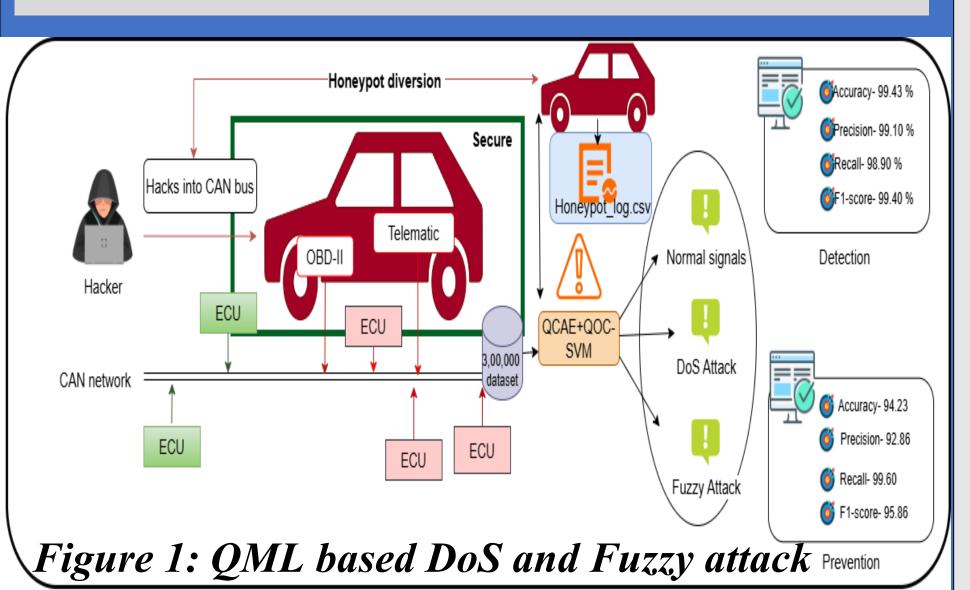


Dissertation Phase II- 18CA497

ABSTRACT

In this study, we introduce an advanced cybersecurity framework for both detection and prevention of Denial-of-Service DoS and Fuzzy attacks on the CAN bus of autonomous vehicles, leveraging Quantum Machine Learning for enhanced threat detection and using a honeypot-based intrusion prevention system for real-time mitigation



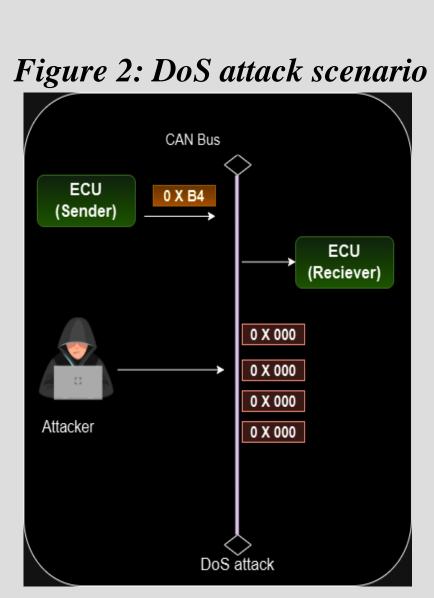
detection and prevention

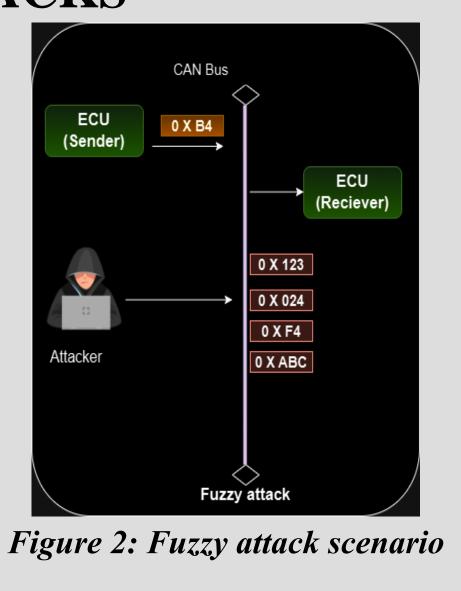
OBJECTIVES

INTRODUCTION

- Develop a QML model to detect DoS and fuzzy attacks on the CAN bus.
- Use quantum autoencoders and SVMs for traffic classification.
- Compare model performance with ML, DL, and QML baselines.
- Build a real-time honeypot system for attack prevention.
- Test system scalability, speed, and real-time efficiency.

