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# 1 Buildings

**Definition 1.** A Polyhedral complex is a certain finite dimensional CW-complex. Each n-cell of the polyhedral complex is

**Definition 2.** Suppose P is a simple convex polytope in  $X^n$ . Let  $F_i$  be the codimension-one faces of P. Suppose that, for any two faces  $F_i$  and  $F_j$ , if their intersection is non-empty, then the dihedral angle between the faces is  $p_i/m_{ij}$ , for some  $m_{ij}$  in  $2, 3, 4, \ldots$  Now set  $m_{ii} = 1, m_{ij} = \inf$  if  $F_i$ ,  $F_j$  empty intersection. Let  $s_i$  be the reflection of  $X^n$  across  $F_i$ , and let W be the group generated by the set of  $S_i$ . Then  $S_i$  is the Coxeter group with generators  $S_i$ , and Coxeter matrix  $S_i$ . Furthermore,  $S_i$  is a discrete subgroup of  $S_i$  is a strict fundamental domain for the  $S_i$  and  $S_i$  is a strict fundamental domain for the  $S_i$  in  $S_i$  is a strict fundamental domain for the  $S_i$  in  $S_i$  in  $S_i$  is a strict fundamental domain for the  $S_i$  in  $S_i$  in S

**Definition 3.** Let (W, S) be a Coxeter group generated by a simple convex polytope P. A building of type (W, S) is a polyhedral complex, which is a union of subcomplexs, called apartments. An apartment is isometric to the tiling of  $X^n$  derived from P, and each copy of P in the tiling is called a chamber. Now the apartments and chambers must satisfy

- 1. Given any two chambers, there exists an apriment containing both of them.
- 2. Given any two apartments A and B, there exists an isometry from A to B which fixes  $A \cap B$  pointwise.

**Example 1.** Let us consider a single copy of  $X^n$ . We can tile this copy by P, and we get a thin building. This means that we only have one apartment. Clearly this satisfies the first condition - any two chambers immediately lie in the only apartment.

Now let us look at the second condition. If the two chambers have no intersection, then, as each chamber is a copy of P, they are clearly isometric, and we are done. Now if the two chambers have a non-empty intersection, we have two cases:

- 1. If they share a common edge, then reflection along this edge gives us our isometry.
- 2. If they only share a common point

**Example 2.** Now we can consider a spherical building. Take the Coxeter group

$$W = \langle s_1, s_2 | s_i^2 = 1, (s_1 s_2)^2 = 1 \rangle.$$

This Coxeter group is isomorphic to  $D_4$ .

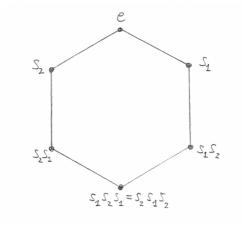
## 2 Cayley graphs

**Definition 4.** The Cayley graph Cay(G,S) of a group G with respect to a generating set S,  $1 \notin S$ , is the graph (V,E), with V=G, and directed edges

$$E = \{(g,gs)|g \in G, s \in S\}.$$

If  $s \in S$  is an involution, we only put a single undirected edge between g and gs, and label the edge s.

**Example 3.** The Cayley graph of  $D_6$ , with generating set  $\{s_1, s_2\}$  is



# 3 Reflection systems

**Definition 5.** Let G be a group. A pre-reflection system for G is a pair (X, R). X is a connected simplicial graph which is acted upon by G, and R is a subset of G. This must satisfy

- 1. every element of R is an involution;
- 2. R is closed under conjugation;
- 3. R generates G;
- 4. given an edge of X, there is a unique element of R which flips the edge; and
- 5. for every element r of R, there is at least one edge of X which is flipped by r.

**Example 4.** Let (W, S) be any Coxeter system. Let X be the Cayley graph of (W, S), and let

$$R = \{wsw^{-1} | w \in W, s \in S\}.$$

Then (X, R) is a pre-reflection system.

**Definition 6.** Consider a pre-reflection system (X, R). For each element r of R, the wall  $H_r$  is the set of midpoints of all the edges flipped by r.

