

Apprentissage supervisé $\{x^{(i)} \in \mathbb{R}^D, t^{(i)}\}_{i=1}^N$

→ Objectif : apprendre un modèle h_{β}

→ 1^{re} solution OLS $l(\beta) = \frac{1}{N} \sum_{i=1}^N (t^{(i)} - h_{\beta}(x^{(i)}))^2$

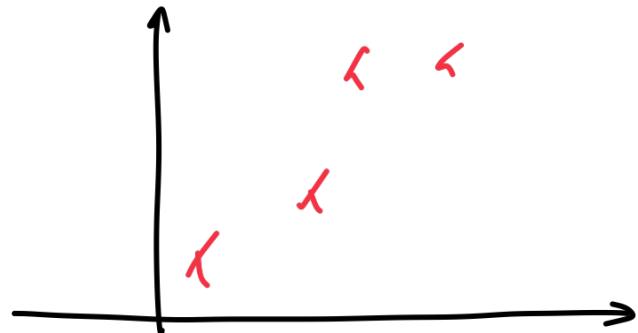
$$h_{\beta} = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \dots + \beta_D x_D$$

↳ 2 approches : descente de gradient

→ Équations normales : $\hat{\beta} = (\tilde{X}^T \tilde{X})^{-1} \tilde{X}^T t$

→ Dans le cas de caractéristiques corrélées / matrice \tilde{X} singulière → On peut toujours éviter un processus d'orthogonalisation

$$\beta_D = \frac{\langle t_\varepsilon, z_D \rangle}{\langle z_D, z_D \rangle} \rightarrow \text{Dans le cas de convolution} \rightarrow \text{amplitude d'erreur des } \beta_j$$



→ Pour déterminer la complexité optimale du modèle

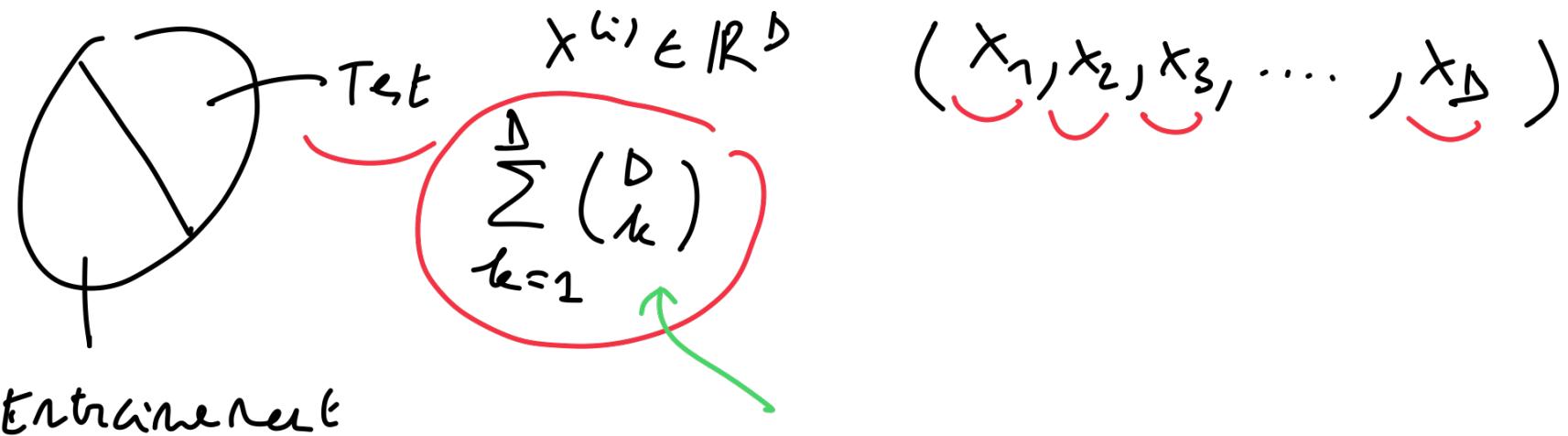
↳ On peut étudier l'erreur quadratique moyenne

