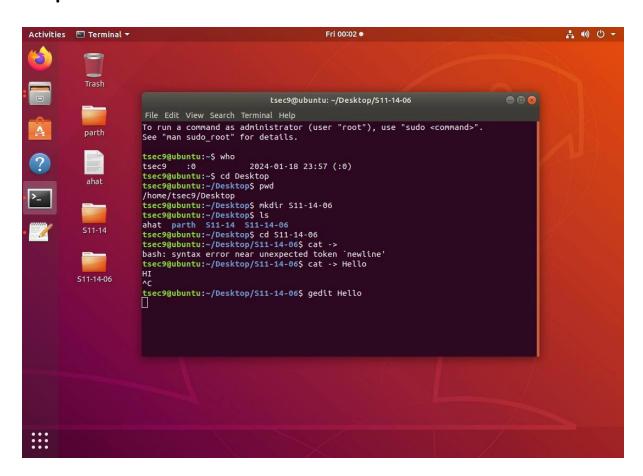
EXPERIMENT NO: 01

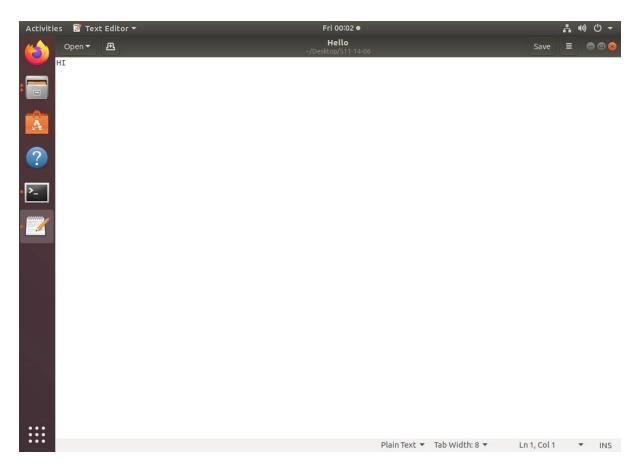
Aim: Explore usage of basic linux commands and system calls for files, directory and process management.

Theory:

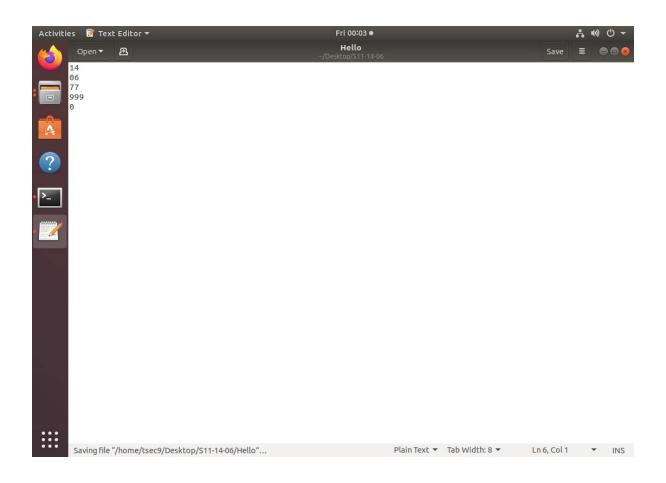
- 1. who: it is used to find out the current user who is logged into the system.
- 2. pwd : present working directory, lets you know the current directory you are in.
- 3. cal: show the calendar of the complete month.
- 4. date: It shows you the current date, along with the time, along with the day, along with the year.
- 5. mkdir: to create a new directory under any directory
- 6. chdir/cd: to change the current working directory
- 7. cat: to create the file and display the contents of the file
- 8. chmod: to change the mode of the file. There are three modes read(r), write(w) and execute(e)
- 9. Is: to list all directories and subdirectories
- a. Is-I: to show the long listing information about the directory
- b. Is-lh: human readable format.
- c. ls-ld: shows the details of the directory content.
- d. Is-d*: to show the sub directories in a directory
- e. Is-a: to show hidden files
- f. Is-lhs: show files in the descending order in which you have used your files.
- 10. sort-r file name.txt : sorts the list in reverse order
- 11. sort-n file name.txt: its sorts the numerical list in ascending order
- 12. sort nr file name.txt: its sorts the numerical list in reverse order
- 13. sort u file name.txt : to remove the duplicates
- 14. sort m file name.txt : Sorts the months in ascending order
- 15. awk: it is used for the user that defines text patterns that are to be searched for each line of the file.

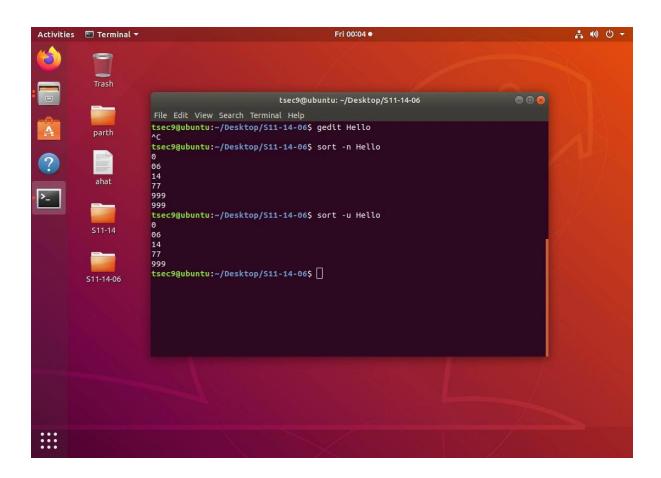
Syntax, awk '{print}' file name.txt awk '/faculty/{print}' file name.txt: awk '{print}NR, \$0}' file name.txt : NR - specifies the number of lines.



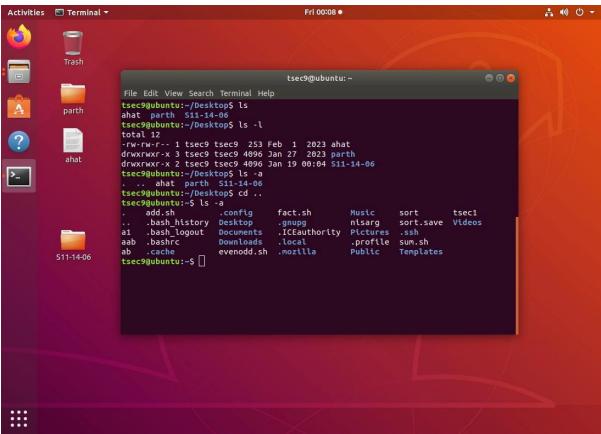












Roll no: 14

Batch: S11

Experiment 2: Linux shell script

Aim:

Write shell scripts to do the following:

- a. Display OS version, release number, kernel version
- b. Display top 10 processes in descending order
- c. Display processes with highest memory usage.
- d. Display current logged in user and log name.

