

High Frequency Planar Magnetics for Power Conversion

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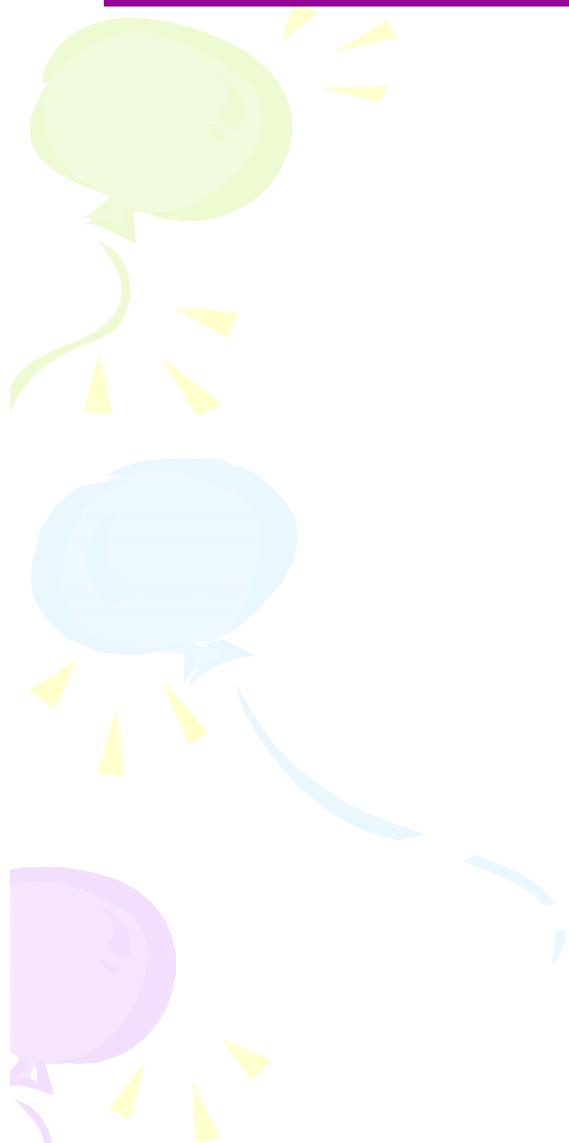


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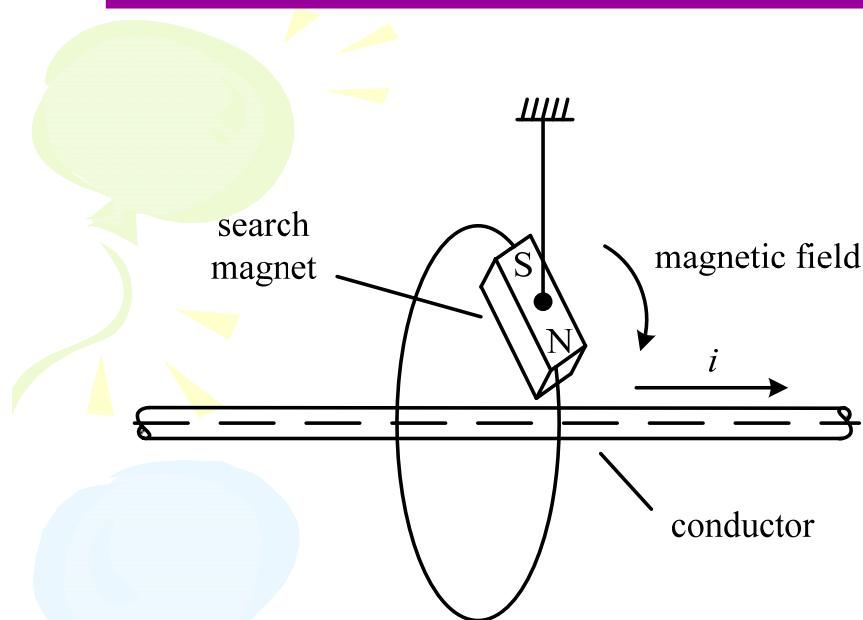
- Magnetics Basics Introduction (WGH)
 - ✓ Transformer Design
 - ✓ High Frequency Effects in the Winding
- Analytical Models for Planar Magnetics (WGH)
- Planar Magnetics – Fundamentals (ZO)
- Planar Magnetic Components Integration (ZO)



