

Galaxy Zoo Hubble: the passive disk fraction decreases from $z = 1.0$ to $z = 0.3$ or maybe increases who even knows

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ABSTRACT

1 INTRODUCTION

It is well known that most galaxies tend to exist in one of two populations: blue, late-type disks exhibiting active star formation, and red, early-type ellipticals showing little to no signs of recent star formation (Strateva et al. 2001; Baldry et al. 2004). The division between the two color populations is quite distinct when visually represented on a color-magnitude (CMD) or color-color diagram. Galaxies tend to populate in one of two regions: the “red sequence” in the upper band, which contains predominantly early-type galaxies, and the “blue cloud” in the lower, containing mostly late-type spirals. This bimodality in the color-morphology relationship of galaxies has been so widely accepted that color is often used as a proxy for morphological classification in large samples of galaxies (e.g. Cooray (2005); Lee & Pen (2007); Salimbeni et al. (2008); Simon et al. (2009)), where expert visual classification is not feasible on such scales, while measurements of colors are readily available.

The relatively tight correlation suggests an evolutionary link between a galaxy’s dynamical history (traced by its morphology) and stellar content (traced by its color). In the simplest interpretation, it could be deduced that galaxies tend to begin their lives as young, star-forming disks, until some mechanism (secular or external) causes star-formation to cease while the galaxy simultaneously undergoes a morphological transformation from disk to spheroidal.

The advent of larger surveys and more reliable methods for measuring morphology (independently of color) has allowed for more nuanced interpretations of the simple model. For instance, the degree of incompleteness in the color-morphology relationship is now much more realized, with the recent identifications of significantly large samples of red spirals and blue ellipticals. Using morphological classifications from GZ1, Masters et al. (2010) found 6% of a sample of ~ 5000 spirals to be red; similarly, Schawinski et al. (2009) found 6% of early-type galaxies to be blue. The existence of these objects may represent transition phases in the pathway from the blue cloud to the red sequence, and also give insight into what processes may quench or initiate star-formation without inducing a morphological change, or visa versa.

Another probe for understanding the transition from blue cloud to red sequence is the “green valley”, the inter-

mediate region between the two. In addition to the ellipticals in the blue cloud and spirals in the red sequence, galaxies of all types residing in the green valley were thought to represent the transition stages of this evolutionary pathway. The intermediate colors in this region indicate a recent quenching of star-formation (Martin et al. 2007; Salim et al. 2007), and the dearth of galaxies here (as compared to the high populations in the red sequence and blue cloud) initially suggested that the quenching process initiating transition across the CMD is very rapid.

A closer look at the populations within the green valley show that the processes causing galaxies to evolve from the blue cloud to red sequence may be very different. Schawinski et al. (2009) studied the morphological distribution (measured by the GZ1 project) of ~ 4000 green-valley galaxies, finding that late-type and early-types likely go through two different evolutionary tracks. For late-types, the quenching process is gradual, and initiated by a cutoff of a gas reservoir. Galaxies quenched recently in this way would populate the green valley at $z = 0$, and those which quenched at an earlier time would be currently identified as red passive disks. Whether these red disks continue to evolve into spheroidals via some process after the initial quenching is unclear from a local Universe analysis. For early-types, the quenching is rapid and probably external and violent, thus triggering the morphological change from disk to spheroidal.

Analysis of the color-morphology relationship in the local Universe has revealed a close but imperfect bimodality as well as proposed mechanisms by which galaxies undergo different quenching processes, driving their evolution along the CMD. Even more may be revealed by studying the different populations as a function of cosmic time, which is becoming more possible with the data from large high-redshift surveys such as COSMOS and deep imaging via HST-ACS. It has been established now, for instance, that the bimodality does exist out to $z \sim 1$ (Bell et al. 2004; Cirasuolo et al. 2007; Mignoli et al. 2009) and possibly beyond (Giallongo et al. 2005; van Dokkum et al. 2006; Franzetti et al. 2007; Cassata et al. 2008). What requires further study is how exactly the proportions change at different epochs.

