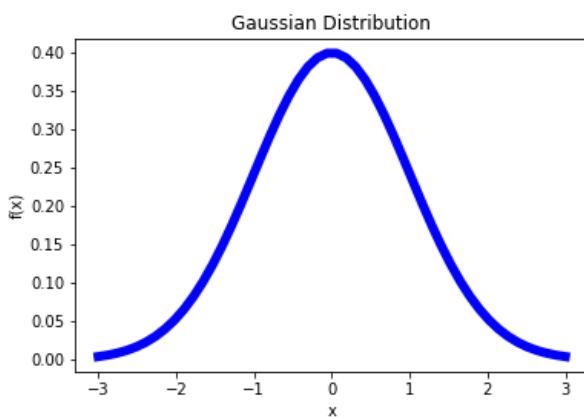


## Problem-1: Histogram & Cross-Validation

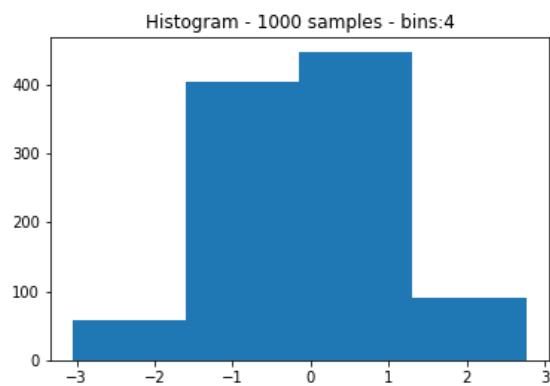
(a)



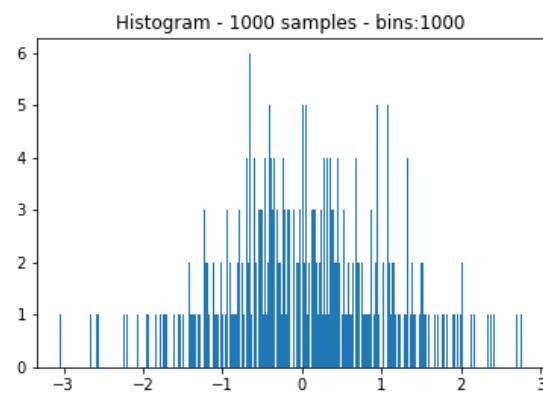
(b)

Drawing  $N=1000$  samples

(ii)  $\text{Bins} = 4$



$\text{Bins} = 1000$



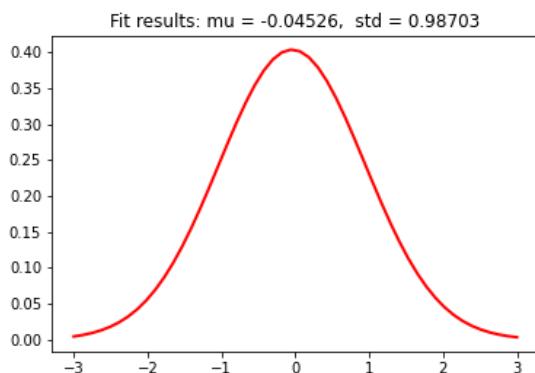
(iii) Estimating the mean & std. deviation of our data

