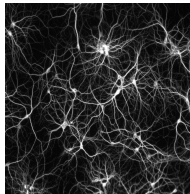
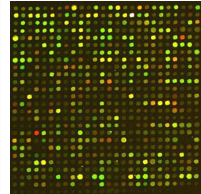


# Beyond Sparse Graphical Models: Incorporating Mixtures and Residuals

**Anima Anandkumar**

U.C. Irvine

# Data Deluge and Data Desert

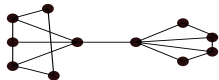


- Current **technologies** unable to handle data **deluge**.
- Current **algorithms** unable to handle data **desert**.

High-dimensional data: Many variables, few samples

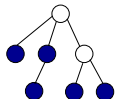
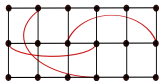
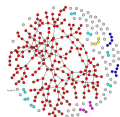
# Graph-Based Models for High-Dimensional Data

- Qualitative: **Graph structure(s)**.
- Quantitative: **Interaction strengths**.



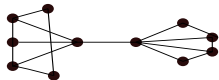
Parsimonious representation via sparse graphs

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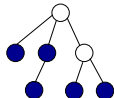
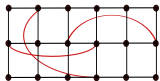
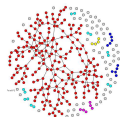
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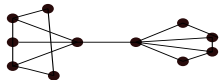
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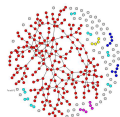
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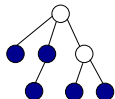
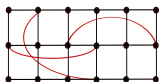
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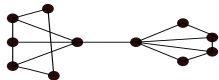
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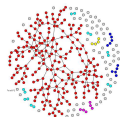
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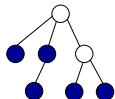
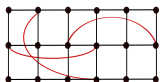
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## Goals

Tractable **models**, Novel **algorithms**, Provable **guarantees**, **Applications**.

# Examples of Graph-based Representations

## Motivating Example: Topic Modeling

**Data:** word counts in documents.

**Graph:** Topic-word relationships.

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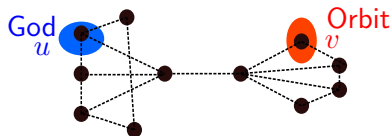
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## Independence models



Marginal Independence

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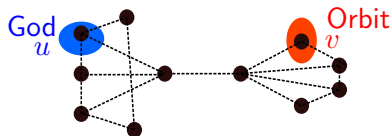
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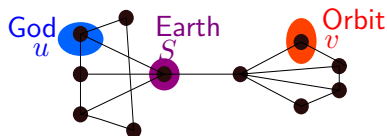
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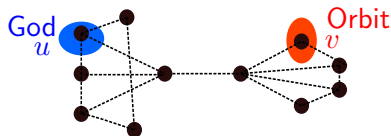
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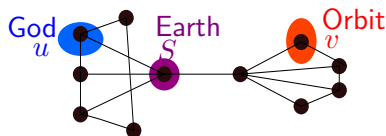
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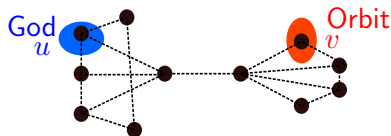
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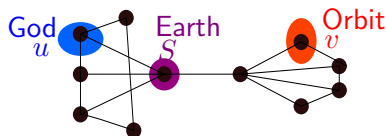
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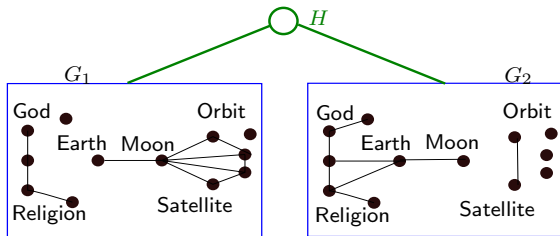
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**Solution:** High-dimensional modeling via multiple graphs