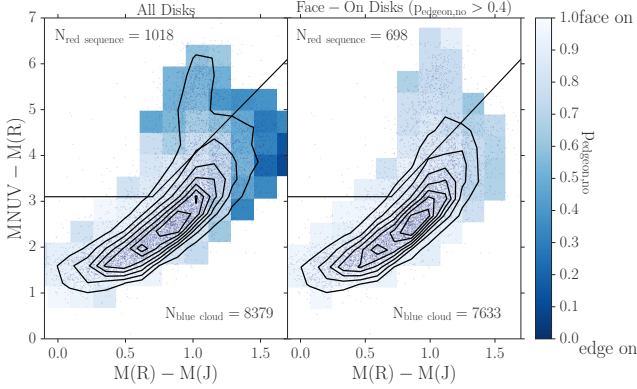


Figure 1. Completeness ξ as a function of redshift and surface brightness for red sequence (left) and blue cloud galaxies (right).

2 DATA

The parent sample of galaxies in this paper is drawn from the Galaxy Zoo: Hubble (GZH) catalog (Willett et al. 2016), which provides morphological classifications for galaxies sourced from the HST Legacy Surveys. From the main catalog we select galaxies with imaging from the Cosmic Evolution Survey (COSMOS, Scoville et al. (2007)) in the redshift range $0 < z < 1$. From this, we apply a magnitude cut of $M_{r+} < -20.5$ to create a volume-limited sample (see Figure 2). Rest frame NUV-r and r-J colors are taken from the UltraVISTA catalog (McCracken et al. 2012; Ilbert et al. 2013).

2.1 Selecting passive disk galaxies

We identify a sample of non-clumpy disk galaxies using the morphological classifications provided by GZH. The sample includes subjects which meet the following criteria: $f_{\text{features}} > 0.23$ and $f_{\text{clumpy, no}} > 0.30$, where f is the debiased vote fraction. We also require at least 20 votes for each question ($N_{\text{smooth or features}} \geq 20$ and $N_{\text{clumpy}} \geq 20$) to reduce uncertainty in the vote fractions.

To classify the galaxies as quiescent or star-forming, a method similar to that described by Ilbert et al. (2013) (hereafter I13) was used, which implements a rest-frame $NUV-r^+$ versus r^+-J diagnostic. Here are some reasons these colors are great (NUV-r): (Arnouts et al. 2007; Salim et al. 2005; Wyder et al. 2007), (Martin et al. 2007)

The demarcation line to separate the quiescent and active populations at $z = 1$ is adopted from I13, which defines the quiescent galaxies as those which satisfy: $M_{NUV} - M_{r+} > 3(M_{r+} - M_J) + 1$ and $M_{NUV} - M_{r+} > 3.1$. I13 applies this criteria to all galaxies in a range of $0.2 < z < 3$, although it performs best at separating the two populations in the redshift bin $0.7 < z < 1.2$, where $> 98\%$ of galaxies identified as quiescent exhibited star formation rates less than $\log(SFR) = -11$ (see Figure 3 of I13). Therefore this work uses the I13 separation criteria at $z = 1$, and computes the evolution of the demarcation lines as a function of redshift to $z = 0$.

The evolution of $r-J$ and $NUV-r$ colors was measured using a stellar population synthesis model from Bruzual & Charlot (2003). An instantaneous-burst model (ssp) was

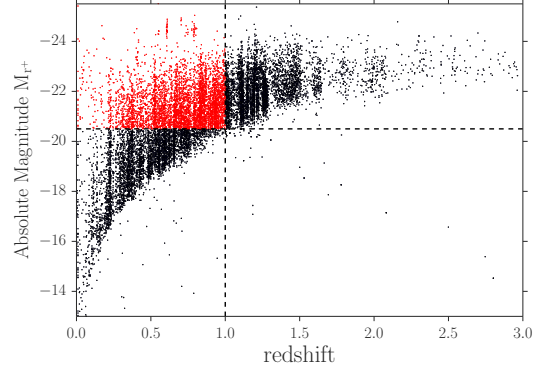


Figure 2. 70,198 COSMOS galaxies cross-matched in GZH and UltraVISTA (black). 27,584 are in volume-limited sample (red).

