# Mohammad Mehdi Bahmani

curriculum vitæ

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Research **Interests:** 

Design and Developing, Automation and Robotics, Electric Vehicles, Robot Delivery, Air Taxi and Flying Cars, Mechatronics, Hardware Development, Renewable Energy

Work **Experience:** 

#### RoboSky Lab Ltd.

- Address: Tehran, Iran.
- Position: Hardware Team Lead
- Responsibilities:
  - Manage and control activities in multi-functional areas.
  - Ensure appropriate operational planning is effectively executed to meet specifications
  - 3. Engage in technical discussions with mechanical and firmware engineers
  - 4. Manage the team and assist team members with their career planning and daily technical challenges
  - 5. Keep up-to-date with the latest technologies and selecting the right components to solve given problems.
  - 6. Collaborate with the team to identify the best technological solutions
  - 7. Actively participate in planning meetings
  - 8. Moving designs and optimizing BOMs from development to manufacturing
- Position: Electronic Specialist

Jan 2020 - Dec 2021

Dec 2021 – Aug 2024

- Responsibilities:
  - Designing various dc-dc converters in a wide range of power and switching frequencies.
  - Developing data logger systems to monitor system's vital stats, storing on a cool disk while sending them off on wireless link simultaneously.
  - Developing an android app to receive and save data logger data.
  - 4. Designing high frequency PCBs featuring Raspberry Pi compute module and ARM co-processor
  - 5. Designing evaluation PCBs for new electronics components and performing standard test procedures
  - 6. Performing operational testing procedures for electronics systems
  - Setting up laboratory test equipment and composing test scenarios
  - 8. Assembling data and assisting in the upkeep of documentation
- Position: Firmware Developer

Jul 2019 - Jan 2020

- Responsibilities:
  - Making some tweaks and improvements on existing communications over CAN and making automatic filtering
  - Developing digital data logging system
  - 3. Designing a new file transfer protocol over CAN to reprogram the main board using boot-loader system
  - 4. Performing code reviews
  - 5. Writing and maintaining firmware documentation
  - Testing firmware releases 6.
  - 7. Maintaining stable firmware

#### Rahnegar Hooshmand Iranian

- Address: Tehran, Iran
- Position: Electronics Engineer
- Responsibilities:
- Collaborated with a team in designing and programming a GPS-based positioning system with 3G network connectivity utilizing ARM micro

Sep 2017 - Jun 2019

- controller. Developed OTA update infrastructure using FTP connection on the system.
- 2. Designed and manufactured a small passive data logger system using SD card or Flash memory to store debug info of the system to use in debug
- Developed a dynamic encryption algorithm on raw data to make TCP 3. connections more secure
- Upgraded telemetry data protocol to use MQTT instead of TCP/IP to reduce server side process and increase efficiency also increasing compatibility with IoT platform
- Making a complete documentation of system and several user manuals for troubleshooting

## **Auto Mechanic Engineering Group (AMEG)**

Dec 2015 - Sep 2017

- Address: Tehran, Iran
- Position: Electronics Engineer
- Responsibilities:
- Analogue design including power drivers and switching power supplies,
- Digital design including designing and manufacturing micro controller based intelligent systems including circuit design, programming, performing simulations and providing embedded PCB compatible with car ECU
- Design and manufacturing automobile suspension test stand and 3. implementing a variety of sensors on it to monitor and test different parts
- Analogue design including power drivers and switching power supplies.

#### Iran Aircraft Manufacturing Industries Co.

May 2014 - Oct 2014

- Address: Shahinshahr, Iran
- Position: Intern
- Responsibilities:
- 1. Collaborated with a team on developing a PLC-based control system and designing a desktop GUI for the controller.
- Design and manufacturing of a microcontroller based system for an educational projects with various communications including RS232 and CAN.

### **Education:**

## University of Tehran, Tehran, Iran

2014-2017

M.Sc. in Mechatronics Engineering

**Thesis:** Design and manufacturing of a continuum manipulator for suitable interaction with dynamic environment

**GPA:** 16.98

## University of Isfahan, Isfahan, Iran

2010-2014

B.Sc. in Electrical Engineering (3<sup>rd</sup> rank graduate in the department)

Thesis: Performance Evaluation and Analysis of IR-HARQ-based Error Recovery

Techniques on The IEEE 802.11 Protocol

**GPA:** 17.38

## Language **Proficiency:**

Farsi: Native

**English: Working Proficiency** 

Fall 2015

TOEFL iBT Score: (27-29-19-24) 99 **Deutsch: Intermediate** 

# **Projects Experiences:**

#### Design and Simulation of an 8-bit CPU

Fall 2012

Collaborated with a team on designing and simulation of an 8-bit CPU based on Von Neumann architecture consist of a set of arithmetic, logic, memory access and I/O instructions; provided with built-in memory and I/O blocks. I simulated the whole system in Proteus Design Suit and tested it using specific binary language designed for it.