# High-dimensional Modeling via Multiple Graphs

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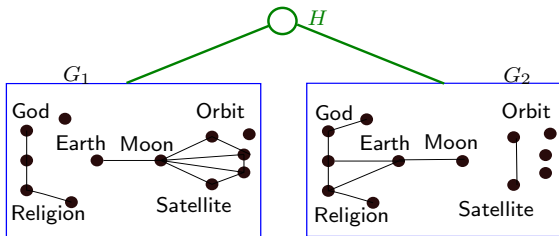
- Multiple graphs: **context specific dependencies**
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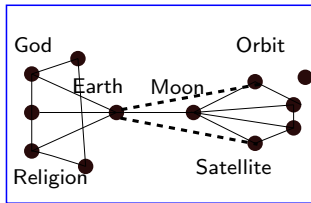
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## Markov+Independence Models

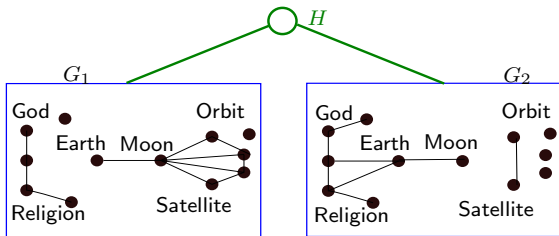
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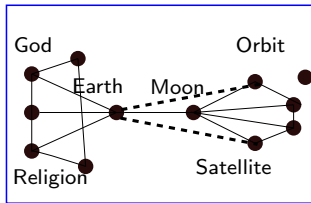
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Novel Approaches Beyond Sparse Graphical Modeling

# State of Art Approaches

## Learning Sparse Graphical Models

- **Combinatorial:** Bresler, Mossel & Sly.  $A^*$ , Tan & Willsky.
- **Convex:** Meinshausen & Bühlmann. Ravikumar, Wainwright & Lafferty.

## Learning with Latent Variables

- **Trees:** Erdős, et. al., Daskalakis, Mossel & Roch. Choi, Tan,  $A^*$  & Willsky.
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## Learning Mixture Models

- **Gaussian Mixtures:** Dasgupta. Kannan et al. Chaudhuri et al.
  - ▶ **Separation** condition for mixture components
- **Method of Moments:** Prony, Belkin & Sinha. Moitra & Valiant.
  - ▶ Comp. & sample complexities **exponential** in no. of components
- **Latent Class Models:** Chang. Hsu, Kakade & Zhang. Mossel & Roch.
  - ▶ Mixtures of **discrete product distributions**.



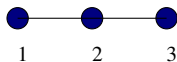
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# Warm-up: Learning Tree Models

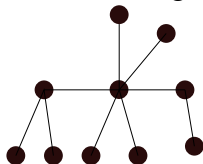
Data processing inequality for Markov chains

$$I(X_1; X_3) \leq I(X_1; X_2), I(X_2; X_3).$$



Tree Structure Estimation (Chow and Liu '68)

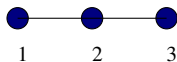
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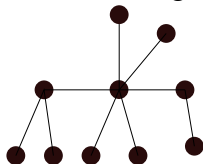
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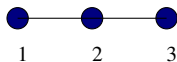
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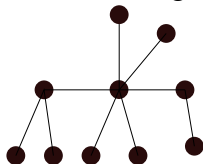
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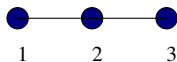
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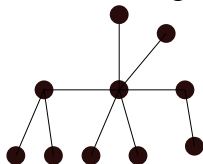
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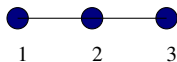


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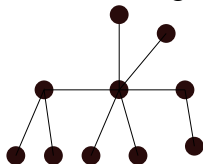
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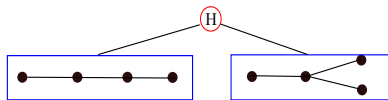
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What other models are tractable for learning and inference?