chosen from the Padova1994 track to represent the color evolution of a passively evolving galaxy, with a metallicity $Z = 0.008 = .4Z_{\odot}$, which is the typical metallicity of passive galaxies with mass $9 < \log(M_*/M_{\odot}) < 10$ (Peng et al. (2015), Figure 2a), chosen to correspond to the median mass of the sample ($\log(M_*/M_{\odot}) = 9.7$). A linear fit was generated for each color within the range $0 < z < 2$, and the slopes for each were used to redefine the demarcation lines in five redshift bins: one with central value $z = 0.007$ (used to classify the SDSS ferengi2 sample), and four with central values $z = [0.30, 0.50, 0.70, 0.90]$ with widths $\Delta z = 0.2$. The quiescent galaxies are thus defined in these bins as those that satisfy:

$$M_{NUV} - M_{r+} > 3.1 + a_1(z) \quad (1)$$

$$M_{NUV} - M_{r+} > 3(M_{r+} - M_J + a_2(z)) + a_1(z) + 1 \quad (2)$$

where $a_1(z) = [0.54, 0.38, 0.27, 0.16, 0.05]$ and $a_2(z) = [0.19, 0.14, 0.10, 0.06, 0.02]$.

3 CORRECTING FOR INCOMPLETENESS IN DISK DETECTION

In this work, we study the growth of the red sequence population by evaluating the fraction of passive disks as a function of redshift, $N_{\text{red disks}}/(N_{\text{red disks}} + N_{\text{blue disks}})$, as well as the fraction of disks occupying the red sequence, $N_{\text{red disks}}/(N_{\text{red disks}} + N_{\text{red ellipticals}})$. To accurately measure these fractions, the number of disks populating each redshift interval must be known with confidence. To identify disk galaxies in our sample, we set a cut of $f_{\text{features}} \geq 0.3$, such that galaxies meeting this criteria are considered to have distinguishable features or disk structure (additional cuts are also placed to eliminate clumpy, highly inclined, and merging galaxies; see Section 2.1). However, it is known that distinguishing disk structure from spheroidal becomes increasingly challenging at high redshifts (for both experts and novice classifiers alike), where features are less resolved and more difficult to identify. Willett et al. (2016) show using a set of artificially-redshifted simulated galaxy images classified in Galaxy Zoo that vote fractions for the same

galaxy can be drastically different measured at $z = 1$ from $z = 0$, often enough to change its morphological classification (we will show the same in Section 3.1). Therefore it is predicted that applying a f_{features} cut to identify disks will increasingly underestimate their true number at increasing redshift intervals. A set of artificially redshifted images was used to quantify and correct for this incompleteness in disk detection, described in the next section.

