

Лабораторная работа №6

По курсу "нейроинформатика"

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группа: М8О-406Б-19

Цель работы:

Исследование свойств слоя Кохонена, карты Кохонена, а также сетей векторного квантования, обучаемых с учителем, алгоритма обучения, а также применение сетей в задачах кластеризации и классификации.

```
In [1]: import numpy as np
import pylab
import copy
import sklearn as skl

import torch
import torch.nn as nn
from tqdm import tqdm
```

Задание 1. Слой Кохонена для кластеризации.

```
In [9]: def plot_dataset(pts):
    for i in pts:
        pylab.plot(i[0],i[1], 'o', color = [0,0,1])
    pylab.show()

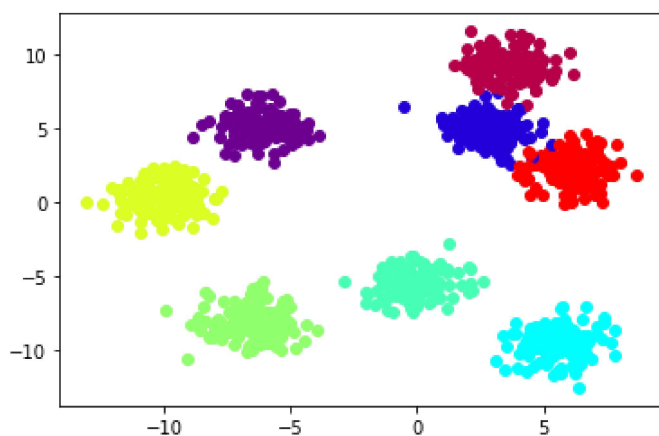
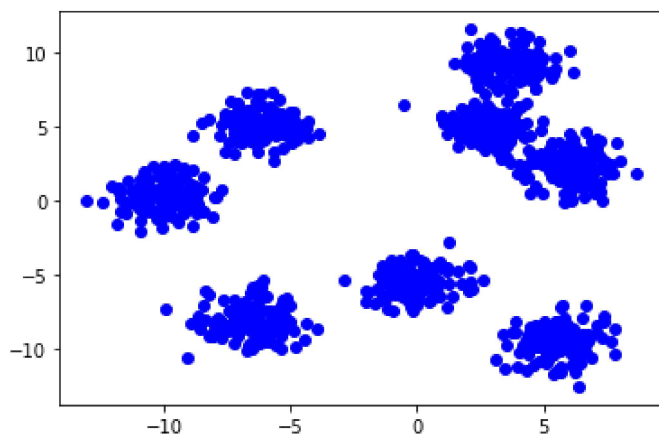
def plot_dataset_by_classes(pts,lbls):
    for i in range(len(pts)):
        pylab.plot(pts[i][0],pts[i][1], 'o', color = [lbls[i]/np.max(lbls),(lbls[i]%2 == 0
        pylab.show()

def plot_dataset_by_classes_cl(pts,lbls,centers):
    for i in range(len(pts)):
        pylab.plot(pts[i][0],pts[i][1], 'o', color = [lbls[i]/np.max(lbls),(lbls[i]%2 == 0
    for i in centers:
        pylab.plot(i[0],i[1], 's', color = [0,0,0])
    pylab.show()
```

```
In [10]: from sklearn.datasets import make_blobs
train_xx,y = make_blobs(n_samples=1000, centers=8, n_features=2,random_state = 10)
```

Сгенерированный датасет:

```
In [88]: plot_dataset(train_xx)
plot_dataset_by_classes(train_xφx,y)
```



Слой Кохонена:

```
In [89]: class cohonenLayer():
    def __init__(self, classes):
        self.wts = np.random.random([classes, 2])

    def train(self, inputs, n_epoch, lr = 0.5):

        for epoch in range(n_epoch):
            cur_elm = inputs[int(np.random.random()*len(inputs))]
            distances = np.zeros(len(self.wts))
            for i in range(len(self.wts)):
                dist = np.sqrt(((cur_elm - self.wts[i])**2).sum())
                distances[i] = dist
            self.wts[np.argmin(distances)] += lr*(cur_elm - self.wts[np.argmin(distances)])

    def predict(self, pt):
        res = np.zeros(len(self.wts))
        for i in range(len(self.wts)):
            res[i] = np.sqrt(((pt - self.wts[i])**2).sum())
        return np.argmin(res)
```

