

```
#include <stdlib.h>
#include <string.h>
#include <ctype.h>
```

```
#define MAXPAROLA 30
#define MAXRIGA 80
```

```
int main(int argc, char *argv[])
{
    int freq[MAXPAROLA]; /* vettore di contatori
delle frequenze delle lunghezze delle parole */
    char riga[MAXRIGA];
    int i, inizio, lunghezza;
    FILE *f;
```

```
for(i=0; i<MAXPAROLA; i++)
    freq[i]=0;
```

```
if(argc != 2)
```

```
{
    fprintf(stderr, "ERRORE, serve un parametro con il nome del file\n");
    exit(1);
}
```

```
f = fopen(argv[1], "r");
if(f==NULL)
```

```
{
    fprintf(stderr, "ERRORE, impossibile aprire il file %s\n", argv[1]);
    exit(1);
}
```

```
while( fgets( riga, MAXRIGA, f ) != NULL )
```



# Multi-Threading

## Multi-Threading POSIX

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# Pthreads

## ❖ POSIX threads or Pthreads

- Is the standard UNIX library for threads
  - The version POSIX 1003.1c was born in 1995
  - Revised in version IEEE POSIX 1003.1-2017
- Defined for the C language, but available for other languages (e.g., FORTRAN)

## ❖ Using Pthreads

- A thread is a **function** that is executed in concurrency with the main thread

A process with multiple threads is a set of independent that share the process resources

# Pthreads

- ❖ The Pthreads library allows
  - Creating and manipulating threads
  - Synchronizing threads
  - Protection of resources shared by threads
  - Thread scheduling
  - Destroying thread
- ❖ It defines more than 60 functions
  - All functions have the prefix **pthread\_**
    - pthread\_equal, pthread\_self, pthread\_create, pthread\_exit, pthread\_join, pthread\_cancel, pthread\_detach

## Library linkage

- ❖ The Pthread system calls are defined in `pthread.h`
  - Insert in all `*.c` files
    - `#include <pthread.h>`
  - Link programs with the pthread library
    - `gcc -Wall -g -o <exeName> <file.c> -lpthread`

## Thread Identifier

- ❖ A thread is uniquely identified
  - By a type identifier **pthread\_t**
    - Similar to the PID of a process (**pid\_t**)
  - The type **pthread\_t** is opaque
    - Its definition is implementation dependent
    - Can be used only by functions specifically defined in Pthreads
    - It is not possible compare directly two identifiers or print their values
  - It has meaning only within the process where the thread is executed
    - Remember that the PID is global within the system

## System call pthread\_equal

```
int pthread_equal (  
    pthread_t tid1,  
    pthread_t tid2  
);
```

- ❖ Compares two thread identifiers
- ❖ Arguments
  - Two thread identifiers
- ❖ Returned values
  - Nonzero if the two threads are equal
  - Zero otherwise

## System call `pthread_create`

```
pthread_t pthread_self (  
    void  
);
```

- ❖ Returns the thread identifier of the calling thread
  - It can be used by a thread (with `pthread_equal`) to self-identify

Self-identification can be important to properly access the data of a specific thread

# System call `pthread_create`

```
int pthread_create (  
    pthread_t *tid,  
    const pthread_attr_t *attr,  
    void *(*startRoutine) (void *),  
    void *arg  
);
```

Return value:  
0, on success  
error code, on failure

## ❖ Arguments

- Identifier of the generated thread (**tid**)
- Thread attributes (**attr**)
  - NULL is the default attribute
- C function executed by the thread (**startRoutine**)
- Argument passed to the start routine (**arg**)
  - NULL if no argument

A **single** argument



## System call `pthread_exit`

- ❖ A whole process (with all its threads) terminates if
  - Its thread calls **exit** (or **\_exit** or **\_Exit**)
  - The main thread execute **return**
  - The main thread receives a signal whose action is to terminate
- ❖ A single thread can terminate (without affecting the other process threads)
  - Executing **return** from its start function
  - Executing **pthread\_exit**
  - Receiving a cancellation request performed by another thread using **pthread\_cancel**