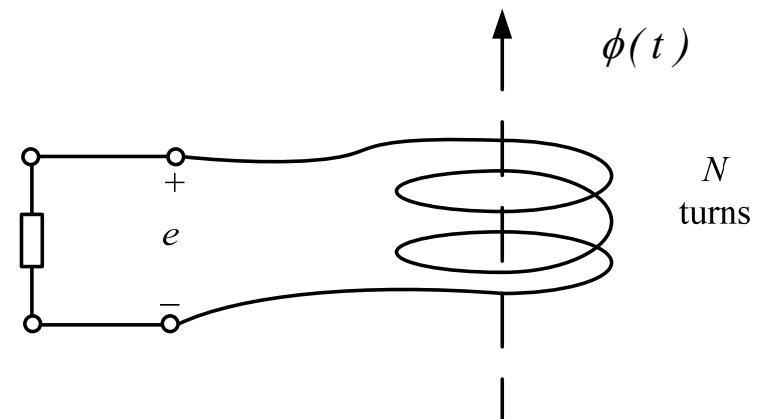
Magnetics Basics



Laws of Electromagnetism



Ampere's Law



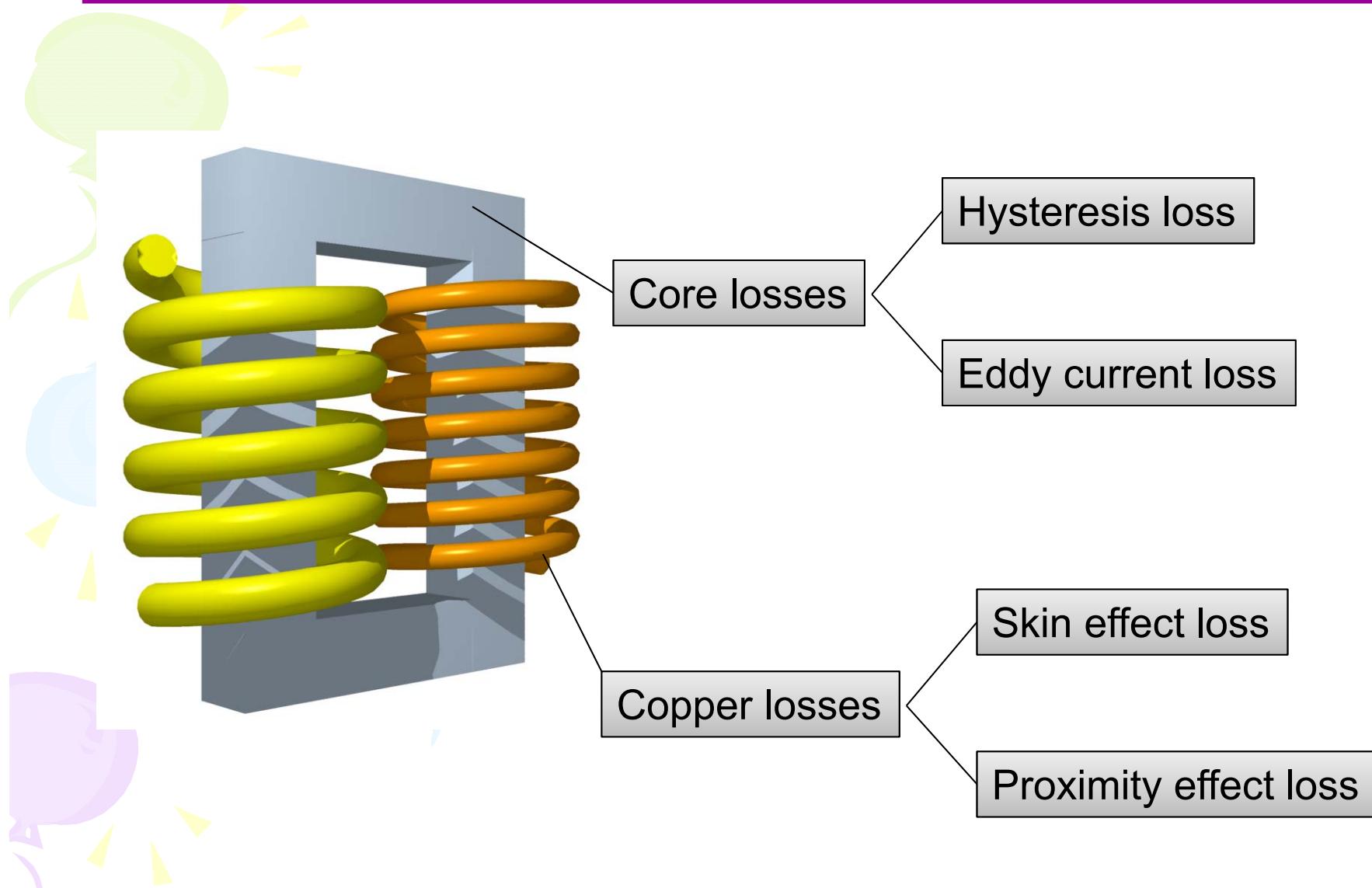
Faraday's Law

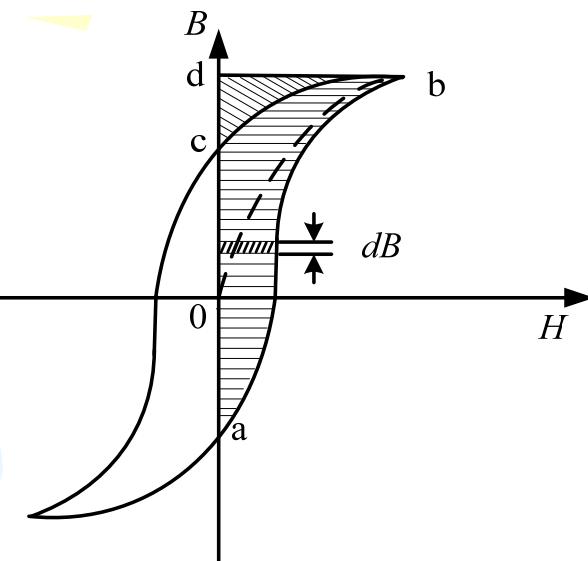
