

Energy Scaling Laws for Distributed Inference in Random Networks

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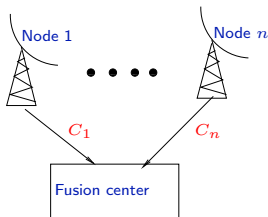
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24th Sept., 2008

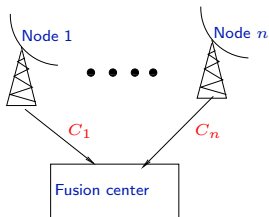
Distributed Statistical Inference



Classical distributed inference

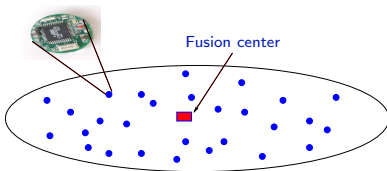
- Many-to-one data fusion
- Rate constraints on fusion links
- Quantization rule at local sensors
- Inference rule at fusion center

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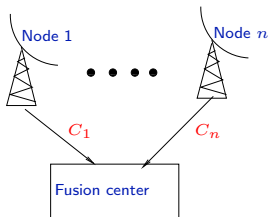
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Sensor networks for inference

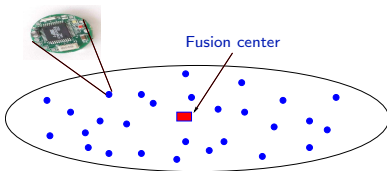
- **Multihop data fusion**
- **Energy constraints**
- Transmission and **routing** policies
- Quantization and inference rules

Distributed Statistical Inference



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Sensor networks for inference

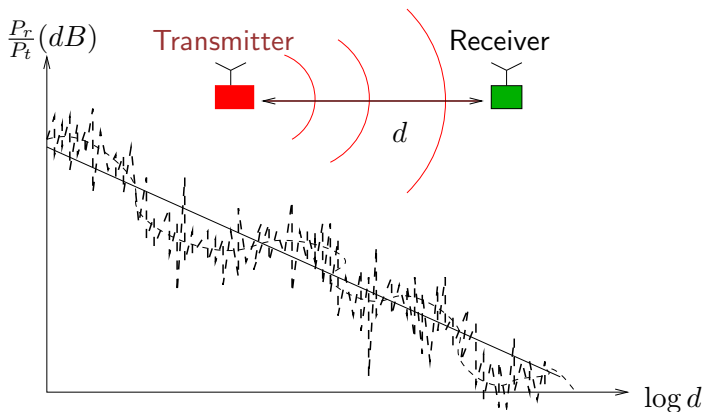
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Energy Consumption for Distributed Inference

Outline

- 1 Introduction
- 2 Models and Assumptions
- 3 Problem Formulation & Summary of Results
- 4 Independent Measurements
- 5 Markov Random Field Measurements
- 6 Conclusion & Outlook

Propagation model and assumptions

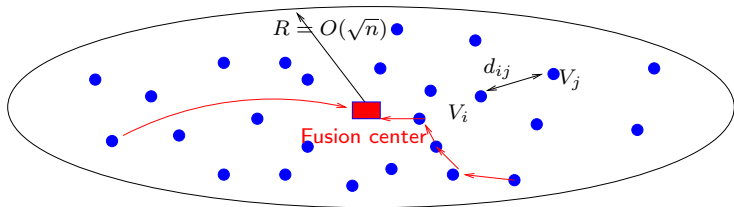


Energy cost per sample: $\mathcal{E} = O(d^\nu)$, $2 \leq \nu \leq 4$, ν is Path Loss.

Network Model and Assumptions

Network Model

- Network has a fixed node density $\lambda = \frac{n}{\pi R^2}$: $R = O(\sqrt{n})$.
- Sensor locations $V_i \stackrel{\text{i.i.d.}}{\sim} \sqrt{\frac{n}{\lambda}} \kappa(x), i = 1, \dots, n$ (e.g., Uniform)
 - ▶ $\kappa(x)$ has support on unit square
- Adjustable transmission power for multihop or direct transmission.
- For connectivity, $\max \mathcal{E}_i, i \in \mathbf{V}_n$ grows at least at $O((\sqrt{\log n})^\nu)$.