$$\mu = -0.04526$$

$$\sigma = 0.98703$$

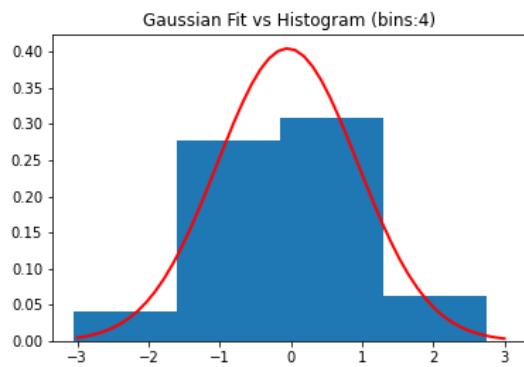
(iv) Gaussian curve vs Histograms

(I) fitted Gaussian Curve

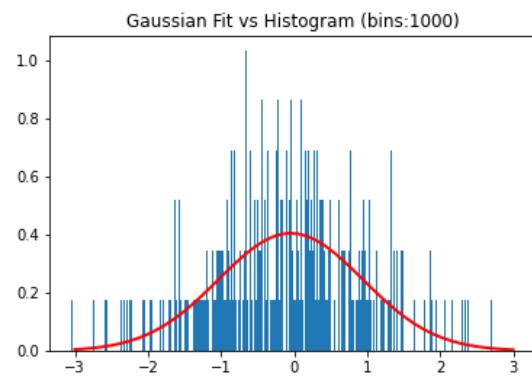


(II) fitted Gaussian vs Histogram

(a) Bins = 4



(b) Bins = 1000



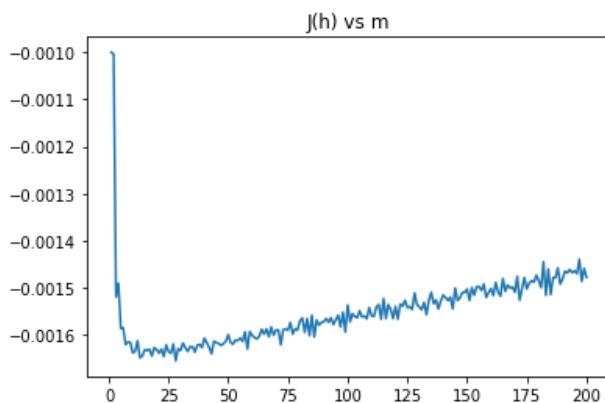
→ red line depicts fitted gaussian curve

(v) Are two histograms representative of our data's distribution?

→ The two histograms are not the ideal representation of our data's distribution.

### (c) Cross Validation

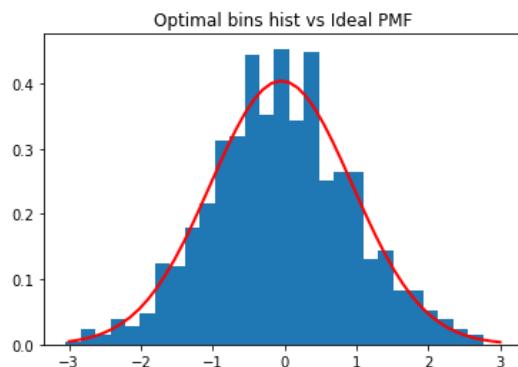
#### (i) $P(\hat{f}) \hat{J}(h)$



#### (ii) Find $m^*$ that minimizes $\hat{J}(h)$

The "m" that minimizes  $\hat{J}(h)$  is  $m=28$

#### (iii) Optimal bins vs histogram with optimal bins



## Problem-2 : Gaussian Whitening

$$\textcircled{a} \quad |\Sigma| = (4-1) = \textcircled{3}$$

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix}^{-1} = \frac{1}{ad-bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

$$\Sigma^{-1} = \frac{1}{3} \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix}$$

$$x - \mu = \begin{bmatrix} x_1 - 2 \\ x_2 - 6 \end{bmatrix}$$

$$S_0 \quad \underline{\Sigma^{-1}(x-\mu)} = \frac{1}{3} \begin{bmatrix} 2 & -1 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} x_1 - 2 \\ x_2 - 6 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} 2(x_1 - 2) - 1(x_2 - 6) \\ -1(x_1 - 2) + 2(x_2 - 6) \end{bmatrix}$$

$$= \frac{1}{3} \begin{bmatrix} 2x_1 - x_2 + 2 \\ 2x_2 - x_1 - 10 \end{bmatrix}$$

$$\underline{(x-\mu)^T \Sigma^{-1} (x-\mu)} \Rightarrow \begin{bmatrix} (x_1 - 2) & (x_2 - 6) \end{bmatrix} \times \frac{1}{3} \begin{bmatrix} 2x_1 - x_2 + 2 \\ 2x_2 - x_1 - 10 \end{bmatrix}$$

