



**Sharif University of Technology
Department of Computer Science and Engineering**

**Lec. 2:
Automata-Based Programming:
An Example**



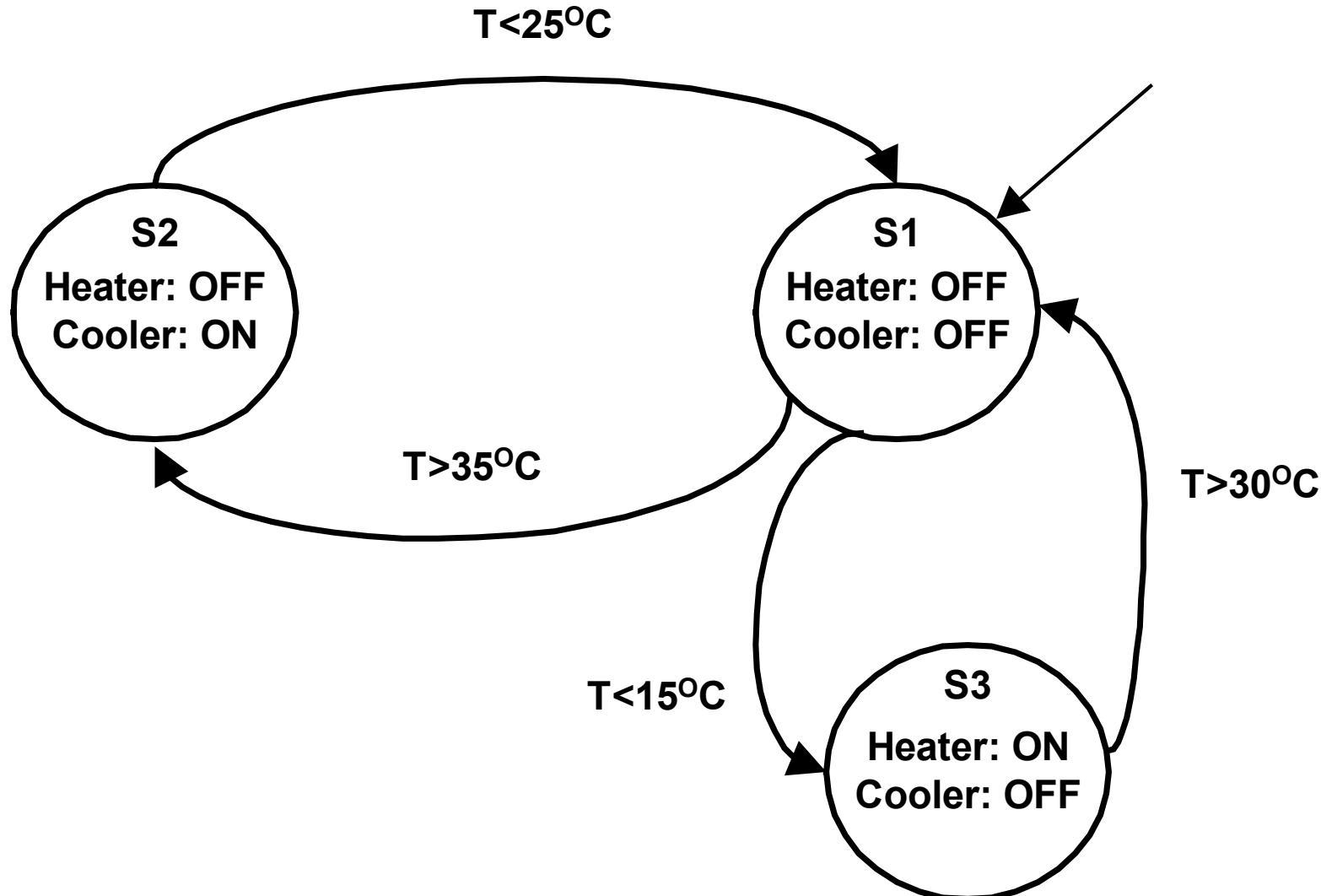
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Reactive Systems

- ❖ Typically ES are reactive systems.