# Beyond Trees: Tree Mixture Models

## Tree Mixture Model

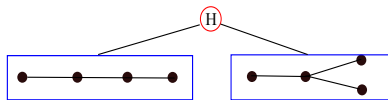
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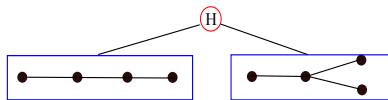
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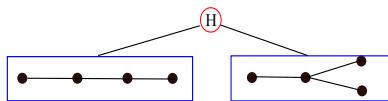
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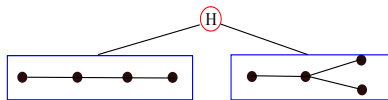
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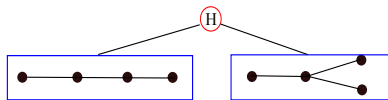
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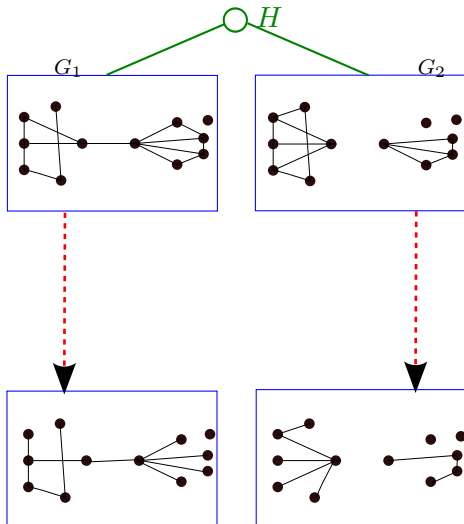
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Novel approach to learning tree mixture approximations

# Mixtures of Graphical Models: Our Approach

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- Consider data from **graphical model mixture**
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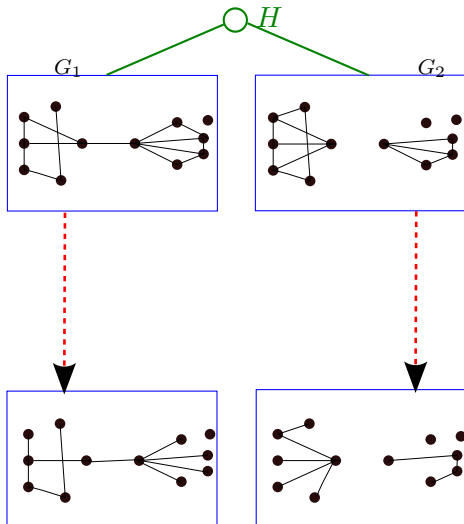


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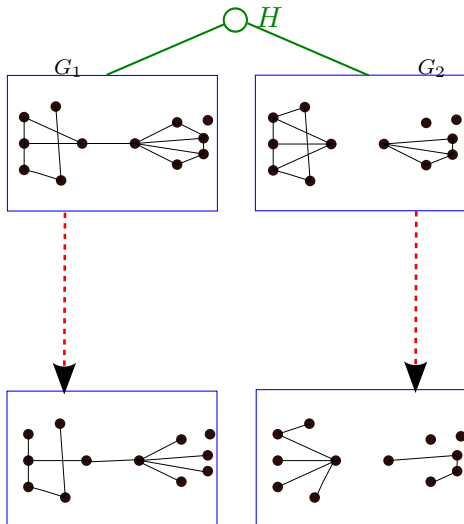
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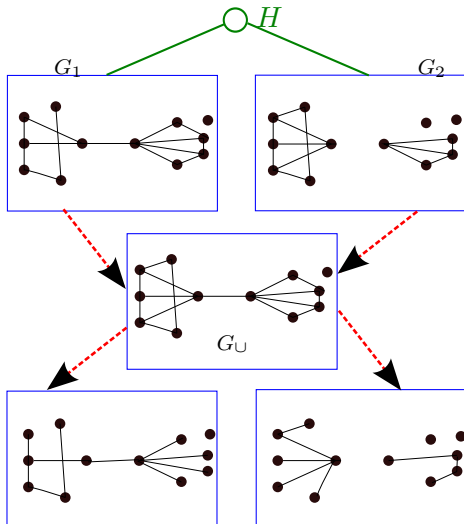
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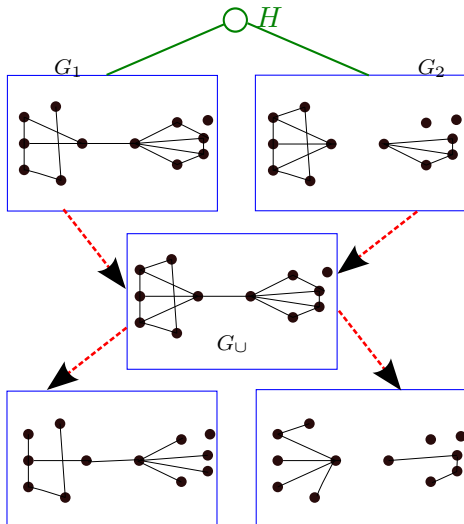
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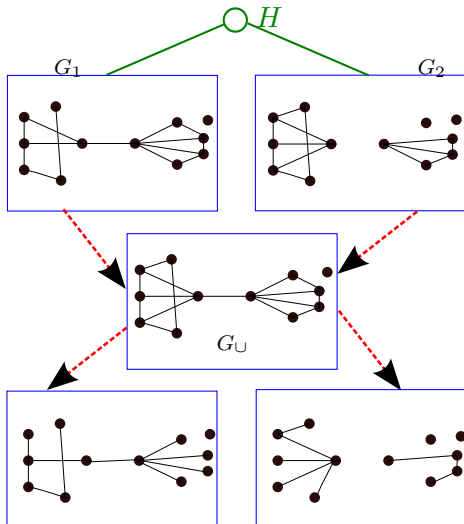
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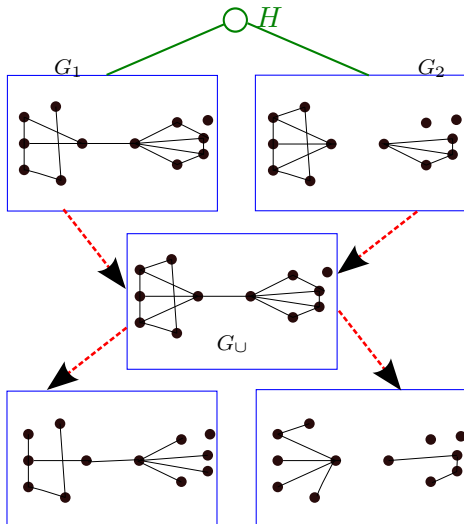
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Efficient Learning of Tree Mixture Approximations