$$= \frac{(x_1 - 2)(2x_1 - x_2 + 2) + (x_2 - 6)(2x_2 - x_1 - 10)}{3}$$

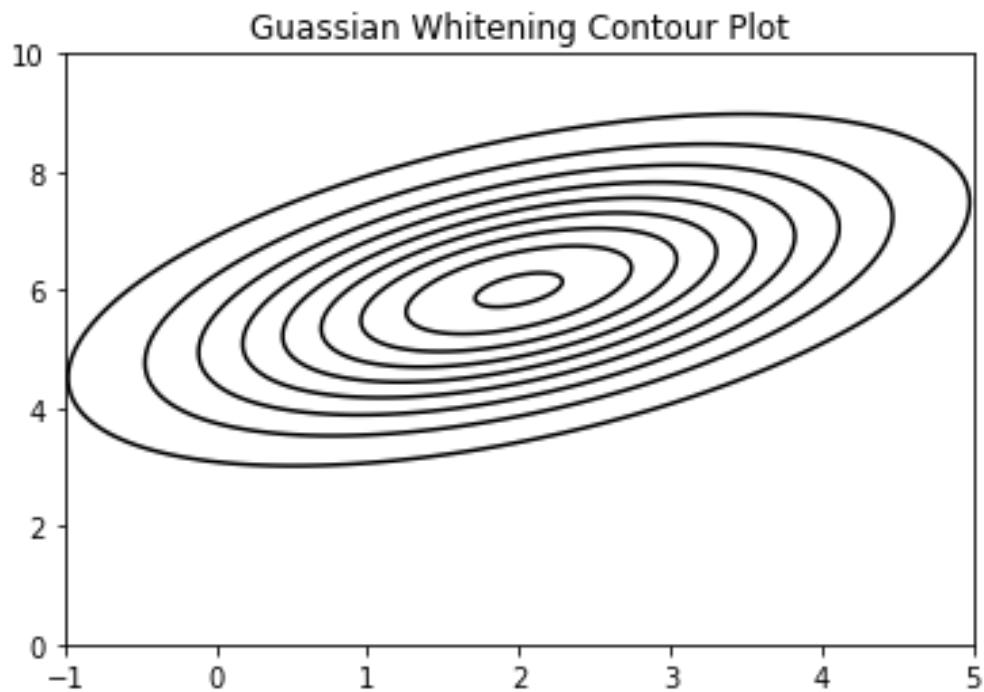
$$= \frac{\left( 2x_1^2 - x_1 x_2 + 2x_1 - 4x_1 + 2x_2 - 4 \right) + \left( 2x_2^2 - x_1 x_2 - 10x_2 - 12x_2 + 6x_1 + 60 \right)}{3}$$

$$z = \left( \frac{2x_1^2 + 2x_2^2 - 2x_1x_2 + 4x_1 - 20x_2 + 56}{3} \right)$$

$$f_x(x) = \left( \frac{1}{\sqrt{4\pi^2 \times 3}} \right) \exp \left\{ -\frac{1}{2} \left( \frac{2x_1^2 + 2x_2^2 - 2x_1x_2 + 4x_1 - 20x_2 + 56}{3} \right) \right\}$$

$$f_x(x) = \frac{1}{\sqrt{12\pi^2}} \exp \left\{ \left( \frac{x_1x_2 + 10x_2 - 2x_1 - x_1^2 - x_2^2 - 28}{3} \right) \right\}$$

(ii) Contour Plot of  $f_x(x)$



6 PDF of  $X \sim N(0, I)$

$$f_X(x) = \frac{1}{\sqrt{(2\pi)^2 |\Sigma|}} \exp \left\{ -\frac{1}{2} (x - \mu)^T \Sigma^{-1} (x - \mu) \right\}$$

here  $\mu = 0$ ,  $\Sigma = I$

Given  $y = ax + b$

$$(i) \quad \mu_y \triangleq \mathbb{E}[y] \Rightarrow \mathbb{E}[Ax+b] = A\mathbb{E}[x] + \mathbb{E}[b] \\ = A\mu_x + b \int_{-\infty}^{\infty} f_x(x) dx$$

$$\text{So } \mu_y = 0 + b \Rightarrow \boxed{\mu_y = b}$$

$$\begin{aligned}
 \sum_y &\triangleq \mathbb{E}[(y - \mu_y)(y - \mu_y)^T] \\
 &\triangleq \mathbb{E}[(y - \mu_y)(y^T - \mu_y^T)] \\
 &\Rightarrow \mathbb{E}[yy^T - \mu_y y^T - y\mu_y^T + \mu_y \mu_y^T] \\
 &\Rightarrow \mathbb{E}[(Ax+b)(x^TA^T+b^T) - \mu_y(x^TA^T+b^T) \dots \\
 &\quad \dots - (Ax+b)\mu_y^T + \mu_y \mu_y^T] \\
 &\Rightarrow \mathbb{E}[(Ax x^T A^T) + \cancel{A x b^T} + \cancel{b x^T A^T} + \cancel{b b^T} - \cancel{b x^T A^T} - \cancel{b b^T} - \cancel{A x b^T} - \cancel{b b^T} + \cancel{b b^T}] \\
 &\quad [\text{since } \mu_y = b]
 \end{aligned}$$