$$MSE(x) = \text{bias}^2 + \text{variance}$$

Selection automatique de modèles / caractéristiques

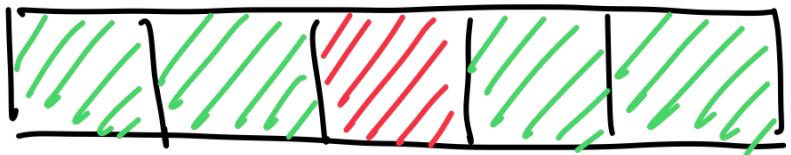
- Best subset selection
- Regression Ridge
- Regression LASSO
- Classification → 2 classes via méthodes carénées
 - >2 classes
 - regression logistique

Question: Comment sélectionner les caractéristiques les plus représentatives



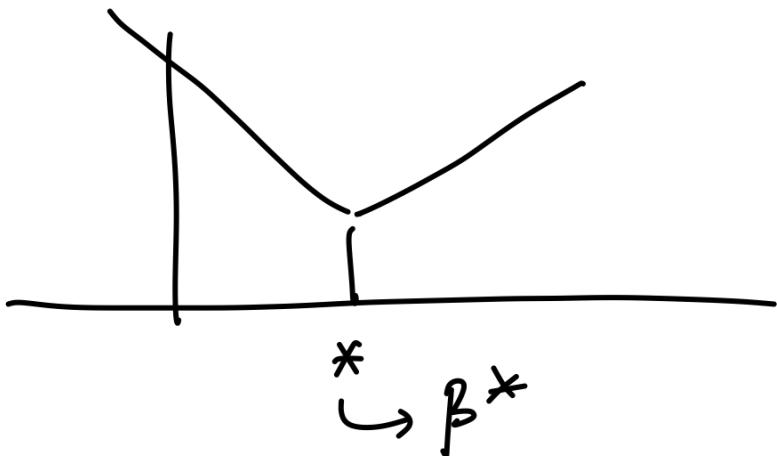
→ Si peu de données → Validation croisée (cross validation)

K-fold cross validation



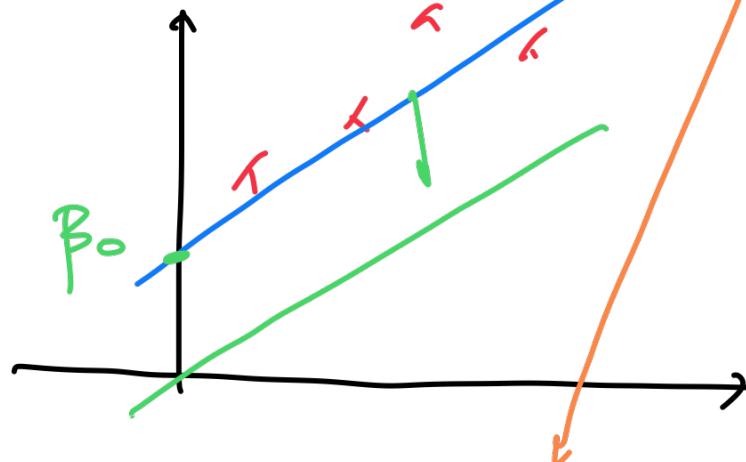
K

$$CV(\beta) = \frac{1}{N} \sum_{i=1}^N (t^{(i)} - \hat{h}_\beta^{-K(i)}(x^{(i)}))^2$$



$$\ell(\beta) = \frac{1}{N} \sum_{i=1}^N (t^{(i)} - h_{\beta}(x^{(i)}))^2 + \lambda \sum_{j=2}^D |\beta_j|^2$$

$$= \frac{1}{N} \sum_{i=1}^N (t^{(i)} - (\beta_0 + \beta_1 x_1^{(i)} + \dots + \beta_D x_D^{(i)}))^2 + \lambda \sum_{j=1}^D |\beta_j|^2$$



