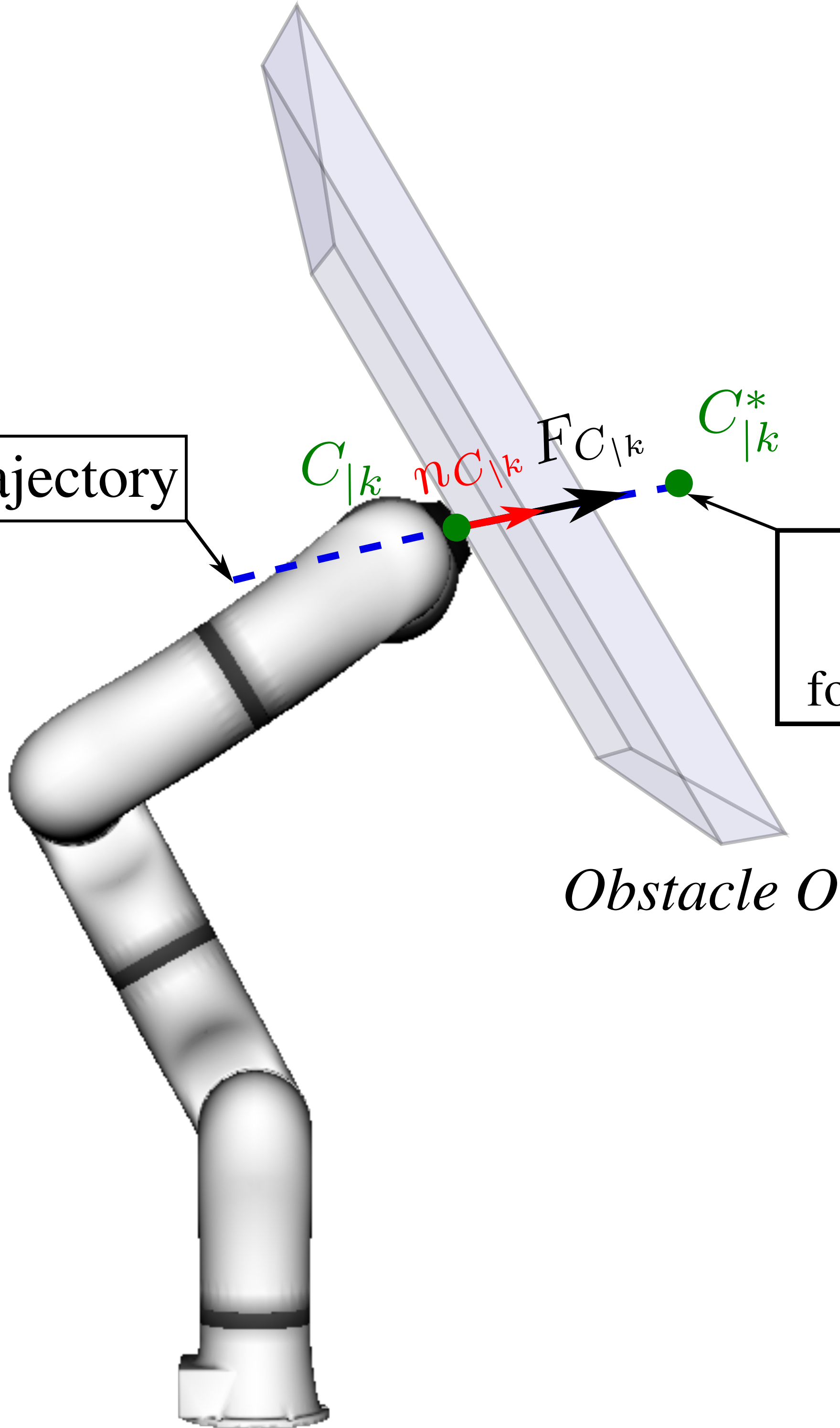


Task Trajectory



Instantaneous
desired position
for the end-effector

Obstacle O