Display current shell, home directory, operating system type, current path setting, current working directory.

Theory:

A

```
i) uname - r{username}
```

To show the OS version, release no. OS release version

ii) uname - v

Shows Kernel version (last when launched)

iii) uname - a

Shows all the details including OS used, PC and other details.

$$us - c + u - r \rightarrow us - a$$

B]

i) ps-aux (i) sort : nk +41 tail

Sorts 10 processes in descending order. It shows logged in users, modes of memory & storage.

OR

ii) ps-aux | tail

Same as above

OR

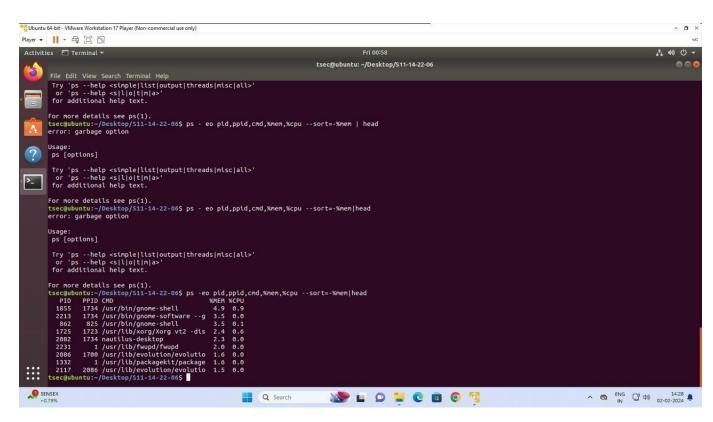
iii) ps-aux | sort -nl+4 | tail - n15 (shows top 15 processes) same with 15

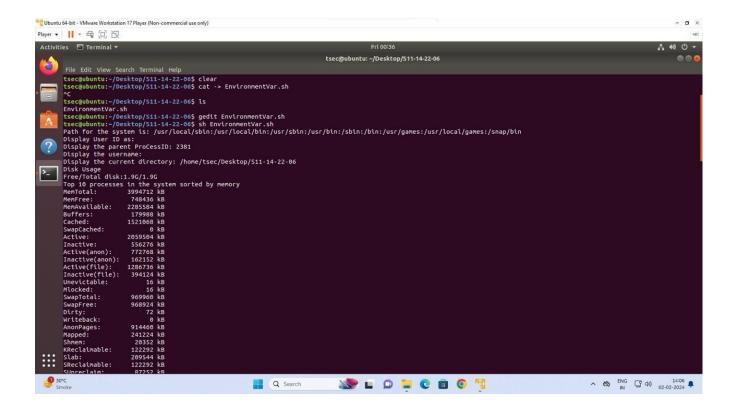
C

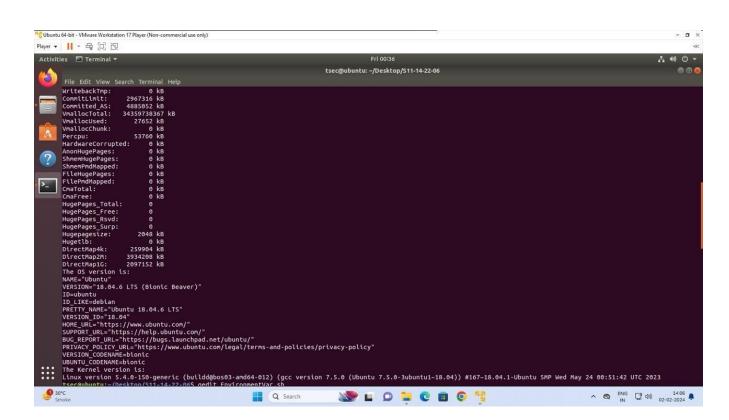
i) sudo apt install htop shows date of processes with highest memory ii) ps - eo pid, ppid, cmd, % mem, % cpu –sort =-% mem | head same as above same as above

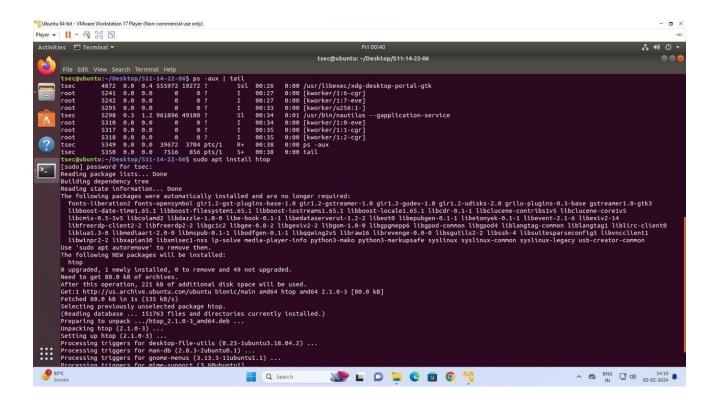
D]

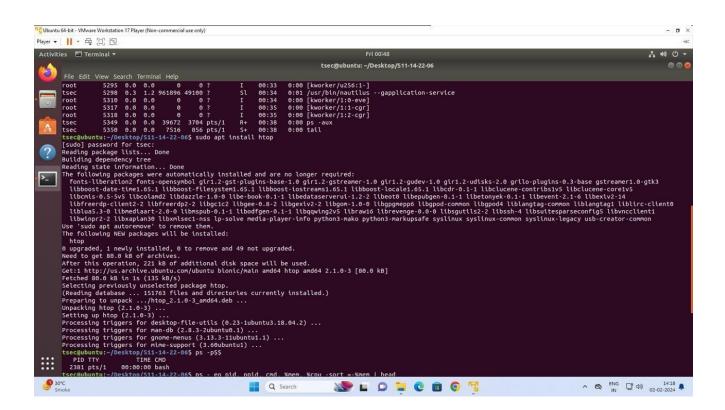
- i) ps-p\$\$
 Shows process ID and current shell
- ii) echo display home directoryecho \$ homeTo display home directory