3.1 FERENGI2 set of artificially redshifted galaxy images

FERENGI2 is a set of simulated galaxy images created using the FERENGI code (Barden et al. 2008). These were created from a parent sample of 936 nearby ($z < 0.01$) SDSS galaxies, all of which had been previously classified in Galaxy Zoo 2 and were cross-matched in 2MASS (Skrutskie et al. 2006) for J magnitudes and GALEX (Martin et al. 2005) for NUV magnitudes, which were necessary to create a color-color separation using a method as similar as possible to that of the COSMOS sample. An evolution factor of $e = -1$ was applied, which brightens each galaxy linearly with redshift: $M' = M + ez$, where M' is the corrected magnitude. This correction is performed to mimic the known physical increase of galaxy magnitude with redshift (Lilly et al. 1998; Loveday et al. 2011), and the value $e = -1$ was chosen based on an analysis of spectra template models provided by Brinchmann et al. (2004), which showed that typical galaxies tend to evolve in brightness by one magnitude per redshift. Each galaxy was artificially redshifted 8 times from $z = 0.3$ to $z = 1$ in intervals of $\Delta z = 0.1$ and processed to mimic *HST* imaging parameters, giving a total of 7,488 images (3 examples are shown in Figure 4). The set was then classified in Galaxy Zoo using the same decision tree as used for Galaxy Zoo Hubble. 134 highly inclined disk galaxies were removed from the sample by excluding any with $N_{\text{edge-on}} > 20$ and $f_{\text{not edge-on}} \geq 0.6$, using the vote fraction associated with the real galaxy image measured in GZ2. This cut was shown in Galloway et al. (2015) to correlate well with inclination angle $\cos(a/b) < 67^\circ$. This was to exclude those which may be mis-classified due to dust-reddening. Using the NUV-J-R selection method described in section 2.1, the remaining sample was divided into a set of red sequence galaxies (259 per redshift bin) and blue cloud (543 per each redshift bin) (see Figure 3).

3.2 Measuring ξ

The FERENGI2 set was used to measure the incompleteness in disk detection, from which a correction factor ξ was derived. This is defined as the number of disks detected divided by the true number of disks expected to exist in a given redshift interval: $\xi(z) = N_{\text{detected}}/N_{\text{true}}$. Acknowledging that the completeness in disk detection may depend on galaxy color, the corrected fraction of passive disks can then be calculated as:

$$f = \frac{N_{RD} \times \xi_{\text{red}}^{-1}}{N_{RD} \times \xi_{\text{red}}^{-1} + N_{BD} \times \xi_{\text{blue}}^{-1}} \quad (3)$$

If there is no color bias in disk detection, $\xi_{\text{red}} = \xi_{\text{blue}}$,

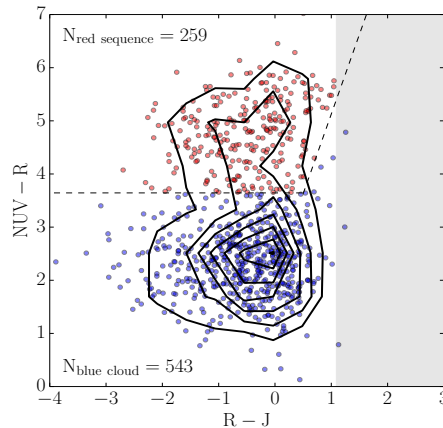


Figure 3. Separation of the quiescent population (red sequence) and active population (blue cloud) of the FERENGI2 sample.

and this term cancels out, leaving the fraction unchanged. If there is a bias, however, the ξ terms do not cancel, and the incompleteness in disk detection could have a large effect on the red disk fraction. Therefore a careful measurement of ξ is estimated for both red and blue disk galaxies using the FERENGI2 set of simulated images.

The completeness values $\xi_{\text{red}}(z)$ and $\xi_{\text{blue}}(z)$ were computed in varying bins of redshift for the red sequence and blue cloud galaxies separately. An example calculation of ξ_{blue} in the $z = 0.7$ bin is shown in Figure 5. Each point represents a FERENGI2 galaxy, where the y-axis indicates the value of f_{features} measured in the image redshifted to $z = 0.7$, and the x-axis indicates the value of f_{features} measured in the same galaxy redshifted to $z = 0.3$. Disk galaxies are identified as those for which $f_{\text{features}} \geq 0.3$. Since, on average, f_{features} decreases for the same galaxy as it is viewed at higher redshifts, the number of galaxies meeting this threshold is generally fewer at higher redshifts than lower redshifts. This is indicated by the dotted lines: galaxies to the right of the vertical dashed line at $f_{\text{features}, z=0.3} = 0.3$ are identified as disks at $z = 0.3$; their sum is considered the “true” number of disks, N_{true} . Similarly, the galaxies above the horizontal line at $f_{\text{features}, z=0.7} = 0.3$ are identified as disks at $z = 0.7$; their sum is the “detected” number of disks at $z = 0.7$, or N_{detected} . As obvious in the figure, N_{detected} is in general much lower than N_{true} , emphasizing the increasing difficulty in detecting features at higher redshifts. Their ratio is the completeness ξ ; in this example $\xi_{\text{blue}}(z = 0.7) = 0.61$, meaning only 61% of disks were detected at this redshift.

