

COMPSCI 3AC3

Assignment 1

January 23 2022

1 Part I

Exercises 3, 4, 5, 8 from Chapter 2.

1.1 Q3

The ordering of these function from smallest to largest is as follows:

$f_2, f_3, f_6, f_1, f_4, f_5$

1.2 Q4

From smallest to largest the right ordering is: $g_1, g_5, g_3, g_4, g_2, g_7, g_6$.

1.3 Q5

- (i) False, as it is possible that $g(n) = 1$ for all n , $f(n) = 2$ for all n , subsequently $\log_2 g(n) = 0$, therefore $\log_2 f(n) \leq c \log_2 g(n)$ cannot be written. Conversely, if we need $g(n) \geq 2$ for all n beyond n_1 , this then remains true. Considering $f(n) \leq cg(n)$ for all $n \geq n_0$, then $\log_2 f(n) \leq \log_2 g(n) + \log_2 c \leq (\log_2 c) (\log_2 g(n))$ once $n \geq \max(n_0, n_1)$.
- (ii) False. Consider $f(n) = 2n$ and $g(n) = n$. Thus, $2^{f(n)} = 4^n$, and $2^{g(n)} = 2^n$.
- (iii) True. As $f(n) \leq cg(n)$ for all $n \geq n_0$, we have $(f(n))^2 \leq c^2(g(n))^2$ for all $n \geq n_0$.

1.4 Q8

- (a) Let us assume for a moment that n is a perfect square. The first jar is dropped from heights of multiples of \sqrt{n} , until it breaks. If it is dropped from the top and doesn't break from height, then no more work needs to be done. However, if it breaks from a height $j\sqrt{n}$, we then know that the highest safe rung lies between $(j-1)\sqrt{n}$ and $j\sqrt{n}$, as such the second jar is dropped from rung $1 + (j-1)\sqrt{n}$ upward, increasing by one progressively. We drop each of the two jars at most \sqrt{n} times, for a total of at most $2\sqrt{n}$. If n isn't a perfect square, the first jar is dropped from heights which are multiples of $\lfloor \sqrt{n} \rfloor$ and then subject the second jar to the aforementioned rule. Thus, the first jar is dropped at most $2\sqrt{n}$ times and the second jar at most \sqrt{n} , which is bounded by $O(\sqrt{n})$.

- (b) By induction, $f_k(n) \leq 2kn^{1/k}$. The first jar is dropped from heights of multiples of $\lfloor n^{(k-1)/k} \rfloor$. Thus, the first jar is dropped at most $2n/n^{(k-1)/k} = 2n^{1/k}$ times, which reduces the sets of potential rungs to intervals of length of at most $n^{(k-1)/k}$.

For $k - 1$ jars, we apply this process recursively. We claim by induction that it uses at most $2(k - 1)(n^{(k-1)/k})^{1/(k-1)} = 2(k - 1)n^{1/k}$ drops. Completing the inductive step, adding $\leq 2n^{1/k}$ drops by the first jar, we obtain a bound of $2kn^{1/k}$.

2 Part II

Exercises 2, 3, 4, 6, 7 from Chapter 5.

2.1 Q2

We can solve this by defining a recursive divide and conquer algorithm DC, taking a sequence of distinct numbers a_1, \dots, a_n returning N and a'_1, \dots, a'_n where N represent the number of significant inversion and a'_1, \dots, a'_n represents the sequence in an increasing order.

The formal definition of this algorithm is as follows, where for $n = 1$ DC returns $N = 0$ and $\{a_1\}$ and for $n > 1$:

- $k = \lfloor n/2 \rfloor$
- Recursive call to DC (a'_1, \dots, a'_k) . Returns b_1, \dots, b_k .
- Recursive call to DC (a'_{k+1}, \dots, a'_n) . Returns N_2 and b_{k+1}, \dots, b_n .
- Calculate the amount N_3 of significant inversions (a_i, a_j) where $i \leq k < j$.
- Return $N - N_1 + N_2 + N_3$ and $a'_1, \dots, a'_n - \text{MERGE}(b_1, \dots, b_k; b_{k+1}, \dots, b_n)$

For MERGE, a version of merge-count of b_1, \dots, b_k and b_{k+1}, \dots, b_n can be implemented as follows.

- Instantiate counters: $i \leftarrow k, j \leftarrow n, N_3 \leftarrow 0$.
- If $b_i \leq 2b_j \rightarrow$
 - if $j > k + 1$ decrease j by 1
 - if $j = k + 1$ return N_3
- If $b_i > 2b_j$, increase N_3 by $j - k$. \rightarrow
 - if $i > 1$ decrease i by 1
 - if $i = 1$ return N_3

For every i we increment N between b_i and all b_j . If $b_i \leq 2b_j$ no significant inversions exist between b_i and any b_m s.t. $m \geq j$; j decreases. If $b_i > 2b_j$ then $b_i > 2b_m$ for all m s.t. $k < m \leq j$. This means that we have found $j - k$

significant inversions with b_i ; we increase N_3 by $j - k$. Once we reach $i = 1$ with b_1 the algorithm completes.