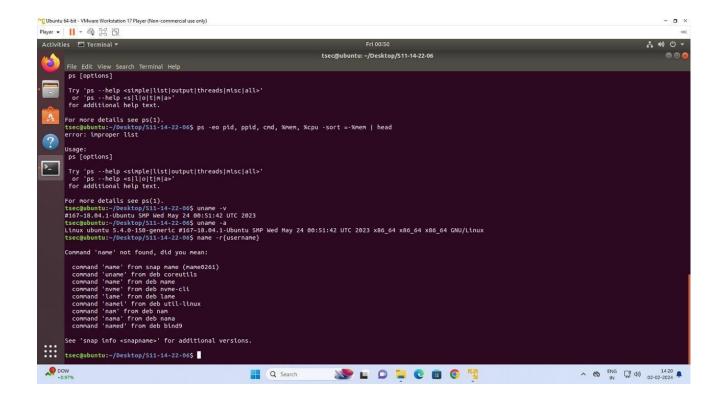


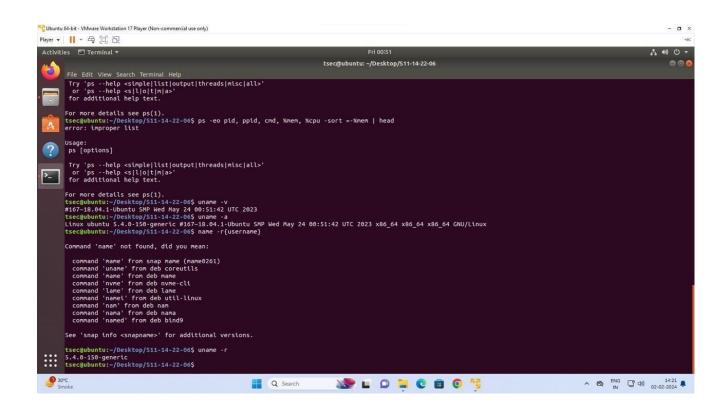


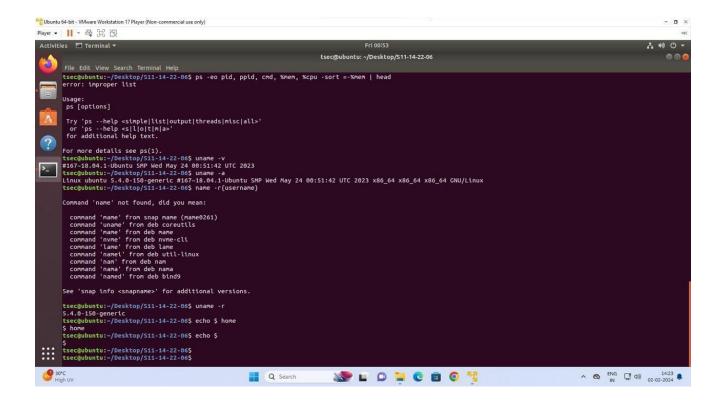


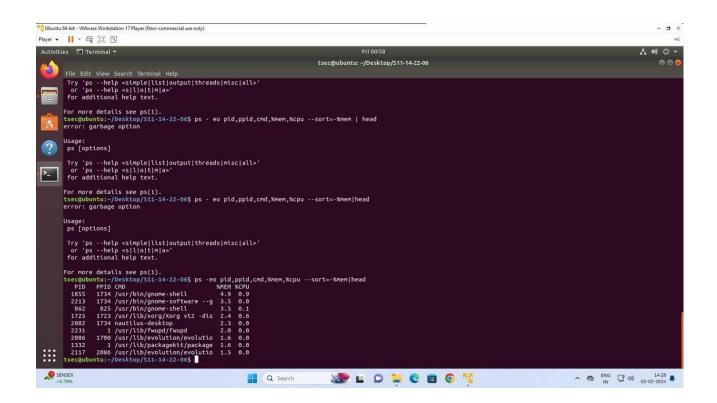












Conclusion: Thus, we have successfully studied and implemented shell scripting languages

Roll No: 14

Batch: S11

Experiment No 3: Linux- API

Aim: Implement Basic Commands of Linux like Is, cp, mv using Kernel APIs.

Theory:

1) cp \rightarrow cp - r \rightarrow copies the file cp - backups \rightarrow It copies the backups of the destination file in the source

folder.

cp - i \rightarrow It asks for confirmation of the user whether yes or no and gives warning to the user before overriding the destination file.

cp-ie.txt b.txt

 $cp - f \rightarrow Unable to open destination file for writing because the user has$

not allowed the writing operation .By writing the command, the destination file is deleted and the content is copied from source to destination.

 $\mbox{cp-v} \rightarrow \mbox{it}$ is used for which command is running in backup.

cp - p \rightarrow It preserves the attributes of files such as last date modification

time, time of last access owners and the file permissions.

Syntax : cp-p source file destination file.

 $cp - I \rightarrow To create a hand link file$

2) mv \rightarrow (move or rename). mv.i \rightarrow Ask the user for confirmation before moving the file.

- $\mbox{mv-f} \rightarrow \mbox{It}$ provides the protection and overrides destination file forcefully and deletes the source file.
- mv f a.txt b.txt mv n \rightarrow It takes/prevents the existing file from being overridden.
- mv n a.txt b.txt mv b \rightarrow To take the backup of an existing file

```
### A PRINCE | Seeth | Demonstrate | Prince |
### A PRINCE | Seeth | Demonstrate |
##
```

```
tsec10@bbntv:-5 sudo apt install htop
[sudo] password for tsec10:

Sorry, try again.
[sudo] password for tsec10:

sorry try again.
[sudo] password for tsec10:

sudo password for tsec1
```

```
сору.с
          Æ
                                                                    Save ≡
                                                                                a
 Open ▼
#include<stdlib.h>
int main()
FILE *fptr1, *fptr2;
char filename [100], c;
printf("Enter the filename to open for reading \n");
scanf("%s", filename); // Open one file for reading
fptr1 = fopen(filename, "r");
if(fptr1 ==NULL)
{printf("Cannot open file %s in", filename); exit(0);}
printf("Enter the filename to open for writing \n");
scanf("%s", filename);
// Open another file for writing
fptr2= fopen(filename, "w"); if (fptr2 == NULL)
{printf("Cannot open file %s\n", filename); exit(0);} // Read contents from file
c = fgetc(fptr1); while (c != EOF) {fputc(c, fptr2);
c = fgetc(fptr1);}printf("\nContents copied to %s", filename);
fclose(fptr1); fclose(fptr2); return 0;
```

```
tsec@ubuntu:~$ gcc -o copy.out copy.c
tsec@ubuntu:~$ ./copy.out
Enter the filename to open for reading
example.txt
Enter the filename to open for writing
example1.txt
Contents copied to example1.txt
```

```
tsec@ubuntu:~$ cat example1.txt
Hello!!!
```

Conclusion: Thus we have successfully studied and implemented various basic commands of Linux like Is, cp and mv using kernel APIs

Roll no: 14

Batch: S11

Experiment 4: Linux - Process

Aim:

a. To create a child process in Linux using the fork system call. From the child process obtain the process ID of both child and parent by using getpid and getpid system call.

b. Explore wait and waitpid before termination of process.

Theory:

1] System call

When a program is in user mode and requires access to Ram or hardware resources, it must ask the kernel to provide access to that resource. This is done via something called a system call. When a program makes a system call, the mode is switched from user mode to Kernel mode. This is called context switch. The kernel provides the resources which the program requested. System calls are made by user level programmes in following cases:

Creating, opening, closing and delete files in the system
Creating and managing new processes
Creating a connection in the network, sending and receiving packets
Requesting access to a hardware device like a mouse or a printer

2] Fork ()

The fork system call is used to create processes. When a process makes a fork().call, an exact copy of the process is created.