It was hypothesized that the completeness in disk detection may be a function of other parameters in addition to redshift. At fixed redshift, for example, it is reasonable to guess that features could be easier to detect galaxies that have higher mass, radius, or surface brightness. To test whether these parameters also impact the number of disks detected, the completeness was measured in fixed redshift bins as a function of surface brightness, effective radius, and mass. The surface brightness was calculated as $\mu = m + 2.5 * \log_{10}(2 * (b/a) * \pi R_e^2)$, using SExtractor outputs MAG_AUTO, b/a and R_e measured in the I_{814W} band images. The effective radius used was the 50% FLUX_RADIUS

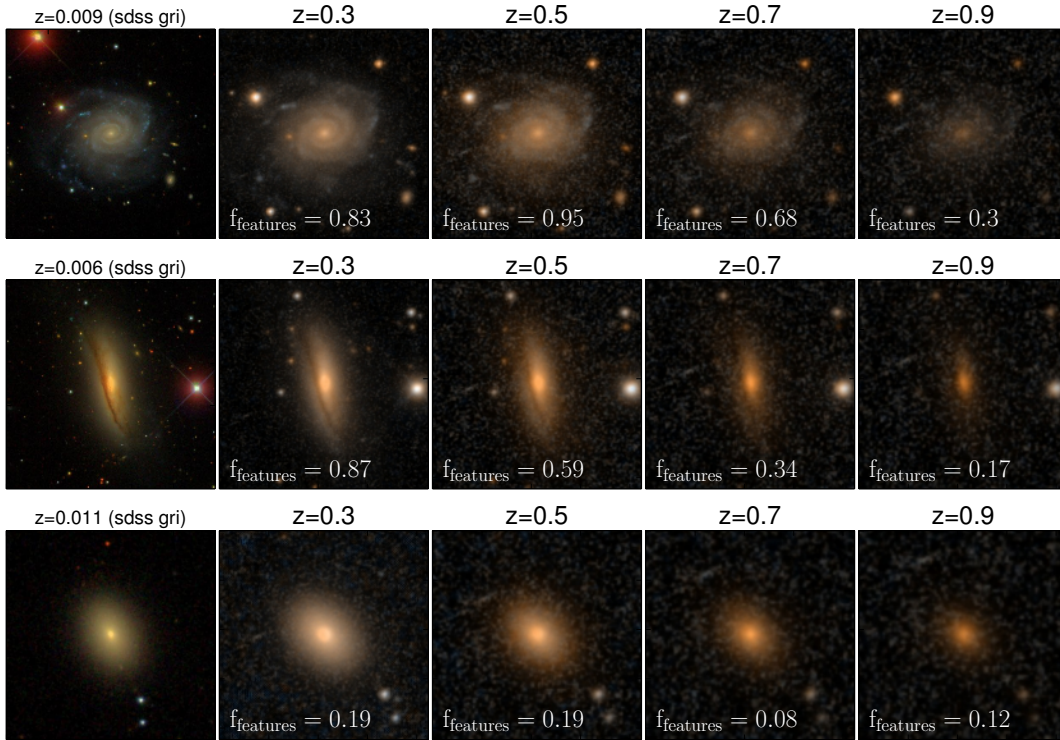


Figure 4. hi

converted in to kpc, and the masses used were the **MEDIAN** values in the MPA-JHU DR7 catalog (Kauffmann et al. 2003).