COMPARISION OF DOS VS FUZZY ATTACKS





DETECTION AND PREVENTION OF DOS AND FUZZY CAN BUS ATTACKS ON AUTONOMOUS CAR USING QUANTUM MACHINE LEARNING

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PROPOSED MODEL FOR DETECTION

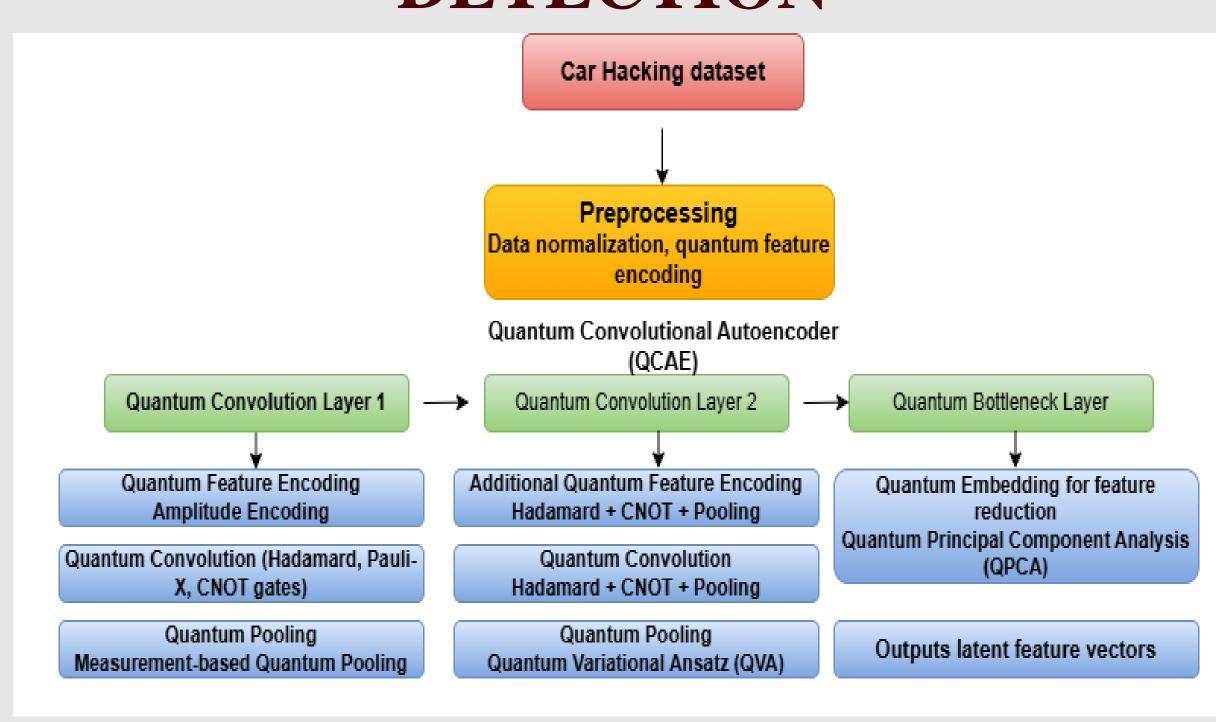


Figure 2: Quantum Convolutional Autoencoder (QCAE)