Inference Model and Assumptions

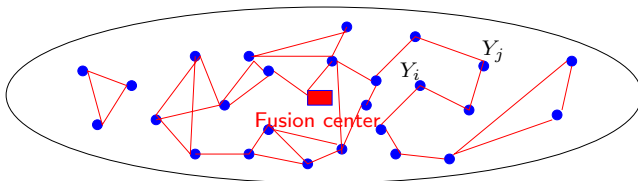
Binary Hypothesis Testing

- Location $\mathbf{V}_n \triangleq (V_1, \dots, V_n)$ and observations $\mathbf{Y}_n \triangleq (Y_1, \dots, Y_n)$.
- $\mathcal{H}_k : (\mathbf{Y}_n, \mathbf{V}_n) \sim f_k(\mathbf{y}_n | \mathbf{v}_n) \kappa(\mathbf{v}_n), \quad k = 0, 1$

\mathbf{Y}_n : **Markov random field** with dependency graph $\mathcal{G}_k = (\mathbf{V}_n, E_k)$

$$-\log f_k(\mathbf{y}_n | \mathbf{v}_n; \mathcal{G}_{n,k}) = \sum_{c \in \mathcal{C}_k} \Psi_{k,c}(\mathbf{y}_c)$$

$\mathcal{C}_{n,k}$: collection of maximal cliques, $\Psi_{k,c} > 0$: clique potentials



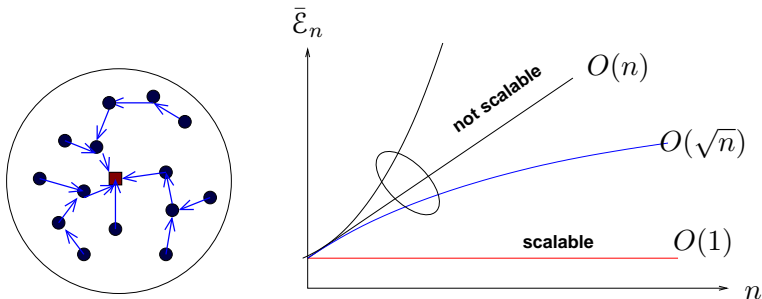
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Energy Scaling Law

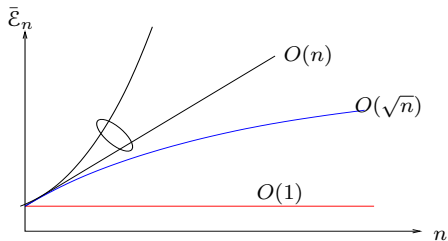
Energy Consumption For Inference

- Require optimal inference at the fusion center
- Examine average energy expenditure: $\bar{\mathcal{E}}_n = \frac{1}{n} \sum_i \mathcal{E}_i$