Design and Implementation of an Accurate Step Motor Controller System Implemented an ARM-based system with a matrix keypad as user input and a character LCD as output to drive a step motor in two modes of speed and state

Spring 2014

|                         |                  | control. Getting current feedback to ensure smooth movement and avoiding stall.  |                                     |
|-------------------------|------------------|--|-------------------------------------|
|                         | _                | · · · · · · · · · · · · · · · · · · ·  | Spring 2014                         |
|                         |                  | Development of a Wireless Communication System Using Bluetooth Module  | 3pmg 2014                           |
|                         |                  | Collaborated with a team on developing a wireless communication system for controlling a DC motor using wireless link over a Bluetooth module. |                                     |
|                         | >                | Design, Simulation and Implementation of a 3DoF Articulated Robotic Arm  | Fall 2014                           |
|                         |                  | Collaborated with a team on designing and implementation of the robotic arm and  | 1 un 2011                           |
|                         |                  | making Windows-based software with graphical interface for controlling the end-  |                                     |
|                         |                  | effector position.   |                                     |
|                         |                  | Design and Simulation of a Multi-Layer Perceptron(MLP) Neural  | Fall 2014                           |
|                         |                  | Network(NN) for Separating 4 Different Gas Types   |                                     |
|                         |                  | Designed a MLP network trained with thermal data of 4 gases and then perform   |                                     |
|                         |                  | successful simulation of network separating them.  | a                                   |
|                         |                  | Design and Development of a Bio Inspired Steerable Robot Actuated by   | Spring 2015                         |
|                         |                  | Shape Memory Alloy Springs   |                                     |
|                         |                  | Collaborated with a classmate on developing a steerable robot platform using only  |                                     |
|                         |                  | SMA actuators with a high power to weight ratio able to transfer up to 5 times its weight.   |                                     |
|                         |                  | Obstacle-Avoiding Mobile Robot   | Spring 2016                         |
|                         |                  | Developed an obstacle-avoiding robot equipped with ultrasonic sensors to detect  | 5ping 2010                          |
|                         |                  | and maneuver around obstacles in its path. This project demonstrated my  |                                     |
|                         |                  | proficiency in sensor integration and autonomous navigation algorithms.  |                                     |
|                         |                  | proficiency in sensor integration and autonomous navigation argorithms.  |                                     |
| Skills:                 | >                | Skills:  |                                     |
| <b>31111</b> 5 <b>•</b> |                  | Analog Design: amplifier, pulse generator and power electronic circuit design  |                                     |
|                         |                  | 2. Microcontroller-based systems: design, simulation and implementation  |                                     |
|                         |                  | 3. PCB Designing up to 8 layer stack up (Altium designer)  |                                     |
|                         |                  | 4. Problem-solving and ability to create new solutions   |                                     |
|                         |                  | 5. C# programming in Microsoft Visual Studio environment   |                                     |
|                         |                  | 6. C/C++ programming on ARM based processors utilizing STM32 CubeIDE, Keil   |                                     |
|                         |                  | uVision 7. Version Control Systems (Git, SVN)  |                                     |
|                         |                  | <ol> <li>Version Control Systems (Git, SVN)</li> <li>Management and leadership</li> </ol>  |                                     |
| Published               | >                | A. Hadi, <b>Mohammad Mehdi Bahmani</b> , M. Davari "Developing a bio   | Fall 2015                           |
| Papers:                 |                  | inspired steerable robot actuated by shape memory alloy springs," IEEE   |                                     |
| •                       |                  | Int. Conf. Robotics and Mechatronics, Tehran, Iran, Oct. 2015  |                                     |
| Honor and               | >                | Top 1% Iranian University Entrance Exam (Konkour)  | Sep 2010                            |
| Awards:                 |                  | Best Artistic Achievement Award, issued by Biotechnology Committee of  | Oct 2017                            |
|                         |                  | Iran Science and Technology Vice Presidency, awarded for "GeneCraft" a   |                                     |
|                         |                  | videogame designed and developed by our team for biotechnology   |                                     |
|                         |                  | committee game jam.  |                                     |
|                         | $\triangleright$ | Technical Achievement Nominee, issued by Biotechnology Committee of  | Oct 2017                            |
|                         |                  | Iran Science and Technology Vice Presidency, awarded for "GeneCraft" a   |                                     |
|                         |                  | videogame designed and developed by our team for biotechnology   |                                     |
|                         |                  | committee game jam.  |                                     |
|                         |                  | Continue of Completion II Continue II II   | Jul 2010                            |
| Licenses and            | <b>&gt;</b>      |  | Jul 2019<br>May 2018                |
| Certifications:         | <b>&gt;</b>      | Certificate of Completion – <u>SQL Fundamentals</u> , issued by sololearn  | May 2018                            |
| T. 1.                   | <u> </u>         | Certificate of Completion – <u>C# Course</u> , issued by sololearn   | Sep 2016                            |
| <b>Feaching</b>         | >                | Teaching Assistant, Logical Circuits   | Fall 2012 Spring 2014               |
| Experiences:            | >                | Teaching Assistant, Computer Architecture and Organization   | Fall 2013, Spring 2014              |
|                         |                  | Teaching Assistant, Microprocessors  | Fall 2013, Spring 2014<br>Fall 2015 |
|                         |                  | Teaching Assistant, Mechatronics   | 1°a11 2013                          |
| Reference:              |                  | Available upon request   |                                     |
|                         |                  |  |                                     |