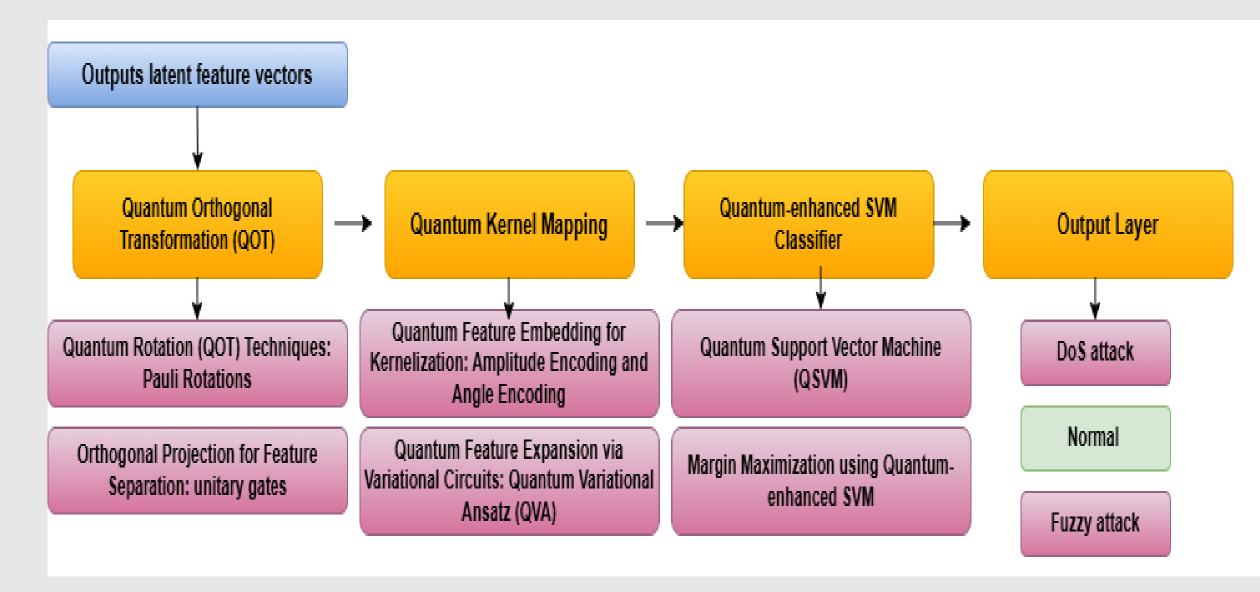


Figure 3: Quantum Orthogonal Classifier with SVM (QOC-SVM)

