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## 1 Buildings

**Definition 1.** *A Polyhedral complex is a certain finite dimensional CW-complex. Each  $n$ -cell of the polyhedral complex is*

**Definition 2.** *Suppose  $P$  is a simple convex polytope in  $X^n$ . Let  $F_i$  be the codimension-one faces of  $P$ . Suppose that, for any two faces  $F_i$  and  $F_j$ , if their intersection is non-empty, then the dihedral angle between the faces is  $\pi/m_{ij}$ , for some  $m_{ij}$  in  $2, 3, 4, \dots$ . Now set  $m_{ii} = 1$ ,  $m_{ij} = \infty$  if  $F_i, F_j$  empty intersection. Let  $s_i$  be the reflection of  $X^n$  across  $F_i$ , and let  $W$  be the group generated by the set of  $s_i$ 's. Then  $W$  is the Coxeter group with generators  $s_i$ , and Coxeter matrix  $(m_{ij})$ . Furthermore,  $W$  is a discrete subgroup of  $\text{Isom}(X^n)$ ,  $P$  is a strict fundamental domain for the  $W$  action, and  $P$  tiles  $X^n$ .*

**Definition 3.** *Let  $(W, S)$  be a Coxeter group generated by a simple convex polytope  $P$ . A building of type  $(W, S)$  is a polyhedral complex, which is a union of subcomplexes, called apartments. An apartment is isometric to the tiling of  $X^n$  derived from  $P$ , and each copy of  $P$  in the tiling is called a chamber. Now the apartments and chambers must satisfy*

1. *Given any two chambers, there exists an apartment containing both of them.*

2. Given any two apartments  $A$  and  $B$ , there exists an isometry from  $A$  to  $B$  which fixes  $A \cap B$  pointwise.

**Example 1.** Let us consider a single copy of  $X^n$ . We can tile this copy by  $P$ , and we get a thin building. This means that we only have one apartment. Clearly this satisfies the first condition - any two chambers immediately lie in the only apartment.

Now let us look at the second condition. If the two chambers have no intersection, then, as each chamber is a copy of  $P$ , they are clearly isometric, and we are done. Now if the two chambers have a non-empty intersection, we have two cases:

1. If they share a common edge, then reflection along this edge gives us our isometry.
2. If they only share a common point

**Example 2.** Now we can consider a spherical building. Take the Coxeter group

$$W = \langle s_1, s_2 | s_i^2 = 1, (s_1 s_2)^2 = 1 \rangle.$$

This Coxeter group is isomorphic to  $D_4$ .

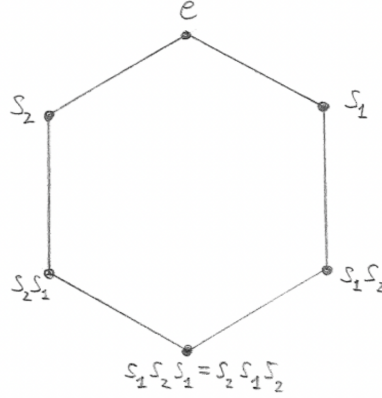
## 2 Cayley graphs

**Definition 4.** The Cayley graph  $\text{Cay}(G, S)$  of a group  $G$  with respect to a generating set  $S$ ,  $1 \notin S$ , is the graph  $(V, E)$ , with  $V = G$ , and directed edges

$$E = \{(g, gs) | g \in G, s \in S\}.$$

If  $s \in S$  is an involution, we only put a single undirected edge between  $g$  and  $gs$ , and label the edge  $s$ .

**Example 3.** The Cayley graph of  $D_6$ , with generating set  $\{s_1, s_2\}$  is



### 3 Reflection systems

**Definition 5.** Let  $G$  be a group. A pre-reflection system for  $G$  is a pair  $(X, R)$ .  $X$  is a connected simplicial graph which is acted upon by  $G$ , and  $R$  is a subset of  $G$ . This must satisfy

1. every element of  $R$  is an involution;
2.  $R$  is closed under conjugation;
3.  $R$  generates  $G$ ;
4. given an edge of  $X$ , there is a unique element of  $R$  which flips the edge;  
and
5. for every element  $r$  of  $R$ , there is at least one edge of  $X$  which is flipped by  $r$ .

