KONGU ENGINEERING COLLEGE

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DERPARTMENT OF ELECTRONICS AND COMMUNICATION ENGINEERING

20ECE02-MICROCONTROLLER BASED AUTOMATION PROJECT REPORT

TEMPERATURE DEPENDENT FAN CONTROL SYSTEM USING PIC16F877A

AIM:

To simulate and design the temperature dependent fan control system using pic16f877a.

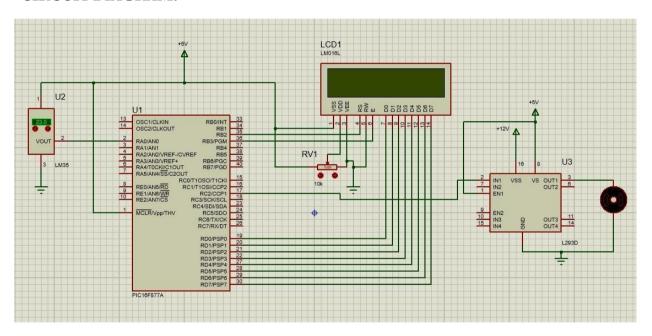
SOFTWARE REQUIRED:

Proteus 8 Professional, PIC CSS.

HARDWARE REQUIRED:

S.No	Component Name	Value	Quantity
1)	Microcontroller	PIC16F877A	1
2)	Crystal Oscillator		1
3)	Temperature sensor	LM35	1
4)	Motor driver	L293D	1
5)	DC motor	9v	1
6)	Potentiometer	10k	1
7)	LCD display		1
8)	Power supply	12v, 9v	1

CIRCUIT DIAGRAM:



WORKING:

- The temperature is measured by means of a temperature sensor LM35.
- The output voltage of the sensor is fed to the A/D channel of the Microcontroller.
- Based on the sensed temperature the speed of the motor is controlled using PWM.
- Several temperature ranges was set in the code to vary the motor speed based on the level of temperature sensed.
- The speed of the motor is controlled by using PWM.
- The motor is driven using a driver IC 1293D, See a brief explanation on its working and wiring.

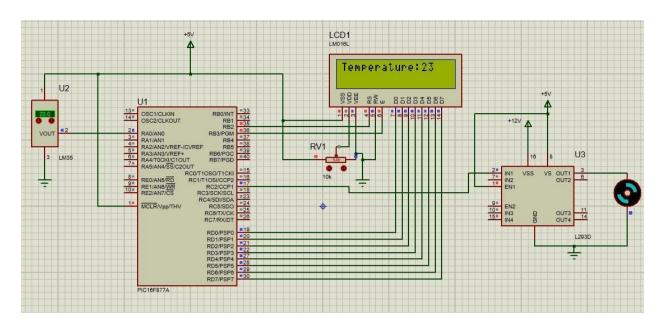
- The rise in temperature will result in increase in speed of the motor and vice versa. These type of Temperature controlled fan systems can generally be used to maintain temperature of a room or object automatically.
- The received analog value is calibrated to display the temperature in the LCD. The "real_value" int value is converted to character using "sprintf" in order to display the temperature values.
- The temperature ranges and duty cycle of the PWM is given using the subroutine ".motor". So the microcontroller runs a check on the temperature every time and alters the speed of the motor based on it.

PROGRAM CODE:

```
#include <16F877A.h>
#device ADC=10
#FUSES NOWDT
#FUSES NOBROWNOUT
#FUSES NOLVP
#use delay(crystal=20000000)
#byte lcd=0x08
#byte TRIS lcd=0x88
#bit rs=0x06.2
#bit en=0x06.3
#bit TRIS_rs=0x86.2
#bit TRIS_en=0x86.3
long int adc_value,real_value;
int i:
char value[4];
unsigned char text[]="Temperature:";
void display(unsigned char a, int b);
void motor();
void main()
 TRIS_lcd=TRIS_rs=TRIS_en=0;
 display(0x38,0);
 display(0x01,0);
 display(0x0c,0);
 for(i=0;i<=12;i++)
  display(text[i],1);
 setup_timer_2(T2_DIV_BY_16,255,1);
 SETUP ADC PORTS(AN0);
 SET_ADC_CHANNEL(0);
 SETUP_ADC(ADC_CLOCK_INTERNAL);
  while(TRUE)
   {
    delay us(20);
    adc_value=READ_ADC();
    delay_us(10);
    real_value=adc_value/2;
    motor();
```

```
sprintf(value,"%lu",real_value);
     display(0x8c,0);
     for(i=0;i<=3;i++)
       display(value[i],1);
}
void display(unsigned char a, int b)
  lcd=a;
  rs=b;
  en=1;
  delay_ms(10);
  en=0;
  delay_ms(10);
void motor()
 if(real_value<10)
 setup_ccp1(CCP_OFF);
 if(real_value>10)
  setup_ccp1(CCP_PWM);
   if(real_value>=10&&real_value<=29)
    set_pwm1_duty((int16)204);
   else if(real_value>=30&&real_value<=69)
   set_pwm1_duty((int16)510);
   else if(real_value>=70&&real_value<=99)
     set_pwm1_duty((int16)715);
   else if(real_value>=100&&real_value<=150)
     set_pwm1_duty((int16)919);
```

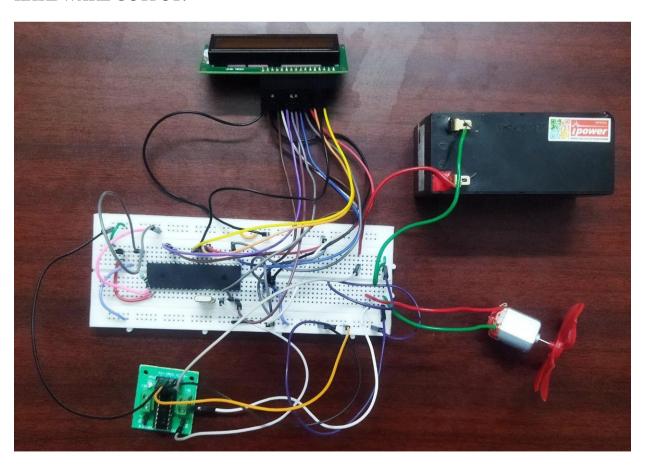
SIMULATION OUTPUT:



VIDEO LINK:

 $\underline{https://drive.google.com/file/d/1QG4QEs-XzDDqwN1mI3ek-xbmEeqDxJhd/view?usp=sharing}$

HARDWARE OUTPUT:



1	VIDEO LINK:
h	nttps://drive.google.com/file/d/1A84PpG_03NUvajDlF0TCT1Zk8ZHtZBSs/view?usp=sharing
F	RESULT: Thus, a temperature dependent fan control system using pic16f877a microcontroller