There are now two processes, one being the parent process and the other being the child process. The process which called fork()call is the parent process and the process which is created newly is called child process. The child process will be exactly the same as the parent. The process state of the parent i.e the address space, variables, open files etc is copied into the child process. The change of values in the parent process doesn't affect the child and vice versa.

Code:

```
#include <iostream>
#include<sys/wait.h>
#include<unistd.h>
using namespace std;
int wait func()
 int pid_1 = fork();
if(pid 1==0)
 { cout<<"process pid_1 succesfully
created"<<"\n"; cout<<"process pid_1 id: "<<
getpid() << "\n"; exit(0); 
 waitpid(pid 1, NULL,0);
 cout << "pid_1 process terminated."<<"\n";</pre>
return 0;
}
int main()
 int pid=fork();
if(pid==0)
 cout<<"child process created"<<"\n";
cout<<"current child is: "<<getppid()<<"\n";
cout<<"current parents is: "<<getpid()<<"\n";</pre>
exit(0); } wait(NULL); cout<<"child process
is terminated."<<"\n";
 wait_func();
 return 0;
}
```

```
## File Edit View Search Terminal Help

## tsec@ubuntu: ~/Desktop/S11$ g++ S11.cpp

## tsec@ubuntu: ~/Desktop/S11$ g++ S11.cpp

## tsec@ubuntu: ~/Desktop/S11$ ./a.out

## child process created

## current child is: 5141

## current parents is: 5142

## child process is terminated.

## process pid_1 succesfully created

## process pid_1 id: 5143

## pid_1 process terminated.

## tsec@ubuntu: ~/Desktop/S11$

## Tsec@ubuntu: ~/Desktop/S11$
```

Conclusion:

Thus, we have successfully studied and implemented how to create child process in Linux using fork() system calls.

Roll no: 14

Batch: S-11

Aim: a) To study and implement non preemptive scheduling algorithm FCFS.

b) To study and implement preemptive scheduling algorithm SRTF.

Theory:

Non preemptive algorithm:

FCFS, SJF 1] FCFS: First Come

First Serve

It is a non-preemptive scheduling algorithm and the criteria for this is the arrival time of the

process CPU is allotted to the process that requires it first. Jobs arriving later are placed at the end of the queue.

FCFS (Example)

Process	Duration	Oder	Arrival Time
P1	24	1	0
P2	3	2	0
Р3	4	3	0

Gantt Chart:

P1(24) P2(3) P3(4)

P1 waiting time: 0

The Average waiting time:

P2 waiting time: 24 P3 waiting time: 27

(0+24+27)/3 = 17

2] SJF: shortest job first

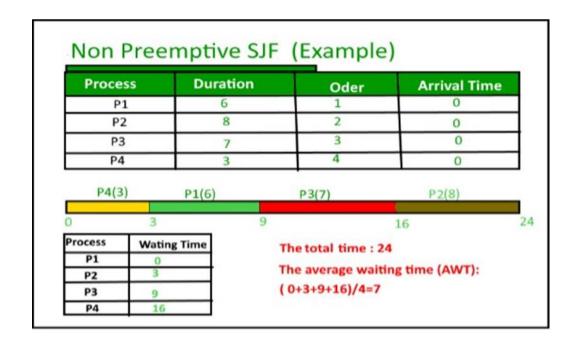
This is a non preemptive scheduling algorithm, which associates with each process the length of

the processes next CPU

first. Criteria: Burst Time.

This algorithm assigns processes according to BT if BT of two processes is the same we use

FCFS scheduling criteria.

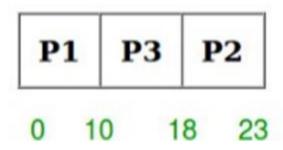


3] Priority Scheduling

This is a non preemptive scheduling algorithm. Each process here has a priority that is either

assigned already or externally done.

Process	Burst Time	Priority
P1	10	2
P2	5	0
Р3	8	1



Preemptive Scheduling Algorithm: SRTF/STRN

Shortest Remaining Time First / Shortest Remaining Time Next scheduling.

It is a preemptive SJF Algorithm. The choice arrives when a new process arrives as the ready

queue. While a previous process is still executing. The next CPU burst if the newly arrived

process may be shorter than what is left of the currently executing process. A preemptive SJF

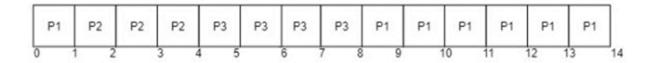
will preempt the current executing process and not allow the currently running process to finish

its CPU burst.

Round Robin is also one preemptive algorithm.

Process	Burst Time	Arrival Time
P1	7	0
P2	3	1
P3	4	3

The Gantt Chart for SRTF will be:



Implementation with code FCFS:

```
#include <stdio.h>
#include <stdib.h>

int main() {
    int n;
    printf("Enter no. of processes : ");
    scanf("%d", &n);

int *at = (int *)malloc(n * sizeof(int));
    int *bt = (int *)malloc(n * sizeof(int));
    int *ct = (int *)malloc(n * sizeof(int));
    int *wt = (int *)malloc(n * sizeof(int));
    int *tat = (int *)malloc(n * sizeof(int));

    printf("Enter arrival and burst times of the processes:\n");
    for (int i = 0; i < n; i++) {
        scanf("%d%d", &at[i], &bt[i]);
    }
}</pre>
```

```
int total_tat = 0;
  int t = at[0];
  for (int i = 0; i < n; i++) {
     t += bt[i];
     ct[i] = t;
     tat[i] = ct[i] - at[i];
     total_tat += tat[i];
     wt[i] = ct[i] - bt[i];
  }
  printf(" AT BT CT TAT WT\n");
  for (int i = 0; i < n; i++) {
     printf("%6d%6d%6d%7d%6d\n", at[i], bt[i], ct[i], tat[i], wt[i]);
  }
  printf("Average TAT = %.2f\n", (float)total_tat / n);
  free(at);
  free(bt);
  free(ct);
  free(wt);
  free(tat);
  return 0;
}
```

```
Enter no. of processes : 3
Enter arrival and burst times of the processes:
0 5
1 3
2 8
AT BT CT TAT WT
0 5 5 5 0
1 3 8 7 5
2 8 16 14 8
Average TAT = 8.67
```

