

High-Dimensional Covariance Decomposition into Sparse Markov and Independence Domains

Majid Janzamin and Anima Anandkumar

U.C. Irvine

High-Dimensional Covariance Estimation

- n i.i.d. samples, p variables $\mathbf{X} := [X_1, \dots, X_p]^T$.

- Covariance estimation:

$$\Sigma^* := \mathbb{E}[\mathbf{X}\mathbf{X}^T].$$

- High-dimensional regime: both $n, p \rightarrow \infty$ and $n \ll p$.
- Challenge: empirical (sample) covariance ill-posed when $n \ll p$:

$$\hat{\Sigma}^n := \frac{1}{n} \sum_{k=1}^n \mathbf{x}(k)\mathbf{x}(k)^T.$$

Solution: Imposing Sparsity for Tractable High-dimensional Estimation

Incorporating Sparsity in High Dimensions

Sparse Covariance

$$\begin{bmatrix} \\ \\ \\ \\ \\ \\ \\ \\ \\ \end{bmatrix} = \begin{bmatrix} \text{red squares} \\ \\ \\ \\ \\ \\ \\ \\ \\ \end{bmatrix}$$

Σ^* Σ_R^*

Sparse Inverse Covariance

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Relationship with Statistical Properties (Gaussian)

- Sparse Covariance (Independence Model): **marginal independence**

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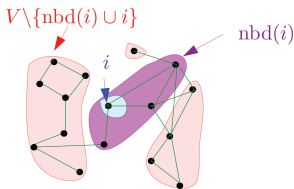
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Relationship with Statistical Properties (Gaussian)

- Sparse Inverse Covariance (Markov Model): conditional independence



Local Markov Property:

$$X_i \perp X_{V \setminus \{nbd(i) \cup i\}} \mid X_{nbd(i)}$$

For Gaussian:

$$J_{ij} = 0 \Leftrightarrow (i, j) \notin E$$

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Guarantees under Sparsity Constraints in High Dimensions

Consistent Estimation when $n = \Omega(\log p) \Rightarrow n \ll p$.

Consistent: **Sparsistent** and Satisfying reasonable **Norm Guarantees**.

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Going beyond Sparsity in High Dimensions?

Going Beyond Sparse Models

Motivation

- Sparsity constraints restrictive to have faithful representation.
 - Data not sparse in a single domain
 - **Solution: Sparsity in Multiple Domains.**
 - Challenge: Hard to impose sparsity in different domains
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One Possibility (This Work): Proposing Sparse Markov Model by adding Sparse Residual Perturbation

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Efficient Decomposition and Estimation in High Dimensions?

Unique Decomposition? Good Sample Requirements?

Summary of Results

$$\Sigma^* + \Sigma_R^* = J_M^{*-1}.$$

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- Decomposition into Markov and residual domains.
 - Statistically meaningful model
 - **Unification** of Sparse Covariance and Inverse Covariance Estimation.
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Contribution 2: Methods and Guarantees

- Conditions for unique decomposition (**exact statistics**).
- **Sparsistency** and **norm guarantees** in both Markov and independence domains (**sample analysis**)
- **Sample requirement**: no. of samples $n = \Omega(\log p)$ for p variables.

Efficient Method for Covariance Decomposition and Estimation in High-Dimension

Related Works

Sparse Covariance/Inverse Covariance Estimation

- Sparse Covariance Estimation: **Covariance Thresholding**.
 - ▶ (Bickel & Levina) (Wagaman & Levina) (Cai et. al.)
 - Sparse Inverse Covariance Estimation:
 - ▶ ℓ_1 **Penalization** (Meinshausen and Bühlmann) (Ravikumar et. al)
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Beyond Sparse Models: Decomposition Issues

- Sparse + Low Rank (Chandrasekaran et. al) (Candes et. al)
 - Decomposable Regularizers (Negahban et. al)
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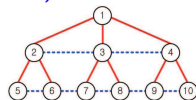
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Multi-Resolution Markov+Independence Models (Choi et. al)

- Decomposition in inverse covariance domain
- **Lack theoretical guarantees**



Our contribution: Guaranteed Decomposition and Estimation

Outline

- 1 Introduction
- 2 Algorithm**
- 3 Guarantees
- 4 Experiments
- 5 Proof Techniques
- 6 Conclusion

Some Intuitions and Ideas

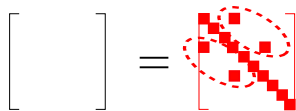
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- $\Sigma^* = \Sigma_I^*$.
- $\hat{\Sigma}^n$: sample covariance using n samples
- p variables: $p \gg n$.