**Definition 7.** Consider a pre-reflection system (X, R). If, additionally, it satisfies

6. for every element r in R,  $X\backslash H_r$  has exactly two components, then (X,R) is a reflection system.

**Theorem 1.** Suppose we have a group W, generated by a set S of distinct involutions. Then the following are equivalent:

- 1. (W, S) is a Coxeter system;
- 2. (X,R) is a reflection system, where X = Cay(W,S) and

$$R = \{wsw^{-1} | w \in W, s \in S\}.$$

- 3. (W, S) satisfies the Deletion Condition; and
- 4. (W, S) satisfies the Exchange Condition.

### 4 Tits' solution to the word problem

**Definition 8.** Let W be generated by a set S of distinct involutions. Let  $s, t \in S$ , with  $s \neq t$ , and let  $m_{st}$  be the order of st in W. If  $m_{st}$  is finite, consider a word in S with the subword sts... with  $m_{st}$  letters. A braid move on the word replaces the subword sts... with tst..., again with  $m_{st}$  letters.

**Theorem 2.** (Tits) Suppose we have a group W, generated by a set S of distinct involutions. Also suppose that the Exchange Condition holds. Then

- 1. A word  $s_1s_2...s_k$  is reduced iff we cannot shorten it by a sequence of
  - deleting an instance of ss from the word, or
  - applying a braid move to the word.
- 2. Two reduced words will represent the same group element iff a sequence of braid moves sends one to the other.

### 5 Tits' Representation Theorem

**Theorem 3.** (Tits' Representation Theorem) Let (W, S) be a Coxeter system. Then there is a map

$$\rho: W \longrightarrow GL(N, \mathbb{R})$$

which is a faithful representation, with N = |S|, such that

- 1.  $\sigma_i = \rho(s_i)$  is a linear involution, whose fixed set is a hyperplane; and
- 2. If  $s_i, s_j \in S$  are distinct, then  $\sigma_i \sigma_j$  has order  $m_{ij}$ .

**Definition 9.** The representation  $\rho$  above is called the Tits representation, or sometimes the standard geometric representation.

#### 5.1 Corollaries

### 6 Construction of a geometric realisation

### 6.1 Simplicial complexes

**Definition 10.** Let V be a, possibly infinite, set, called the vertex set. Let X be a collection of finite subsets of V such that

- 1.  $\{v\} \in X$  for all elements  $v \in V$ ; and
- 2. if  $\Delta \in X$  and  $\Delta'$  is a subset of  $\Delta$ , then  $\Delta'$  is in X.

Then (V, X) is an abstract simplicial complex.

**Definition 11.** A simplex is any element of X. A simplex  $\Delta$  has dimension

$$\dim \Delta = |\Delta| - 1.$$

A simplex of dimension k is called a k-simplex. A 0-simplex is called a vertex, and a 1-simplex is called an edge, intuitively. The set of all simplices of dimension k is the k-skeleton  $X^{(k)}$ .

Lemma 1. The k-skeleton is also a simplicial complex.

**Definition 12.** The dimension of X is

$$\dim X = \max\{\dim(\Delta)Delta \in X\}.$$

If all the maximal elements of X have the same dimension, then the simplicial complex is pure.

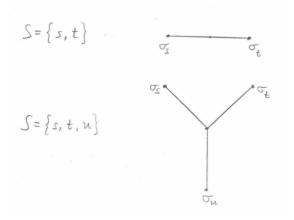
**Definition 13.** The standard n-simplex  $\Delta^n$  is the convex hull of the (n+1) points (1,0,...,0),...,(0,...,0,1) in  $\mathbb{R}^{n+1}$ .

Given an n-simplex  $\Delta$  in X, we can identify  $\Delta$  with a copy of  $\Delta^n$ .

#### 6.2 The basic construction

**Definition 14.** Let X be a connected Hausdorff topological space. Let (W, S) be a Coxeter system. Let  $(X_s)_{s \in X}$  be a collection of non-empty, closed subspaces of X. Then  $(X_s)_{s \in X}$  is a mirror structure on X over S, and  $X_s$  is called the s-mirror.