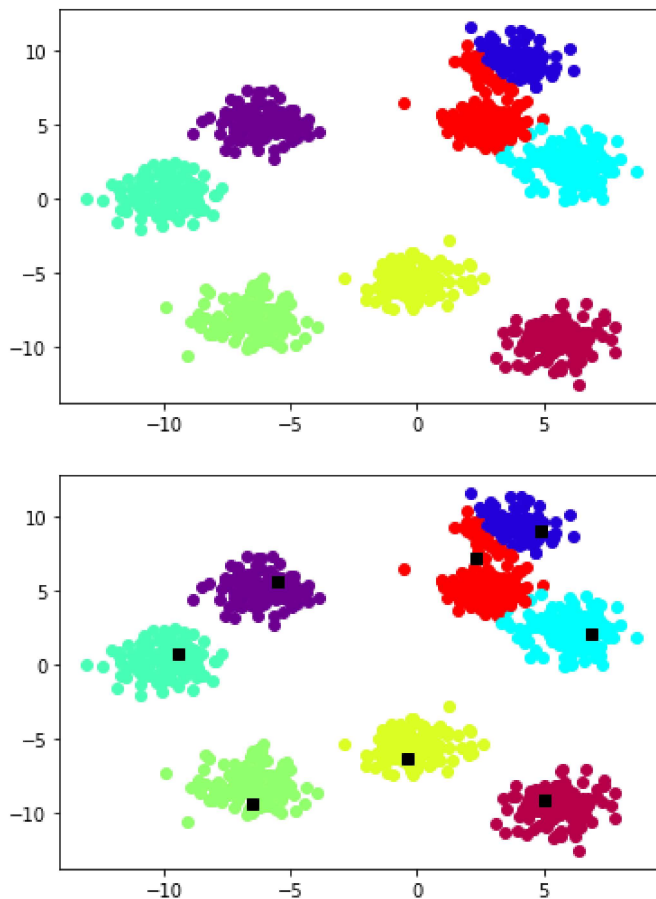
```
In [90]: test_layer = cohonenLayer(8)
```

```
In [91]: test_layer.train(train_xx, 2000)
```

```
In [92]: pred_lbl = []
    for pt in train_xx:
        pred_lbl.append(test_layer.predict(pt))
    pred_lbl = np.array(pred_lbl)
```

Результат кластеризации:

```
In [99]: plot_dataset_by_classes(train_xx, pred_lbl)
    plot_dataset_by_classes_cl(train_xx, pred_lbl, test_layer.wts)
```



Задание 2. Карта Кохонена

```
In [3]: def visualise(matr): #представить двумерный массив в виде черно-белой картинки
        pylab.figure(figsize = (matr.shape[1]/10,matr.shape[0]/10))
        for i in range(matr.shape[0]):
            for j in range(matr.shape[1]):
                pylab.plot(j,matr.shape[0] - i, 's', color = (matr[i][j][0],matr[i][j][1],0))
        pylab.show()
```

```
In [4]: def h(t,dist):
        return np.exp(-dist)
```

```
In [5]: class kohonenMap():
        def __init__(self,shape):
            self.shape = shape
            self.mesh = np.random.random([self.shape[0],self.shape[1],2])

        def expand(self,examples,n_epoch = 10, h = h, radius = 5):
            rad = radius
            for epoch in range(n_epoch):
                lr = n_epoch/(epoch + n_epoch)
                selected_node = examples[int(np.random.random()*len(examples))]
                tmp = self.mesh - selected_node

                tmp_norm = (np.abs(tmp).sum(axis = 2)) #не l2, но вроде норма

                min_val = np.min(tmp_norm)
                min_crd = np.argmin(tmp_norm)
                ril_min_crd = [int(min_crd / self.shape[0]),int(min_crd % self.shape[0])]

                for i in range(ril_min_crd[0] - rad,ril_min_crd[0] + rad):
                    for j in range(ril_min_crd[1] - rad,ril_min_crd[1] + rad):
                        if(i >= 0 and j >= 0 and i < self.mesh.shape[0] and j < self.mesh.sh
                            dst = np.sqrt((ril_min_crd[0] - i)**2 + (ril_min_crd[1] - j)**2)

                            self.mesh[i,j] -= tmp[i,j]*h(epoch,dst/rad)*lr
                            #self.mesh[i,j] -= tmp[ril_min_crd[1],ril_min_crd[0]]*h(epoch,ds

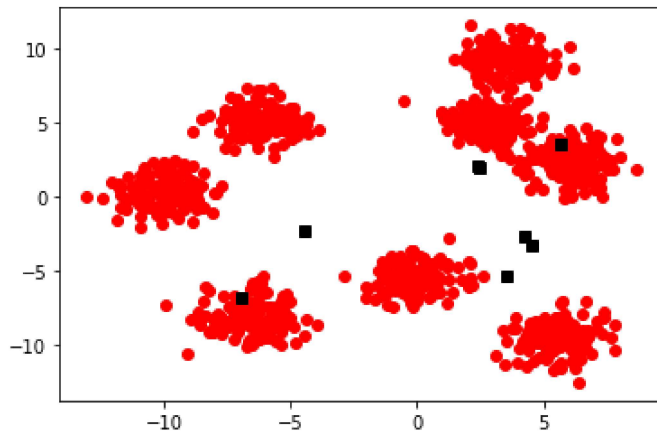
                if(rad > 1):
                    rad -= 1

        def plot(self):
            tmp = np.abs(self.mesh / np.max(np.abs(self.mesh)))
            visualise(tmp)
```