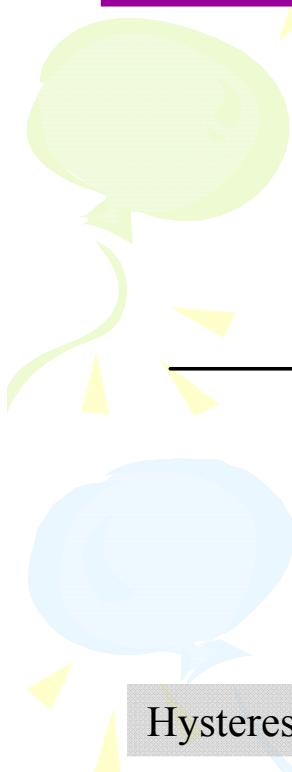
$$\sum H \cdot l = Ni$$

$$e = -N \frac{d\phi}{dt}$$

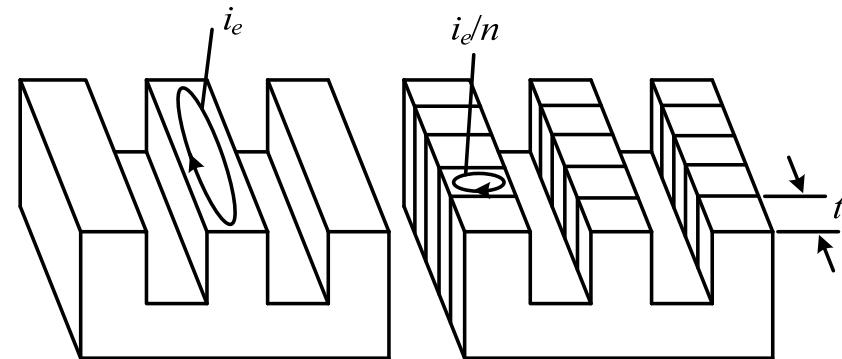
$$\mathbf{B} = \mu \mathbf{H} \quad \mu = \mu_r \mu_0$$