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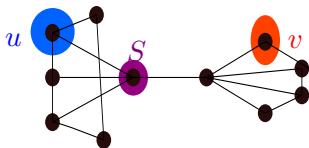
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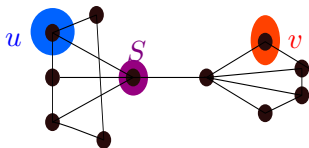
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Alternative Test for Conditional Independence?



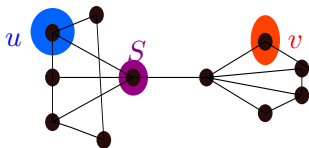
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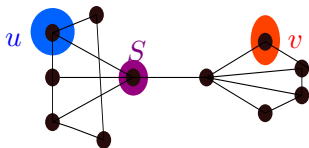
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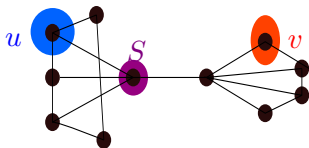
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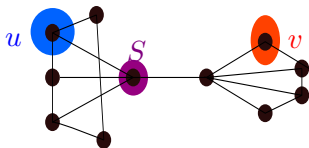
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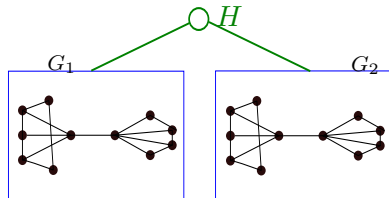
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Rank Test on Pairwise Probability Matrices

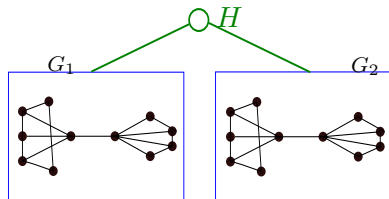
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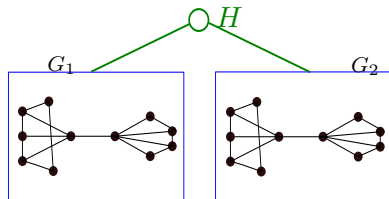
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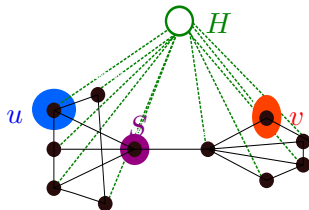