$$\Rightarrow \mathbb{E}[A x x^T A^T]$$

$$\Rightarrow A \mathbb{E}[x x^T] A^T \quad \text{---} \quad \textcircled{1}$$

We know  $\Sigma_x = I$  i.e.  $\Sigma_x = \mathbb{E}[(x - \mu)(x - \mu)^T]$  as  $\mu_x = 0$

$$\text{so } I = \mathbb{E}[x x^T] \quad \text{---} \quad \textcircled{2}$$

Using \textcircled{2} in \textcircled{1} we get

$$\Sigma_y = A A^T$$

(ii) Show  $\Sigma_y$  is symmetric positive semi-definite

$$\text{i.e. } \Sigma_y = \Sigma_y^T$$

$$\textcircled{a} \quad \Sigma_y = A A^T \quad \Sigma_y^T = (A A^T)^T = A A^T$$

$$\therefore \Sigma_y = \Sigma_y^T \text{ so } \Sigma_y \text{ is symmetric.}$$

\textcircled{b} Positive Semi Definite

$$\text{To prove: } v^T \Sigma_y v \geq 0 \quad \forall v \in \mathbb{R}^d$$

$$\begin{aligned} v^T \Sigma_y v &= v^T \mathbb{E}[(y - \mu_y)(y - \mu_y)^T] v \\ &= \mathbb{E}[v^T (y - \mu_y)(y - \mu_y)^T v] \end{aligned}$$

$$= \mathbb{E}[b^T b] \quad (\text{where } b = (Y - \mu_y)^T v)$$

$$= \mathbb{E}[||b||^2] \text{ i.e. } \geq 0$$

so  $v^T \Sigma_y v \geq 0 \therefore \Sigma_y$  is positive semi-definite

(iii)  $A$  &  $\Sigma_y$ ? such that  $\Sigma_y = \text{sym. \& positive definite}$

If  $\Sigma_y$  is positive definite then  $v^T \Sigma_y v > 0$   
i.e.  $v^T (A A^T) v > 0$  for all  $v \in \mathbb{R}^n$  as  $\Sigma_y = A A^T$ .

$$\text{So } (v^T A)(A^T v) > 0 ; \text{ let } d = A^T v$$

i.e.  $d^T \cdot d > 0$ , we know  $d^T \cdot d \geq 0$

but for  $d^T \cdot d > 0$  it means that  $d = A^T v$   
can't be zero.

So the nullspace of  $A^T$  should be  
empty such that  $A^T v$  never goes to zero for  
any  $v \in \mathbb{R}^n$ .

That means " $A$ " should be invertible

$$(iv) \text{ Given } \underline{\mu_y} = \begin{bmatrix} 2 \\ 6 \end{bmatrix} \text{ & } \underline{\Sigma_y} = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$$

Finding A:

$$\text{So } b = \begin{bmatrix} 2 \\ 6 \end{bmatrix}$$

$$\Sigma_y = U \Lambda U^T$$

[eigen decomposition]

$$U^T U = I \Rightarrow \begin{bmatrix} v_1 & v_3 \\ v_2 & v_4 \end{bmatrix} \begin{bmatrix} v_1 & v_2 \\ v_3 & v_4 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$\Rightarrow v_1^2 + v_3^2 = 1 \quad v_1 v_2 + v_3 v_4 = 0$$

$$v_3^2 = 1 - v_1^2 \quad v_4 = \underbrace{\left( \begin{array}{c} -v_1 v_2 \\ v_3 \end{array} \right)}_{\text{ }} \quad v_2^2 + v_4^2 = 1$$

$$\begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} v_1 & v_2 \\ v_3 & v_4 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} v_1 & v_3 \\ v_2 & v_4 \end{bmatrix}$$