Нахождение центров кластеров

```
In [239]: test_map = kohonenMap([2,4])
          test_map.expand(train_xx,radius = 4, n_epoch = 10000)
```

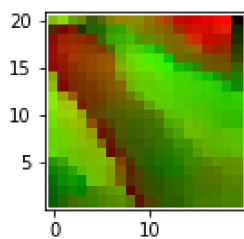
```
In [240]: plot_dataset_by_classes_cl(train_xx,[1 for i in train_xx],test_map.mesh.reshape(8,2))
```



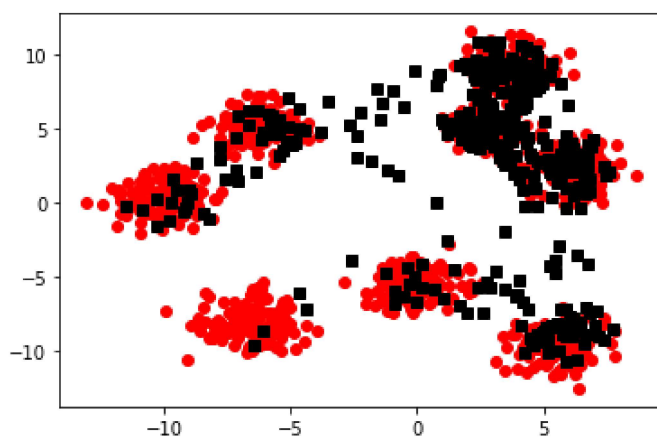
Карта большего размера

```
In [244]: test_map = cohonenMap([20,20])  
test_map.expand(train_xx,radius = 10, n_epoch = 10000)
```

```
In [245]: test_map.plot()
```



```
In [246]: plot_dataset_by_classes_cl(train_xx,[1 for i in train_xx],test_map.mesh.reshape(400,2))
```



