## **JOURNAL PUBLICATIONS**

- 1. Rithu R, R Karthikeyan, "Comparison of PID and Adaptive Controller for Pitch and Roll motion of Humanoid Arm", Journal of Computational and Theoretical Nanoscience", Jan. 2020; 17(1), pp 87-91.
- 2. Rachapalle Reddi Sudhir, P. Pavani Murthy, Sirisha Tadepalli, Subashree Murugan, Prema Padmanabhan, Ashwini Krishnamurthy, Stephanie L. Dickinson, R. Karthikeyan, Uday B. Kompella, Sangly P. Srinivas, "Ocular spot fluorometer equipped with a lock-in amplifier", Translational Vision Science & Technology(TVST), Association for Research in Vision and Ophthalmology Inc. Nov. 2018; 7(6):32.
- 3. Rithu R. and R. Karthikeyan, "Fuzzy tuned Proportional Integral controller with decouplers for quadruple tank process", International Journal of Control Theory and Applications, Volume 10(9), pp 831-839, 2017.
- 4. R.Karthikeyan, Bhargav. Ch, Karthik .Koneru, Syam .G, Shikha Tripathi and KVV. Murthy, "Enhanced MRAC based parallel cascade control strategy for unstable process with application to a continuous bioreactor", Advances in Intelligent Systems and Computing (Springer), Volume 235, pp 283-291, 2014.
- R.Karthikeyan, Sreekanth Pasam, S. Sudheer, Vallabhaneni Teja and Shikha Tripathi, "Fuzzy fractional order PID based parallel cascade control system", Advances in Intelligent Systems and Computing (Springer), Volume 235, pp 293-302, 2014.

Indexed by: SCOPUS (Elsevier); Impact Factor (SJR): 0.4

## **CONFERENCE PUBLICATIONS**

- 1. Rithu R, R Karthikeyan, "Comparison of PID and Adaptive Controller for Pitch and Roll motion of Humanoid Arm", Proc. 1st International Conference on **Intelligent Computing (ICIC 2018), Bengaluru, India, 2**5th 27th October, 2018.
- 2. R. Sunitha, R.Karthikeyan, "High Voltage Capacitor Discharge during Crash in Automobiles", Proc. International Conference on Emerging Trends in Engineering and Technology, Mysuru, India, 21 August 2016, pp. 51 55.

3. GV Sai Yeswanth, Sakshi Singh, Akash Kannegulla, R.Karthikeyan, "The Modelling of an Autonomous Triple Mode Vehicle", Proc. Of the International Conference on Advanced in Mechanical and Robotics Engineering – MRE 2014, Kuala Lumpur, Malaysia, 8-9 March 2014, pp. 45-48.