$$\begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} v_1 & 3v_2 \\ v_3 & 3v_4 \end{bmatrix} \begin{bmatrix} v_1 & v_3 \\ v_2 & v_4 \end{bmatrix} = \begin{bmatrix} v_1^2 + 3v_2^2 & . \\ v_1 v_3 + 3v_4 v_2 & v_3^2 + 3v_4^2 \end{bmatrix}$$

$$2 = v_1^2 + 3v_2^2$$

$$1 = v_1 v_3 + 3v_4 v_2$$

$$2 = v_3^2 + 3v_4^2$$

$$2 = (1 - v_1^2) + 3(1 - v_2^2)$$

$$\Rightarrow 2 = 4 - v_1^2 - 3v_2^2$$

$$1 = v_1 v_3 + 3 v_2 \left( -\frac{v_1 v_2}{v_3} \right)$$

$$\Rightarrow \frac{v_3}{v_1} = v_3^2 - 3 v_2^2 = 1 - v_1^2 - 3 v_2^2$$

$$= 1 - (2) = \textcircled{-1}$$

$v_1 = -v_3$

$$\text{So } v_1 = v_3 = \pm \frac{1}{\sqrt{2}}$$

Let's say  $v_1 = \begin{pmatrix} 1 \\ \frac{1}{\sqrt{2}} \end{pmatrix}$   $v_3 = \begin{pmatrix} -1 \\ \frac{1}{\sqrt{2}} \end{pmatrix}$

$$v_4 v_2 = \textcircled{\frac{1}{2}} \quad \& \quad v_2^2 = \frac{1}{2}$$

$$\text{So } v_2 = +\frac{1}{\sqrt{2}} \quad \& \quad v_4 = +\frac{1}{\sqrt{2}}$$

(2)

$$v_2 = \begin{pmatrix} -1 \\ \frac{1}{\sqrt{2}} \end{pmatrix} \quad \& \quad v_4 = \begin{pmatrix} -1 \\ \frac{1}{\sqrt{2}} \end{pmatrix}$$

$v_1$	$v_3$
$\frac{1}{\sqrt{2}}$	$-\frac{1}{\sqrt{2}}$
$-1$	$\frac{1}{\sqrt{2}}$

$$\text{So } U = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix}$$

(1)

$$\begin{pmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \end{pmatrix}$$

$$(3) \begin{bmatrix} -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} \xrightarrow{\text{circled 3)} } \begin{bmatrix} -\frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix}$$

$$\begin{array}{c} U \\ \left[ \begin{array}{cc} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{array} \right] \end{array} \begin{array}{c} \Lambda \\ \left[ \begin{array}{cc} 1 & 0 \\ 0 & 3 \end{array} \right] \end{array} \begin{array}{c} U^T \\ \left[ \begin{array}{cc} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{array} \right] \end{array} = AA^T$$

$$= \begin{bmatrix} \frac{1}{\sqrt{2}} & \frac{3}{\sqrt{2}} \\ -\frac{1}{\sqrt{2}} & \frac{3}{\sqrt{2}} \end{bmatrix} \begin{bmatrix} \frac{1}{\sqrt{2}} & -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{bmatrix} = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$$

$$\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \begin{bmatrix} a_{11} & a_{21} \\ a_{12} & a_{22} \end{bmatrix} = \begin{bmatrix} a_{11}^2 + a_{12}^2 & a_{11}a_{21} + a_{12}a_{22} \\ a_{21}a_{11} + a_{22}a_{12} & a_{21}^2 + a_{22}^2 \end{bmatrix}$$