Задание 3. Задача коммивояжера

```
In [211]: class cohonenMap():
    def __init__(self, shape):
        self.shape = shape
        self.mesh = np.random.random([self.shape[0], self.shape[1], 2])

    def expand(self, examples, n_epoch = 10, h = h, radius = 5):
        rad = radius
        for epoch in range(n_epoch):
            lr = n_epoch / (epoch + n_epoch)
            selected_node = examples[int(np.random.random()*len(examples))]
            tmp = self.mesh - selected_node

            tmp_norm = (np.abs(tmp).sum(axis = 2)) #не L2, но вроде норма

            min_val = np.min(tmp_norm)
            min_crd = np.argmin(tmp_norm)
            ril_min_crd = [int(min_crd / self.shape[1]), int(min_crd % self.shape[1])]

            #номер города в выходном слое
            no_outer = ril_min_crd[1]

            for i in range(ril_min_crd[0] - rad, ril_min_crd[0] + rad):
                for j in range(ril_min_crd[1] - rad, ril_min_crd[1] + rad):
                    #прохождение через границу
                    i = i % self.mesh.shape[0]
                    j = j % self.mesh.shape[1]
                    #if(i >= 0 and j >= 0 and i < self.mesh.shape[0] and j < self.mesh.s

                    dst = np.sqrt((ril_min_crd[0] - i)**2 + (ril_min_crd[1] - j)**2)

                    self.mesh[i, j] -= tmp[i, j]*h(epoch, dst/rad)*lr
                    #self.mesh[i, j] -= tmp[ril_min_crd[1], ril_min_crd[0]]*h(epoch, dst/ra

            if(rad > 1):
                rad -= 1

    def closest(self, vec):
        selected_node = vec
        tmp = self.mesh - selected_node

        tmp_norm = (np.abs(tmp).sum(axis = 2)) #не L2, но вроде норма

        min_val = np.min(tmp_norm)
        min_crd = np.argmin(tmp_norm)
        ril_min_crd = [int(min_crd / self.shape[1]), int(min_crd % self.shape[1])]

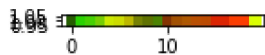
        #номер города в выходном слое
        return ril_min_crd

    def plot(self):
        tmp = np.abs(self.mesh / np.max(np.abs(self.mesh)))
        visualise(tmp)
```

```
In [283]: cities = np.random.random([20, 2])
```

```
In [284]: test_map = cohonenMap([1, 20])
test_map.expand(cities, radius = 5, n_epoch = 10000)
```

In [285]: test_map.plot()



```
In [286]: route = []
for x in cities:
    route.append(test_map.closest(x)[1])
route = np.array(route)
```

In [287]: route

Out[287]: array([9, 4, 1, 0, 1, 4, 3, 6, 12, 10, 16, 14, 8, 2, 0, 0, 18,
3, 7, 5])

```
In [288]: def display_route(cities,order):
    for i in cities:
        pylab.plot(i[0],i[1],'o',color = [0,0,1])

    for num in range(len(route)):
        for i in range(len(route)):
            if(route[i] == num):
                for numnext in range(num + 1,len(route)): #возможные индексы следующего
                    found = 0
                    for j in range(len(route)): #поиск города с соответствующим индексом
                        #print("-- {} {} \n".format(route[j],numnext))
                        if(route[j] == numnext):
                            print("{}:\t from node: {} \tto {} \t\t|\t ({} ) -> ({} )".for
                                found = 1
                                pylab.plot([cities[i][0],cities[j][0]],[cities[i][1],cities[

                    if(found == 1):
                        break

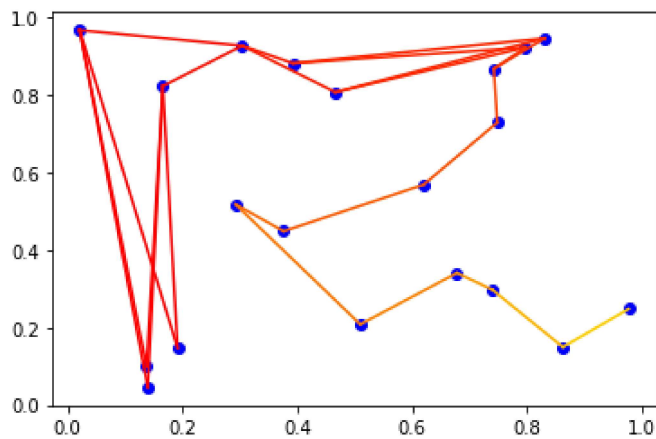
    pylab.show()
```