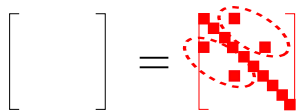


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- Hard-thresholding the off-diagonal entries of $\hat{\Sigma}^n$ (Bickel & Levina):

threshold chosen as


$$\sqrt{\frac{\log p}{n}}$$

- Sparsistency (support recovery) and Norm Guarantees when

$$n = \Omega(\log p) \Rightarrow n \ll p.$$

Recap of Inverse Covariance (Markov) Estimation

- $\Sigma^* = J_M^{*-1}$
 - $\hat{\Sigma}^n$: sample covariance
using n i.i.d. samples
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$$\begin{bmatrix} & \\ & \end{bmatrix} = \begin{bmatrix} & \\ & \end{bmatrix}^{-1}$$
A diagram illustrating the inverse of a sparse matrix. It shows a square matrix with a blue dashed border. Inside, a blue dashed circle highlights a small submatrix. The rest of the matrix is filled with blue squares, representing non-zero elements. The matrix is followed by a superscript -1, indicating its inverse.

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$$\hat{J}_M := \operatorname{argmin} \langle \hat{\Sigma}^n, J_M \rangle - \log \det J_M + \gamma \|J_M\|_{1,\text{off}}$$

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Consistent Estimation Under Certain Conditions, $n = \Omega(\log p)$

Extension to Markov+Independence Models?

$$\Sigma^* + \Sigma_R^* = J_M^{*-1}.$$

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Add ℓ_1 penalty to maximum likelihood program (involving inverse covariance matrix estimation)

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- Insight: Consider **dual program of MLE**
Dual program is in covariance domain for Markov model.

Our Algorithm: Covariance Decomposition

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- Extend ℓ_1 -penalized MLE

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Observations regarding the Proposed Method

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- $\lambda = \sqrt{\log p/n}$ reduces to approximate shrinkage estimator.

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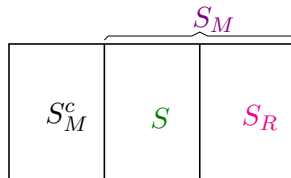
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KKT conditions results **identifiability** conditions.

- The main identifiability condition: $\text{Supp}(\Sigma_R^*) \subseteq \text{Supp}(J_M^*)$.

Node pairs are **partitioned** as follows:

$$\begin{aligned}S_M &:= \text{Supp}(J_M^*) \\ S_R &:= \text{Supp}(\Sigma_R^*) \\ S &:= S_M \setminus S_R\end{aligned}$$



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- 2 Algorithm
- 3 Guarantees**
- 4 Experiments
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- 6 Conclusion

Guarantees for High-Dimensional Estimation

$$\Sigma^* + \Sigma_R^* = J_M^{*-1}.$$

$$\begin{bmatrix} & \\ & \end{bmatrix} + \begin{bmatrix} & \\ & \end{bmatrix} = \begin{bmatrix} & \\ & \end{bmatrix}^{-1}$$

Conditions for Recovery

- Maximum degree Δ in the Markov graph (corresponding to J_M^*).
- Number of samples n , number of nodes p satisfy $n = \Omega(\Delta^2 \log p)$.
- Mutual-Incoherence type conditions.

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Theorem

The proposed method outputs estimates $(\hat{J}_M, \hat{\Sigma}_R)$ such that (w.h.p.)

- $(\hat{J}_M, \hat{\Sigma}_R)$ are **sparsistent** and **sign consistent**.
- satisfy **norm guarantees**.

$$\|\hat{J}_M - J_M^*\|_\infty, \|\hat{\Sigma}_R - \Sigma_R^*\|_\infty = O\left(\sqrt{\log p/n}\right).$$

Guarantee Sparsistency and Efficient Estimation in Both Domains

Observations

Corollary 1 (Sparse Covariance Estimation)

With $\lambda = \Theta(\sqrt{\log p/n})$, our method reduces to shrinkage estimator (comparable to Bickel & Levina which is hard-threshold estimator) and is sparsistent for covariance estimation.

Corollary 2 (Sparse Inverse Covariance Estimation)

With $\lambda \rightarrow \infty$, our method reduces to ℓ_1 -penalized MLE (Ravikumar et. al) and is sparsistent for inverse covariance estimation.

Conditions for Recovery

- Mutual incoherence-type conditions
- Sample complexity $n = \Omega(\Delta^2 \log p)$.
- Comparable to inverse covariance estimation (Ravikumar et. al).

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Synthetic Data

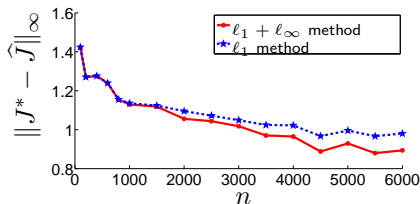
$$\Sigma^* + \Sigma_R^* = J_M^{*-1}, \quad J^* = (\Sigma^*)^{-1}.$$

$$\begin{bmatrix} & \\ & \end{bmatrix} + \begin{bmatrix} \text{red diagonal} & \\ & \end{bmatrix} = \begin{bmatrix} \text{blue diagonal} & \\ & \end{bmatrix}^{-1}$$

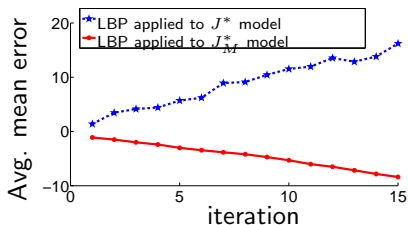
Setup

- 8×8 2-d grid for Markov model.
- Mixed Markov model (both positive and negative correlations).