PROPOSED MODEL FOR PRVENTION

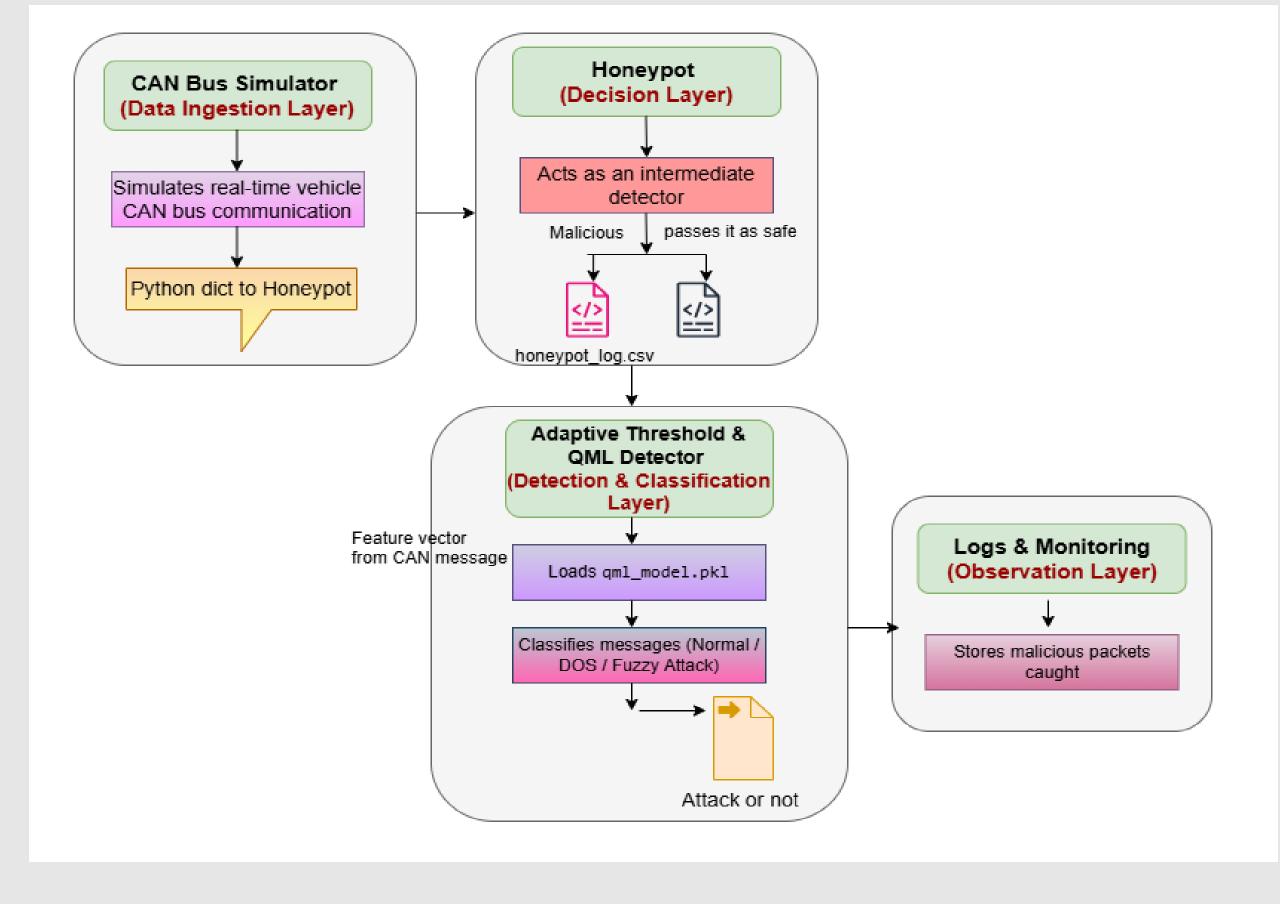
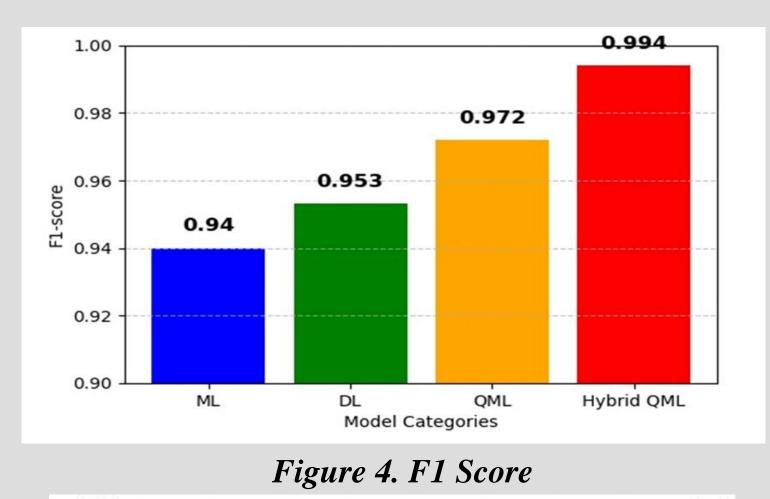


Figure 4:QML based Honeypot prevention model

EXPERIMENTAL RESULTS

Models	Accuracy	Precision	Recall	F1-score	No. of Batches: Batch Size						
Models	(%)	FIECISIOII	Necali		No. of Batches. Batch Size						
Machine Learning											
SVM	84.31	0.89	0.84	0.84	6000:40						
RF	88.95	0.89	0.89	0.89	6153:39						
KNN	94.05	0.94	0.94	0.94	-						
Naive Bayes	94.31	0.94	0.94	0.94	-						
XGB	91.00	0.91	0.91	0.91	-						
Deep Learning											
CNN	94.50	0.9453	0.9457	0.9445	7500:32						
MLP	93.80	0.92	0.926	0.929	6154:39						
FNN	95.00	0.9510	0.950	0.9530	7500:32						
Models	Accuracy	Precisi	Recall	F1-	No. of Batches: Batch						
	(%)	on		score	Size						
QML											
QAE	97.30	0.97	0.93	0.972	4897:49						
VQC	91.05	0.92	0.91	0.91	2891:83						
QSVM	97.80	0.978	0.96	0.965	6000:40						
QKNN	82.61	0.88	0.83	0.82	13333:18						
Hybrid QML											
QAE+QRF	93.26	0.9298	0.9278	0.9328	4363:55						
QAE+QKNN	94.98	0.9470	0.9450	0.9500	4897:49						
QCAE+QOC-	<mark>99.43</mark>	0.991	<mark>0.989</mark>	<mark>0.994</mark>	<mark>7741:31</mark>						
SVM											