In [289]: `display_route(cities,route)`

```

0:      from node: 3   to 2   |      ([0.13918294 0.04510845]) -> ([0.16540
635 0.82354954])
0:      from node: 3   to 4   |      ([0.13918294 0.04510845]) -> ([0.02069
403 0.96802678])
0:      from node: 14  to 2   |      ([0.13713818 0.09950256]) -> ([0.16540
635 0.82354954])
0:      from node: 14  to 4   |      ([0.13713818 0.09950256]) -> ([0.02069
403 0.96802678])
0:      from node: 15  to 2   |      ([0.19114129 0.14737807]) -> ([0.16540
635 0.82354954])
0:      from node: 15  to 4   |      ([0.19114129 0.14737807]) -> ([0.02069
403 0.96802678])
1:      from node: 2   to 13  |      ([0.16540635 0.82354954]) -> ([0.30368
346 0.92790086])
1:      from node: 4   to 13  |      ([0.02069403 0.96802678]) -> ([0.30368
346 0.92790086])
2:      from node: 13  to 6   |      ([0.30368346 0.92790086]) -> ([0.46562
166 0.8078606 ])
2:      from node: 13  to 17  |      ([0.30368346 0.92790086]) -> ([0.39189
83 0.88264813])
3:      from node: 6   to 1   |      ([0.46562166 0.8078606 ]) -> ([0.83017
697 0.94696334])
3:      from node: 6   to 5   |      ([0.46562166 0.8078606 ]) -> ([0.79664
982 0.92317549])
3:      from node: 17  to 1   |      ([0.3918983 0.88264813]) -> ([0.83017
697 0.94696334])
3:      from node: 17  to 5   |      ([0.3918983 0.88264813]) -> ([0.79664
982 0.92317549])
4:      from node: 1   to 19  |      ([0.83017697 0.94696334]) -> ([0.74149
461 0.8683806 ])
4:      from node: 5   to 19  |      ([0.79664982 0.92317549]) -> ([0.74149
461 0.8683806 ])
5:      from node: 19  to 7   |      ([0.74149461 0.8683806 ]) -> ([0.74755
035 0.72931662])
6:      from node: 7   to 18  |      ([0.74755035 0.72931662]) -> ([0.61922
165 0.56868409])
7:      from node: 18  to 12  |      ([0.61922165 0.56868409]) -> ([0.37569
489 0.44868175])
8:      from node: 12  to 0   |      ([0.37569489 0.44868175]) -> ([0.29199
364 0.51802053])
9:      from node: 0   to 9   |      ([0.29199364 0.51802053]) -> ([0.50920
447 0.20808433])
10:     from node: 9   to 8   |      ([0.50920447 0.20808433]) -> ([0.67743
487 0.34067109])
12:     from node: 8   to 11  |      ([0.67743487 0.34067109]) -> ([0.73898
764 0.29750065])
14:     from node: 11  to 10  |      ([0.73898764 0.29750065]) -> ([0.86180
122 0.14939888])
16:     from node: 10  to 16  |      ([0.86180122 0.14939888]) -> ([0.97638
898 0.2478762 ])

```

Задание 4. LVQ сеть

Датасет для классификации:

```
In [273]: data_c1 = [-0.3, -0.3, -1.1, -1.1, 1.1, 0.5, 0, 0.2, -0.7, -0.3, 0.1, -0.3]
data_c2 = [1.4, 0.3, -0.4, 0.7, -0.5, -0.7, 0.9, -0.5, -0.2, -0.5, 0.7, -0.3]
data_lb = [1, 1, 1, 1, 1, 1, 1, 1, -1, -1, 1, -1]
```

```
In [274]: examples = np.array([[data_c1[i], data_c2[i]] for i in range(len(data_c1))])
examples = examples / np.max(examples)
examples
```

```
Out[274]: array([[ -0.21428571,  1.          ],
 [ -0.21428571,  0.21428571],
 [ -0.78571429, -0.28571429],
 [ -0.78571429,  0.5         ],
 [  0.78571429, -0.35714286],
 [  0.35714286, -0.5         ],
 [  0.          ,  0.64285714],
 [  0.14285714, -0.35714286],
 [ -0.5         , -0.14285714],
 [ -0.21428571, -0.35714286],
 [  0.07142857,  0.5         ],
 [ -0.21428571, -0.21428571]])
```

```
In [285]: data_lb = np.array((np.array(data_lb) + 1) / 2)
data_lb
```

```
Out[285]: array([1., 1., 1., 1., 1., 1., 1., 1., 0., 0., 1., 0.])
```

```
In [350]: class cohonenLayer(nn.Module):
def __init__(self, classes):
    super(cohonenLayer, self).__init__()
    self.wts = np.random.random([classes, 2])

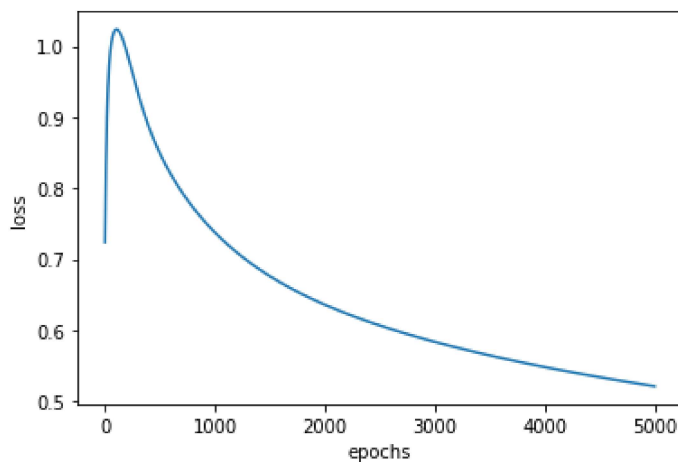
def train(self, inputs, n_epoch, lr = 0.5):

    for epoch in range(n_epoch):
        cur_elm = inputs[int(np.random.random()*len(inputs))]
        distances = np.zeros(len(self.wts))
        for i in range(len(self.wts)):
            dist = np.sqrt(((cur_elm - self.wts[i])**2).sum())
            distances[i] = dist
        self.wts[np.argmin(distances)] += lr*(cur_elm - self.wts[np.argmin(distances)

def predict(self, pt):
    res = np.zeros(len(self.wts))
    for i in range(len(self.wts)):
        res[i] = np.sqrt(((pt - self.wts[i])**2).sum())
    return np.argmin(res)

def __call__(self, x):
    res = np.zeros(len(self.wts))
    for i in range(len(self.wts)):
        res[i] = np.sqrt(((x - self.wts[i])**2).sum())
    return torch.tensor(res, dtype = torch.float32)
```

