

Dynamic Gaussian Graphical Model: coefficient varying model for partial correlation estimation

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1 Overview of estimation in graphical models

Graphical models are quite useful in many domains to uncover the dependence structure among observed variables. Typically, we consider a p -dimensional multivariate normal distributed random variable $X = (X_1, \dots, X_p) \sim \mathcal{N}(\mu, \Sigma)$, where p is the number of features. Then a graph of these p features can be constructed based on there conditional dependence structure. More precisely, we can construct a Gaussian graphical model $\mathcal{G} = (V, E)$, where $V = \{1, \dots, p\}$ is the set of nodes and $E = \{(i, j) | X_i \text{ is conditionally dependent with } X_j, \text{ given } X_{V/\{i, j\}}\}$.

Let $\Omega = \Sigma^{-1} = (\omega_{i,j})_{1 \leq i, j \leq p}$ be the precision matrix. Then X_i and X_j are conditionally dependent given other features if and only if $\omega_{ij} \neq 0$. Therefore, estimating the covariance matrix and precision matrix of X is equivalent to estimate the structure of Gaussian graphical model \mathcal{G} . More discussion can be found in [7].

There are lots of literatures discussing about estimating Σ and Ω . Utilizing the idea of LASSO from Tibshirani [?], Meinshausen and Bühlmann [8] performed a computationally attractive method for nearest neighborhood selection at each node in the graph. Another nature way is to estimate Σ and Ω is the penalized likelihood approach. Friedman, Hastie and Tibshirani [4] proposed the graphical lasso. Fan, Feng and Wu [1] studied the penalized likelihood methods with the SCAD penalty and the adaptive LASSO penalty. Cai, Liu and Luo [?] performed a constrained l_1 minimization approach to estimate sparse precision matrix (CLIME).

In practice, dynamic graphical model are very attractive. We can consider dynamic graphical model under the context of varying coefficient model [5, 2, 3]. Zhou, Lafferty and Wasserman [9] developed a nonparametric framework for estimating time varying graphical model for estimating time varying graphical structure for multivariate Gaussian distributions $X^t \sim \mathcal{N}(0, \Sigma(t))$ using l_1 regularization method. Zhou's model assumed that the observations X^t are independent and changed smoothly. Kolar and Xing [6] showed the model selection consistency for

the procedure proposed in Zhou et al. [9] and for the modified neighborhood selection procedure of Meinshausen and Bühlmann [8].

1.1 Nearest neighbor selection approach

1.2 Penalized likelihood approach

1.3 Constrained l_1 Minimization Approach

1.4 time-varying graph and coefficient varying models

2 Joint estimation of multiple graphs

2.1 Stationary graphs with spacial-temporal dependence: GEMINI

2.2 Time varying graph estimation through smoothed covariance matrix

2.3 Fused Graphical Lasso

2.4 Smoothed Kendall's tau correlation matrix

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