## System call pthread\_exit

```
void pthread_exit (  
    void *valuePtr  
);
```

- ❖ It allows a thread to terminate returning a termination status
- ❖ Arguments
  - The **ValuePtr** value is kept by the kernel until a thread calls **pthread\_join**
  - This value is available to the thread that calls **pthread\_join**

# Example

Thread creation  
of 1 thread  
without  
parameters

```
void *tF () {  
    ...  
    pthread_exit (NULL);  
}
```

Attributes

Arguments

```
pthread_t tid;  
int rc;  
rc = pthread_create (&tid, NULL, tF, NULL);  
if (rc) {  
    // Error ...  
    exit (-1);  
}  
...  
pthread_exit (NULL);  
// exit (0);  
// return (0); (in main)
```

Terminates only  
the main thread

Terminates the  
process  
(all its threads)

# Example

Creation of N threads with 1 argument

A thread can be executed when t is changed

```
void *tF (void *par) {  
    int *tidP, tid;  
    ...  
    tidP = (int *) par;  
    tid = *tidP;  
    ...  
    pthread_exit (NULL)  
}
```

The content is being modified by the main thread

```
pthread_t th[NUM_THREADS];  
int rc, t;
```

```
for (t=0; t<NUM_THREADS; t++) {  
    rc = pthread_create (&th[t], NULL, tF,  
        (void *) &t);  
    if (rc) {...}  
}  
pthread_exit(NULL);
```

## ERROR

&t is the address of a variable, the main thread changes its content in concurrency with the created threads that read its value

# Example

Creation of N  
threads with 1  
argument

Cast of a value  
`void *`  $\leftrightarrow$  **`long int`**

```
void *tF (void *par) {  
    long int tid;  
    ...  
    tid = (long int) par;  
    ...  
    pthread_exit(NULL);  
}
```

```
pthread_t th[NUM_THREADS];  
int rc; long int t;
```

```
for (t=0; t<NUM_THREADS; t++) {  
    rc = pthread_create (&th[t], NULL, tF,  
        (void *) t);  
    if (rc) { ... }  
}  
pthread_exit (NULL);
```

Tricky:

We pass a `long int` as it were an address, because `pthread_create` requires an address as its last argument

# Example

Creation of N  
threads with 1  
struct

```
struct tS {  
    int tid;  
    char str[N];  
};
```

```
void *tF (void *par) {  
    struct tS *tD;  
    int tid; char str[L];
```

```
    tD = (struct tS *) par;  
    tid = tD->tid; strcpy (str, tD->str);  
    ...
```

Cast to a vector  
of structs

```
pthread_t t[NUM_THREADS];  
struct tS v[NUM_THREADS];  
...  
for (t=0; t<NUM_THREADS; t++) {  
    v[t].tid = t;  
    strcpy (v[t].str, str);  
    rc = pthread_create (&t[t], NULL, tF, (void *) &v[t]);  
    ...  
}  
...
```

Address of a struct

## System call `pthread_join`

### ❖ At its creation a thread can be declared

#### ➤ Joinable

- Another thread may "wait" (**`pthread_join`**) for its termination, and collect its exit status
- The termination status of the thread is retained until another thread performs a **`pthread_join`** for that thread

#### ➤ Detached

- No thread can explicitly wait for its termination (not joinable)
- The termination status of the thread is immediately released

# System call pthread\_join

```
int pthread_join (  
    pthread_t tid,  
    void **valuePtr  
);
```

Return value:  
0, on success  
error code, on failure

## ❖ Arguments

- Identifier (tid) of the waited-for thread
- The void pointer **ValuePtr** will be the value returned by thread **tid**
  - Returned by **pthread\_exit** or by **return**
  - **PTHREAD\_CANCELED** if the thread was deleted
  - Can be set to NULL if you are not interested in the return value



# Example

Returns the exit status  
(**tid** in this example)

```
void *tF (void *par) {  
    long int tid;  
    ...  
    tid = (long int) par;  
    ...  
    pthread_exit ((void *) tid);  
}
```

```
void *status;  
long int s;  
...  
/* Wait for threads */  
for (t=0; t<NUM_THREADS; t++) {  
    rc = pthread_join (th[t], &status);  
    s = (long int) status;  
    if (rc) { ... }  
}  
...
```