Implementation with code SRTF:

```
#include <stdio.h>
#include <stdlib.h>
#include #include
```

```
while (complete != n) {
     for (int j = 0; j < n; j++) {
        if ((proc[j].art <= t) && (rt[j] < minm) && rt[j] > 0) {
           minm = rt[i];
           shortest = j;
           check = 1;
        }
     }
     if (check == 0) {
        t++;
        continue;
     }
     rt[shortest]--;
     minm = rt[shortest];
     if (minm == 0)
        minm = INT_MAX;
     if (rt[shortest] == 0) {
        complete++;
        check = 0;
        finish time = t + 1;
        wt[shortest] = finish_time - proc[shortest].bt - proc[shortest].art;
        if (wt[shortest] < 0)
          wt[shortest] = 0;
     }
     t++;
  }
}
void findTurnAroundTime(struct Process proc[], int n, int wt[], int tat[]) {
  for (int i = 0; i < n; i++)
     tat[i] = proc[i].bt + wt[i];
}
void findavgTime(struct Process proc[], int n) {
```

```
int *wt = (int *)malloc(n * sizeof(int));
  int *tat = (int *)malloc(n * sizeof(int));
  int total_wt = 0, total_tat = 0;
  findWaitingTime(proc, n, wt);
  findTurnAroundTime(proc. n. wt. tat):
  printf(" P\t\tBT\t\tWT\t\tTAT\t\t\n");
  for (int i = 0; i < n; i++) {
     total_wt += wt[i];
     total_tat += tat[i];
     printf(" %d\t\t%d\t\t%d\t\t%d\n", proc[i].pid, proc[i].bt, wt[i], tat[i]);
  }
  printf("\nAverage waiting time = %.2f\n", (float)total_wt / (float)n);
  printf("Average turn around time = %.2f\n", (float)total_tat / (float)n);
  free(wt);
  free(tat);
}
int main() {
  int n:
  printf("Enter the number of processes: ");
  scanf("%d", &n);
  struct Process *proc = (struct Process *)malloc(n * sizeof(struct
Process));
  printf("Enter arrival time and burst time for each process:\n");
  for (int i = 0; i < n; i++) {
     printf("Process %d: ", i + 1);
     scanf("%d %d", &proc[i].art, &proc[i].bt);
     proc[i].pid = i + 1;
  }
  findavgTime(proc, n);
```

```
free(proc);
return 0;
}
```

```
Enter the number of processes: 5
Enter arrival time and burst time for each process:

Process 1: 2 6
Process 2: 5 2
Process 3: 1 8
Process 4: 0 3
Process 5: 4 4

P BT WT TAT

1 6 7 13
2 2 2 0 0 2
3 8 14 22
4 3 0 3
5 4 2 6

Average waiting time = 4.60
Average turn around time = 9.20
```

Conclusion: Thus we have successfully implemented preemptive and non preemptive scheduling algorithms.

Roll no: 14

Batch: S11

EXP 6:

Aim: Write a C program to implement solution of Producer consumer problem through Semaphore.

Theory:

In concurrent programming, concurrency represents a pivotal concept necessary to comprehend fully how such systems operate. Among the various challenges encountered by practitioners working with these systems stands out the producer-consumer problem - one of the most renowned synchronization issues. In this text, our objective consists of analyzing this topic and highlighting its significance for concurrent computing while also examining possible solutions rooted within C.

Introduction

In concurrent systems, multiple threads or processes may access shared resources simultaneously. The producer-consumer problem involves two entities: producers that generate data or tasks, and consumers that process or consume the generated data. The challenge lies in ensuring that producers and consumers synchronize their activities to avoid issues like race conditions or resource conflicts.

Understanding the Producer-Consumer Problem

Problem Statement

One possible definition of the producer-consumer problem involves two main groups: producers of data who store their work in a communal space called the buffer, and processors (consumers) of that content saved in said space. These

people use their expertise around gathered items within this temporary holding scenario to analyze it comprehensively before delivering insightful results.

Synchronization Requirements

Achieving resolution of the producer-consumer conundrum will necessarily involve implementing techniques for synchronized collaboration among all stakeholders involved. The integration of optimal synchronization protocols is fundamental in avoiding scenarios where device buffers are either overloaded by producing units or depleted by consuming ones.

Implementing the Producer-Consumer Problem in C

Shared Buffer

In C, a shared buffer can be implemented using an array or a queue data structure. The buffer should have a fixed size and support operations like adding data (producer) and retrieving data (consumer).

Synchronization Techniques

Several synchronization techniques can be used to solve the producer-consumer problem in C, including –

Mutex and Condition Variables – Mutexes provide mutual exclusion to protect critical sections of code, while condition variables allow threads to wait for specific conditions to be met before proceeding.

Semaphores – Semaphores can be used to control access to the shared buffer by tracking the number of empty and full slots.

Monitors – Monitors provide a higher-level abstraction for synchronization and encapsulate shared data and the operations that can be performed on it.

Solutions to the Producer-Consumer Problem in C

Bounded Buffer Solution

One common solution to the producer-consumer problem is the bounded buffer solution. It involves using a fixed-size buffer with synchronization mechanisms to ensure that producers and consumers cooperate correctly. The capacity for

item production is limited by the buffer size making it crucial to factor in this specification so as not to exceed the available space in the buffer.

Producer and Consumer Threads

In C, the producer and consumer activities can be implemented as separate threads. Each producer thread generates data and adds it to the shared buffer, while each consumer thread retrieves data from the buffer and processes it.

Synchronization mechanisms are used to coordinate the activities of the threads.

Handling Edge Cases

In real-world scenarios, additional considerations may be necessary. For example, if the producers generate data at a faster rate than the consumers can process, buffering mechanisms like blocking or dropping data may be required to prevent data loss or deadlock situations.

Code:

```
#include <stdio.h>
#include <stdib.h>

// Initialize a mutex to 1 and Number of full slots as 0 and Number of empty slots as size of buffer
int mutex = 1;
int full = 0;
int empty = 10, x = 0;

// Function to produce an item and add it to the buffer void producer()

{
    // Decrease mutex value by 1 and Increase the number of full slots
```

```
by 1 and Decrease the number of empty slots by 1
    --mutex;
    ++full;
    --empty;
```

```
// Item produced
    x++;
   printf("\nProducer produces item %d",x);
// Increase mutex value by 1
   ++mutex;
// Function to consume an item and remove it from buffer
void consumer()
    // Decrease mutex value by 1 and Decrease the number of full slots
by 1
   --mutex;
    --full;
// Increase the number of empty slots by 1
   ++empty;
   printf("\nConsumer consumes item %d",x);
   x--;
// Increase mutex value by 1
   ++mutex;
int main()
```

```
int n, i; printf("\n1. Press 1 for Producer \n2. Press 2 for
Consumer \n3.

Press 3 for Exit");

for (i = 1; i > 0; i++) {
```

```
printf("\nEnter your choice:");
       scanf("%d", &n);
       switch (n) {
       case 1:
// If mutex is 1 and empty is non-zero, then it is possible to produce
            if ((mutex == 1)
                && (empty != 0)) {
               producer();
            else { printf("Buffer is
                full!");
            break;
       case 2:
 // If mutex is 1 and full is non-zero, then it is possible to consume
            if ((mutex == 1) && (full != 0)) {
               consumer();
```