Figure 6 shows completeness as a function of redshift and surface brightness, for the red sequence and blue cloud galaxies. 8 redshift bins were further divided into bins of surface brightness with varying widths, where the sizes were chosen to satisfy that $N_{\text{detected}} + N_{\text{true}} \geq 10$ in each bin. This was chosen as a compromise between having a sufficient number of galaxies in each bin to compute the completeness fraction $\xi = N_{\text{detected}}/N_{\text{true}}$, and to have enough bins of surface brightness to measure a trend with confidence of completeness as a function of μ . Visual inspection of the data did not suggest any relationship between the two. To be sure, the data were fit to a linear function in each redshift bin. For each fit, a p-value representing a hypothesis test whose null hypothesis is that the slope is zero was computed. Only one reached the criteria $p < 0.05$, but with a low R^2 value of 0.28 which is not considered large enough to represent a good fit. This process was repeated using effective radius and mass as parameters, with the same results. Therefore only redshift was used as a parameter which impacted completeness value with confidence.

4 RESULTS

5 DISCUSSION

6 CONCLUSIONS

The data in this paper are the result of the efforts of the Galaxy Zoo Hubble volunteers, without whom none of this work would be possible. Their efforts are individually acknowledged at authors.galaxyzoo.org. Please contact the author(s) to request access to research materials discussed in this paper.

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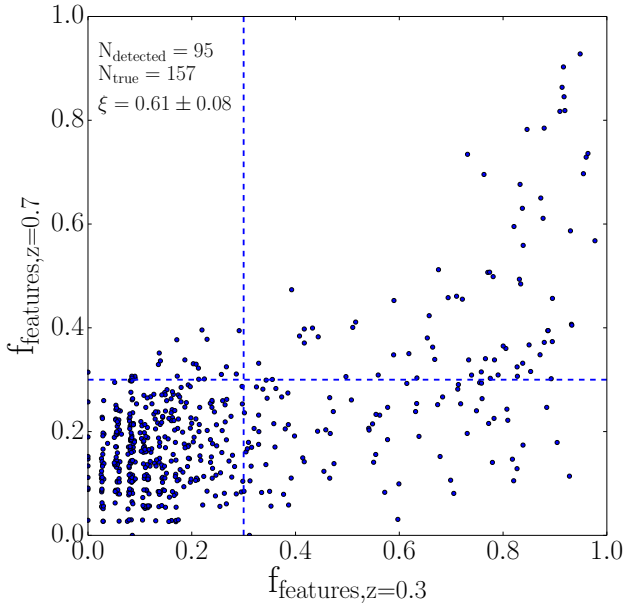


Figure 5. Example calculation of completeness ξ at redshift $z = 0.7$. Points represent FERENGI2 images classified in Galaxy Zoo. The y-axis corresponds to the value of f_{features} measured at the galaxy redshifted to $z = 0.7$, and the x-axis corresponds to the value of f_{features} measured at the galaxy redshifted to $z = 0.3$. On average, the f_{features} is lower at the higher redshift, indicating users on average have more difficulty identifying features in images at higher redshifts. The dotted lines correspond to $f_{\text{features}}=0.3$, the threshold above which a galaxy is considered to have a disk. Galaxies to the right of the vertical dashed line were identified as disks at the lowest redshift $z = 0.3$, the total number defined as N_{true} , the true number of disks. Galaxies above the horizontal dash line were identified as disks at the higher redshift $z = 0.7$, the total number defined as N_{detected} . The ratio $\xi = N_{\text{detected}}/N_{\text{true}}$ is the completeness value; in this example, only 61% of disks were detected at $z = 0.7$.

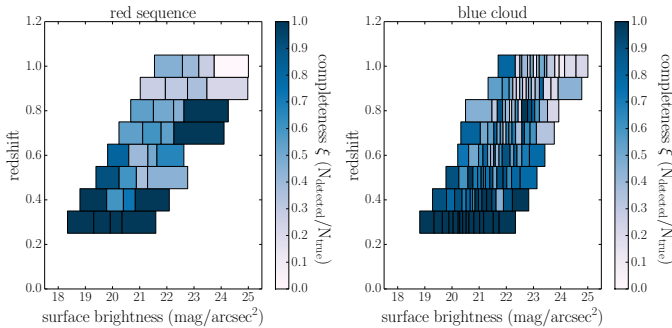


Figure 6. Completeness ξ as a function of redshift and surface brightness for red sequence (left) and blue cloud galaxies (right).