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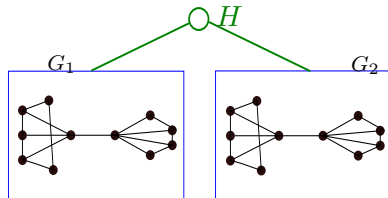


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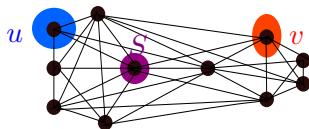


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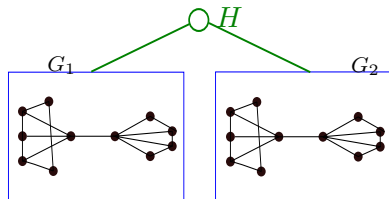


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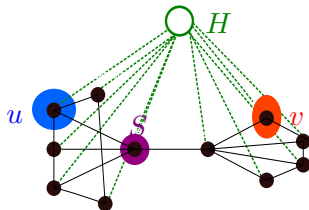


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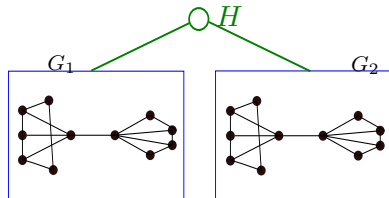


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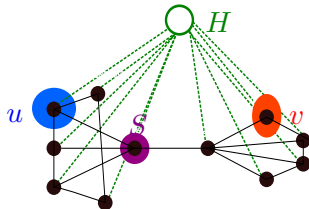


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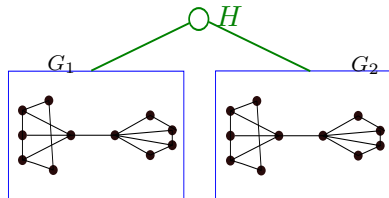
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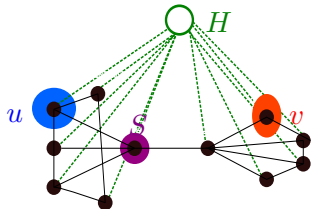


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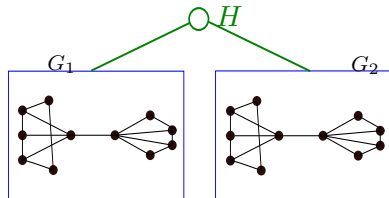
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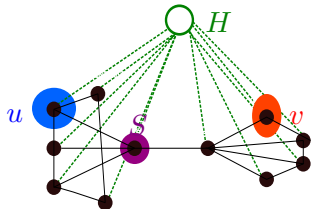
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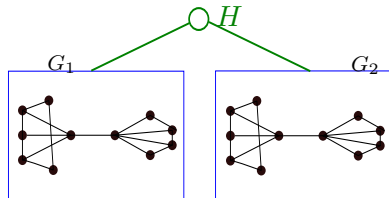
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 d \times d & & d \times r \quad r \times r \quad r \times d
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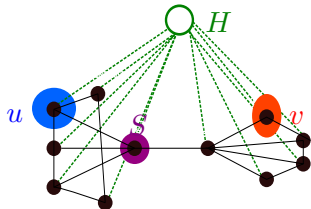
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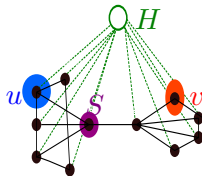
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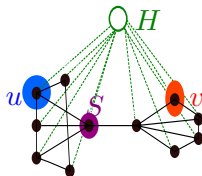
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Declare  $(u, v)$  as edge if  $\min_{S \subset V \setminus \{u,v\}} \max_{\substack{k \in \mathcal{X}^{|S|} \\ |S| \leq \eta}} \text{Rank}(M_{u,v,\{S;k\}}; \xi_{n,p}) > r$ .