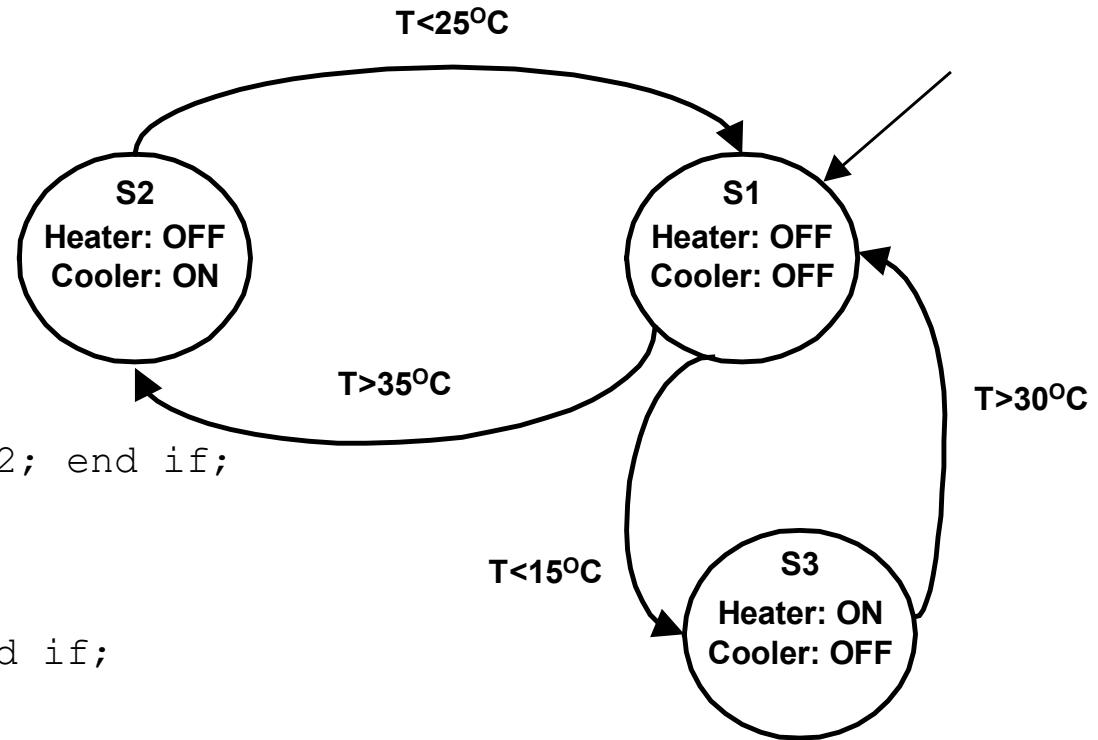
“A reactive system is in **continual interaction** with its environment and executes at a pace determined by that **environment**.”