$$l = a_{11}a_{21} + a_{12}a_{22}$$

$$z = a_{11}^2 + a_{12}^2$$

$$2 = a_{21}^2 + a_{22}^2$$

$$a_{11} = \frac{\sqrt{3}}{\sqrt{2}}, \quad a_{12} = \frac{1}{\sqrt{2}}$$

$$a_{21} = \frac{\sqrt{3}}{\sqrt{2}}, \quad a_{22} = \frac{-1}{\sqrt{2}}$$

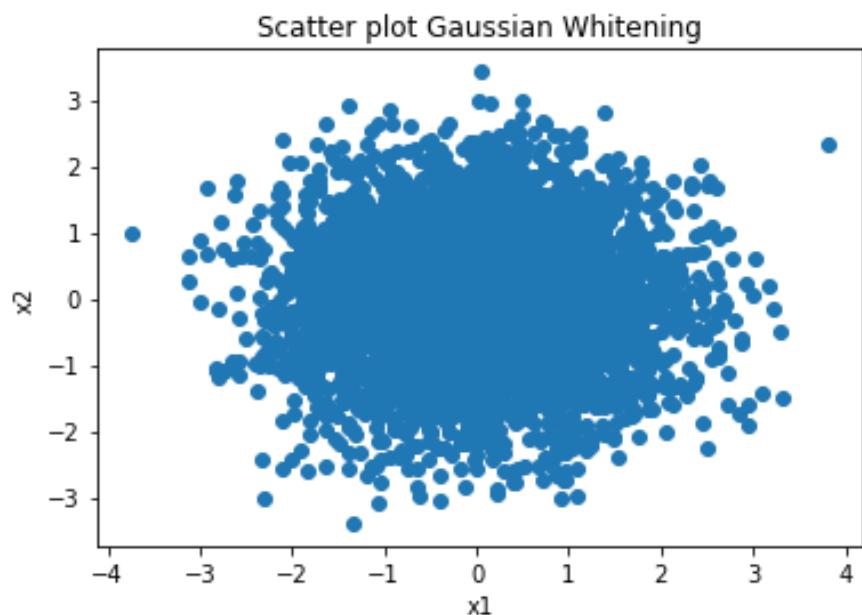
$$a_{11}a_{21} = \frac{\sqrt{3}}{\sqrt{2}} \cdot \frac{\sqrt{3}}{\sqrt{2}}$$

$$a_{12}a_{22} = \frac{1}{\sqrt{2}} \cdot -\frac{1}{\sqrt{2}}$$

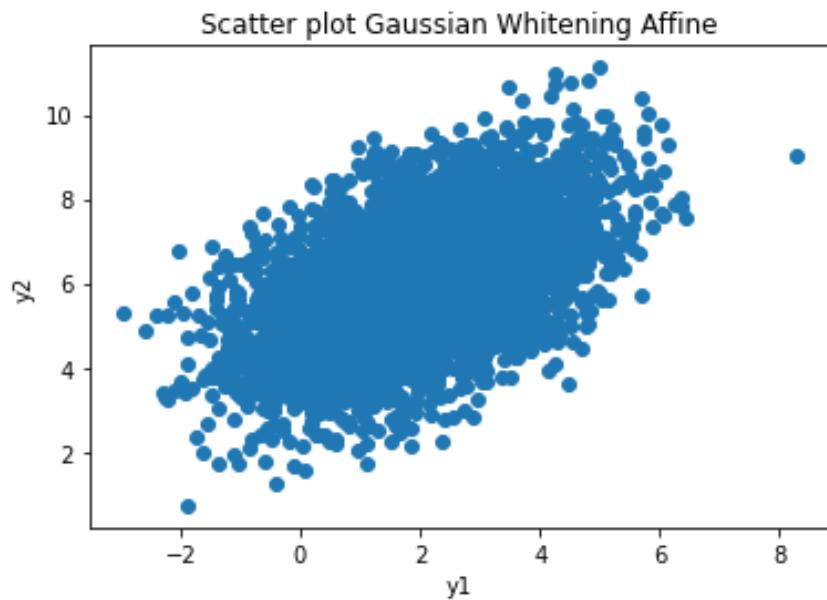
$$A = \frac{1}{\sqrt{2}} \begin{bmatrix} \sqrt{3} & 1 \\ \sqrt{3} & -1 \end{bmatrix}$$

This is  
one possible solution  
for "A"