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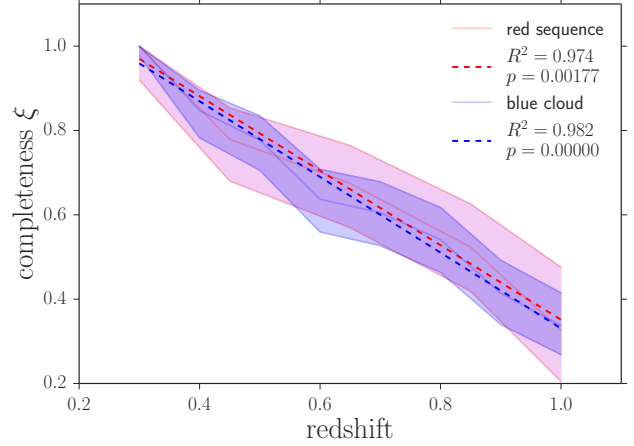


Figure 7. Completeness ξ as a function of redshift moneyplot

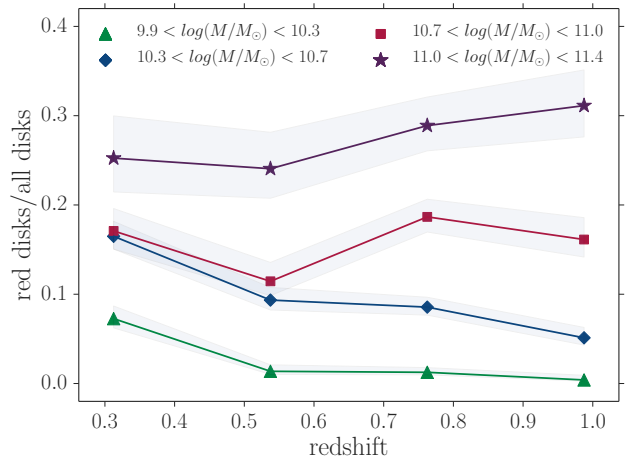


Figure 8. fraction1

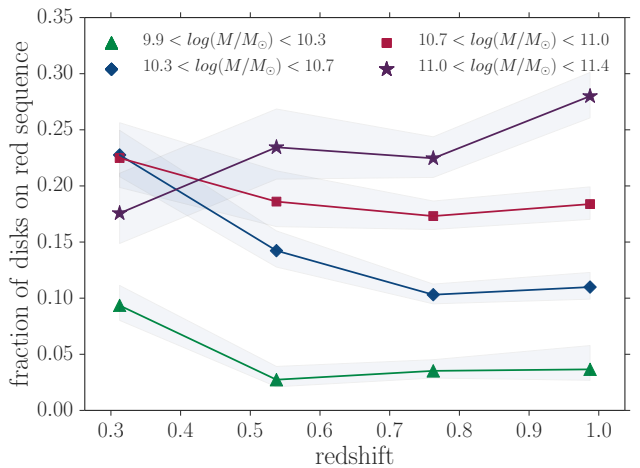


Figure 9. fraction2

Basel, University of Cambridge, Case Western Reserve University, University of Chicago, Drexel University, Fermilab, the Institute for Advanced Study, the Japan Participation Group, Johns Hopkins University, the Joint Institute for Nuclear Astrophysics, the Kavli Institute for Particle Astrophysics and Cosmology, the Korean Scientist Group, the Chinese Academy of Sciences (LAMOST), Los Alamos National Laboratory, the Max-Planck-Institute for Astronomy (MPIA), the Max-Planck-Institute for Astrophysics (MPA), New Mexico State University, Ohio State University, University of Pittsburgh, University of Portsmouth, Princeton University, the United States Naval Observatory and the University of Washington.

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