Example: Air Conditioning

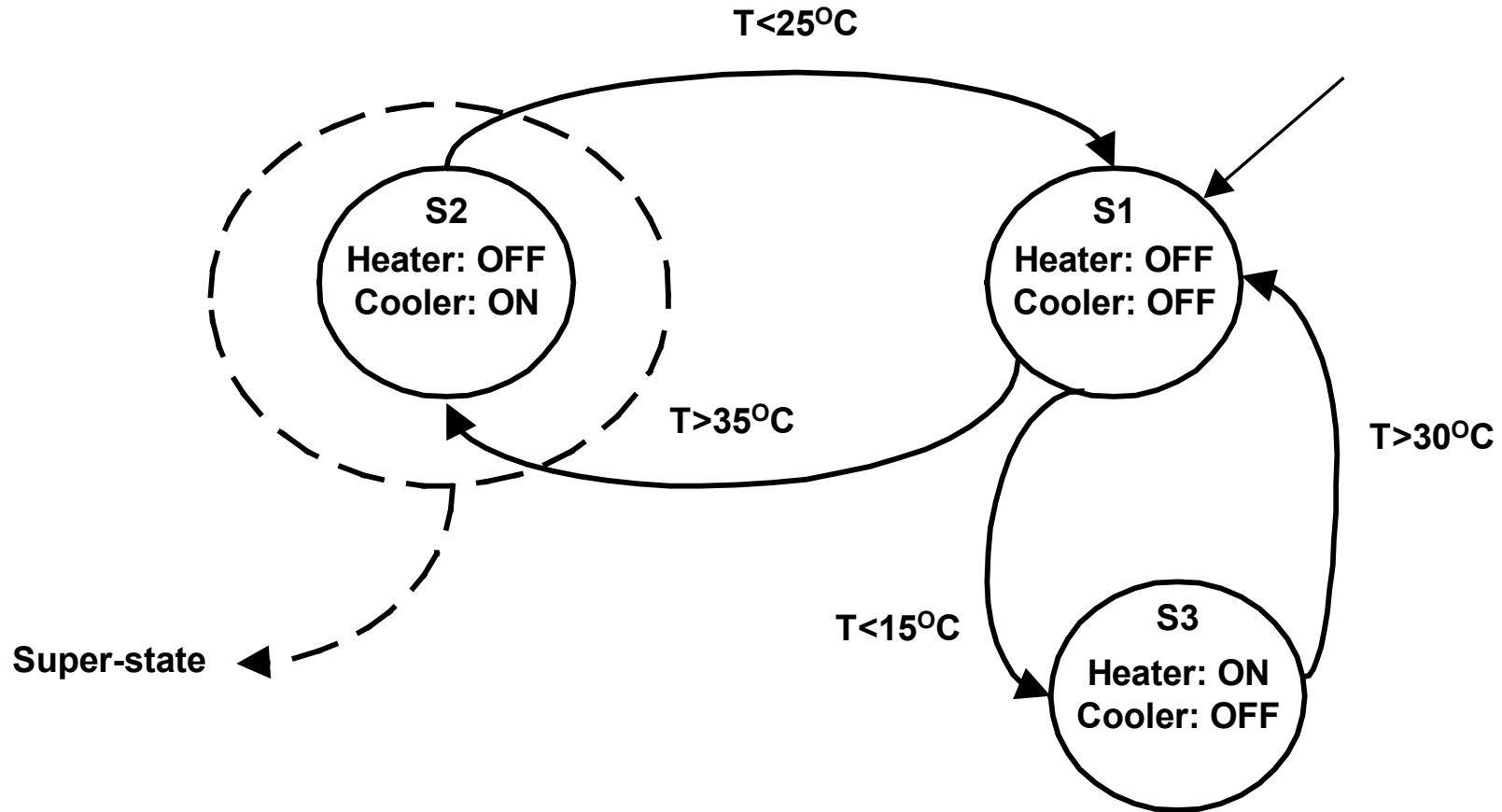


Example: Embedded Software

```
State PS=S1,NS;  
Event e;  
  
while(1) {  
    case(PS) {  
        S1:  
            Turn_off(Heater);  
            Turn_off(Cooler);  
            e=Wait_for_event();  
            if(e=='T<15') NS=S3;  
            else if(e=='T>35') NS=S2; end if;  
        S2:  
            Turn_off(Heater);  
            Turn_on(Cooler);  
            e=Wait_for_event();  
            if(e=='T<25') NS=S1; end if;  
        S3:  
            Turn_on(Heater);  
            Turn_off(Cooler);  
            e=Wait_for_event();  
            if(e=='T>30') NS=S1; end if;  
    }  
    PS=NS;  
}
```