Fidélité
au dominé

2 possiblités

- descente du gradient
- Résolution des équations normales

RIDGE

fidélité
Complexité

Equations normales

Étape 2 Centrer les vecteurs $x^{(i)} \in \mathbb{R}^D$

$$x^{(i)} \leftarrow x^{(i)} - \frac{1}{N} \sum_{j=1}^N x^{(j)}$$

$$\frac{1}{N} \sum_{j=1}^N x^{(j)} = 0$$

$$l_{\text{RIDGE}}(\beta) = \frac{1}{N} \sum_{i=1}^N (t^{(i)} - (\beta_0 + \beta_1 x_1^{(i)} + \dots + \beta_D x_D^{(i)}))^2 + \lambda \sum_{j=1}^D |\beta_j|^2$$

$$\frac{\partial l}{\partial \beta_0} = \frac{2}{N} \sum_{i=1}^N (t^{(i)} - (\beta_0 + \beta_1 x_1^{(i)} + \dots + \beta_D x_D^{(i)})) (-1)$$

$$= \frac{2}{N} \sum_{i=1}^N t^{(i)} + \frac{2}{N} \sum_{i=1}^N \beta_0 + \frac{2}{N} \sum_{i=1}^N (\beta_1 x_1^{(i)} + \dots + \beta_D x_D^{(i)})$$

$$2\beta_0 = \frac{2}{N} \sum t^{(i)} \rightarrow \beta_0 = \frac{1}{N} \sum_{i=1}^N t^{(i)}$$

$$\text{Etape 2: centrer les } t^{(i)} \quad t_c^{(i)} = t^{(i)} - \frac{1}{N} \sum_{i=1}^N t^{(i)}$$

$$\lambda(\beta) = \frac{1}{N} \sum_{i=1}^N (t_c^{(i)} - (\beta_0 x_0^{(i)} + \dots + \beta_D x_D^{(i)}))^2 + 2 \sum_{j=1}^D \beta_j^2$$

$$\frac{\partial \lambda}{\partial \beta_j} = \frac{2}{N} \sum_{i=1}^N (t_c^{(i)} - (\underbrace{\beta_0 x_0^{(i)} + \dots + \beta_D x_D^{(i)}}_{e_i})) (-x_j^{(i)}) + 2\lambda \beta_j$$

$$= \frac{2}{N} \sum_{i=1}^N e_i \cdot \underbrace{x_j^{(i)}}_{c_i} + 2\lambda \beta_j \quad \leftarrow$$

$$x = \begin{bmatrix} -x^{(1)}- \\ -x^{(2)}- \\ \vdots \\ -x^{(n)}- \end{bmatrix}$$

$$\begin{aligned} \text{grad}_{\beta} &= \left[\frac{\partial \lambda}{\partial \beta_1}, \frac{\partial \lambda}{\partial \beta_2}, \dots, \frac{\partial \lambda}{\partial \beta_D} \right] = \\ &= \underbrace{-\frac{2}{N} \sum_{i=1}^N e_i \cdot \overrightarrow{x}^{(i)}}_{\text{c}} + 2\lambda \beta \end{aligned}$$

$$c_i = \vec{t}_i - \underbrace{(\vec{x} \vec{\beta})_i}_{\text{c}}$$

$$= \left(-\frac{2}{N} \left(t - \underline{\underline{x}} \beta \right)^T x \right)^T + 2\lambda \beta \leftarrow$$

$$\vec{t} = \begin{bmatrix} t^{(1)} \\ \vdots \\ t^{(N)} \end{bmatrix}$$

$$= -\frac{2}{N} x^T (t - x \beta) + 2\lambda \beta \leftarrow$$

$$= -\frac{2}{N} \overbrace{x^T t} + \underbrace{2x^T x \beta}_{2\lambda \beta}$$

$$\Rightarrow \left(\frac{2}{N} x^T x + 2\lambda I \right) \beta = \frac{2}{N} x^T t$$

$$\sum_i e_i \vec{x}^{(i)} + 2\lambda \beta$$

$$\sum_i e_i \left[\vec{x}^{(i)} \right]$$

$$\cdot \begin{bmatrix} -x^{(1)} \\ \vdots \\ -x^{(N)} \end{bmatrix}$$

$$\beta_{\text{RIDGE}} = \left(\frac{2}{N} x^T x + 2\lambda I \right)^{-1} \frac{2}{N} x^T t$$

$$X^T X \nu = \alpha \nu$$

$$\underbrace{(X^T X + \lambda I)}_{\text{Matrix}} \nu = \alpha' \nu$$

$$X^T X \nu + \lambda \nu = \alpha' \nu + \lambda \nu \\ = (\alpha + \lambda) \nu$$

$$\ell_{LASSO}(\beta) = \frac{1}{N} \sum_{i=1}^N (t^{(i)} - (\beta_0 + \beta_1 x_1^{(i)} + \dots + \beta_d x_d^{(i)}))^2 + \lambda \sum_{j=1}^d |\beta_j|$$