(i) 2D standard normal distribution



(ii) Affine transformation



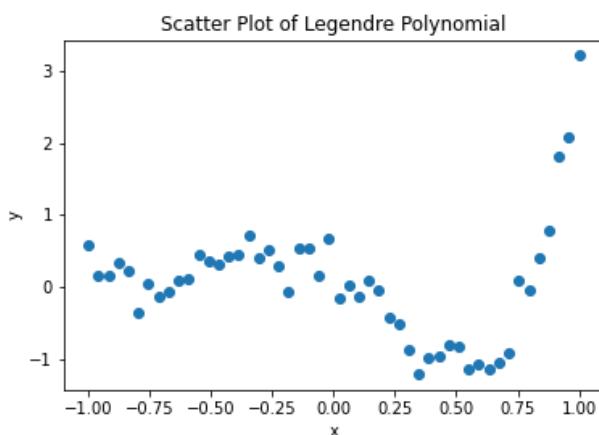
$$\begin{aligned}
 AA^T &= U \Lambda U^T \\
 &= (U \sqrt{\Lambda})(\sqrt{\Lambda} U^T) \\
 &= (U \sqrt{\Lambda}) (\sqrt{\Lambda} U)^T
 \end{aligned}$$

So  $A = U \sqrt{\Lambda}$

$U$  &  $\Lambda$  are obtained from eigen value decomposition of  $\Sigma_y$ .

Problem-3:

(a) Scatter Plot Data



(b) Given N=50

$$\hat{\beta} = \underset{\beta}{\operatorname{argmin}} \|y - X\beta\|^2$$

$$y = \begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_{50} \end{bmatrix}$$

where  $y_i = \beta_0 + \beta_1 L_1(x_i) + \beta_2 L_2(x_i)$   
 $+ \beta_3 L_3(x_i) + \beta_4 L_4(x_i)$

&  $x_i = i^{\text{th}}$  element in np.linspace(-1, 1, 50)

$$X = \begin{bmatrix} L_0(x_1) & L_1(x_1) & L_2(x_1) & L_3(x_1) & L_4(x_1) \\ L_0(x_2) & L_1(x_2) & L_2(x_2) & L_3(x_2) & L_4(x_2) \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ L_0(x_{50}) & L_1(x_{50}) & L_2(x_{50}) & L_3(x_{50}) & L_4(x_{50}) \end{bmatrix}$$

$$\beta = [\beta_0 \ \beta_1 \ \beta_2 \ \beta_3 \ \beta_4]^T \quad \xrightarrow{\textcirclearrowleft} \textcircled{X}_{50 \times 5}$$

$$\beta_0 = -0.001 \quad \beta_1 = 0.01 \quad \beta_2 = 0.55 \quad \beta_3 = 1.5 \quad \beta_4 = 1.2$$

Deriving optimal solution:

$$\hat{\beta} = \underset{\beta}{\operatorname{argmin}} \|y - X\beta\|^2$$

$$y = \underbrace{X \beta}_{50 \times 1} + \underbrace{e}_{5 \times 1} \quad \text{Over-determined system}$$

$$y = \underbrace{X \beta}_{N \times d} + \underbrace{e}_{d \times 1} \quad N=50 \quad d=5$$

→ Using python code to find rank of  $x$ , i.e  
numpy.linalg.matrix\_rank( $x$ ) we get rank=5

→ As  $\text{rank}(x) = d$  the optimal solution derivation  
is as follows:

$$\text{where } J = \|x\beta - y\|^2$$

$$\frac{\partial J}{\partial \beta} = 2x^T(x\beta - y) = 0$$

$$\Rightarrow x^T x\beta = x^T y$$

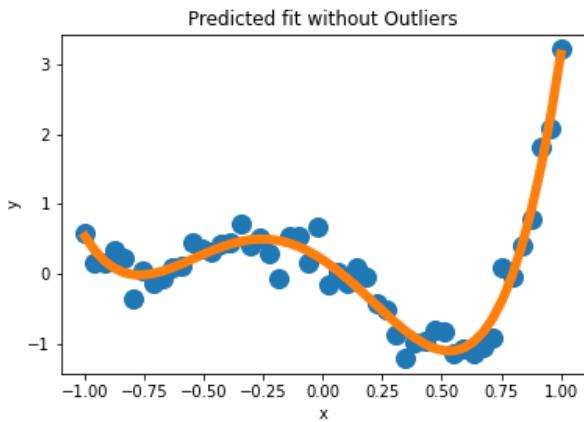
$$\Rightarrow \beta = \underline{(x^T x)^{-1}} x^T y$$

$\downarrow$   
 $(x^T x)$  is invertible because  
rank of  $(x) = \underline{d}$ .

