

```
#include <stdlib.h>
#include <string.h>
#include <ctype.h>
```

```
#define MAXPAROLA 30
#define MAXRIGA 80
```

```
int main(int argc, char *argv[])
{
    int freq[MAXPAROLA]; /* vettore di contatori
delle frequenze delle lunghezze delle parole */
    char riga[MAXRIGA];
    int i, inizio, lunghezza;
    FILE *f;
```

```
for(i=0; i<MAXPAROLA; i++)
    freq[i]=0;
```

```
if(argc != 2)
```

```
{
    printf(stderr, "ERRORE, serve un parametro con il nome del file\n");
    exit(1);
}
```

```
f = fopen(argv[1], "r");
if(f==NULL)
```

```
{
    printf(stderr, "ERRORE, impossibile aprire il file %s\n", argv[1]);
    exit(1);
}
```

```
while( fgets( riga, MAXRIGA, f ) != NULL )
```



Multi-Threading

Multi-Threading in C++

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Introduction

❖ The header `thread` defines the class `std::thread` that can be used to start new threads

➤ Using this class is the best way to use platform-independent threads

The `std::thread` class encapsulates many of the details of thread management, making it easier to work with threads compared to using platform-specific APIs like POSIX threads.

```
#include <thread>
```

➤ Using it may require additional compiler flags

- For gcc and clang, use `-pthread`

```
set(CMAKE_CXX_FLAGS  
    "${CMAKE_CXX_FLAGS} -std=c++14 -pthread")
```

Introduction

- ❖ The library is based on objects of type `std::thread`
 - The operator `std::thread` works with any callable object like a function, an instance of a class, a lambda expression

```
void threadFunction(int id) {  
    cout << "Thread id: " << id << endl;  
}
```

```
int main() {  
    // Create a thread and start it with threadFunction  
    thread t1(threadFunction,  
              1); // The two arguments are the function to be called and the arguments to be passed to that function.  
  
    // join the thread with the main thread  
    t1.join(); // The main thread waits for the thread to finish its execution.  
    cout << "Print this after the main thread has joined the thread t1" << endl;
```

Main thread primitives

- ❖ The library covers all main functionalities
 - But ... there is no way to automatically capture the data computed by a thread

Type	Main characteristics
<code>std::thread t;</code>	Creates a thread object t.
<code>std::thread t(f);</code>	Creates a thread object t associated with the thread function f.
<code>std::thread t(f,p1,p2,...);</code> <code>std::thread t{f(p1,p2,...)};</code>	Creates a thread object t associated with the thread function f which receives the parameters p1, p2, etc.
<code>t2=std::move(t1);</code>	Move the thread associated to the thread object t1 to object t2. <small>Moves the thread associated with the thread object t1 to object t2. After this operation, t1 no longer owns the thread, and t2 becomes the owner.</small>
<code>t.detach()</code>	Makes the thread t as detached. <small>Detaches the thread associated with t. This means that the thread can continue to execute independently of the thread object. After detaching, the thread is no longer joinable.</small>
<code>t.join()</code>	Waits the thread t for joining. <small>Waits for the thread associated with t to finish its execution. This blocks the current thread until the thread associated with t completes its execution. After joining, the thread object t is no longer associated with any thread.</small>

Other primitives

- ❖ The thread library also contains useful functions related to starting and stopping threads

Type	Main characteristics
<code>std::this_thread::sleep_for</code>	Stop the current thread for a given amount of time.
<code>std::this_thread::sleep_until</code>	Stop the current thread until a given point in time.
<code>std::this_thread::yield</code>	Let the operating system schedule another thread. <small>The term "yield" in the context of <code>std::this_thread::yield</code> refers to a mechanism that allows a thread to voluntarily give up its current time slice or CPU execution time to allow another thread to run.</small>
<code>std::this_thread::get_id</code>	Get the (operating-system-specific) id of the current thread. <small>This function returns an object representing the identifier of the current thread. This identifier is specific to the operating system and can be used to uniquely identify the thread</small>
<code>std::thread::hardware_concurrency</code>	Reports the actual max number of threads based on your architecture. <small>This function returns an estimate of the maximum number of concurrent threads that can be executed simultaneously on the current hardware architecture.</small>

Examples

```
void f1() {  
    ...  
}
```

Function definitions
(without and with parameters)

```
void f2(int a, int b) {  
    ...  
}
```

Creates an object that
does not refer to a thread

```
std::thread t1;
```

Starts an object thread that calls f1()

```
std::thread t2(f1);
```

```
std::thread t3(f2, 123, 456);
```

Starts a thread that
calls f2(123, 456)

```
std::thread t4([] { f2(123, 456); });
```

Works also with
lambda functions

creates a thread object t4 that is associated with the execution of a lambda function. The lambda function itself calls the function f2 with parameters 123 and 456. This is a way to start a thread with a function call and parameters without explicitly defining a separate function.

Join and Move

- ❖ The member function **join** can be used to wait for a thread to finish
 - Function **join** must be called exactly once for each thread
- ❖ Standard threads are not copyable, but movable, so they can be used in containers
 - Moving an **std::thread** transfers all resources associated with the running thread
 - Only the new thread can be joined

Examples

```
void f1() {  
    ...  
}  
  
void f2(int a, int b) {  
    ...  
}
```

Function definitions
(without and with parameters)

```
std::thread t1;  
std::thread t2(f2, 123, 456);  
// Alternative syntax  
std::thread t3{f2(123, 456)};
```

Starts a thread that
calls f2(123, 456)

```
t1 = std::move(t2);  
t1.detach();  
t3.join();
```

std::thread is moveable not copyable
Associate f2 to thread object t1

Examples

```
void f(int &result) {  
    ...  
    result = ...;  
}
```

Function definition
(with a parameter by reference)

```
int main() {  
    ...  
    std::thread t (f, std::ref(i));  
    ...  
    t.join();  
}
```

Parameter by
reference

Variable i will assume
the value once the
execution is terminated

Examples

```
std::thread t1([] { std::cout << "Hi\n"; });  
  
std::thread t2 = std::move(t1);  
  
t2.join();
```

The thread originally
started in t1 is joined

t1 is now empty

```
std::thread t1(some_function);  
std::thread t2 = std::move(t1);  
std::thread t1(some_other_function);  
std::thread t3;  
t3 = std::move(t2);  
t1 = std::move(t3);
```

Error: t1 is running some_other_function
The assignment terminates the program

Examples

```
void my_thread () {  
    std::cout << "TID" <<  
        std::this_thread::get_id() << endl;  
}  
  
main() {  
    std::thread t1{mythread};  
    std::thread t2{mythread};  
  
    t1.join();  
    t2.join();  
  
    return 1;  
}
```

The output operation
should be protected

Examples

```
void safe_print (int i) {  
    ... Enter critical section ...  
    std::cout << i;  
    ... Exit critical section ...  
    return;  
}
```

For example, use a mutex
(see, unit 06)

```
std::vector<std::thread> threadPool;  
  
for (int i = 1; i <= 9; ++i) {  
    threadPool.emplace_back([i] { safe_print(i); });  
}  
  
for (auto& t : threadPool) {  
    t.join();  
}
```

Digits 1 to 9 are
printed (unordered)