**th[t]** collects the **tids**

Wait for each thread,  
and collects its exit  
status

## System call `pthread_cancel`

```
int pthread_cancel (  
    pthread_t tid  
);
```

Return value:  
0, on success  
error code, on failure

- ❖ Terminates the target thread
- ❖ The thread calling **`pthread_cancel`** does not wait for termination of the target thread (it continues immediately after the calling)
- ❖ Arguments
  - Target thread (tid) identifier

## System call `pthread_detach`

```
int pthread_detach (  
    pthread_t tid  
);
```

Return value:  
0, on success  
error code, on failure

- ❖ Declares thread **tid** as detached
  - The status information will not be kept by the kernel at the termination of the thread
  - No thread can join with that thread
    - Calls to **pthread\_join** should fail
- ❖ Arguments
  - Thread (tid) identifier

# Example

Create a thread and  
then make it detached

```
pthread_t tid;  
int rc;  
void *status;
```

```
rc = pthread_create (&tid, NULL, PrintHello, NULL);  
if (rc) { ... }
```

```
pthread_detach (tid);
```

Detach a thread

```
rc = pthread_join (tid, &status);  
if (rc) {  
    // Error  
    exit (-1);  
}
```

Error if try to join

```
pthread_exit (NULL);
```

## Example

Create a detached thread using the attribute field

```
pthread_attr_t attr;  
void *status;
```

```
pthread_attr_init (&attr);  
pthread_attr_setdetachstate (&attr,  
    PTHREAD_CREATE_DETACHED);  
//PTHREAD_CREATE_JOINABLE);
```

Creates a detached thread

```
rc = pthread_create (&t[t], &attr, tF, NULL);  
if (rc) {...}
```

```
pthread_attr_destroy (&attr);
```

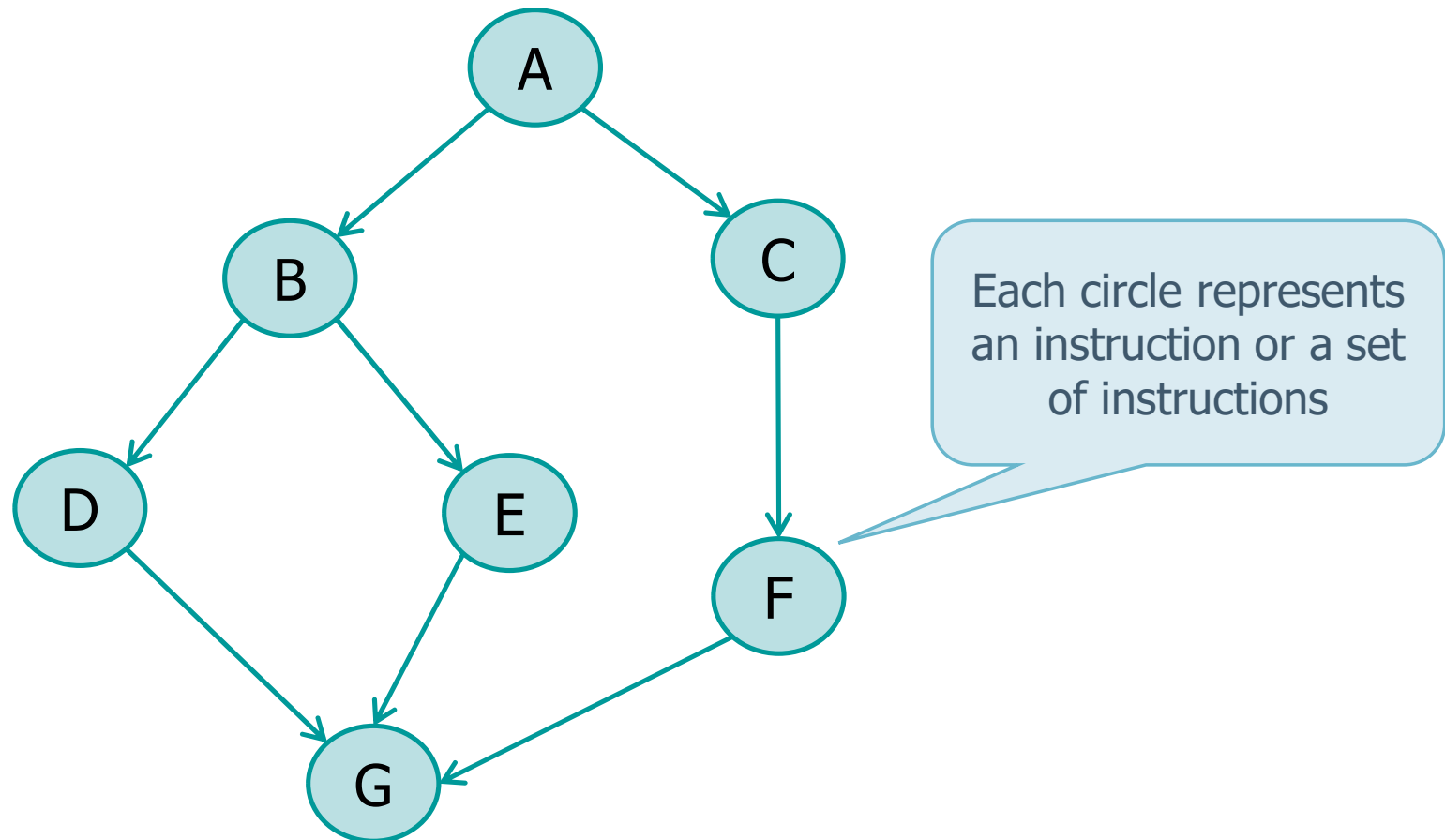
Destroys the attribute object

```
rc = pthread_join (thread[t], &status);  
if (rc) {  
    // Error  
    exit (-1);  
}
```

