

## Fenwick Tree

It is a data structure that supports 2 kind of operations:

1. Point update:  $\text{update}(i, x)$  will increment  $a(i)$  by  $x$ .
2. Range query:  $\text{query}(i)$  will return the value of  $a(1) + a(2) + \dots + a(i)$

Using array:

1. Point update can be done in  $O(1)$
2. Range query can be done in  $O(n)$

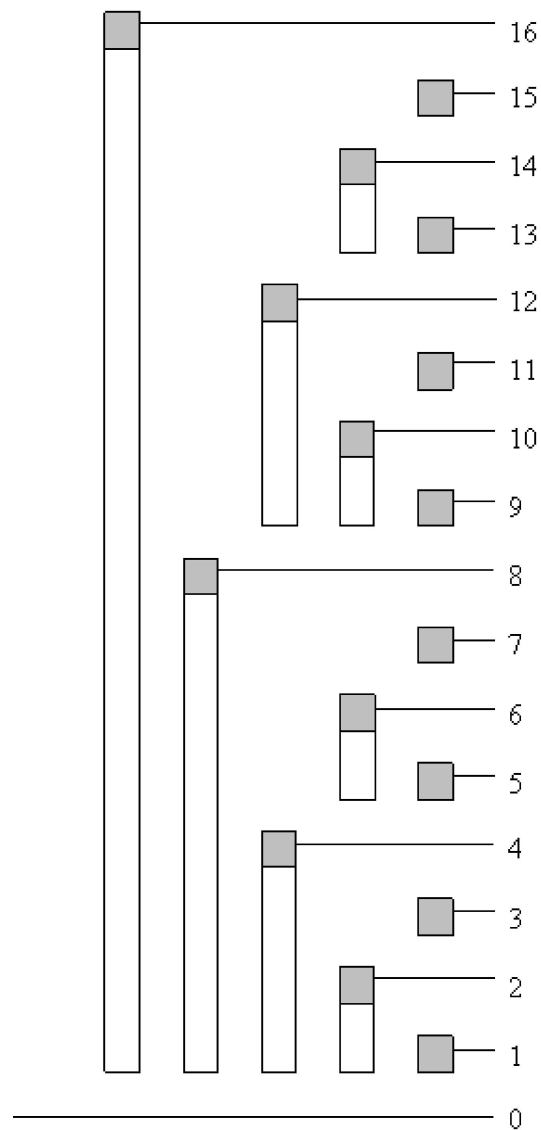
By maintaining a prefix array:

1. Point update can be done in  $O(n)$
2. Range query can be done in  $O(1)$

Fenwick tree allows us to perform both the operations in  $O(\log(n))$  by solving the shortcomings of these 2 approaches.

### What are the shortcomings?

1. In a normal array, every index stores only the value of itself. So, to answer the query, there is no other way but to iterate through the range  $[l, r]$ .
2. In the prefix array, every index  $i$  stores the sum of elements with index  $\leq i$ . So,  $a(i)$  contributes its value to every index  $\geq i$  in the prefix array.
3. In order to carry out both operations in  $O(\log(n))$ , we must ensure that:
  - a.  $t(i)$  contains a sum of a segment  $(g(i), i]$ . Also the range  $(0, i]$  should be expressible as a concatenation of at most  $\log(n)$  such segments.
  - b.  $a(i)$  should contribute its value to at most  $\log(n)$  indexes of  $t$ . In another words, there should exists at most  $\log(n)$  values of  $j$  satisfying:
 
$$g(j) < i \leq j \leq n$$



### Tree of responsibility

The segments represent the range whose sum is stored in  $t(i)$

For example:

1.  $(0, 10]$  can be expressed as  $(0, 8] + (8, 10]$ . So,  $\text{query}(10)$  can be executed in 2 steps.
2. Index 10 contributes its value to segments  $(8, 10]$ ,  $(8, 12]$ ,  $(0, 16]$ . So,  $\text{update}(10, x)$  can be executed in 3 steps.

### Definition of $g(i)$

Let  $g$  be a function defined in the domain of natural numbers. We first express  $i$  in its binary form, and then set the last 'on' bit to 'off'.