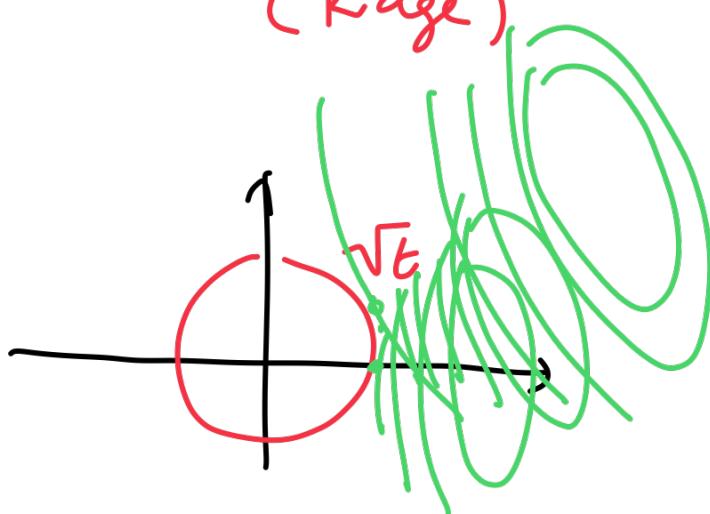
formulation of constraints

$$\min_{\beta} \ell(\beta) = \frac{1}{N} \sum_{i=1}^N (t^{(i)} - (\beta_0 + \beta_1 x_1^{(i)} + \dots + \beta_D x_D^{(i)}))^2$$

s.t.

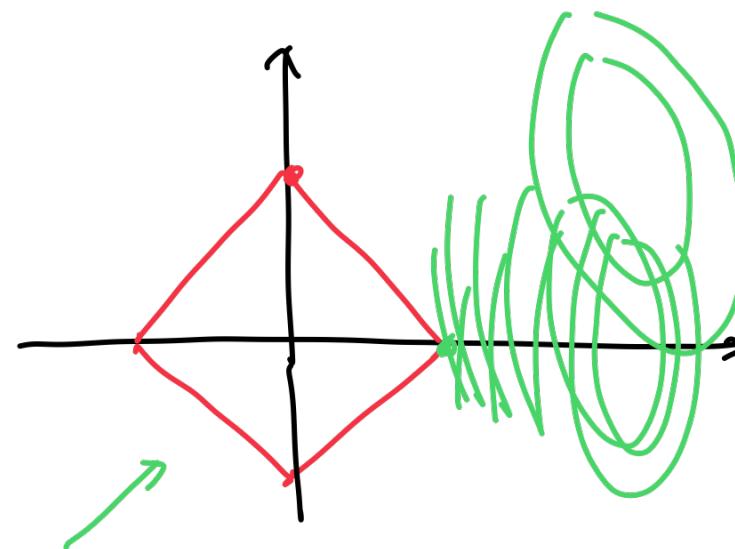
$$\left(\sum_{j=1}^D \beta_j^2 \leq t \right)$$

(Ridge)



