Mohammad Mehdi Bahmani

curriculum vitæ

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Research Interests:

➤ **Design and Developing,** Automation and Robotics, Electric Vehicles, Robot Delivery, Air Taxi and Flying Cars, Mechatronics, Hardware Development, Renewable Energy

Work Experience:

RoboSky Lab Ltd.

- Address: Tehran, Iran.
- Position: Hardware Team Lead
- Responsibilities:
 - 1. Manage and control activities in multi-functional areas.
 - 2. Ensure appropriate operational planning is effectively executed to meet specifications
 - 3. Engage in technical discussions with mechanical and firmware engineers
 - 4. Manage the team and assist team members with their career planning and daily technical challenges
 - 5. Keep up-to-date with the latest technologies and selecting the right components to solve given problems.
 - 6. Collaborate with the team to identify the best technological solutions
 - 7. Actively participate in planning meetings
 - 8. Moving designs and optimizing BOMs from development to manufacturing
- Position: Electronic Specialist
- Responsibilities:
 - 1. Designing various dc-dc converters in a wide range of power and switching frequencies.
 - 2. Developing data logger systems to monitor system's vital stats, storing on a cool disk while sending them off on wireless link simultaneously.
 - 3. Developing an android app to receive and save data logger data.
 - 4. Designing high frequency PCBs featuring Raspberry Pi compute module and ARM co-processor
 - 5. Designing evaluation PCBs for new electronics components and performing standard test procedures
 - 6. Performing operational testing procedures for electronics systems
 - 7. Setting up laboratory test equipment and composing test scenarios
 - 8. Assembling data and assisting in the upkeep of documentation
- Position: Firmware Developer
- Responsibilities:
 - 1. Making some tweaks and improvements on existing communications over CAN and making automatic filtering
 - 2. Developing digital data logging system
 - 3. Designing a new file transfer protocol over CAN to reprogram the main board using boot-loader system
 - 4. Performing code reviews
 - 5. Writing and maintaining firmware documentation
 - 6. Testing firmware releases
 - 7. Maintaining stable firmware

> Rahnegar Hooshmand Iranian

- Address: Tehran, Iran
- Position: Electronics Engineer
- Responsibilities:
- 1. Collaborated with a team in designing and programming a GPS-based positioning system with 3G network connectivity utilizing ARM micro

Jan 2020 – Dec 2021

Dec 2021 - Jul 2024

Jul 2019 – Jan 2020

	controller. Developed OTA update infrastructure using FTP connection	
	on the system.	0 2017 1 2010
	2. Designed and manufactured a small passive data logger system using SD card or Flash memory to store debug info of the system to use in debug	Sep 2017 – Jun 2019
	process 3. Developed a dynamic encryption algorithm on raw data to make TCP	
	connections more secure 4. Upgraded telemetry data protocol to use MQTT instead of TCP/IP to	
	reduce server side process and increase efficiency also increasing	
	compatibility with IoT platform	
	5. Making a complete documentation of system and several user manuals	
	for troubleshooting	
	> Auto Mechanic Engineering Group (AMEG)	
	Address: Tehran, Iran	
	Position: Electronics Engineer	
	Responsibilities:	
	1. Analogue design including power drivers and switching power supplies,	
	2. Digital design including designing and manufacturing micro controller	
	based intelligent systems including circuit design, programming, performing simulations and providing embedded PCB compatible with	Dec 2015 – Sep 2017
	car ECU	
	 Design and manufacturing automobile suspension test stand and implementing a variety of sensors on it to monitor and test different parts 	
	4. Analogue design including power drivers and switching power supplies.	
	> Iran Aircraft Manufacturing Industries Co.	
	Address: Shahinshahr, Iran	
	Position: Intern	
	Responsibilities:	
	1. Collaborated with a team on developing a PLC-based control system and	
	designing a desktop GUI for the controller.	
	2. Design and manufacturing of a microcontroller based system for an	
	educational projects with various communications including RS232 and	May 2014 – Oct 2014
	CAN.	•
Education:	University of Tehran, Tehran, Iran	2014-2017
	M.Sc. in Mechatronics Engineering	
	Thesis: Design and manufacturing of a continuum manipulator for suitable interaction	
	with dynamic environment	
	GPA: 16.98	
	University of Isfahan, Isfahan, Iran	2010-2014
	B.Sc. in Electrical Engineering (3 rd rank graduate in the department)	
	Thesis: Performance Evaluation and Analysis of IR-HARQ-based Error Recovery	
	Techniques on The IEEE 802.11 Protocol GPA: 17.38	
Language	> Farsi: Native	
Proficiency:	> English: Working Proficiency	Fall 2015
v	TOEFL iBT Score: (27-29-19-24) 99	
	> Deutsch: Intermediate	E II 2012
Projects	> Design and Simulation of an 8-bit CPU	Fall 2012
Experiences:	Collaborated with a team on designing and simulation of an 8-bit CPU based on	
	Von Neumann architecture consist of a set of arithmetic, logic, memory access and	
	I/O instructions; provided with built-in memory and I/O blocks. I simulated the	
	whole system in Proteus Design Suit and tested it using specific binary language	
	designed for it.	Spring 2014
	Design and Implementation of an Accurate Step Motor Controller System	Spring 2014
	Implemented an ARM-based system with a matrix keypad as user input and a	
	character LCD as output to drive a step motor in two modes of speed and state	