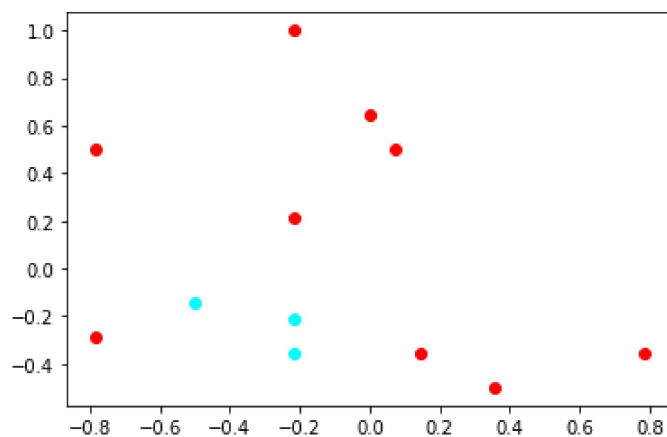
```
In [360]: pylab.ylabel("loss")
pylab.xlabel("epochs")
pylab.plot(arr[:,0],arr[:,1])
pylab.show()
```



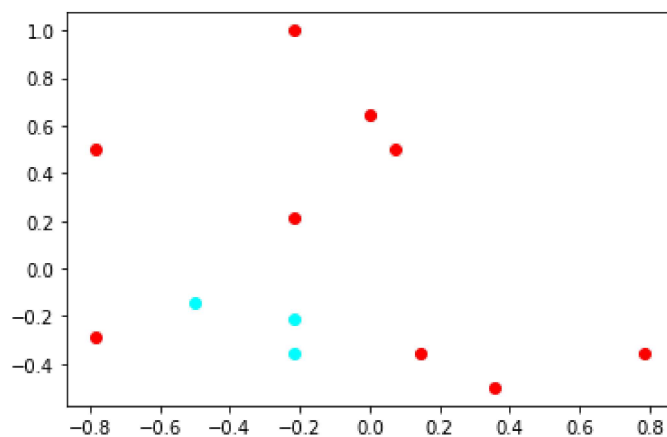
```
In [361]: pred_lbl = []
for pt in examples:
    pred_lbl.append(np.argmax(model(pt).detach().numpy()))
pred_lbl = np.array(pred_lbl)
```

```
In [362]: print("required result:")
plot_dataset_by_classes(examples,data_lb)
print("gained result:")
plot_dataset_by_classes(examples,pred_lbl)
```

required result:

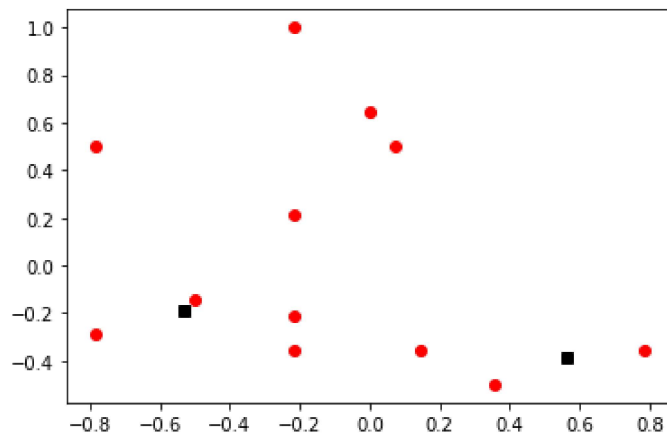


gained result:

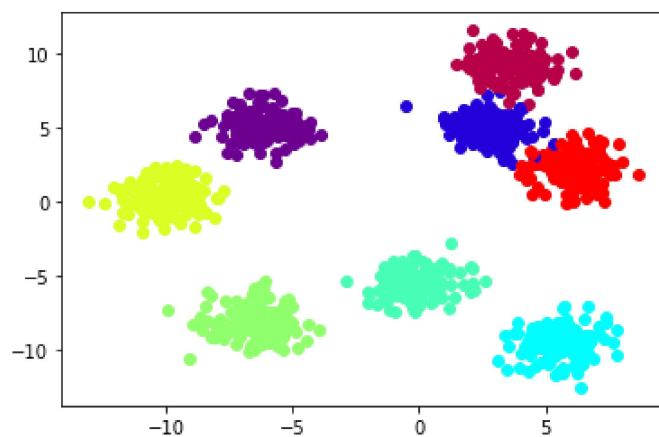
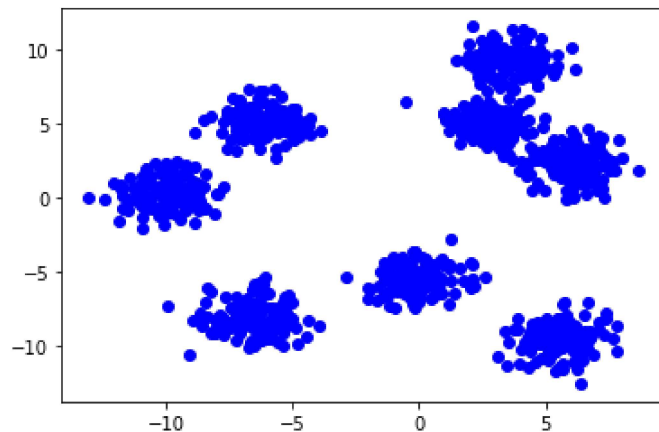


Центры кластеров, определенные слоем кохонена:

```
In [363]: plot_dataset_by_classes_cl(examples,[1 for i in examples],model[0].wts)
```

**Попробуем классифицировать датасет из задания 1.**

```
In [365]: plot_dataset(train_xx)
plot_dataset_by_classes(train_xx,y)
```

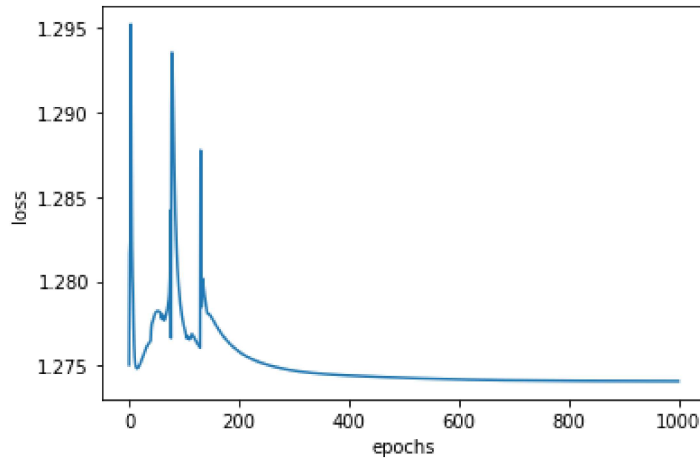


```
In [368]: model = torch.nn.Sequential(
    cohenenLayer(8),
    torch.nn.Linear(8,8),
    torch.nn.Softmax(0)
)
```

```
In [369]: model[0].train(train_xx,5000)
arr = train(model,train_xx,torch.tensor(y,dtype = torch.long),1000,0.01)
```