Error if try to join

## Exercise

- ❖ Implement, using threads, the following precedence graph using threads

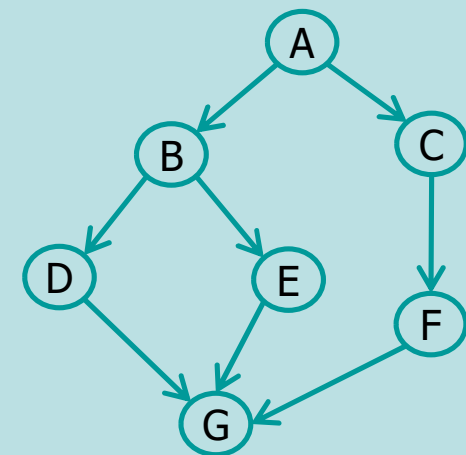


# Solution

```
void waitRandomTime (int max){  
    sleep ((int)(rand() % max) + 1);  
}
```

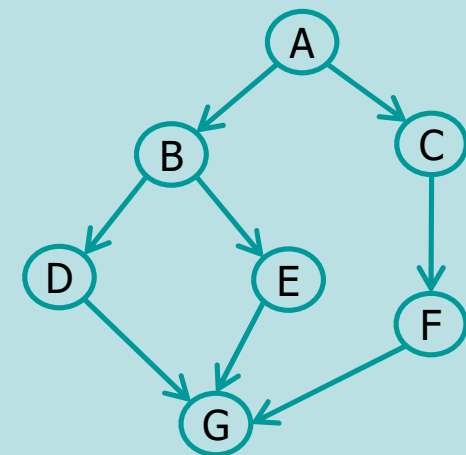
```
int main (void) {  
    pthread_t th_cf, th_e;  
    void *retval;
```

```
    srand (getpid());  
    waitRandomTime (10);  
    printf ("A\n");
```