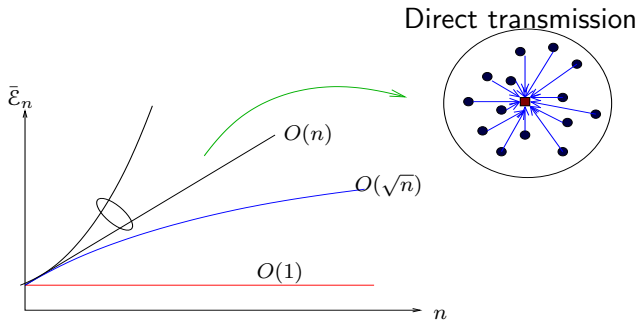


Goal: find a scalable data fusion strategy for optimal inference

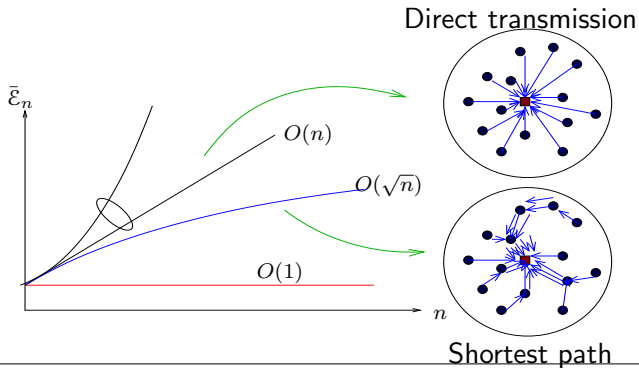
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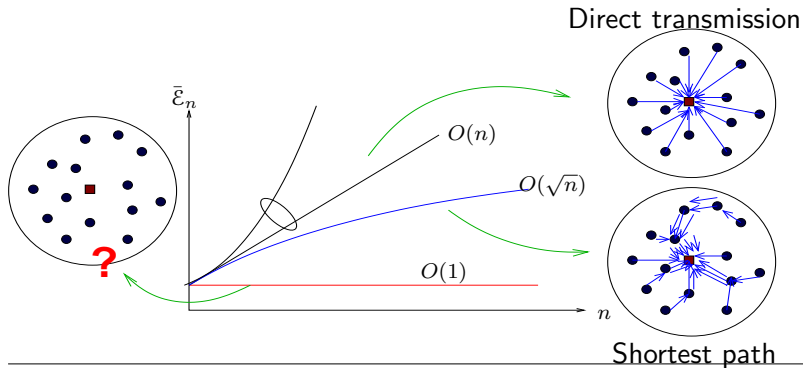
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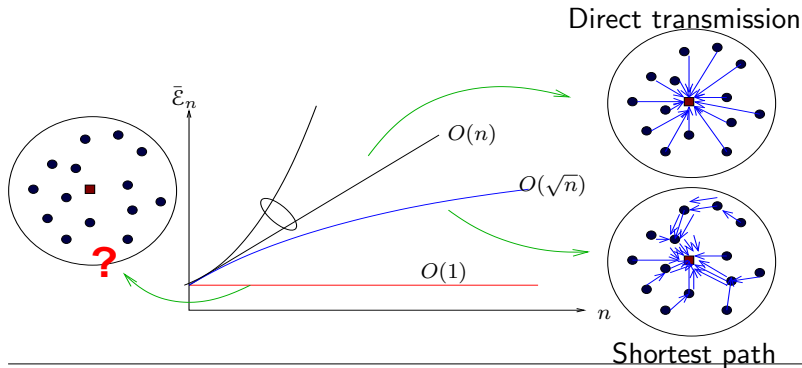
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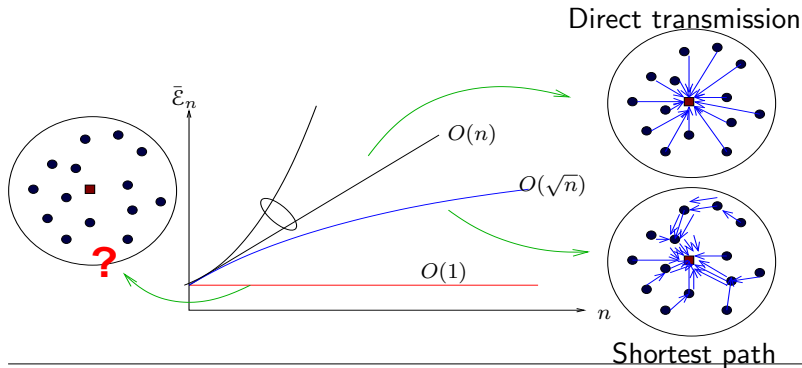


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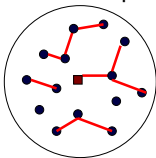
Finite Scaling for Local Spatial Dependencies

Energy Scaling Law

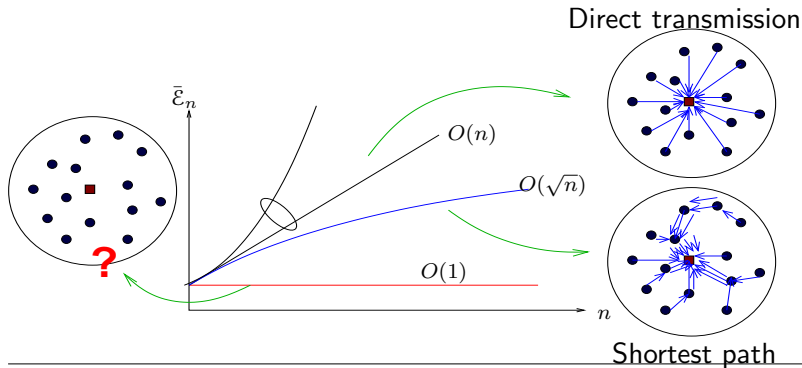


Finite Scaling for Local Spatial Dependencies

Finite Disk Graph: **Yes**

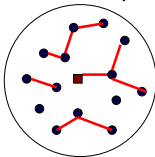


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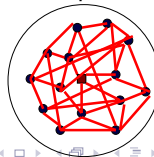