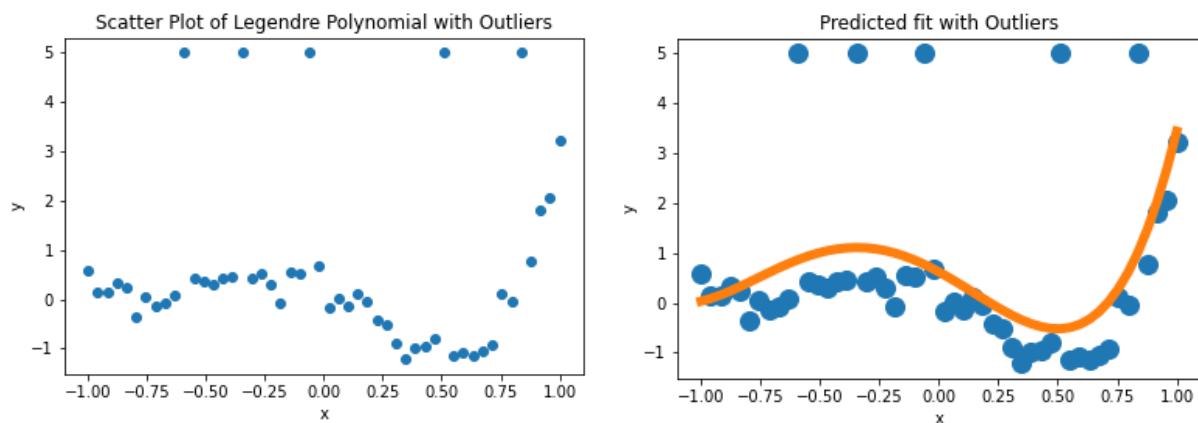
So now the predicted curve ( $\hat{y}$ ) would be

$$\hat{y} = X \hat{\beta} \quad \text{where } \hat{\beta} = (x^T x)^{-1} x^T y$$

## E Predicted curve with Scatter plot



## d Predicted curve with outliers



### Comment on difference:

The prediction curve has shifted upwards due to the presence of the outliers , the farther the outliers are, the prediction curve would deviate from the data points .

(e) Optimization

$$\hat{\beta} = \underset{\beta}{\operatorname{argmin}} \|y - X\beta\|_1$$

In linear programming form :

$$\begin{aligned} & \underset{x}{\text{minimize}} \quad C^T x \\ & \text{subject to } Ax \leq b \end{aligned}$$

Sol:

$$\min_{\bar{\beta} \cdot \bar{u}} \|\bar{u}\|_1 \quad \text{s.t.} \quad \bar{u} \geq |y - X\beta|$$

$$\bar{u} \geq -(y - X\beta)$$

$$-\bar{u} \geq (y - X\beta)$$

so

$$\min_{\bar{\beta} \cdot \bar{u}} \|\bar{u}\|_1 \Rightarrow \min_{\bar{\beta} \cdot \bar{u}} \begin{bmatrix} \bar{0} \\ \bar{1} \end{bmatrix}^T \begin{bmatrix} \bar{\beta} \\ \bar{u} \end{bmatrix}$$

such that

$$\begin{bmatrix} X & -I \\ X & -I \end{bmatrix} \begin{bmatrix} \bar{\beta} \\ \bar{u} \end{bmatrix} \leq \begin{bmatrix} \bar{y} \\ -y \end{bmatrix}$$

i.e

$$C_{[50 \times 1]} = \begin{bmatrix} \bar{0} \\ \bar{1} \end{bmatrix} ; \text{ where } \bar{0} = [0 \ 0 \ 0 \ 0 \ 0]^T$$

$$\bar{1} = \underbrace{[1 \ \dots \ 1]^T}_{50 \text{ elements}}$$

$$A_{[100 \times 50]} = \begin{bmatrix} X & -I \\ -X & -I \end{bmatrix} ; \quad X = \text{Same as defined in (b)}$$

$$I = [I]_{50 \times 50}$$

$$\underline{B} = \begin{bmatrix} \bar{y} \\ -\bar{y} \end{bmatrix} ; \quad \bar{y} = [\bar{y}]_{50 \times 1}$$

$$\underline{x} = \begin{bmatrix} \bar{p} \\ \bar{u} \end{bmatrix} ; \quad \bar{p} = [\bar{p}]_{3 \times 1}$$

$$\bar{u} = [\bar{u}]_{50 \times 1}$$

(+) Linear programming