# Solution

```
waitRandomTime (10);  
pthread_create (&th_cf, NULL, CF, NULL);  
waitRandomTime (10);  
printf ("B\n");  
waitRandomTime (10);  
pthread_create (&th_e, NULL, E, NULL);  
waitRandomTime (10);  
printf ("D\n");  
pthread_join (th_e, &retval);  
pthread_join (th_cf, &retval);  
waitRandomTime (10);  
printf ("G\n");  
  
return 0;  
}
```

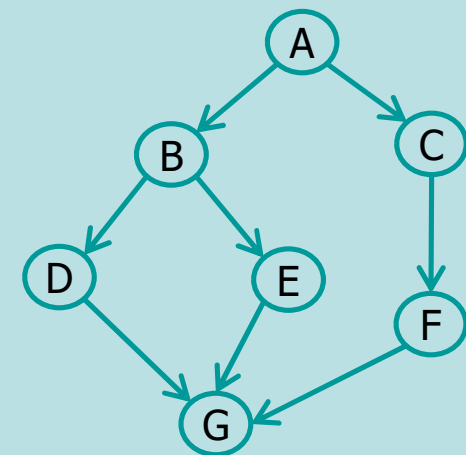




# Solution

```
static void *CF () {  
    waitRandomTime (10);  
    printf ("C\n");  
    waitRandomTime (10);  
    printf ("F\n");  
    return ((void *) 1); // Return code  
}
```

```
static void *E () {  
    waitRandomTime (10);  
    printf ("E\n");  
    return ((void *) 2); // Return code  
}
```