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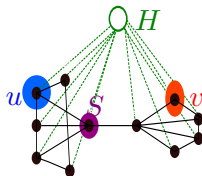


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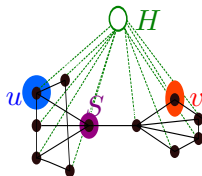
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Simple Test for Estimation of Union Graph of Mixtures

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Theorem (A. , Hsu, Kakade '12)

Rank test recovers graph structure  $G_U$  correctly w.h.p on  $p$  nodes under  $n$  samples when

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Recall examples of graphs  $G_U$  with small  $\eta$

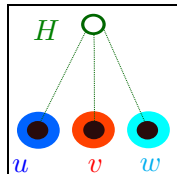
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# Outline

- 1 Introduction
- 2 Decomposition of Graphical Model Mixtures
  - Estimation of Union Graph Structure
  - Parameter Estimation of Mixture Components
- 3 Decomposition into Markov and Independence Domains
- 4 Conclusion

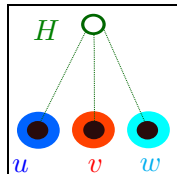
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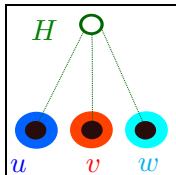


## Parameter Estimation: Generalized Eigenvalue Problem

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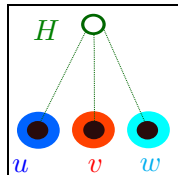
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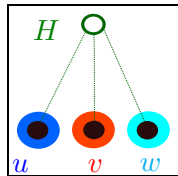
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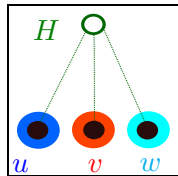
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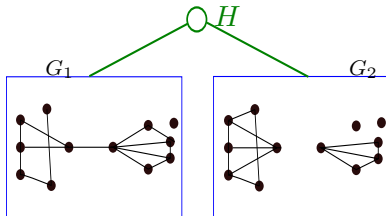
Efficient estimation of non-singular product mixtures

# Learning Graphical Model Mixtures

## Adapt Eigenvalue Method for Graphical Model Mixtures?

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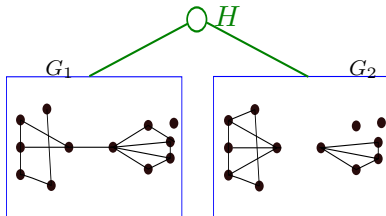
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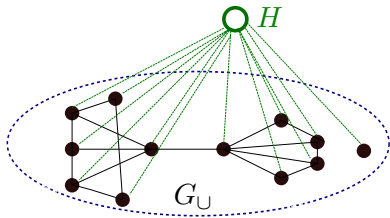
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### Solutions

- $G_U$ : **union graph** learnt from rank test

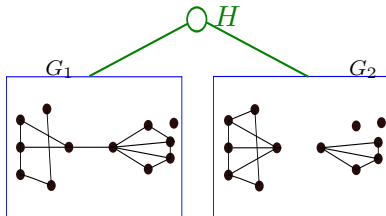


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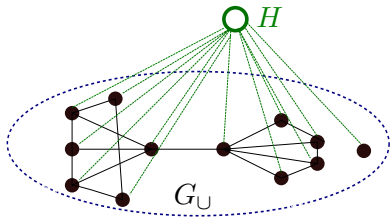
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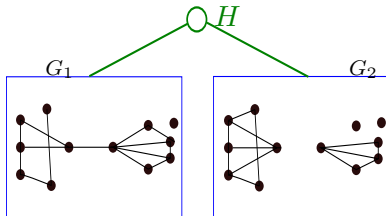


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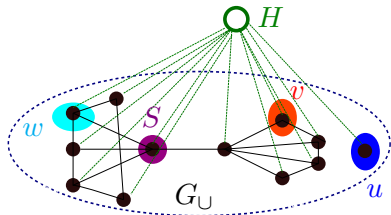
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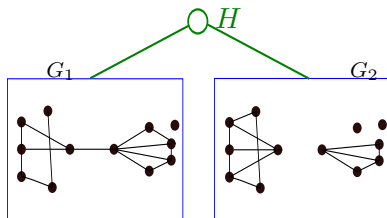


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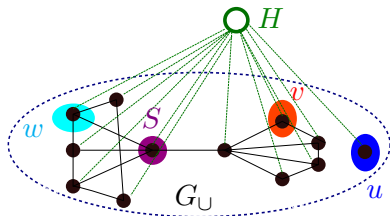
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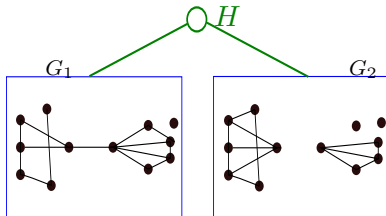