Output Clear 1. Press 1 for Producer 2. Press 2 for Consumer 3. Press 3 for Exit Enter your choice:2 Buffer is empty! Enter your choice:1 Producer produces item 1 Enter your choice:1 Producer produces item 2 Enter your choice:1 Producer produces item 3 Enter your choice:1 Producer produces item 4 Enter your choice:1 Producer produces item 5 Enter your choice:1 Producer produces item 6

Enter your choice:1

Producer produces item 7 Enter your choice:1 Producer produces item 8 Enter your choice:1 Producer produces item 9 Enter your choice:1 Producer produces item 10 Enter your choice:1 Buffer is full! Enter your choice:2 Consumer consumes item 10 Enter your choice:2 Consumer consumes item 9 Enter your choice:2 Consumer consumes item 8 Enter your choice:2 Consumer consumes item 7 Enter your choice:2 Consumer consumes item 6 Enter your choice:2 Consumer consumes item 5 Enter your choice:2 Consumer consumes item 4 Enter your choice:2 Consumer consumes item 3 Enter your choice:2 Consumer consumes item 2 Enter your choice:2 Consumer consumes item 1 Enter your choice:2 Buffer is empty! Enter your choice:3

Conclusion: Thus we have successfully implemented Producer Consumer problem using Semaphore.

Name: Meet Brijwani

Roll no: 14

Batch: S11

EXP 7:

Aim: Process Management: Deadlock

- a. Write a program to demonstrate the concept of deadlock avoidance through Banker's Algorithm
- b. Write a program demonstrate the concept of Dining Philospher's Problem

Theory: The banker's algorithm is a resource allocation and deadlock avoidance algorithm that tests for safety by simulating the allocation for the predetermined maximum possible amounts of all resources, then makes an "s-state" check to test for possible activities, before deciding whether allocation should be allowed to continue

Available

It is a 1-d array of size 'm' indicating the number of available resources of each type.

Available[j] = k means there are 'k' instances of resource type Rj Max

It is a 2-d array of size 'n*m' that defines the maximum demand of each process in a system.

Max[i, j] = k means process Pi may request at most 'k' instances of resource type Rj.

Allocation

It is a 2-d array of size 'n*m' that defines the number of resources of each type currently allocated to each process.

Allocation[i, j] = k means process Pi is currently allocated 'k' instances of resource type Rj

Need

It is a 2-d array of size 'n*m' that indicates the remaining resource need of each process.

Need [i, j] = k means process Pi currently needs 'k' instances of resource type Rj Need [i, j] = Max [i, j] - Allocation [i, j]

Allocation specifies the resources currently allocated to process Pi and Needi specifies the additional resources that process Pi may still request to complete its task. Banker's algorithm consists of a Safety algorithm and a Resource request algorithm.

Banker's Algorithm

1. Active:= Running U Blocked;

for k=1...r

New_request[k]:= Requested_resources[requesting_process, k];

2. Simulated allocation:= Allocated resources; for k=1....r

//Compute projected allocation state

Simulated_ allocation [requesting _process, k]:= Simulated_ allocation [requesting _process, k] + New_ request[k]; 3. feasible:= true; for

k=1....r // Check whether projected allocation state is feasible if Total_
resources[k]< Simulated total alloc [k] then feasible:= false;

4. if feasible= true

then // Check whether projected allocation state is a safe allocation state

while set Active contains a process P1 such that

For all k, Total _resources[k] - Simulated_ total_ alloc[k]>= Max_ need [l

```
,k]-Simulated_
allocation[l, k]
```

Delete Pl from Active;

```
for k=1.....r
Simulated_ total_ alloc[k]:= Simulated_ total_ alloc[k]- Simulated_ allocation[l, k]:
```

5. If set Active is empty then // Projected allocation state is a safe

allocation state for k=1....r // Delete the request from pending

requests Requested resources[requesting process, k]:=0; for

k=1....r // Grant the request

Allocated_resources[requesting_process, k]:= Allocated_resources[requesting_process, k] + New_request[k];

Total alloc[k] := Total alloc[k] + New request[k];

Safety Algorithm

The algorithm for finding out whether or not a system is in a safe state can be described as follows:

1) Let Work and Finish be vectors of length 'm' and 'n' respectively.

Initialize: Work = Available

Finish[i] = false; for i=1, 2, 3, 4....n

2) Find an i such that both a)

Finish[i] = false

b) Needi <= Work if no such i

exists goto step (4) 3) Work =

Work + Allocation[i] Finish[i]

= true goto step (2)

4) if Finish [i] = true for all i

then the system is in a safe state Safety Algorithm

Resource-Request Algorithm

Let Requesti be the request array for process Pi. Requesti [j] = k means process Pi wants k

instances of resource type Rj. When a request for resources is made by process Pi, the following actions are taken:

1) If Requesti <= Needi

Goto step (2); otherwise, raise an error condition, since the process has exceeded its maximum claim.

2) If Requesti <= Available

Goto step (3); otherwise, Pi must wait, since the resources are not available. 3) Have the system pretend to have allocated the requested resources to process Pi by modifying the state as follows:

```
Available = Available - Requesti
```

Allocationi = Allocationi + Requesti

Needi = Needi - Requesti

Code: // Banker's Algorithm

```
#include <iostream>
using namespace std;
```

```
int main()
{
int n, m, i, j, k;
n = 5;
m = 3;
```

```
int alloc[5][3] = { { 0, 1, 0 },
{ 2, 0, 0 },
{ 3, 0, 2 },
{ 2, 1, 1 },
{ 0, 0, 2 } };
int max[5][3] = { { 7, 5, 3 },
{ 3, 2, 2 },
{ 9, 0, 2 },
{ 2, 2, 2 },
{ 4, 3, 3 } ;
int avail[3] = { 3, 3, 2 };
int f[n], ans[n], ind = 0;
for (k = 0; k < n; k++) {
f[k] = 0;
```

```
int need[n][m];
for (i = 0; i < n; i++) {</pre>
```

```
for (j = 0; j < m; j++)
need[i][j] = max[i][j] - alloc[i][j];
int y = 0;
for (k = 0; k < 5; k++) {
for (i = 0; i < n; i++) {
if (f[i] == 0) {
int flag = 0;
for (j = 0; j < m; j++) {
if (need[i][j] > avail[j]){
flag = 1;
break;
if (flag == 0) {
ans[ind++] = i;
for (y = 0; y < m; y++)
avail[y] += alloc[i][y];
f[i] = 1;
```

```
int flag = 1;
for(int i = 0;i<n;i++)</pre>
if(f[i]==0)
flag = 0;
cout << "The given sequence is not safe";</pre>
break;
if(flag==1)
cout << "Following is the SAFE Sequence" << endl;</pre>
for (i = 0; i < n - 1; i++)
cout << " P" << ans[i] << " ->";
cout << " P" << ans[n - 1] <<endl;
} return
(0);
```

