#### **Project: Credit card detection**

#### Method

- 1. Edge detection for the input image is performed. Detected edges will be helpful in extracting structural objects in the image. Edge detection is done using cv2.canny function.
- 2. Contours are obtained using cv2.findContours function. Detected edge map is passed as input to the function.
- 3. The contours are sorted in decreasing order of area. This is done to avoid selection of minute details in the next step.
- 4. The contours are processed to check if the contour approximates a quadrilateral.
- 5. The contour approximating a polygon with 4 corners is selected and drawn on the input image to explicitly show the detected contour.

#### **Results and Evaluation**

### **Positive Examples**

#### **INPUT IMAGE**

#### **DETECTED CONTOUR**



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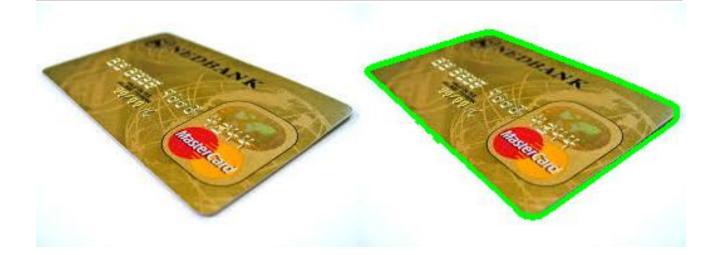












#### **Failure cases**

# Wrong contour detected











The pattern in card causes prediction of incomplete contour of the card and the quadrilateral check fails. This causes detection of smaller polygon.

# **Update on failure cases**

I evaluated for below design choices

- 1. Choosing contour of largest perimeter
- 2. Approximating bounding rectangle based on largest contour

Method 1 Method 2













# **Update on Failure cases**

I experimented with blurring the images before extracting edges from them. I can find the results are improved for selective cases