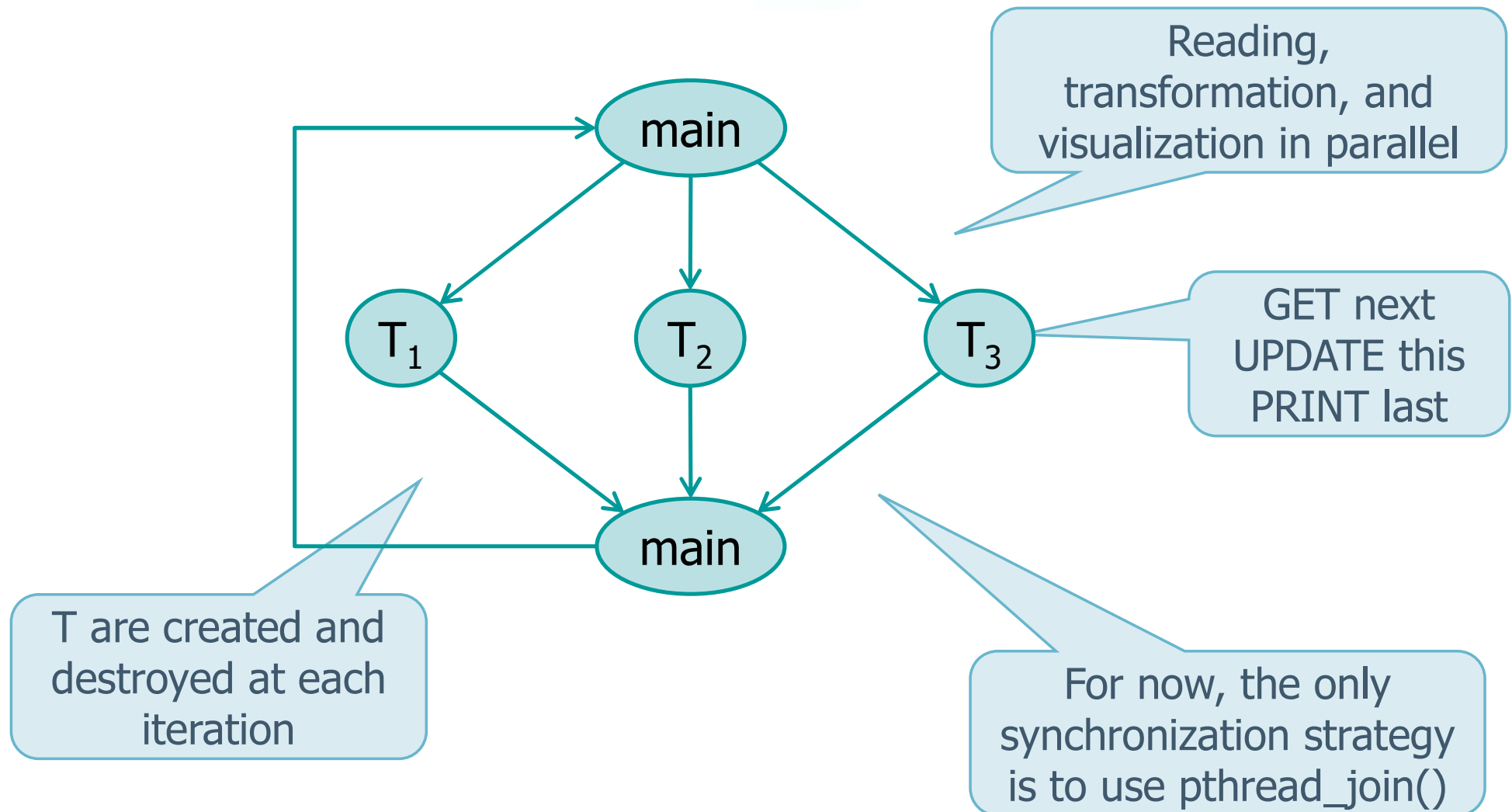


## Exercise

- ❖ Given a text file, with an undefined number of characters, passed as an argument of the command line
- ❖ Implement a concurrent program using three threads (**T<sub>1</sub>**, **T<sub>2</sub>**, **T<sub>3</sub>**) that process the file content in pipeline
  - **T<sub>1</sub>**: Read from file the next character
  - **T<sub>2</sub>**: Transforms the character read by **T<sub>1</sub>** in uppercase
  - **T<sub>3</sub>**: Displays the character produced by **T<sub>2</sub>** on standard output

# Solution

❖ Implement, using threads, this precedence graph



# Solution

```
static void *GET (void *arg) {
    char *c = (char *) arg;
    *c = fgetc (fg);
    return NULL;
}

static void *UPD (void *arg) {
    char *c = (char *) arg;
    *c = toupper (*c);
    return NULL;
}

static void *PRINT (void *arg) {
    char *c = (char *) arg;
    putchar (*c);
    return NULL;
}
```

# Solution

```
FILE *fg;

int main (int argc, char ** argv) {
    char next, this, last;
    int retC;
    pthread_t tGet, tUpd, tPrint;
    void *retV;

    if ((fg = fopen(argv[1], "r")) == NULL) {
        perror ("Error fopen\n");
        exit (0);
    }
    this = ' ';
    last = ' ';
    next = ' ';
```

## Solution

The first two characters  
can be managed  
separately

```
while (next != EOF) {
    retC = pthread_create (&tGet, NULL, GET, &next);
    if (retC != 0) fprintf (stderr, ...);
    retC = pthread_create (&tUpd, NULL, UPD, &this);
    if (retC != 0) fprintf (stderr, ...);
    retC = pthread_create (&tPrint, NULL, PRINT, &last);
    if (retcode != 0) fprintf (stderr, ...);
    retC = pthread_join (tGet, &retV);
    if (retC != 0) fprintf (stderr, ...);
    retC = pthread_join (tUpd, &retV);
    if (retC != 0) fprintf (stderr, ...);
    retC = pthread_join (tPrint, &retV);
    if (retC != 0) fprintf (stderr, ...);
    last = this;
    this = next;
}
```

## Solution

Management of the last two characters (queue)

```
// Last two chars processing
retC = pthread_create(&tUpd, NULL, UPD, &this);
if (retC!=0) fprintf (stderr, ...);
retC = pthread_create(&tPrint, NULL, PRINT, &last);
if (retC != 0) fprintf (stderr, ...);
retC = pthread_join (tUpd, &retV);
if (retC != 0) fprintf (stderr, ...);
retC = pthread_join (tPrint, &retV);
if (retC != 0) fprintf (stderr, ...);
retC = pthread_create(&tPrint, NULL, PRINT, &this);
if (retC != 0) fprintf (stderr, ...);
return 0;
}
```