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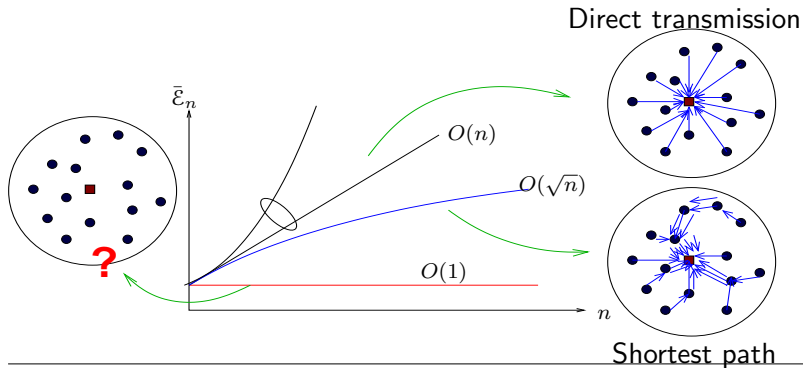
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Complete Dependency: **No**

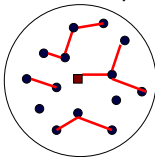


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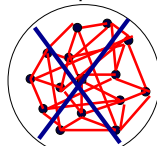


Finite Scaling for Local Spatial Dependencies

Finite Disk Graph: **Yes**



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Summary of Results

Finite Average Energy Scaling

For Stabilizing Dependency Graphs e.g., k -NNG, disk graph

- Construction of a suboptimal fusion scheme DFMRF and its analysis

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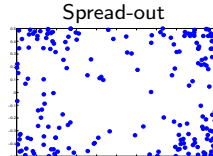
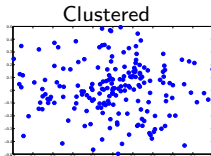
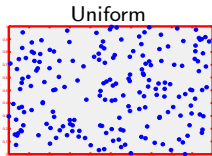
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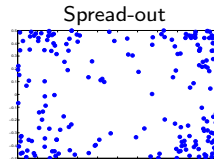
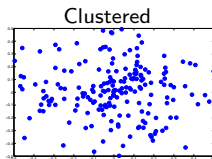
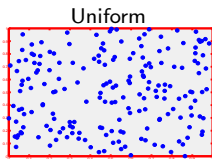
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Optimality of Uniform Placement Over IID Placements

For Scale-Invariant Dependency (k -NNG) and Path loss ≥ 2

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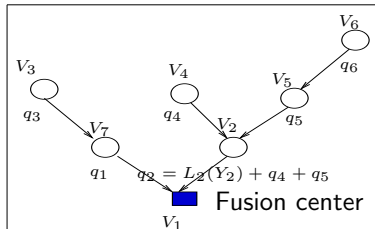
Optimal Fusion: Independent Case

IID Measurements

$$\mathcal{H}_k : \mathbf{Y}_n \sim \prod_i f_k(y_i)$$

Sufficient Statistic

$$L(\mathbf{y}_n) = \log \frac{f_0(\mathbf{y}_n)}{f_1(\mathbf{y}_n)} = \sum_i L_i(y_i)$$



Optimal data fusion is LLR aggregation over MST

- Each node must transmit at least once
- MST minimizes edge sum for spanning trees: $\min \sum_i |e_i|^\nu$
- Fusion rule: $q_i = \sum_{j \in \mathcal{N}(i)} q_j + L_i(Y_i)$

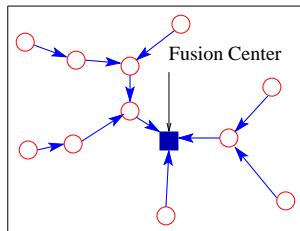
Optimal fusion: energy analysis

Average energy per node

$$\bar{\mathcal{E}}_n = \frac{1}{n} \sum_{e \in \text{MST}} |e|^\nu$$

LLN: Steele'88, Penrose-Yukich'03

$$\frac{1}{n} \sum_{e \in \text{MST}} |e|^\nu \xrightarrow{L^2} \bar{\mathcal{E}}_\infty$$