J estimation



Performance under LBP

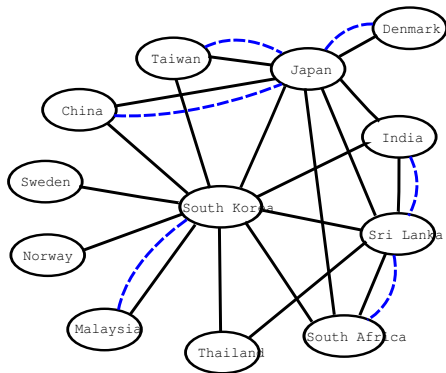


Learned model is amenable for efficient Inference.
 Advantage over existing techniques.

Experiments on Foreign Exchange Rate Data

Setup

- Monthly Foreign Exchange Rates to US Dollar.
- Apply the proposed method.

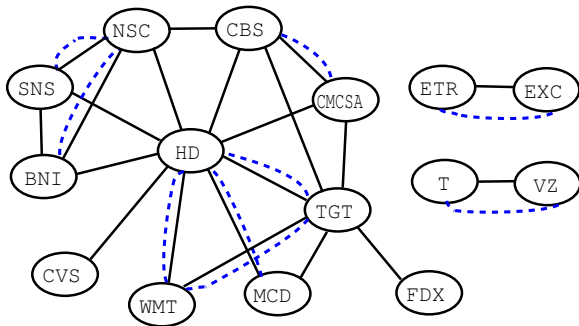


- Solid line: Markov graph. Dotted line: Independence graph.

Experiments on Stock Market Data

Setup

- Monthly stock returns of companies on S&P index.
- Companies in divisions **E.Trans**, **Comm**, **Elec&Gas** and **G.Retail Trade**.
- Apply the proposed method.



- Solid line: Markov graph. Dotted line: Independence graph.

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Analysis under Sample Statistics

$$\begin{aligned}\hat{J}_M &:= \operatorname{argmin}_{J_M \succ 0} \langle \hat{\Sigma}^n, J_M \rangle - \log \det J_M + \gamma \|J_M\|_{1,\text{off}} \\ &\text{s. t. } \|J_M\|_{\infty,\text{off}} \leq \lambda.\end{aligned}$$

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- Challenges

1) Sparsistency guarantee: hard to show $\text{Supp}(\hat{J}_M) \subseteq \text{Supp}(J_M^*)$.

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Challenges

- 1) **Sparsistency** guarantee: **hard** to show $\text{Supp}(\hat{J}_M) \subseteq \text{Supp}(J_M^*)$.
- 2) **Decoupling** the errors: $\Sigma^* + \Sigma_R^* = J_M^{*-1}$.

- Proposing a modified version which is **easier** to analyze.

Modified Program (**R**estricted and **R**elaxed)

$$\tilde{J}_M := \operatorname{argmin}_{J_M \succ 0} \langle \hat{\Sigma}^n, J_M \rangle - \log \det J_M + \gamma \|J_M\|_{1,\text{off}}$$

$$\text{s. t. } (J_M)_{S_M^c} = 0, \quad (J_M)_{S_R} = \lambda \operatorname{sign}\left((J_M^*)_{S_R}\right).$$



Primal-Dual Witness Method

$$\tilde{J}_M := \operatorname{argmin}_{J_M \succ 0} \langle \hat{\Sigma}^n, J_M \rangle - \log \det J_M + \gamma \|J_M\|_{1,\text{off}}$$

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Sparsistency Guarantee

$$\operatorname{Supp}(\tilde{J}_M) \subseteq \operatorname{Supp}(J_M^*)$$

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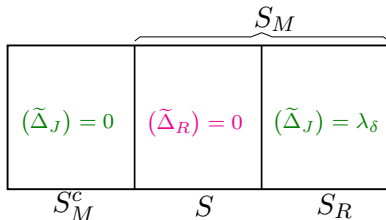
Sparsistency Guarantee

$$\operatorname{Supp}(\tilde{J}_M) \subseteq \operatorname{Supp}(J_M^*)$$

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Error Decoupling

$$\tilde{\Delta}_J := \tilde{J}_M - J_M^*, \quad \tilde{\Delta}_R := \tilde{\Sigma}_R - \Sigma_R^*$$



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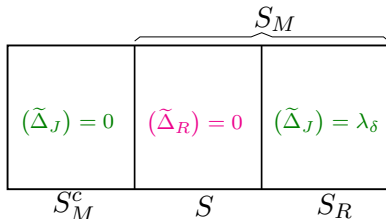
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- **Sufficient Conditions** for equivalence between the modified and original programs (**Mutual Incoherence**): $(\tilde{J}_M, \tilde{\Sigma}_R) = (\hat{J}_M, \hat{\Sigma}_R)$.

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Conclusion

Summary

- Combination of Markov and independence models
- Unifying sparse covariance/inverse covariance estimation methods
- Efficient method and guarantees for estimation in both domains

Conclusion

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-

Outlook

- Other forms of residuals (e.g. low rank)
- Discrete Model (via pseudo-likelihood)

<http://arxiv.org/abs/1211.0919>