Hysteresis loss in a ferromagnetic material

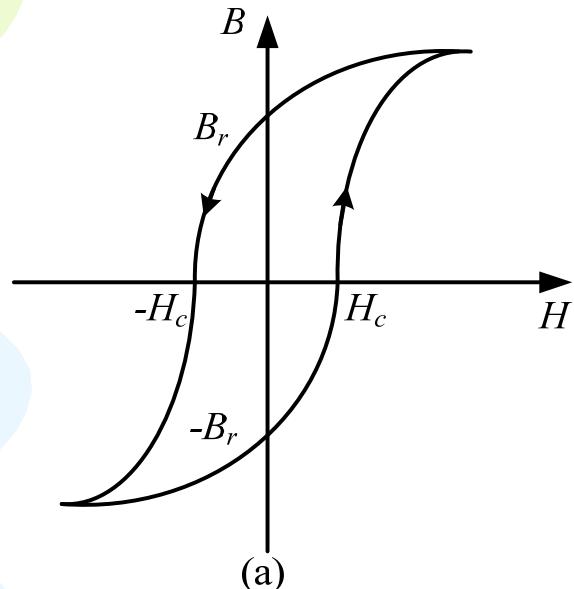


Eddy current loss in a ferromagnetic material

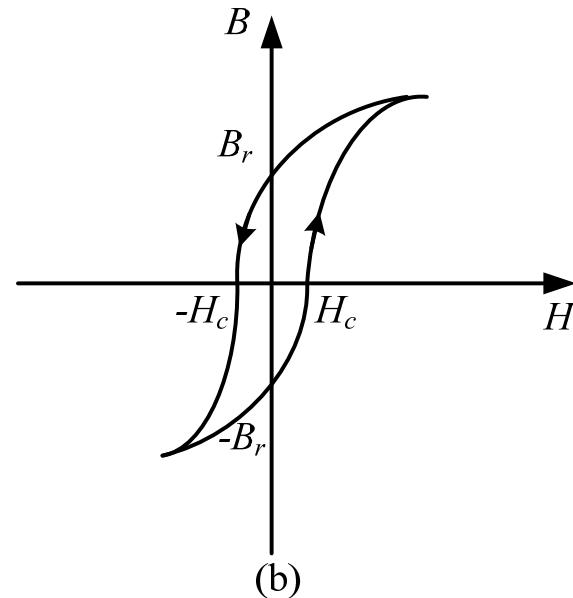
$$P_{fe} = K_c f^\alpha B_{\max}^\beta$$

- ❖ Hysteresis loss is the area inside the B-H loop
- ❖ Eddy current loss is reduced by laminations





(a) Hard magnetic materials



(b) Soft magnetic materials

Soft Magnetic Materials

The magnetic and operating properties of some soft magnetic materials

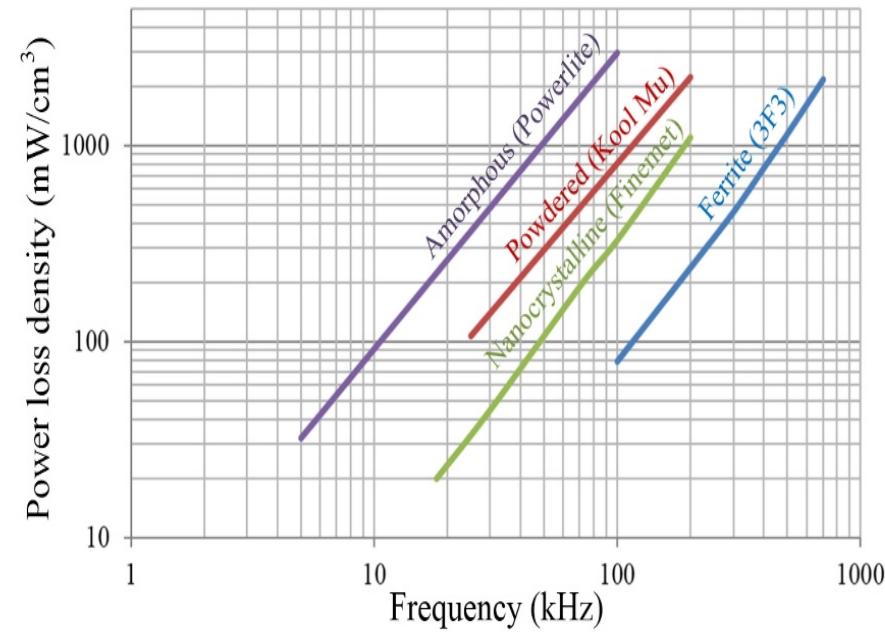
Materials	Ferrites	Nanocrystalline	Amorphous	Si Iron	Ni-Fe (Permalloy)	Powdered iron
Model	TDK P40	VIROPERM 500F	METGLAS 2605	AK Oriented M-4	MAGNETICS PERMALLOY 80	MICROMET -ALS 35 μ
Permeability, μ_i	1500-4000	15000	10,000- 150, 000	5,000- 10,000	20,000	3-550
B_{peak} , T	0.45-0.81	1.2	1.56	2.0	0.82	0.6-1.3
ρ , $\mu\Omega m$	6.5×10^6	1.15	1.3	0.51	0.57	10^6
Curie temp. T_c , ° C	215	600	399	746	460	665
P_{loss}	60 mW/ cm ³ at 0.1T/50kHz	588 mW/cm ³ at 0.3T/100kHz	72 m W/cm ³ at 0.2T/25kHz	2.295- 30.6mW/cm ³ at 1.5T/50Hz	192.28mW/cm ³ at 0.2T/5kHz	126- 315mW/cm ³ at 0.1T/10kHz