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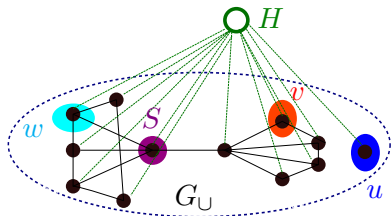
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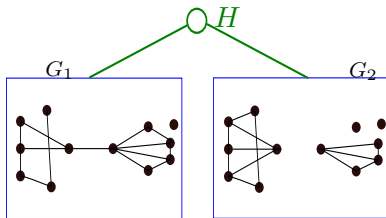


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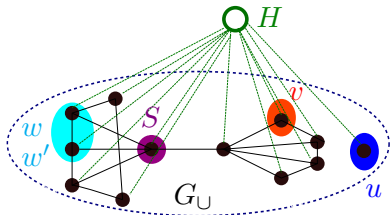
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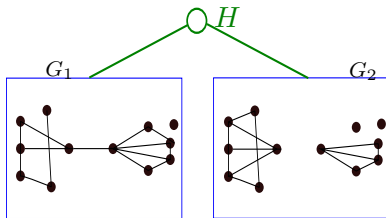


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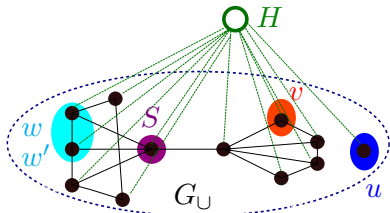
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## Efficient Estimation of Tree Mixture Approximations

# Guarantees for Learning Graphical Model Mixtures

## Steps Involved in Tree Mixture Approximation

- Rank tests for structure estimation of union graph  $G_U$
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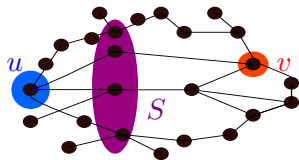
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## Efficient Learning of Multiple Graphs and Models in High Dimensions

# Extensions and Connections

## Exact vs. Local Separators in Union Graph

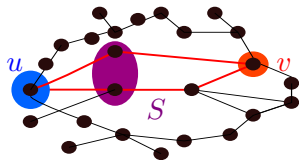
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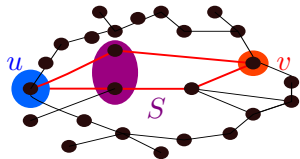
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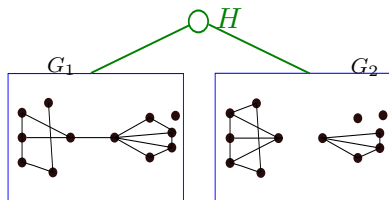
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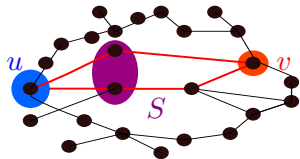
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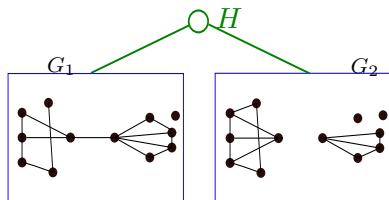
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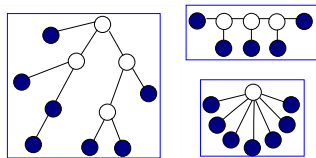
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## Estimation in other models

- **HMM**, **latent trees** and general **multiview** mixtures
- Improvement for **product** mixtures





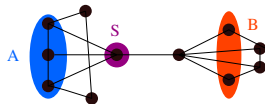
# Outline

- 1 Introduction
- 2 Decomposition of Graphical Model Mixtures
  - Estimation of Union Graph Structure
  - Parameter Estimation of Mixture Components
- 3 Decomposition into Markov and Independence Domains
- 4 Conclusion

# Beyond Graphical Modeling: Incorporating Residuals

Recall notion of graphical models...