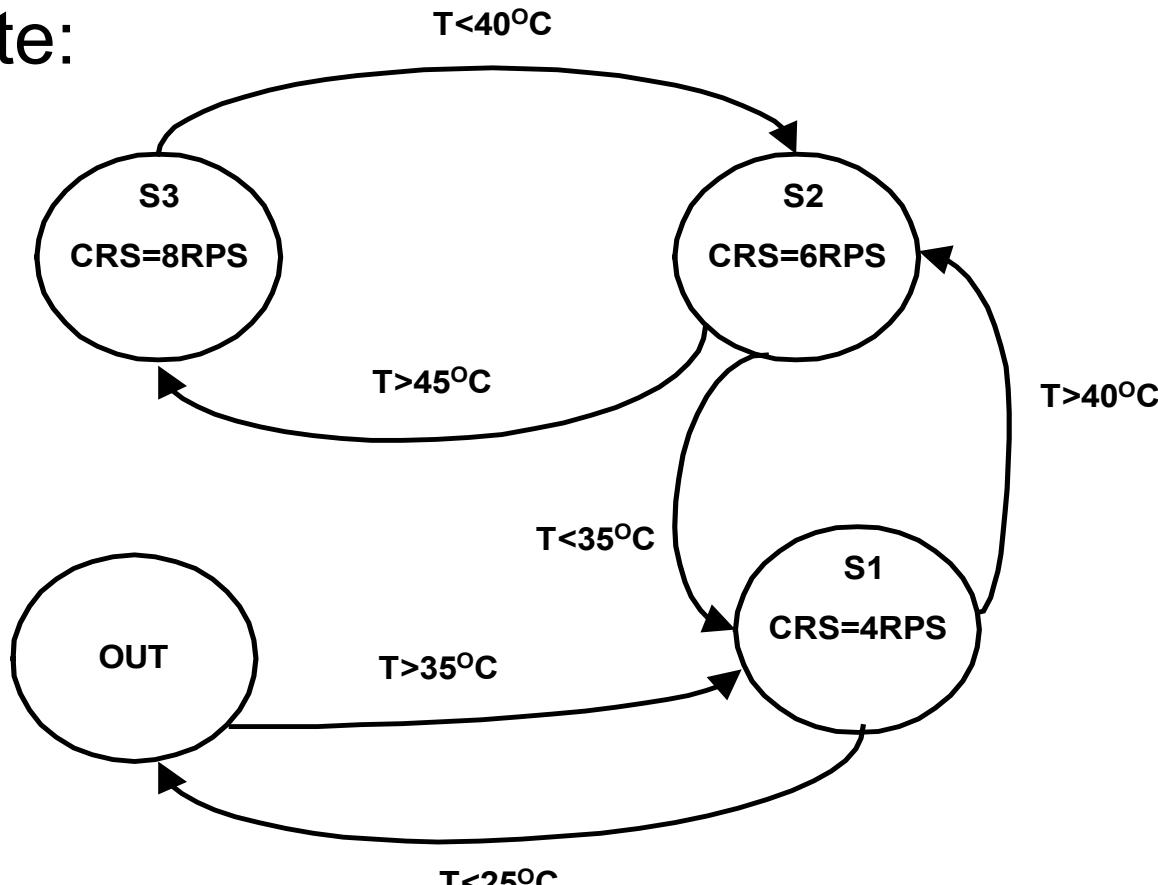


Example: Super-state



Example: Super-state (Cont.)

Super-state:

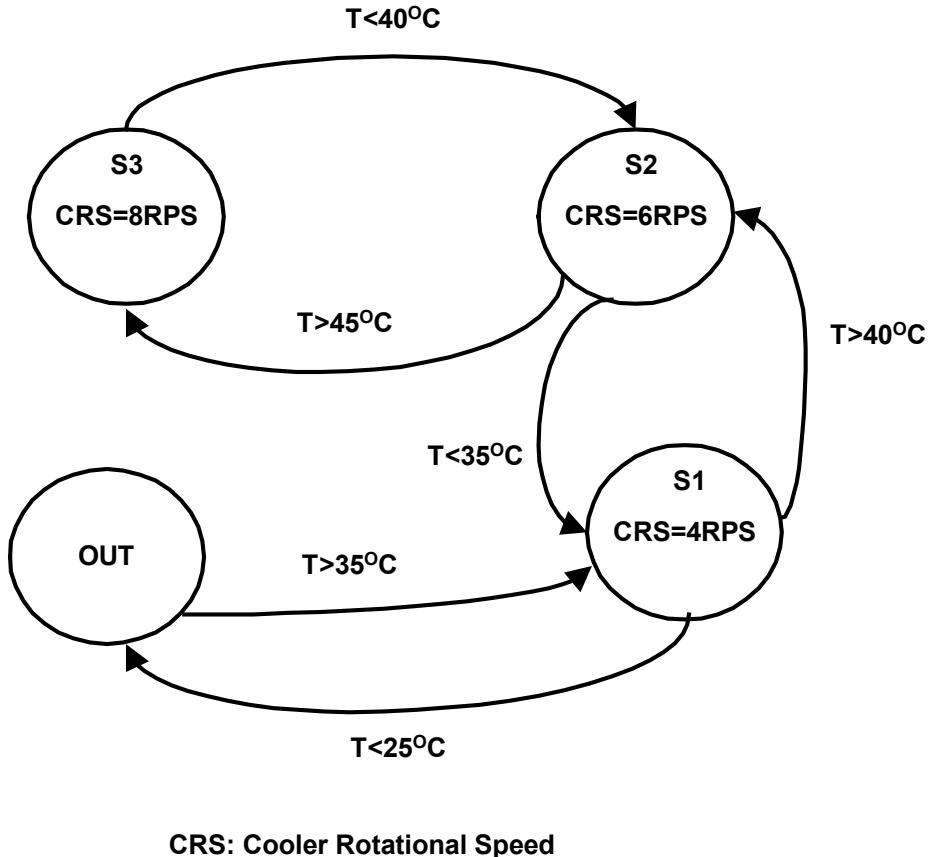


CRS: Cooler Rotational Speed

Example: Embedded Software

```
State PS=S1,NS;
State S2_PS,S2_NS;
Event e;

while(1){
  case(PS) {
    S1: ...
    S2:
      Turn_off(Heater);
      Turn_on(Cooler);
      S2_PS=S1;
      while(S2_PS != OUT) {
        case(S2_PS) {
          S1:
            CRS(4);
            e=Wait_for_event();
            if(e=='T<25') S2_NS=OUT;
            else if(e=='T>40') S2_NS=S2; end if;
          S2:
            CRS(6);
            e=Wait_for_event();
            if(e=='T<35') S2_NS=S1;
            else if(e=='T>45') S2_NS=S3; end if;
          S3:
            CRS(8);
            e=Wait_for_event();
            if(e=='T<40') S2_NS=S2; end if;
          }
          S2_PS=S2_NS;
        }
        if(e=='T<25') NS=S1; end if;
      S3: ...
    }
  PS=NS;
}
```



Assignment

- ❖ Simulate the air conditioning example
 - Use software programming languages, e.g. C, C++, Java, Python, MATLAB, etc.

Advantages of this paradigm

- ❖ Some of the advantages:
 - Suitable for reactive systems
 - Hierarchical (e.g. Super-states)
 - Human beings are not capable of comprehending systems with more than 3~5 objects.
 - Verification
 - Each automata is simple and easy to understand
 - Each automata has to comply with the super-state that it belongs to.
 - Automatic code generation

TrueTime Toolbox

- ❖ Matlab/Simulink-based simulator
- ❖ Co-simulation of embedded systems and electromechanical components.
- ❖ Supports
 - DVS
 - Networking protocols (CAN, TTP)
 - Wireless networks (ZigBee)

Assignment

- ❖ Run the example ‘Mobile Motes’ of the TrueTime Reference Manual.
- ❖ Please write a report about this experiment.