**Example 4.** Let  $(W, S)$  be any Coxeter system. Let  $X$  be the Cayley graph of  $(W, S)$ , and let

$$R = \{wsw^{-1} | w \in W, s \in S\}.$$

Then  $(X, R)$  is a pre-reflection system.

**Definition 6.** Consider a pre-reflection system  $(X, R)$ . For each element  $r$  of  $R$ , the wall  $H_r$  is the set of midpoints of all the edges flipped by  $r$ .

**Definition 7.** Consider a pre-reflection system  $(X, R)$ . If, additionally, it satisfies

6. for every element  $r$  in  $R$ ,  $X \setminus H_r$  has exactly two components,  
then  $(X, R)$  is a reflection system.

**Theorem 1.** Suppose we have a group  $W$ , generated by a set  $S$  of distinct involutions. Then the following are equivalent:

1.  $(W, S)$  is a Coxeter system;
2.  $(X, R)$  is a reflection system, where  $X = \text{Cay}(W, S)$  and

$$R = \{wsw^{-1} | w \in W, s \in S\}.$$

3.  $(W, S)$  satisfies the Deletion Condition; and
4.  $(W, S)$  satisfies the Exchange Condition.

## 4 Tits' solution to the word problem

**Definition 8.** Let  $W$  be generated by a set  $S$  of distinct involutions. Let  $s, t \in S$ , with  $s \neq t$ , and let  $m_{st}$  be the order of  $st$  in  $W$ . If  $m_{st}$  is finite, consider a word in  $S$  with the subword  $sts\dots$  with  $m_{st}$  letters. A braid move on the word replaces the subword  $sts\dots$  with  $tst\dots$ , again with  $m_{st}$  letters.

**Theorem 2.** (Tits) Suppose we have a group  $W$ , generated by a set  $S$  of distinct involutions. Also suppose that the Exchange Condition holds. Then

1. A word  $s_1s_2\dots s_k$  is reduced iff we cannot shorten it by a sequence of
  - deleting an instance of  $ss$  from the word, or
  - applying a braid move to the word.
2. Two reduced words will represent the same group element iff a sequence of braid moves sends one to the other.

## 5 Tits' Representation Theorem

**Theorem 3.** (*Tits' Representation Theorem*) Let  $(W, S)$  be a Coxeter system. Then there is a map

$$\rho : W \longrightarrow GL(N, \mathbb{R})$$

which is a faithful representation, with  $N = |S|$ , such that

1.  $\sigma_i = \rho(s_i)$  is a linear involution, whose fixed set is a hyperplane; and
2. If  $s_i, s_j \in S$  are distinct, then  $\sigma_i \sigma_j$  has order  $m_{ij}$ .

**Definition 9.** The representation  $\rho$  above is called the Tits representation, or sometimes the standard geometric representation.

### 5.1 Corollaries

## 6 Construction of a geometric realisation

### 6.1 Simplicial complexes

**Definition 10.** Let  $V$  be a, possibly infinite, set, called the vertex set. Let  $X$  be a collection of finite subsets of  $V$  such that

1.  $\{v\} \in X$  for all elements  $v \in V$ ; and
2. if  $\Delta \in X$  and  $\Delta'$  is a subset of  $\Delta$ , then  $\Delta'$  is in  $X$ .

Then  $(V, X)$  is an abstract simplicial complex.

**Definition 11.** A simplex is any element of  $X$ . A simplex  $\Delta$  has dimension

$$\dim \Delta = |\Delta| - 1.$$

A simplex of dimension  $k$  is called a  $k$ -simplex. A 0-simplex is called a vertex, and a 1-simplex is called an edge, intuitively. The set of all simplices of dimension  $k$  is the  $k$ -skeleton  $X^{(k)}$ .

**Lemma 1.** The  $k$ -skeleton is also a simplicial complex.

**Definition 12.** *The dimension of  $X$  is*

$$\dim X = \max\{\dim(\Delta) \mid \Delta \in X\}.$$

*If all the maximal elements of  $X$  have the same dimension, then the simplicial complex is pure.*