[illegible]

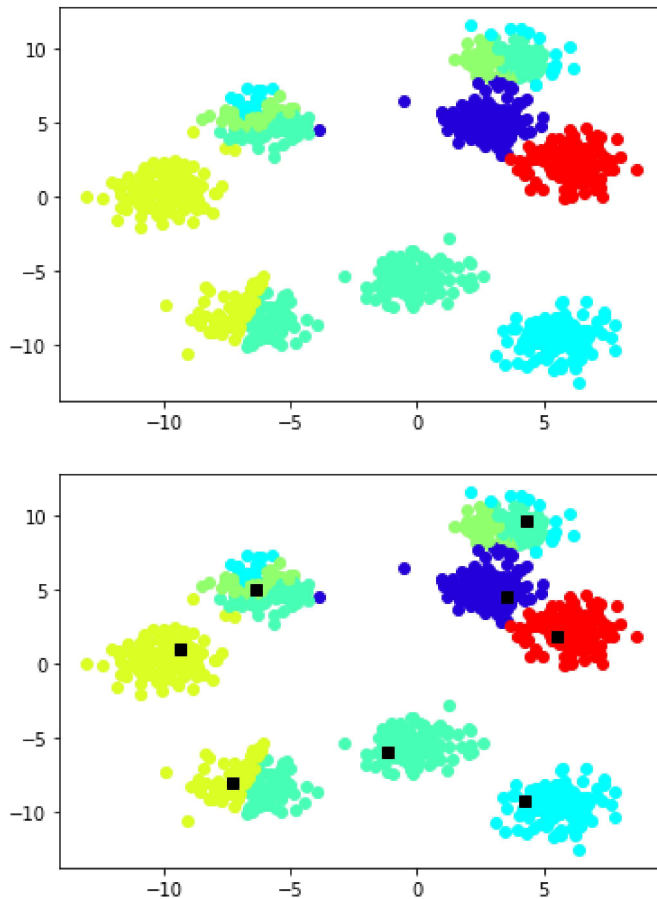
```
In [370]: pylab.ylabel("loss")
          pylab.xlabel("epochs")
          pylab.plot(arr[:,0],arr[:,1])
          pylab.show()
```



```
In [378]: pred_lbl = []
          for pt in train_xx:
              pred_lbl.append(np.argmax(model(pt).detach().numpy()))
          pred_lbl = np.array(pred_lbl)
```

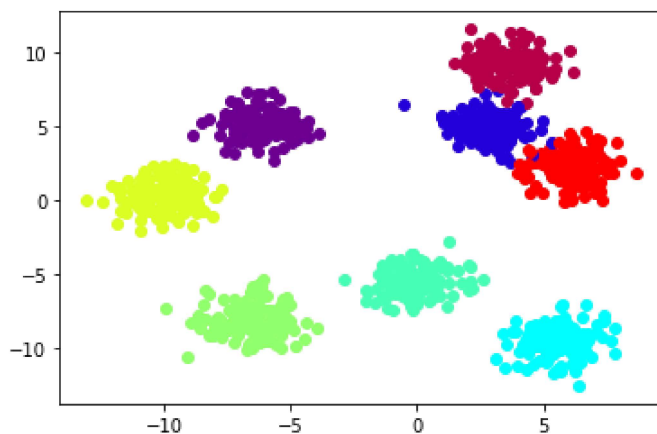
Результат классификации:

```
In [381]: plot_dataset_by_classes(train_xx, pred_lbl)
plot_dataset_by_classes_cl(train_xx, pred_lbl, model[0].wts)
```



Настоящие классы:

```
In [382]: plot_dataset_by_classes(train_xx, y)
```



Выводы

В ходе выполнения этой лабораторной работы я ознакомился со слоем Кохонена и картой Кохонена, получил опыт применения этих технологий для решения задачи кластеризации и классификации.

```
In [ ]:
```