- Conditional Independence:  $\mathbf{X}_A \perp\!\!\!\perp \mathbf{X}_B | \mathbf{X}_S$
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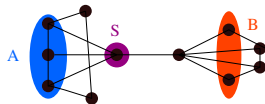
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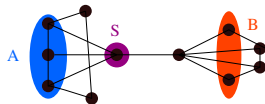
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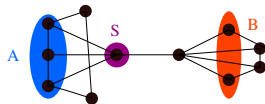
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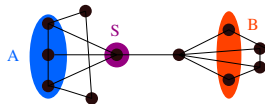
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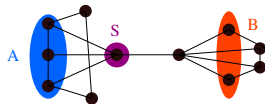
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$\ell_1$  penalized MLE for Graphical Models (Ravikumar et. al. '08)

- $\hat{\Sigma}^n$ : sample covariance using  $n$  i.i.d. samples

$$\begin{aligned} \hat{J}_M &:= \underset{J_M \succ 0}{\operatorname{argmin}} \langle \hat{\Sigma}^n, J_M \rangle - \log \det J_M + \gamma \|J_M\|_{1,\text{off}} \\ \text{s. t. } &\|J_M\|_{\infty,\text{off}} \leq \lambda, \end{aligned}$$

Max-entropy Formulation for Graphical Models (Janzamin, A. '12)

- Lagrangian dual of  $\ell_1$ -penalized MLE

$$\begin{aligned} (\hat{\Sigma}_M, \hat{\Sigma}_R) &:= \underset{\Sigma_M \succ 0, \Sigma_R}{\operatorname{argmax}} \log \det \Sigma_M - \lambda \|\Sigma_R\|_{1,\text{off}} \\ \text{s. t. } &\|\hat{\Sigma}^n - \Sigma_M - \Sigma_R\|_{\infty,\text{off}} \leq \gamma, \quad (\Sigma_M)_d = (\hat{\Sigma}^n)_d, \quad (\Sigma_R)_d = 0. \end{aligned}$$

Efficient Method for Covariance Decomposition and Estimation



# Guarantees for High-Dimensional Estimation

$$\Sigma^* = J_M^{*-1} + \Sigma_R^*.$$

$$\begin{bmatrix} & \\ & \end{bmatrix} = \begin{bmatrix} \text{blue } \times & \\ & \text{blue } \times \end{bmatrix}^{-1} + \begin{bmatrix} \text{red } \times & \\ & \text{red } \times \end{bmatrix}$$

Theorem (Janzamin and A. '12)

When the number of samples  $n$ , number of nodes  $p$  and maximum degree  $\Delta$  in the Markov graph (corresponding to  $J_M^*$ ) satisfy

$$\frac{\Delta^2 \log p}{n} = O(1),$$

- $(\hat{J}_M, \hat{\Sigma}_R)$  are **sparsistent** and **sign consistent**
- satisfy **norm guarantees**

$$\|\hat{J}_M - J_M^*\|_\infty, \|\hat{\Sigma}_R - \Sigma_R^*\|_\infty = O\left(\sqrt{\frac{\log p}{n}}\right).$$

Guarantee Sparsistency and Efficient Estimation in Both Domains

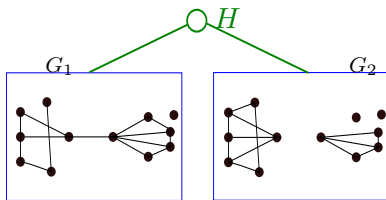
# Outline

- 1 Introduction
- 2 Decomposition of Graphical Model Mixtures
  - Estimation of Union Graph Structure
  - Parameter Estimation of Mixture Components
- 3 Decomposition into Markov and Independence Domains
- 4 Conclusion

# Summary and Outlook

## Learning Graphical Model Mixtures

- Tree mixture approximations
- Combinatorial search + spectral decomposition
- Computational and sample guarantees



## Markov/Independence Decomposition

- Efficient convex program for decomposition
- Similar requirements as graphical model selection

$$\begin{bmatrix} & \end{bmatrix} = \begin{bmatrix} & \end{bmatrix}^{-1} + \begin{bmatrix} & \end{bmatrix}$$

The equation shows a matrix decomposition. The first term is a blue matrix with a dashed blue circle around its upper triangular part. The second term is a red matrix with a dashed red circle around its upper triangular part. The matrices are added together.

## Outlook

- Converse results for learning graphical mixtures
- Mixed variables, latent models etc.