YOLO IN



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SATRDAY'19



YOU ONLY LOOK ONCE (YOLO)

- YOLO is a state-of-the-art object detection algorithm that was first introduced by Redmon et al in 2015.
- It involves the combination of classification (class labels) and localisation (bounding box coordinates) of objects found in an image.
- It is popularly known for it's speed because the algorithm requires only one forward pass to make detections.

YOU ONLY LOOK ONCE (YOLO)

Summarised YOLO Process:

- □Step 1: Overlay a *KxK* grid on the image.
- □Step 2: For each grid cell, N bounding boxes, the associated localisation confidence scores, and the classification scores are predicted.
- **Step 3**: A set threshold (p ∈ [0,1]) is used to discard predicted bounding boxes with low localisation confidence scores.
- □Step 4: The bounding box that corresponds to the highest combined localisation and classification score is selected to be the detection.

LET'S YOLO IN R

SETUP

Install image.darknet Package via github:

devtools::install_github("bnosac/image", subdir = "image.darknet", build_vignettes = TRUE)

Required Libraries:



library(image.darknet)

I. INSTANTIATE DETECTION MODEL

Function: image_darknet_model(...)

Arguments:

- type = type of computer vision task ("detect" for object detection)
- model = file path to the model configuration
- weights= file path to the trained model weights
- labels = vector of labels

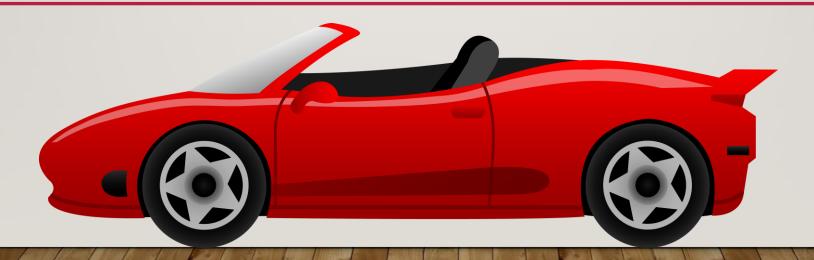
2. DETECT OBJECTS

Function: image_darknet_detect(...)

Arguments:

- file = image file path
- object = instantiated model object
- threshold = detection threshold

DEMO: CAR DETECTION



I. INSTANTIATE YOLO MODEL

2. DETECT CARS

```
x = image\_darknet\_detect(file = "example.png", \\ object = yolo\_model, \\ threshold = 0.65)
```

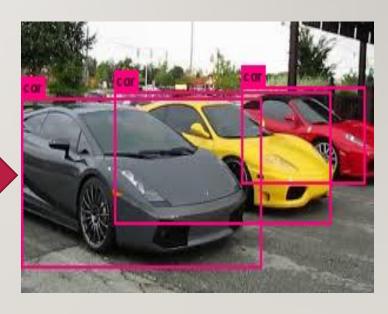
CAR DETECTION OUTPUT

Input



image_darknet_detect

Output



REFERENCES

- Redmon. J and Farhadi, A. 2016.
 YOLO9000: Better, Faster, Stronger. CoRR abs/1612.08242
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- Wijffels, J. 2017. Computer vision algorithms for R users.
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THANK YOU