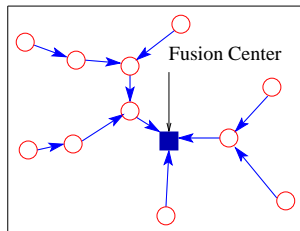
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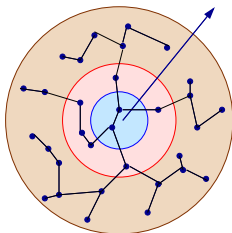
Scaling Constant for κ bounded away from 0 & ∞

$$\bar{\mathcal{E}}_\infty = \zeta(\nu; \text{MST}) \int_{[-\frac{1}{2}, \frac{1}{2}]^2} \kappa(x)^{1-\frac{\nu}{2}} dx, \quad \zeta(\nu; \text{MST}) = \frac{1}{2} \mathbb{E} \left[\sum_{\substack{e \in \text{MST}(\mathcal{P}_1 \cup \mathbf{0}) \\ \mathbf{0} \in e}} |e|^\nu \right]$$

Key idea: global property to local property

Scaling Constant: Law of Large Numbers (Penrose & Yukich '03)

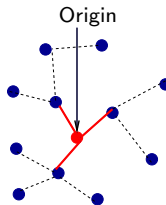
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Normalized sum of edge weights

$$\frac{1}{n} \sum_{e \in \text{MST}(\mathbf{V}_n)} |e|^\nu$$

$n \rightarrow \infty$



Expectation for edges
of origin of Poisson process

$$\bar{\mathcal{E}}_\infty$$



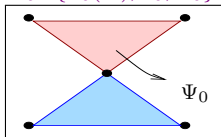
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Fusion for Markov random field

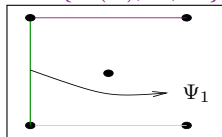
Null Hypothesis

$$\mathcal{H}_0 : \{\mathcal{G}_0(\mathbf{V}), \mathcal{C}_0, \Psi_0\}$$



Alternative Hypothesis

$$\mathcal{H}_1 : \{\mathcal{G}_1(\mathbf{V}), \mathcal{C}_1, \Psi_1\}$$



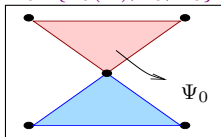
Binary hypothesis on MRF

$$\text{for } k = 0, 1, \quad \mathcal{H}_k : \mathbf{Y}_n \sim f_k(\mathbf{y}_{\mathbf{V}}; \mathcal{G}_k) = \exp\left\{-\sum_{c \in \mathcal{C}_k} \Psi_{k,c}(\mathbf{y}_c)\right\}$$

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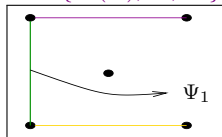
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Minimal Sufficient Statistic: $\mathcal{G} \triangleq \mathcal{G}_0 \cup \mathcal{G}_1 = (\mathbf{V}, \mathcal{E}_0 \cup \mathcal{E}_1)$

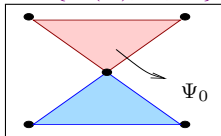
$$L_{\mathcal{G}}(\mathbf{Y}_{\mathbf{V}}) = \log \frac{f_0(\mathbf{Y}_{\mathbf{V}}; \mathcal{G}_0)}{f_1(\mathbf{Y}_{\mathbf{V}}; \mathcal{G}_1)} = \sum_{c \in \mathcal{C}} \phi_c(\mathbf{Y}_c),$$

where \mathcal{C} is the collection of maximal cliques of \mathcal{G}

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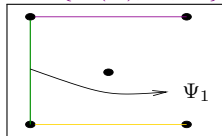
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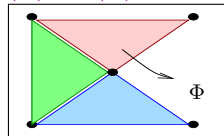
Alternative Hypothesis

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Effective MRF For LLR

$$\{\mathcal{G}_0(\mathbf{V}) \cup \mathcal{G}_1(\mathbf{V}), \mathcal{C}_0 \cup \mathcal{C}_1, \Phi\}$$



Binary hypothesis on MRF

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Optimal Fusion Scheme for Inference

Optimization Statement: π^*

- Minimize sum routing costs s.t. $L_g(\mathbf{Y}_n) = \sum_{c \in \mathcal{C}} \Phi_c(\mathbf{Y}_c)$ is delivered
- Steiner tree reduction under local processor assignment: **NP-hard**

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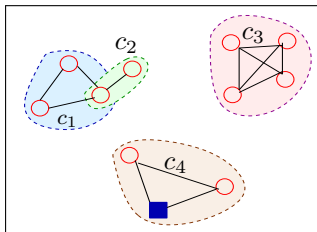
Data Fusion for Markov random field: DFMRF