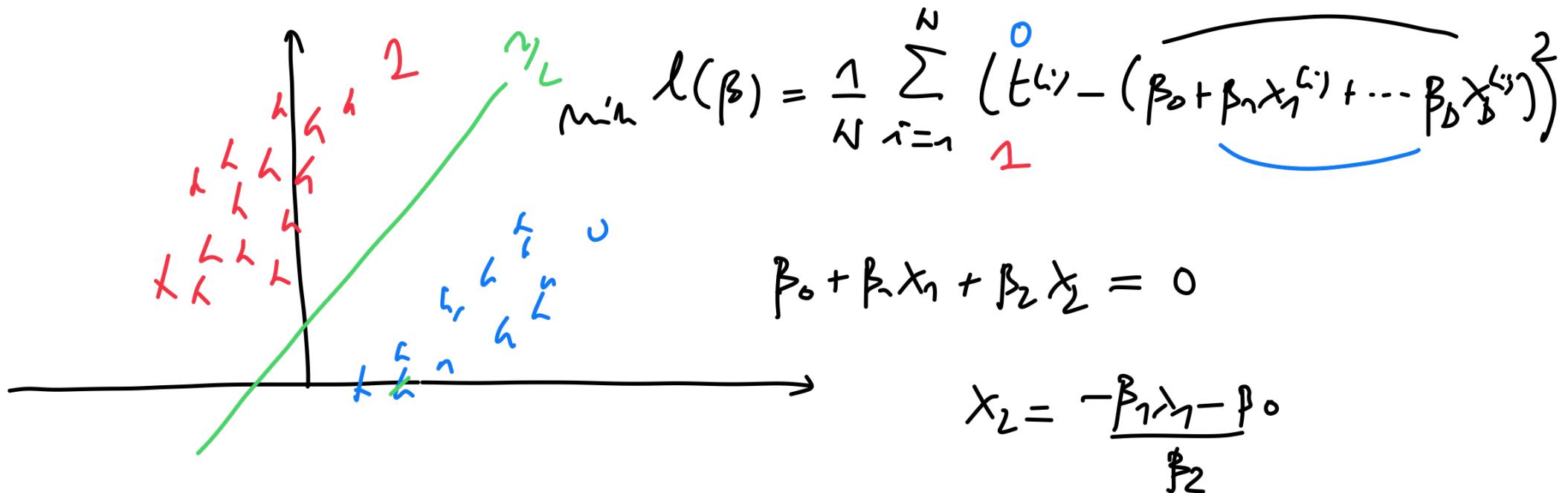
$$\sum_{j=1}^D |\beta_j| \leq t$$

(LASSO)



