# **RESUME**

#### Chaitali Chandrakant Bodare.

B.E(Electronics & Telecommunication) &

M.E(Electronics & Telecommunication Pursuing)

Vhora complex, Juna Phaltan Road,

Lonand -415521

Contact No: (+91)9975145275 Email Id: chaitalib20@gmail.com

### **CAREER OBJECTIVE**

To pursue a career in a motivated organization wherein my personal skills and technical expertise would be utilized and to achieve personal growth through the organization's progress.

**Training undergone:** ADST (Advance Diploma in Software Testing)

Institute: Seed infotech pvt limited ,Pune.

Skill set: Manual testing, Automation testing(Selenium) with test management tool Test

link and defect tracking tool Bugzilla.

## TRAINING PROJECT:

• Project Name: Orange HRM

• Team Size: 4

• Duration: 1 Week

• Role: Tester

• **Description:** Orange HRM is web based HR management application. It is used to fulfill the requirements of many companies to track the record of their Employees. As a tester we perform black box testing to check the functionalities working properly or not. We founded out some functionality, UI and usability defects.

ACADEMIC QUALIFICATIONS					
Exam /Degree	Year Of Exam	School/College	University / Board	Per Cent (%)	
M.E.( 2 <sup>nd</sup> year)		ADCET ,Ashta	Kolhapur	pursuing	
M.E(1 <sup>St</sup> year)	2015	ADCET ,Ashta	Kolhapur	62.51%	
B.E.	2012	D.K.T.E.Institute, Ichalkaranji	Kolhapur	68.44%	

12 <sup>th</sup> Board	2008	Malojiraje vidyalaya & Jr.college Lonand.	Kolhapur	78.33%
10 <sup>th</sup> Board	2006	New English School Lonand	Kolhapur	79.60%

AGGREGATE OF B.E.(E&TC): 61%

<b>College Projects</b>	
1. TE	"Product counter using IC 74C926"  Project Description:  Product counter using IC 74c926 used 5V power supply and LDR for sensing the light. This light used for frequency counting of light.
2. BE	"Automatically Controlled Obstacle Detector Robot" Project Description: Automatically obstacle detector robot is basically used to detect obstacles automatically without manual interpretation. This type of robot used in the areas where human can't reach. We have used different sensors for the obstacle detection purpose and ZigB technology for transfering data between PC and robot chip.
3.ME	"Vehicle Localization in Intelligent Transportation System (ITS) Project Description: This project is used to develop a Integrated and Smart vehicle localization Algorithm for to detect a vehicle in transportation. This work helpful for a driver ,traveler to detect location using localization techniques which is used in this project.

# TECHNICAL SKILLS

1. Programming Languages: C, C++,Core Java.

2. Software: MATLAB 7.0.

3. Operating System: Windows.

### **EXTRA CURRICULAR**

- Participated in social (Traditional day) at D.K.T.E.
- Participated in paper presentation Event\_at D.K.T.E on optical fiber and mobile communication.
- Participated in paper presentation Event\_at K.I.T on optical wireless communication.
- Active member of COMSA committee at DKTE.
- Member of "IMPULSE2K11" A National event at D.K.T.E.
- Attended workshop on labview in D.K.T.E.
- Attended STTP Training program on "Research Methodology & Latex" at ADCET Ashta.

### PERSONAL PROFILE

Name : Miss. Chaitali Bodare.
Fathers's Name : Mr. Chandrakant Bodare.
Mothers's Name : Mrs. Suvarna Bodare.

Nationality : Indian Gender : Female Date of Birth : 20march,1991

Alternate Email id : chaitalibodare20@gmail.com

Permanent Address: Vhora Complex, Juna Phaltan Road Lonand.

### **Declaration:**

I hereby declare that above information is correct to the best of my knowledge and belief.

**Place**: Lonand (MAHARASHTRA)

CHAITALI BODARE.