Output:

```
#include <stdio.h>
```

```
Following is the SAFE Sequence
P1 -> P3 -> P4 -> P0 -> P2

=== Code Execution Successful ===
```

Code:

```
#include <stdlib.h>
#include <pthread.h>
#include <semaphore.h>
#define NUM_PHILOSOPHERS 5

#define NUM_CHOPSTICKS 5

void dine(int n);

pthread_t philosopher[NUM_PHILOSOPHERS];

pthread_mutex_t chopstick[NUM_CHOPSTICKS];

int main()
```

```
int i, status_message;
void *msg;
for (i = 1; i <= NUM_CHOPSTICKS; i++)
status_message = pthread_mutex_init(&chopstick[i], NULL);
if (status message == -1)
printf("\n Mutex initialization failed");
exit(1);
for (i = 1; i <= NUM_PHILOSOPHERS; i++)
```

status_message = pthread_create(&philosopher[i], NULL, (void *)dine,

(int *)i);

```
if (status_message != 0)
printf("\n Thread creation error \n");
exit(1);
for (i = 1; i <= NUM_PHILOSOPHERS; i++)
status_message = pthread_join(philosopher[i], &msg);
if (status message != 0)
printf("\n Thread join failed \n");
exit(1);
for (i = 1; i <= NUM_CHOPSTICKS; i++)
status_message = pthread_mutex_destroy(&chopstick[i]);
if (status_message != 0)
printf("\n Mutex Destroyed \n");
exit(1);
```

```
return 0;
void dine(int n)
printf("\nPhilosopher % d is thinking ", n);
pthread_mutex_lock(&chopstick[n]);
pthread_mutex_lock(&chopstick[(n + 1) % NUM_CHOPSTICKS]);
printf("\nPhilosopher % d is eating ", n);
sleep(3);
pthread_mutex_unlock(&chopstick[n]);
pthread_mutex_unlock(&chopstick[(n + 1) % NUM_CHOPSTICKS]);
```

```
printf("\nPhilosopher % d Finished eating ", n);
}
```

Output:

```
Philosopher 2 is thinking
Philosopher 3 is thinking
Philosopher 5 is thinking
Philosopher 5 is eating
Philosopher 1 is thinking
Philosopher 4 is thinking
Philosopher 4 is eating
Philosopher 5 Finished eating
Philosopher 5 Finished eating
Philosopher 1 is eating
Philosopher 4 Finished eating
Philosopher 5 Finished eating
Philosopher 1 is eating
Philosopher 3 is eating
Philosopher 3 Finished eating
Philosopher 3 Finished eating
```

Conclusion: Thus we have successfully implemented Banker's Algorithm and the concept of Dining Philospher's Problem using C++.

Name: Meet Brijwani

Roll no: 14

Batch: S11

EXP 8:

Aim: Write a program to demonstrate the concept of dynamic partitioning placement algorithms i.e. Best Fit, First Fit, Worst Fit.

Theory:

In the operating system, the following are four common memory management techniques.

Single contiguous allocation: Simplest allocation method used by MS-DOS. All memory (except some reserved for OS) is available to a process.

Partitioned allocation: Memory is divided into different blocks or partitions. Each process is allocated according to the requirement. Paged memory management: Memory is divided into fixed-sized units called page frames, used in a virtual memory environment. Segmented memory management: Memory is divided into different segments (a segment is a logical grouping of the process' data or code). In this management, allocated memory doesn't have to be contiguous.

Most of the operating systems (for example Windows and Linux) use Segmentation with Paging. A process is divided into segments and individual segments have pages.

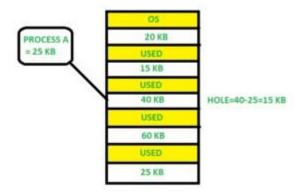
In Partition Allocation, when there is more than one partition freely available to accommodate a process's request, a partition must be selected. To choose a particular partition, a partition allocation method is needed. A partition allocation method is considered better if it avoids internal fragmentation.

When it is time to load a process into the main memory and if there is more than one free block of memory of sufficient size then the OS decides which free block to allocate.

There are different Placement Algorithm:

A. First Fit

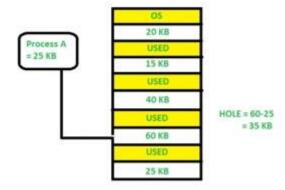
- B. Best Fit
- C. Worst Fit
- D. Next Fit
- 1. First Fit: In the first fit, the partition is allocated which is the first sufficient block from the top of Main Memory. It scans memory from the beginning and chooses the first available block that is large enough. Thus it allocates the first hole that is large enough.



2. Best Fit Allocate the process to the partition which is the first smallest sufficient partition among the free available partition. It searches the entire list of holes to find the smallest hole whose size is greater than or equal to the size of the process.



3. Worst Fit Allocate the process to the partition which is the largest sufficient among the freely available partitions available in the main memory. It is opposite to the best-fit algorithm. It searches the entire list of holes to find the largest hole and allocate it to process.



4. Next Fit: Next fit is similar to the first fit but it will search for the first sufficient partition from the last allocation point.

Is Best-Fit really best?

Although best fit minimises the wastage space, it consumes a lot of processor time for searching the block which is close to the required size. Also, Best-fit may perform poorer than other algorithms in some cases. For example, see the exercise below.

SI.No.	Partition Allocation Method	Advantages	Disadvantages
1.	Fixed Partition	Simple, easy to use, no complex algorithms needed	Memory waste, inefficient use of memory resources
2.	Dynamic Partition	Flexible, more efficient, partitions allocated as required	Requires complex algorithms for memory allocation
3.	Best-fit Allocation	Minimizes memory waste, allocates smallest suitable partition	More computational overhead to find smallest split
4.	Worst-fit Allocation	Ensures larger processes have sufficient memory	May result in substantial memory waste

Comparison of Partition Allocation Methods:Exercise: Consider the requests from processes in given order 300K, 25K, 125K, and 50K. Let there be two blocks of memory available of size 150K followed by a block size 350K.

Which of the following partition allocation schemes can satisfy the above requests?

- A) Best fit but not first fit.
- B) First fit but not best fit.
- C) Both First fit & Best fit.
- D) neither first fit nor best fit.

Solution: Let us try all options.

Best Fit:

5.

300K is allocated from a block of size 350K. 50 is left in the block.

25K is allocated from the remaining 50K block. 25K is left in the block.

125K is allocated from 150 K block. 25K is left in this block also.