2.2 Q3

We can solve this problem with a divide and conquer solution. First, let v_1, \dots, v_n denote the equivalence of the cards; cards a and b are equivalent if $v_i = v_j$. The problem is solved if we can find a value x such that more than $\frac{n}{2}$ of the indices have $v_i = x$. We first divide the set of cards into two approximately equal piles: one set of $\lfloor n/2 \rfloor$ cards and the other a set of $\lceil n/2 \rceil$ cards. On both sets the algorithm will run recursively, with the directive that, if it finds an equivalence class with more than half of the cards total, it returns a sample card in the class. If there are more than $\frac{n}{2}$ cards that are equivalent in the entire set; namely equivalence class x , then at the least one of the sides will possess cards with more than half equivalent to x . As such, one of the recursive calls will return a card with equivalence class x .

The reverse of this does not hold. It is possible for there to exist, on one side, a majority of equivalence cards without possessing more than $\frac{n}{2}$ cards in total. Therefore, if a card with a majority equivalence is found in either set of cards, we have to test this card with all the other cards.

The algorithm has two recursive calls, at most $2n$ tests performed outside recursive calls. The following recurrence is then derived:

$$T(n) \leq 2T(n/2) + 2n.$$

Which implies that $T(n) = O(n \log n)$.

2.3 Q4

We can solve this through a convolution. One vector is defined as (q_1, q_2, \dots, q_n) and the other vector is defined as $b = (n^{-2}, (n-1)^{-2}, \dots, 1/4, 1, 0, -1, -1/4, \dots, -n^{-2})$. For each j the convolutions a and b will have entries:

$$\sum_{i < j} \frac{q_i}{(j-i)^2} + \sum_{i > j} \frac{-q_i}{(j-i)^2}$$

We then multiply this term by Cq_j to obtain the net force F_j . This process takes $O(n \log n)$ time, and obtaining F_j takes $O(n)$ time.

2.4 Q6

First some definitions: - u is smaller than v , or $u \prec v$, if $x_u < x_v$. - If S is a set of nodes, $u \prec S$ if u is smaller than any node in S .

The algorithm is defined as follows: Starting at the root r of the tree, detect if r is smaller compared to its children. If this is proven true, the root is then a

local minimum; else we proceed to smaller children and iterate from there. If a (1) node v is reached that is smaller than both children, (2) or a leaf w is reached, the algorithm terminates.

The runtime of this algorithm is in $O(d) = O(\log n)$ probes of the tree; with a local minimum as a return value, which is proven as follows:

- As explained above, if root r is return, then it follows that it is a local minimum
- If the algorithm terminates in case (1), v is determined to be a local minimum as v is smaller than its two children and its parent.
- In case (2) if we terminate, w is a local minimum because w is smaller than its parent.

2.5 Q7

First some definitions:

- B will signify the set of nodes on the border of the grid G
- G has Property (*) if it has a node $v \notin B$ adjacent to a node B which satisfies $v \prec B$
- In grid G with Property (*), the global minimum is not on the border B , as such G has at least one local minimum that is not on the border B . These can be denoted as a local minimum and an internal local minimum.

This problem can be solved with a recursive algorithm which takes a grid satisfying Property (*) returning an internal local minimum, with $O(n)$ probes. Let G satisfy Property (*), and $v \notin B$ is adjacent to a node B and smaller than every node in B . C will denote the union of nodes in the middle row and column of G (excepting nodes on border G). Let $S = B \cup C$; removing S from G allocates G into four sub-grids. Then let T denote all nodes adjacent to S .

With $O(n)$ probes, we detect a minimum value node $u \in S \cup T$. As $u \notin B$, since $v \in S \cup T$ and $v \prec B$; there are two cases. If $u \in C$ then u is an internal local minimum, as all neighbors of u are in $S \cup T$, u is also smaller than all of them; else $u \in T$. G' will denote a sub-grid with u , with parts of S on its border. As u is adjacent to the border of G' and is also smaller than all nodes on the border of G' , G' satisfies Property (*). Therefore, G' possesses an internal local minimum, that is an internal local minimum of G as well. The algorithm is recursively called on G' to find said minimum.

If $I'(n)$ represents the amount of probes required to detect an internal local minimum, the recurrence $T(n) = O(n) + T(n/2)$ occurs, which is $T(n) = O(n)$. To find a local minimum of grid G , using $O(n)$ probes, the node v on the border B with a minimum values is detected. If there exists a corner node v , we have found a local minimum and the algorithm terminates; else there is a unique neighbor of u of v that doesn't exist on B . If $v \prec u$, again we detect a local minimum v and the algorithm terminates, else G satisfies Property (*), and we call the algorithm on G .