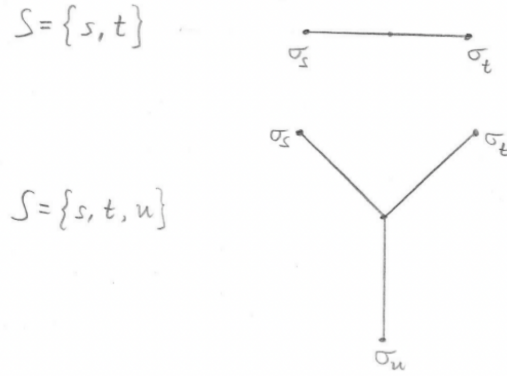
**Definition 13.** *The standard  $n$ -simplex  $\Delta^n$  is the convex hull of the  $(n+1)$  points  $(1, 0, \dots, 0), \dots, (0, \dots, 0, 1)$  in  $\mathbb{R}^{n+1}$ .*

Given an  $n$ -simplex  $\Delta$  in  $X$ , we can identify  $\Delta$  with a copy of  $\Delta^n$ .

## 6.2 The basic construction

**Definition 14.** *Let  $X$  be a connected Hausdorff topological space. Let  $(W, S)$  be a Coxeter system. Let  $(X_s)_{s \in S}$  be a collection of non-empty, closed subspaces of  $X$ . Then  $(X_s)_{s \in S}$  is a mirror structure on  $X$  over  $S$ , and  $X_s$  is called the  $s$ -mirror.*

**Example 5.** *Consider the cone with  $|S|$  vertices. This is the graph with a node in the centre, and a branch for each element in  $|S|$ . Label the vertices  $\{\sigma_s \mid s \in S\}$ . Then we can set  $X_s = \sigma_s$ . This means that we take, for each element of  $S$ , the closed set of a single point as the  $s$ -mirror.*



**Example 6.** *Consider the  $n$ -simplex, with  $n = |S| - 1$ . Let  $\{\Sigma_s \mid s \in S\}$  be the codimension-one faces. Now let  $X_s = \Sigma_s$ . This means that we take, for every element of  $S$ , a codimension-one element of the simplex as the  $s$ -mirror.*

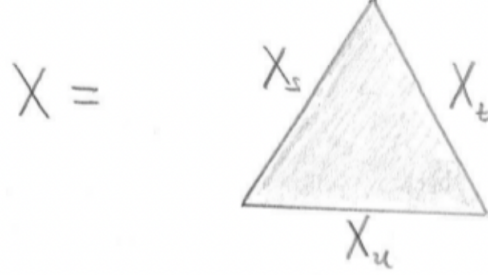


Figure 4.3:  $X$  is a 2-simplex, with codimension-one faces  $\{\Delta_s \mid s \in S\}$  where  $S = \{s, t, u\}$ .

**Definition 15.** For each  $x \in X$ , define the set

$$S(x) := \{s \in S \mid x \in X_s\}.$$

**Example 7.** From example 5, we have

$$S(x) = \begin{cases} \emptyset, & \text{if } x \notin \{\sigma_s \mid s \in S\}, \\ \{s\}, & \text{if } x = \sigma_s. \end{cases}$$

**Example 8.** From example 6, we have

We now want to define an equivalence relation on  $W \times X$ .

**Definition 16.**  $(w, x)$  is equivalent to  $(w'x')$ , i.e  $(w, x) \sim (w'x')$ , if and only if  $x = x'$  and  $w^{-1}w' \in W_{S(x)}$ .

Now we want to equip our group  $W$  with the discrete topology, and then  $W \times X$  with the product topology. Then we define

$$\mathcal{U}(W, X) = W \times X / \sim .$$

Now we will denote by  $[w, x]$  the equivalence class of  $(w, x)$ , and we will write  $wX$  for the image of  $\{w\} \times X$  in  $\mathcal{U}(W, X)$ . Now this must be well-defined, as  $x \mapsto [w, x]$  is an embedding. We call each  $wX$  a chamber.

**Example 9.** Let  $W$  be the  $(3, 3, 3)$ -triangle group, i.e

$$W = \langle s, t, u | s^2 = t^2 = u^2 = 1, (st)^3 = (tu)^3 = (us)^3 = 1 \rangle.$$

Now we let our topological space be  $X = \text{Cone}\{\sigma_s, \sigma_t, \sigma_u\}$ . So we have

$$S(x) = \begin{cases} \emptyset, & \text{if } x \notin \{\sigma_s, \sigma_t, \sigma_u\} \\ \{s\}, \{t\}, \{u\} & \text{if } x = \sigma_s, \sigma_t, \sigma_u \text{ resp.} \end{cases}$$