50K can't be allocated even if there is 25K + 25K space available.

First Fit:

300K request is allocated from 350K block, 50K is left out.

25K is allocated from the 150K block, 125K is left out.

Then 125K and 50K are allocated to the remaining left out partitions.

So, the first fit can handle requests.

So option B is the correct choice.

Program: a)First Fit:

#include<stdio.h>

```
// Function to allocate memory to
// blocks as per First fit algorithm
void firstFit(int blockSize[], int m, int processSize[], int n)
{ int i, j;
```

```
// Stores block id of the //
block allocated to a process
int allocation[n];
// Initially no block is assigned to any process
for(i = 0; i < n; i++)
  allocation[i] = -1;
}
// pick each process and find suitable blocks
// according to its size ad assign to it
for (i = 0; i < n; i++) //here, n -> number of processes
{
   for (j = 0; j < m; j++) //here, m -> number of blocks
     if (blockSize[i] >= processSize[i])
     {
        // allocating block j to the ith process
        allocation[i] = j;
        // Reduce available memory in this block.
        blockSize[j] -= processSize[i];
        break; //go to the next process in the queue
     }
  }
}
printf("\nProcess No.\tProcess Size\tBlock no.\n");
for (int i = 0; i < n; i++)
{ printf(" %i\t\t\t", i+1);
  printf("%i\t\t\t\t",
  processSize[i]);
  if (allocation[i] != -1)
     printf("%i", allocation[i] + 1);
```

```
else
        printf("Not Allocated");
     printf("\n");
}
// Driver code
int main()
{
  int m; //number of blocks in the memory int n;
   //number of processes in the input queue int
   blockSize[] = {100, 500, 200, 300, 600}; int
   processSize[] = {212, 417, 112, 426}; m =
   sizeof(blockSize) / sizeof(blockSize[0]); n =
   sizeof(processSize) / sizeof(processSize[0]);
   firstFit(blockSize, m, processSize, n);
   return 0;
}
b)Best Fit:
#include<stdio.h>
void main()
int fragment[20],b[20],p[20],i,j,nb,np,temp,lowest=9999;
static int barray[20],parray[20]; printf("\n\t\tMemory
Management Scheme - Best Fit"); printf("\nEnter the
number of blocks:"); scanf("%d",&nb); printf("Enter the
number of processes:"); scanf("%d",&np);
printf("\nEnter the size of the blocks:-\n");
for(i=1;i \le nb;i++)
   {
printf("Block no.%d:",i);
     scanf("%d",&b[i]);
```

```
}
printf("\nEnter the size of the processes :-\n");
for(i=1;i\leq np;i++)
   {
     printf("Process no.%d:",i);
     scanf("%d",&p[i]);
for(i=1;i \le np;i++)
{
for(j=1;j\leq nb;j++)
if(barray[j]!=1)
{ temp=b[j]-p[i];
if(temp >= 0)
if(lowest>temp)
{ parray[i]=j;
lowest=temp;
fragment[i]=lowest;
barray[parray[i]]=1;
lowest=10000;
printf("\nProcess no\tProcess size\tBlock no\tBlock size\tFragment");
for(i=1;i<=np && parray[i]!=0;i++)
printf("\n%d\t\t%d\t\t%d\t\t%d\t\t%d\t\t%d",i,p[i],parray[i],b[parray[i]],fragment[i])
c) Worst Fit:
#include <stdio.h>
void implimentWorstFit(int blockSize[], int blocks, int processSize[], int
processes)
  // This will store the block id of the allocated block to a process
   int allocation[processes]; int occupied[blocks];
```

```
// initially assigning -1 to all allocation
indexes // means nothing is allocated
currently for(int i = 0; i < processes; i++){
allocation[i] = -1;
}
for(int i = 0; i < blocks; i++){
  occupied[i] = 0;
}
// pick each process and find suitable
blocks // according to its size ad assign to it
for (int i=0; i < processes; i++)
int indexPlaced = -1;
for(int i = 0; i < blocks;
j++)
  // if not occupied and block size is large enough
  if(blockSize[i] >= processSize[i] && !occupied[j])
        // place it at the first block fit to accomodate process
        if (indexPlaced == -1)
          indexPlaced = j;
        // if any future block is larger than the current block where //
        process is placed, change the block and thus indexPlaced
        else if (blockSize[indexPlaced] < blockSize[j])
           indexPlaced = j;
     }
  }
  // If we were successfully able to find block for the process
  if (indexPlaced != -1)
  {
```

```
// allocate this block j to process p[i]
        allocation[i] = indexPlaced;
        // make the status of the block as occupied
        occupied[indexPlaced] = 1;
        // Reduce available memory for the block
        blockSize[indexPlaced] -= processSize[i];
     }
   }
   printf("\nProcess No.\tProcess Size\tBlock no.\n");
   for (int i = 0; i < processes; i++)
     printf("%d \t\t\t %d \t\t\t", i+1, processSize[i]);
     if (allocation[i] != -1)
        printf("%d\n",allocation[i] + 1);
     else
        printf("Not Allocated\n");
   }
}
// Driver code
int main()
{
  int blockSize[] = {100, 50, 30, 120, 35}; int processSize[] =
   {40, 10, 30, 60}; int blocks =
   sizeof(blockSize)/sizeof(blockSize[0]); int processes =
   sizeof(processSize)/sizeof(processSize[0]);
   implimentWorstFit(blockSize, blocks, processSize,
   processes);
   return 0;
}
```

Output:

a)First Fit:

```
PS C:\Meet\COLLEGE\LAB ASS\Aoa> cd "c:\Meet\COLLEGE\LAB ASS\Aoa\" ; if ($?) { gcc firstfit.c -o firstfit } ; if ($?) { .\firstfit

Process No. Process Size Block no.

1 212 2
2 417 5
3 112 2
4 426 Not Allocated

PS C:\Meet\COLLEGE\LAB ASS\Aoa>
```

b)Best Fit:

```
PS C:\Meet\COLLEGE\LAB ASS\Aoa> cd "c:\Meet\COLLEGE\LAB ASS\Aoa\"; if ($?) { gcc bestfit.c -o bestfit }; if ($?) { .\bestfit }

Memory Management Scheme - Best Fit
Enter the number of blocks:5
Enter the number of processes:3

Enter the size of the blocks:-
Block no.1:10
Block no.2:20
Block no.3:30
Block no.4:30
Block no.5:40

Enter the size of the processes :-
Process no.1:7
Process no.1:7
Process no.2:9
Process no.3:2

Process_no Process_size Block_no Block_size Fragment
1 7 1 10 3
2 9 2 20 11
3 30 28

PS C:\Meet\COLLEGE\LAB ASS\Aoa>
```

c)Worst Fit:

Conclusion: Thus we have successfully implemented dynamic partitioning placement algorithms.