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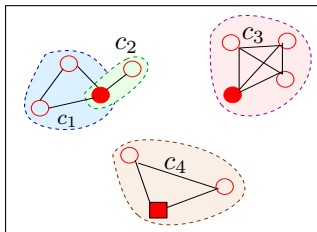


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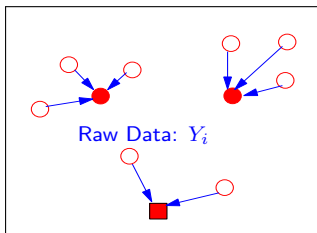


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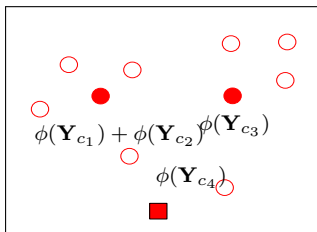


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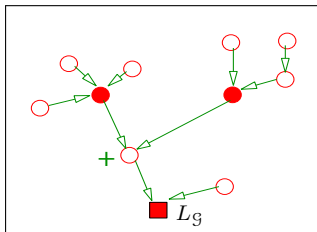


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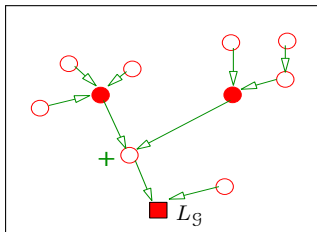


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DFMRF

- Local processor assignment and MST aggregation
- Total energy consumption = Data Forwarding + Aggregation

Fusion on Markov random field: energy scaling law

Assumptions

- Dependency \mathcal{G} translation & scale invariant, stabilizing (k -NNG)
- Set of feasible links is a u -energy spanner for finite constant u
 - ▶ SP energy no more than u times SP energy on complete graph
- Placement distribution κ is bounded away from 0 and ∞ on $[-\frac{1}{2}, \frac{1}{2}]^2$

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Scaling Result for DFMRF

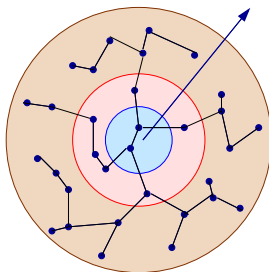
$$\limsup_{n \rightarrow \infty} \frac{\mathcal{E}(\text{DFMRF})}{n} \leq \lambda^{-\frac{\nu}{2}} \underbrace{[u \zeta(\nu; \mathcal{G})]}_{\text{data forward}} + \underbrace{\zeta(\nu; \text{MST})}_{\text{MST aggregation}} \int_{[-\frac{1}{2}, \frac{1}{2}]^2} \kappa(x)^{1-\frac{\nu}{2}} dx,$$

$$\zeta(\nu; \mathcal{G}) \triangleq \frac{1}{2} \mathbb{E} \left[\sum_{\substack{e \in \mathcal{G}(\mathcal{P}_1 \cup \mathbf{0}) \\ \mathbf{0} \subset e}} |e|^\nu \right]$$

Key ideas

Bound on Energy for Forwarding to Processors Proc

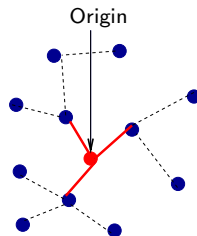
$$\mathcal{E}(\text{Forward}) \leq \sum_{c \in \mathcal{C}(\mathbf{V})} \sum_{i \subset c} \text{SP}(i, \text{Proc}(c)) \leq u \sum_{c \in \mathcal{C}(\mathbf{V})} \sum_{i \subset c} |i, \text{Proc}(c)|^\nu \leq u \sum_{e \in \mathcal{G}} |e|^\nu$$



Normalized sum of edge weights

$$\frac{1}{n} \sum_{e \in \mathcal{G}(\mathbf{V}_n)} |e|^\nu$$

$n \rightarrow \infty$



Expectation for edges
of origin of Poisson process

$$\frac{1}{2} \mathbb{E} \left[\sum_{\substack{e \in \mathcal{G}(\mathcal{P}_1 \cup \mathbf{0}) \\ \mathbf{0} \subset e}} |e|^\nu \right] \int_{[-\frac{1}{2}, \frac{1}{2}]^2} \kappa(x)^{1-\frac{\nu}{2}} dx$$

