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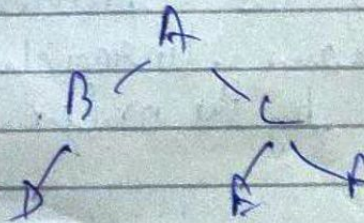
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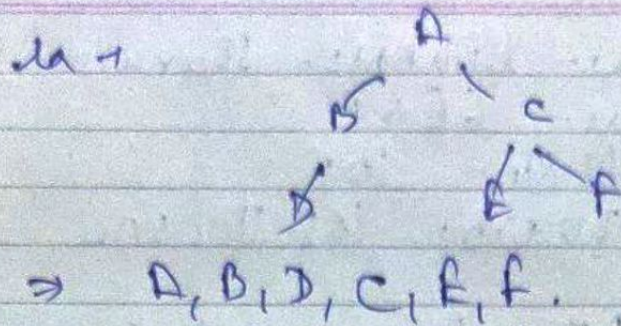
AI Assignment-1

Ans1 BFS \rightarrow Breadth first search is a vertex based technique for finding a shortest path in graph. It uses a queue data structure which follows first in first out. In BFS, one vertex is selected at a time when it is visited & marked then its adjacent are visited & stored in the queue.



\rightarrow Output \Rightarrow A, B, C, D, E, F

DPS stands for depth first search is an edge based technique. It uses the stack data structure, performs two stages, first visited vertices are pushed into stack & second if there is no vertices then visited vertices are popped.



Ans-2 Informed search also have infoⁿ on the goal state which helps on more efficient searching. This info. is obtained by a function that estimates how close a state is to the goal state.

Example → Greedy search & graph search.

Uniformed search are also have no additional infoⁿ on the goal node other than the one provided in the problem defⁿ. The plans to reach the goal state differ only by the order & length of actions.

Ans-3 Constraint satisfaction problem

In AI, constraint satisfaction is the process of finding a solution to a set of constraints that impose condⁿ that the variable must satisfy. A solⁿ is therefore a set of values for the variable that satisfies all constraints - that is, a point in the feasible region.

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The technique used in constraint satisfaction depend on the kind of constraints being considered.

Solving → a constraint problems on finite domains are typically solved using a form of search.

Ans 4 → A^* algo

- often known as OR graph algo.

- used to find just one promising path or solⁿ.

- Application →

→ mostly used in practices

eg → Traffic ~~or~~ navigation system.

eg → Traffic navigation system.

AO^* algo.

- known as AND-OR algo.

- used to find more than one promising path or solⁿ.

- Application

→ rarely used in practices application.

eg → alpha-beta pruning for game tree.

Ans 5 → The great advantage of IDDFS is found in game tree searching where the IDDFS search operation tries to improve the depth defⁿ, heuristics, & scores of searching nodes so as to enable efficiency in the search algo.

- IDDFS gives no hope to find the solⁿ if it exists in the tree.
- When the solⁿ are found at the lower depths payⁿ, then the algo proves to be efficient & in time.
- space & time complexities are expressed as:
 $O(d)$ & here d is defined as goal depth.
- Though the work is done here is more yet the performance of IDDFS is better than single BFS & DFS operating exclusively.
- Quick responsiveness. The early results indications are a plus point in this algo.