view\_frames Result Recorded at time: 25.559 map Broadcaster: /fake\_localization Average rate: 100.201 Hz Most recent transform: 25.639 (-0.080 sec old) Buffer length: 4.970 sec odom Broadcaster: /gazebo Average rate: 50.000 Hz Most recent transform: 25.545 (0.014 sec old) Buffer length: 4.960 sec base\_footprint Broadcaster: /robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (25.559 sec old) Buffer length: 0.000 sec base\_link Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 100.202 Hz Average rate: 100.202 Hz Average rate: 100.202 Hz Most recent transform: 25.515 (0.044 sec old) Most recent transform: 25.515 (0.044 sec old) Most recent transform: 25.515 (0.044 sec old) Buffer length: 4.940 sec Buffer length: 4.940 sec Buffer length: 4.940 sec leg\_lh leg\_rh leg\_rf Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Broadcaster: /robot\_state\_publisher Average rate: 100.202 Hz Average rate: 100.202 Hz Average rate: 100.202 Hz Most recent transform: 25.515 (0.044 sec old) Most recent transform: 25.515 (0.044 sec old) Most recent transform: 25.515 (0.044 sec old) Buffer length: 4.940 sec Buffer length: 4.940 sec Buffer length: 4.940 sec

wheel\_rh

wheel\_rf

Broadcaster: /robot\_state\_publisher

Average rate: 100.202 Hz

Most recent transform: 25.515 (0.044 sec old)

Buffer length: 4.940 sec

Broadcaster: /robot\_state\_publisher

Average rate: 100.202 Hz

Most recent transform: 25.515 ( 0.044 sec old)

Buffer length: 4.940 sec

wheel\_lh

leg\_lf

wheel\_lf