		control. Getting current feedback to ensure smooth movement and avoiding stall.	
	_	· · · · · · · · · · · · · · · · · · ·	Spring 2014
		Development of a Wireless Communication System Using Bluetooth Module	3pmg 2014
		Collaborated with a team on developing a wireless communication system for controlling a DC motor using wireless link over a Bluetooth module.	
	>	Design, Simulation and Implementation of a 3DoF Articulated Robotic Arm	Fall 2014
		Collaborated with a team on designing and implementation of the robotic arm and	1 un 2011
		making Windows-based software with graphical interface for controlling the end-	
		effector position.	
		Design and Simulation of a Multi-Layer Perceptron(MLP) Neural	Fall 2014
		Network(NN) for Separating 4 Different Gas Types	
		Designed a MLP network trained with thermal data of 4 gases and then perform	
		successful simulation of network separating them.	a
		Design and Development of a Bio Inspired Steerable Robot Actuated by	Spring 2015
		Shape Memory Alloy Springs	
		Collaborated with a classmate on developing a steerable robot platform using only	
		SMA actuators with a high power to weight ratio able to transfer up to 5 times its weight.	
		Obstacle-Avoiding Mobile Robot	Spring 2016
		Developed an obstacle-avoiding robot equipped with ultrasonic sensors to detect	5ping 2010
		and maneuver around obstacles in its path. This project demonstrated my	
		proficiency in sensor integration and autonomous navigation algorithms.	
		proficiency in sensor integration and autonomous navigation argorithms.	
Skills:	>	Skills:	
31111 5 •		Analog Design: amplifier, pulse generator and power electronic circuit design	
		2. Microcontroller-based systems: design, simulation and implementation	
		3. PCB Designing up to 8 layer stack up (Altium designer)	
		4. Problem-solving and ability to create new solutions	
		5. C# programming in Microsoft Visual Studio environment	
		6. C/C++ programming on ARM based processors utilizing STM32 CubeIDE, Keil	
		uVision 7. Version Control Systems (Git, SVN)	
		 Version Control Systems (Git, SVN) Management and leadership 	
Published	>	A. Hadi, Mohammad Mehdi Bahmani , M. Davari "Developing a bio	Fall 2015
Papers:		inspired steerable robot actuated by shape memory alloy springs," IEEE	
•		Int. Conf. Robotics and Mechatronics, Tehran, Iran, Oct. 2015	
Honor and	>	Top 1% Iranian University Entrance Exam (Konkour)	Sep 2010
Awards:		Best Artistic Achievement Award, issued by Biotechnology Committee of	Oct 2017
		Iran Science and Technology Vice Presidency, awarded for "GeneCraft" a	
		videogame designed and developed by our team for biotechnology	
		committee game jam.	
	\triangleright	Technical Achievement Nominee, issued by Biotechnology Committee of	Oct 2017
		Iran Science and Technology Vice Presidency, awarded for "GeneCraft" a	
		videogame designed and developed by our team for biotechnology	
		committee game jam.	
		Continue of Completion II Continue II II	Jul 2010
Licenses and	~		Jul 2019 May 2018
Certifications:	>	Certificate of Completion – <u>SQL Fundamentals</u> , issued by sololearn	May 2018
T. 1.		Certificate of Completion – <u>C# Course</u> , issued by sololearn	Sep 2016
Feaching	>	Teaching Assistant, Logical Circuits	Fall 2012 Spring 2014
Experiences:	>	Teaching Assistant, Computer Architecture and Organization	Fall 2013, Spring 2014
		Teaching Assistant, Microprocessors	Fall 2013, Spring 2014 Fall 2015
		Teaching Assistant, Mechatronics	1°a11 2013
Reference:		Available upon request	