E.g:

$$\begin{array}{rcl} 10 & = & 1\ 0\ 1\ 0 \\ g(10) & = & 1\ 0\ 0\ 0 \end{array}$$

$$\begin{array}{rcl} 12 & = & 1\ 1\ 0\ 0 \\ g(12) & = & 1\ 0\ 0\ 0 \end{array}$$

$$\text{So, } g(10) = g(12) = 8$$

### How to calculate $g(i)$

It turns out that  $g(i) = i - (i \& -i)$

The contribution of the last set bit is equal to  $i \& (-i)$ .

E.g:

$$\begin{array}{rcl} 20 & = & 1\ 0\ 1\ 0\ 0 \\ \text{1's complement} & = & 0\ 1\ 0\ 1\ 1 \\ \text{2's complement} & = & 0\ 1\ 1\ 0\ 0 \\ 20 \& (-20) & = & 0\ 0\ 1\ 0\ 0 \end{array}$$

In a  $k$ -bit number, there can exist at most  $k$  'on' bits. Hence we need to go through at most  $k$  segments to answer the query for any number  $< 2^k$ . It proves that the complexity of each query is  $O(\log n)$ .

### How to update?

Whenever we add  $x$  to  $a(i)$ , we must add  $x$  to all such  $t(j)$ , where  $i$  lies inside the segment of  $t(j)$ .

In other words, for all  $j$  satisfying  $g(j) < i \leq j \leq n$ ,  $t(j)$  must be incremented by  $x$ .

### How to find such j ?

Let's suppose there are total k 'on' bits in j.

*Observation 1:* The first k-1 'on' bits of i and j must be in the same position.

*Observation 2:* The k<sup>th</sup> 'on' bit of j should make sure that  $j \geq i$  is satisfied.

### How to iterate over such j ?

Let's try to understand it using an example.

Let i = 1 1 0 0 1 0 1 0 1

For k = 5,

j = 1 1 0 0 1 0 1 0 1  
j = 1 1 0 0 1 0 1 1 0

For k = 4,

j = 1 1 0 0 1 1 0 0 0

For k = 3,

j = 1 1 0 1 0 0 0 0 0  
j = 1 1 1 0 0 0 0 0 0

For k = 2,

No such j

For k = 1,

j = 1 0 0 0 0 0 0 0 0  
j = 1 0 0 0 0 0 0 0 0 ... and so on

Again, it turns out that we can make transition from upper j to the lower j using a simple formula:  
 $j = j + (j \& -j)$

Since the position of the last 'on' bit is decreasing at least by 1 in every transition, the complexity of update(i, x) is  $O(\log n)$ .

**Implementation (One based Indexing):**

```
struct BIT {  
  
    int n;  
    vector<int> t;  
  
    BIT() {}  
    BIT(int n) : n(n + 5), t(n + 5) {}  
  
    // a[i] += val  
    void update(int i, int val){  
        for(; i < n; i += i & -i){  
            t[i] += val;  
        }  
    }  
  
    // returns a[1] + a[2] + ... + a[i]  
    int query(int i){  
        int ret = 0;  
        for(; i; i -= i & -i){  
            ret += t[i];  
        }  
        return ret;  
    }  
  
    // returns a[1] + a[1+1] + ... + a[r]  
    int query(int l, int r){  
        return query(r) - query(l - 1);  
    }  
};
```

**Implementation (Zero based Indexing):**

1. Instead of `update(i, x)`, we execute `update(i + 1, x)`
2. Instead of `query(i)`, we execute `query(i + 1)`

```
struct BIT {  
  
    int n;  
    vector<int> t;  
  
    BIT() {}  
    BIT(int n) : n(n + 1), t(n + 1) {}  
  
    // a[i] += val  
    void update(int i, int val){  
        for(++i; i < n; i += i & -i){  
            t[i] += val;  
        }  
    }  
  
    // returns a[0] + a[1] + ... + a[i]  
    int query(int i){  
        int ret = 0;  
        for(++i; i; i -= i & -i){  
            ret += t[i];  
        }  
        return ret;  
    }  
  
    // returns a[l] + a[l+1] + ... + a[r]  
    int query(int l, int r){  
        return query(r) - query(l - 1);  
    }  
};
```