

view_frames Result

Recorded at time: 389.456

map

Broadcaster: /world_groundtruth_publisher
Average rate: 100.221 Hz
Most recent transform: 389.450 (0.006 sec old)
Buffer length: 4.969 sec

odom

Broadcaster: /gazebo
Average rate: 50.202 Hz
Most recent transform: 389.444 (0.012 sec old)
Buffer length: 4.960 sec

base_footprint

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (389.456 sec old)
Buffer length: 0.000 sec

base_link

Broadcaster: /robot_state_publisher
Average rate: 100.202 Hz
Most recent transform: 389.424 (0.032 sec old)
Buffer length: 4.950 sec

leg_lf

Broadcaster: /robot_state_publisher
Average rate: 100.202 Hz
Most recent transform: 389.424 (0.032 sec old)
Buffer length: 4.950 sec

wheel_lf

Broadcaster: /robot_state_publisher
Average rate: 100.202 Hz
Most recent transform: 389.424 (0.032 sec old)
Buffer length: 4.950 sec

leg_lh

Broadcaster: /robot_state_publisher
Average rate: 100.202 Hz
Most recent transform: 389.424 (0.032 sec old)
Buffer length: 4.950 sec

wheel_lh

Broadcaster: /robot_state_publisher
Average rate: 100.202 Hz
Most recent transform: 389.424 (0.032 sec old)
Buffer length: 4.950 sec

leg_rf

Broadcaster: /robot_state_publisher
Average rate: 100.202 Hz
Most recent transform: 389.424 (0.032 sec old)
Buffer length: 4.950 sec

wheel_rf

Broadcaster: /robot_state_publisher
Average rate: 100.202 Hz
Most recent transform: 389.424 (0.032 sec old)
Buffer length: 4.950 sec

leg_rh

Broadcaster: /robot_state_publisher
Average rate: 100.202 Hz
Most recent transform: 389.424 (0.032 sec old)
Buffer length: 4.950 sec

wheel_rh