Illustration of Stabilization

General LLN on Stabilizing Graph \mathcal{G}

$$\frac{1}{n} \sum_{e \in \mathcal{G}(\mathbf{V}_n)} |e|^\nu \rightarrow \text{constant}$$

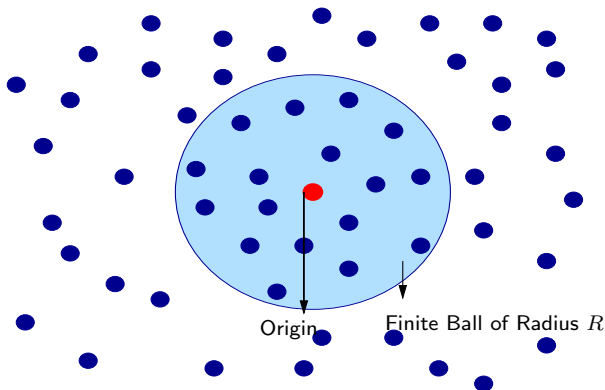


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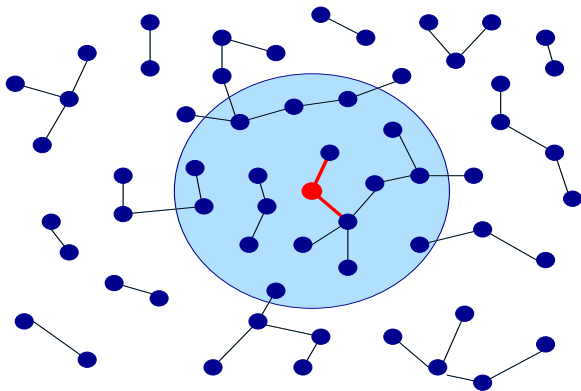


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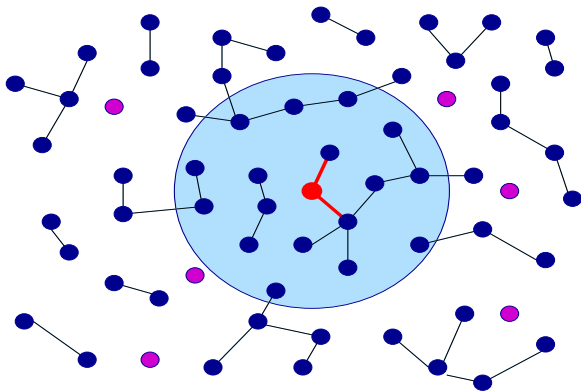


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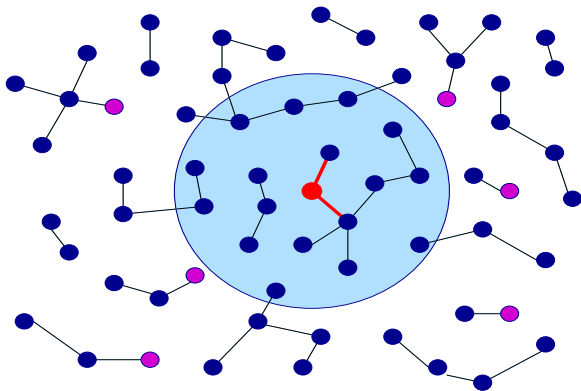


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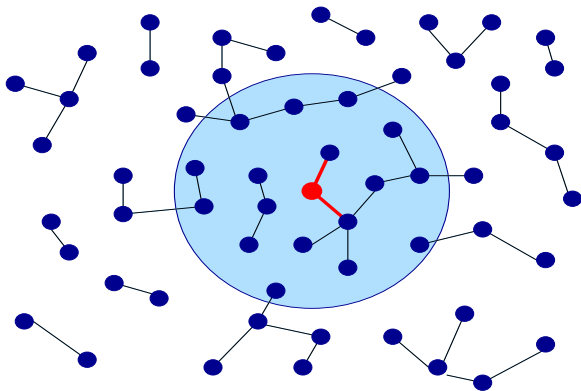