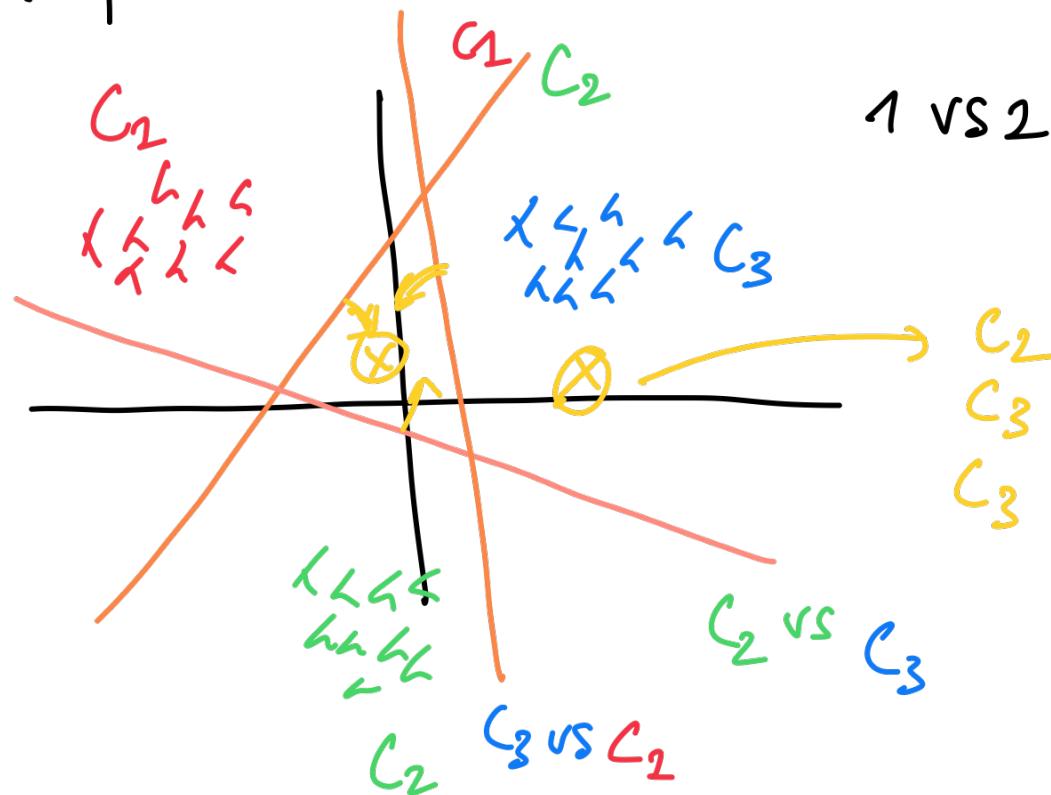
$$\|v\|_2 = \sum_{i=1}^N |v_i|$$

Classification $\{x^{(i)}, t^{(i)}\} \quad t^{(i)} \in \{1, \dots, k\}$



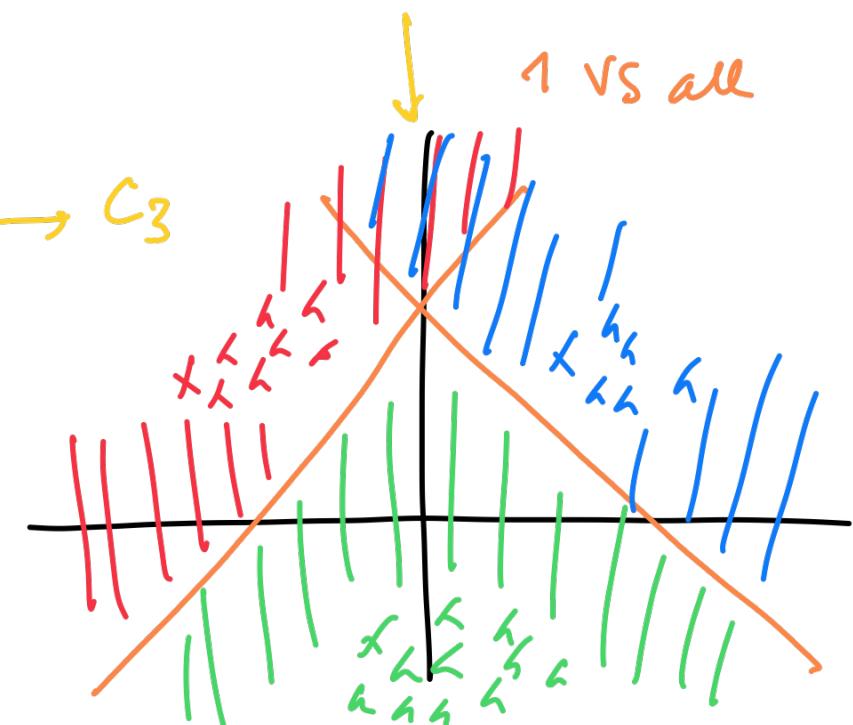
Q2? 2 classes \rightarrow class multiples

Q2? points outliers



1 vs 2

$$\frac{k \cdot k - 1}{2}$$



$$T = \begin{bmatrix} \quad \vec{t}^{(1)} \quad \\ \vdots \\ \quad \vec{t}^{(N)} \quad \end{bmatrix} \quad t^{(i)} \in \{1, \dots, k\}$$

$$\vec{t}^{(i)} = [0, 1, 0 \dots 0]$$

$$B = \begin{bmatrix} \quad \vec{\beta}_2^T \quad \\ \vdots \\ \quad \vec{\beta}_N^T \quad \end{bmatrix} \quad \vec{x}^{(1)}, \vec{x}^{(2)}, \dots, \vec{x}^{(N)} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \\ \vdots & \vdots \\ 0 & 0 \end{bmatrix}$$

$$T \simeq X B^T$$

$$B X^T$$

$$M_B = \frac{1}{NK} \sum_{i=1}^N \sum_{k=1}^K (t_k^{(i)} - (\vec{\beta}_k)^T \vec{x}^{(i)})^2$$

$$B = (X^T X)^{-2} X^T T$$