**Example 5.** Consider the cone with |S| vertices. This is the graph with a node in the centre, and a branch for each element in |S|. Label the vertices  $\{\sigma_s|s\in S\}$ . Then we can set  $X_s=\sigma_s$ . This means that we take, for each element of S, the closed set of a single point as the s-mirror.



**Example 6.** Consider the n-simplex, with n = |S| - 1. Let  $\{\Sigma_s | s \in S\}$  be the codimension-one faces. Now let  $X_s = \Sigma_s$ . This means that we take, for every element of S, a codimension-one element of the simplex as the s-mirror.

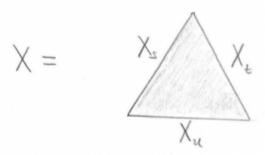


Figure 4.3: X is a 2-simplex, with codimension-one faces  $\{\Delta_s \mid s \in S\}$  where  $S = \{s, t, u\}$ .

**Definition 15.** For each  $x \in X$ , define the set

$$S(x) := \{ s \in S | x \in X_s \}.$$

**Example 7.** From example 5, we have

$$S(x) = \begin{cases} \emptyset, & \text{if } x \notin \{\sigma_s | s \in S\}, \\ \{s\}, & \text{if } x = \sigma_s. \end{cases}$$

**Example 8.** From example 6, we have

We now want to define an equivalence relation on  $W \times X$ .

**Definition 16.** (w, x) is equivalent to (w'x'), i.e  $(w, x) \sim (w'x')$ , if and only if x = x' and  $w^{-1}w' \in W_{S(x)}$ .

Now we want to equip our group W with the discrete topology, and then  $W \times X$  with the product topology. Then we define

$$\mathcal{U}(W,X) = W \times X/\sim$$
.

Now we will denote by [w, x] the equivalence class of (w, x), and we will write wX for the image of  $\{w\} \times X$  in  $\mathcal{U}(W, X)$ . Now this must be well-defined, as  $x \mapsto [w, x]$  is an embedding. We call each wX a chamber.

**Example 9.** Let W be the (3,3,3)-triangle group, i.e

$$W = \langle s, t, u | s^2 = t^2 = u^2 = 1, (st)^3 = (tu)^3 = (us)^3 = 1 \rangle.$$

Now we let our topological space be  $X = Cone\{\sigma_s, \sigma_t, \sigma_u\}$ . So we have

$$S(x) = \begin{cases} \emptyset, & \text{if } x \notin \{\sigma_s, \sigma_t, \sigma_u\}, \\ \{s\}, \{t\}, \{u\} & \text{if } x = \sigma_s, \sigma_t, \sigma_u \text{ resp.} \end{cases}$$

So  $W_{S(x)}$  is one of  $1, \{1, s\}, \{1, t\}, \text{ or } \{1, u\}.$ 

**Definition 17.** Let (W, S) be a Coxeter system. Let X be a simplex with codimension-one faces  $\{\Sigma_s|s\in S\}$ . Then  $\mathcal{U}(W,X)$  is called the Coxeter complex.

### **6.3** Properties of $\mathcal{U}(W,X)$

**Lemma 2.** As a topological space  $\mathcal{M}(W,X)$  is connected.

**Definition 18.** We define  $\mathcal{U}(W,X)$  as locally finite if, given  $[w,x] \in \mathcal{U}(W,X)$ , we can find an open neighbourhood of [w,x] which meets only a finite number of chambers.

**Lemma 3.** The following are equivalent:

- 1.  $\mathcal{U}(W,X)$  is locally finite;
- 2. given any  $x \in X$ ,  $W_{S(x)}$  is finite;
- 3. Given any  $T \subset S$  such that its special subgroup  $W_T$  is infinite, we have  $\bigcap_{x \in T} X_t = \emptyset$ .

**Example 10.** Let  $W = \langle s, t, u | s^2 = t^2 = u^2 = 1, (st)^3 = (tu)^3 = (us)^3 = 1 \rangle$ . The Coxeter complex of W is not locally finite.

### **6.4** Action of W on $\mathcal{U}(W,X)$