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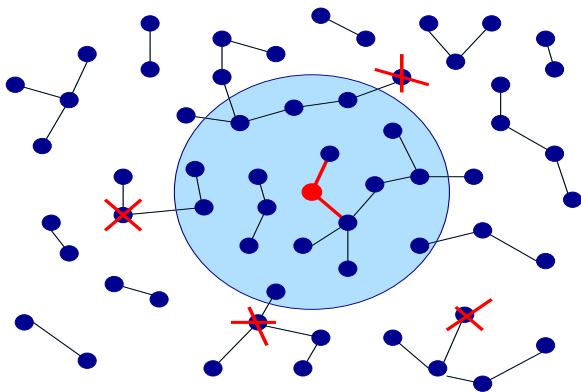
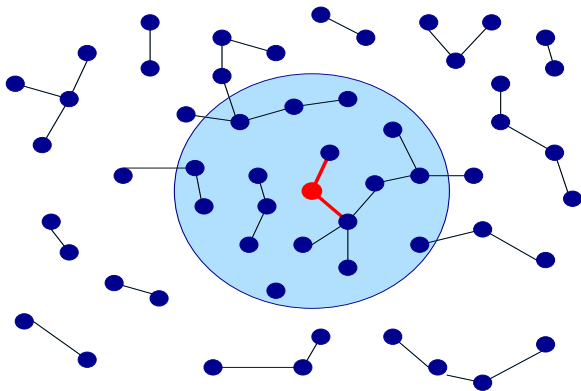


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Scaling Law for Optimal Fusion

Lower and Upper Bounds For Any Network

$$\bar{\mathcal{E}}_n(\text{MST}(\mathbf{V}_n)) \leq \bar{\mathcal{E}}_n(\pi^*(\mathbf{V}_n)) \leq \bar{\mathcal{E}}_n(\text{DFMRF}(\mathbf{V}_n))$$

Bounds For Large Random Networks Under \mathcal{G} Dependency

$$\zeta(\nu; \text{MST}) \leq \lim_{n \rightarrow \infty} \frac{\bar{\mathcal{E}}_n(\pi^*(\mathbf{V}_n))}{\int_{[-\frac{1}{2}, \frac{1}{2}]^2} \kappa(x)^{1-\frac{\nu}{2}} dx} \leq [u \zeta(\nu; \mathcal{G}) + \zeta(\nu; \text{MST})]$$

Finite Average Energy Scaling For Distributed Inference

Approximation ratio of DFMRF for Large Random Networks

$$\limsup_{n \rightarrow \infty} \frac{\mathcal{E}(\text{DFMRF}(\mathbf{V}_n))}{\mathcal{E}(\pi^*(\mathbf{V}_n))} \leq \left(1 + u \frac{\zeta(\nu; \mathcal{G})}{\zeta(\nu; \text{MST})}\right)$$

Constant Factor Approximation for DFMRF

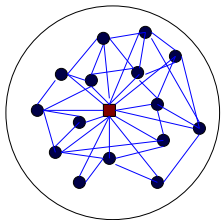
Outline

- 1 Introduction
- 2 Models and Assumptions
- 3 Problem Formulation & Summary of Results
- 4 Independent Measurements
- 5 Markov Random Field Measurements
- 6 Conclusion & Outlook**

Summary

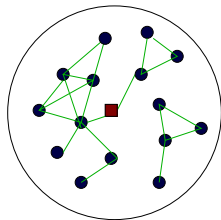
Network graph

Feasible Links for Communication



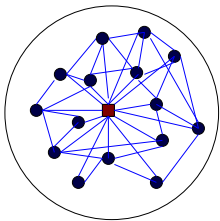
Dependency graph

Correlation Model of Data

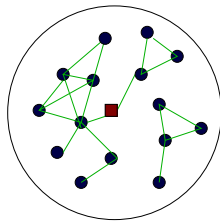


Summary

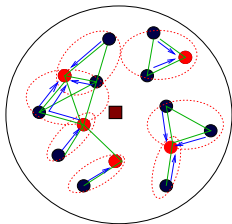
Network graph
Feasible Links for Communication



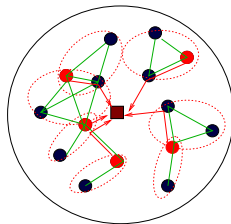
Dependency graph
Correlation Model of Data



DFMRF Scheme



Forwarding on shortest path



Aggregation on MST

Conclusion and future work

Concluding remarks

- Energy consumption is a key design parameter for large wireless sensor networks.
- Sensor location is a new source of randomness in distributed inference
- Asymptotic techniques are useful in overall network design.

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Future work

- General behavior of error exponents in MRF
- Impact of sensor distribution on energy-performance tradeoff.

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