**Before Blurring** 



**After Blurring** 







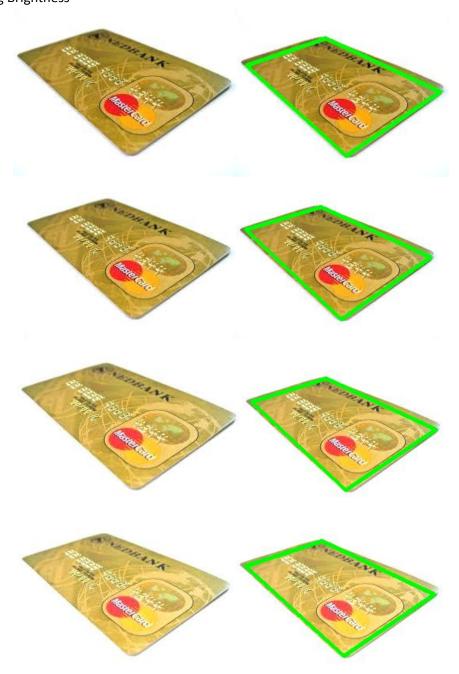
# No improvement in this case



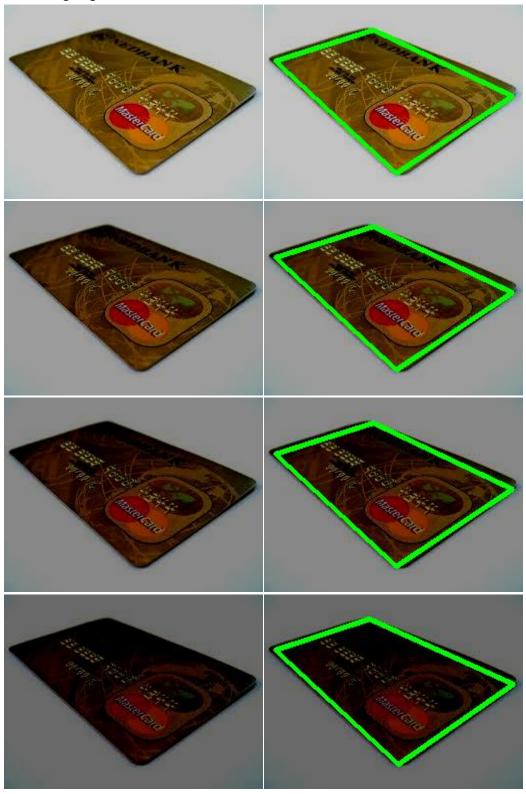


# **Evaluations**

# Light Variation Positive Examples Increasing Brightness

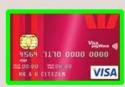


# Decreasing Brightness



# **Increasing Brightness**

























# **Decreasing Brightness**



# **Failure Cases**



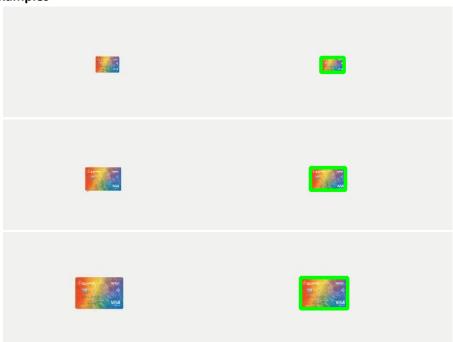
# 2. Blur Variation Positive Examples

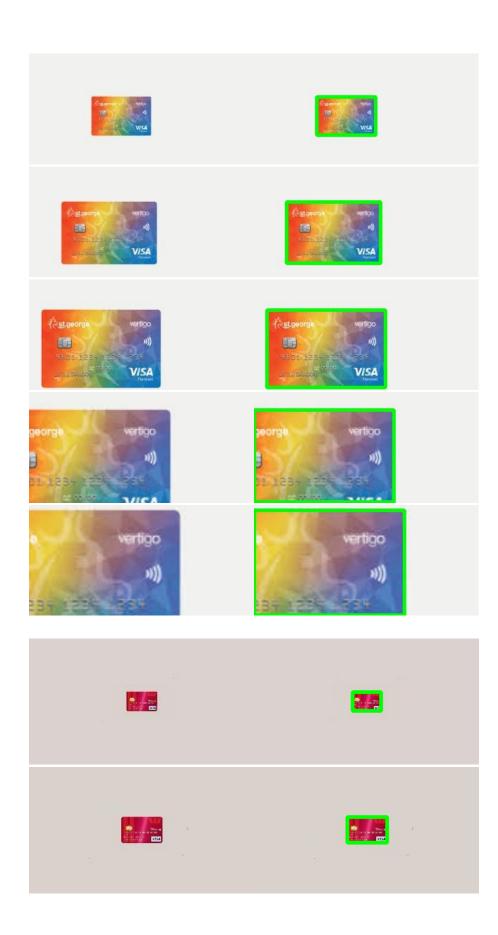






# 3. Scale Variation Positive Examples



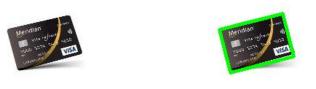














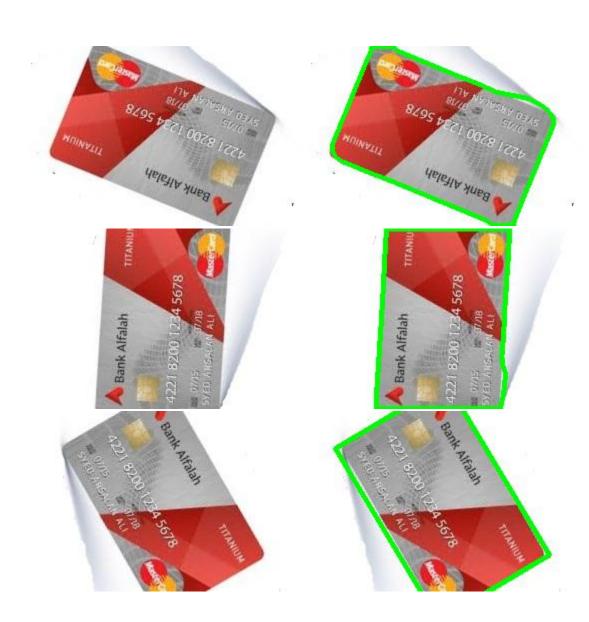


# 4. Position Variation



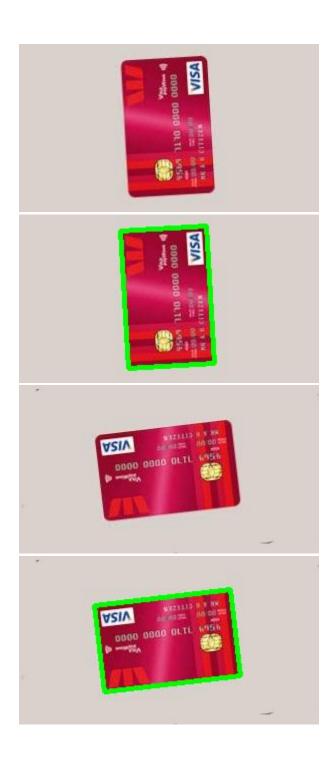












# Failure cases