Table 1. Experimental Results of detection



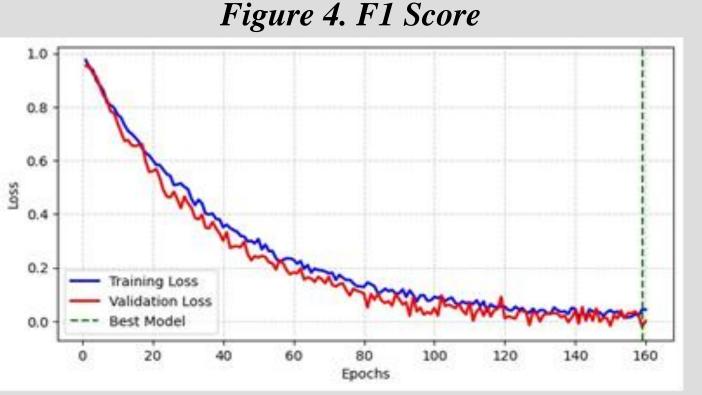


Figure 5. Learning curve

Model	Threshold Dos: Fuzzy: Normal	Accur acy (%)	Precision	Recall	F1 score				
QCAE +QOC- SVM	0.4: 0.3: 0.7	80	68.72	89.60	80.94				
QCAE +QOC- SVM	0.5: 0.5: 0.5	86	72.34	88.56	89.996				
QCAE +QOC- SVM	0.6: 0.6: 0.8	<mark>94.29</mark>	<mark>92.86</mark>	99.06	<mark>95.86</mark>				
Table 1. Experimental Results of Prevention									

100 Accuracy (%)
95 F1 Score

80 75

0.5:0.5:0.5

Threshold (DoS:Fuzzy:Normal)

0.6:0.6:0.8

Figure 6. Accuracy & F1 score vs Threshold

0.4:0.3:0.7

CONCLUSION

This research proposes an integrated detection and prevention framework to secure autonomous vehicles against Denial of Service (DoS) and Fuzzy Attacks on the CAN bus using Quantum Machine Learning (QML).

The detection system uses:

- Quantum Convolutional Autoencoder (QCAE) for feature extraction.
- Quantum Orthogonal Classifier with SVM (QOC-SVM) for message classification.

 The QCAE+QOC-SVM hybrid model effectively distinguishes Normal, DoS, and Fuzzy signals, achieving:
- F1-Score: 99.43%
- On a dataset of over 300,000 CAN messages (public + simulator-generated).
- The model demonstrates robustness and flexibility, requiring minimal supervision and adapting well to complex traffic patterns.
 - The prevention system is integrated into a honeypot setup:

 Malicious messages are detected in real time
 - Malicious messages are detected in real-time.
- Redirected to logging mechanisms, preventing them from affecting the vehicle's control system.
- The prevention layer achieved:
- Accuracy: 94.29%
- F1-Score: 95.86%
- Proving it to be highly reliable and responsive in mitigating real-time threats.

CONFERENCE AND PUBLICATION

- 1. QCAE-QOC-SVM: A Hybrid Quantum Machine Learning Model for DoS and Fuzzy Attack Detection on Autonomous Vehicle CAN Bus.-MethodsX jornal-Submitted.
- 2. Autonomous Vulnerabilities: An In-Depth Review of Cyber Attacks Targeting Self-Driving Cars and Sustainable Development Goals **yet to submit**.
- 3. A Smart Honeypot-Based Intrusion Prevention Framework for Securing In-Vehicle Networks Against DoS and Fuzzy Threats **yet to submit**.

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