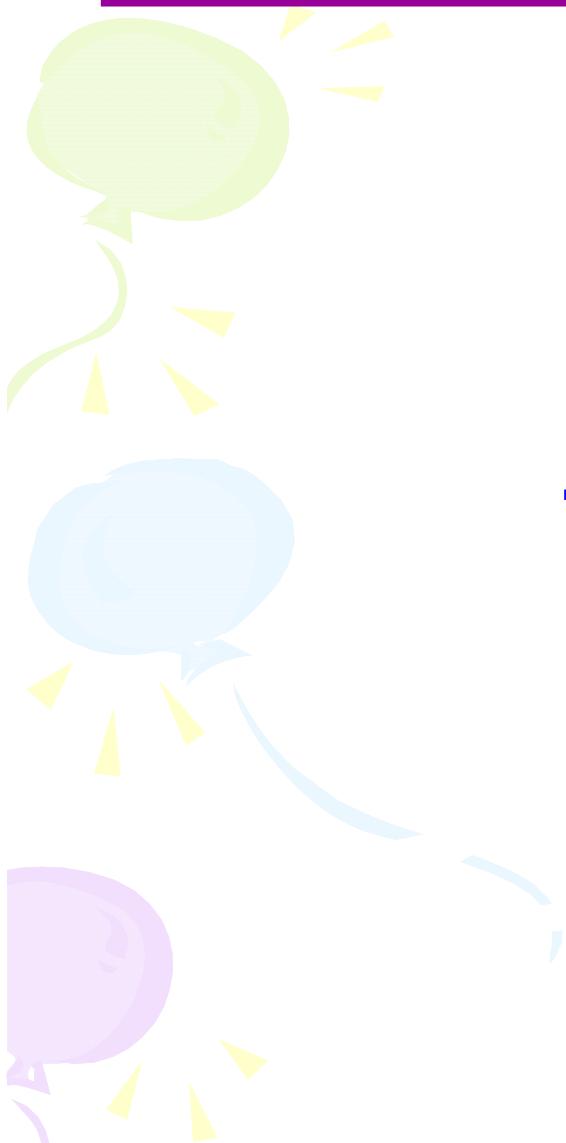


Core Shapes



Core Loss Density vs Frequency





Transformer Design

Voltage equation

$$V_{\text{rms}} = \frac{k}{\tau/T} f N B_{\text{max}} A_m = K_v f N B_{\text{max}} A_m \quad \text{where} \quad k = \frac{V_{\text{rms}}}{<v>} \quad K_v = \frac{k}{\tau} = \frac{k}{Tf}$$

$K_v = 4.44$ for a sinewave
 $= 4.00$ for a squarewave

Power equation

$$\sum \text{VA} = K_v f B_{\text{max}} J_o k_f k_u A_p$$

- | | |
|--------------------|--|
| V_{rms} : | the rms value of the applied voltage |
| $<v>$: | the average value of the applied voltage |
| K_v : | voltage waveform factor |
| k : | the form factor |
| f : | the frequency of the applied voltage |
| T : | the period of the applied voltage |
| τ : | the interval from the point where the flux density is zero to the point where it is at its maximum value |
| k_f : | the core stacking factor |
| J_o : | the current density in each winding |



Winding losses

Total resistive losses

$$P_{cu} = \sum RI^2 = \rho \sum_w \sum_{i=1}^n \frac{N_i M L T (J_o A_{wi})^2}{A_{wi}}$$

$$k_u = \frac{\sum_{i=1}^n N_i A_{wi}}{W_a}$$

is window utilization factor

$V_w = M L T \times W_a$ is volume of the windings

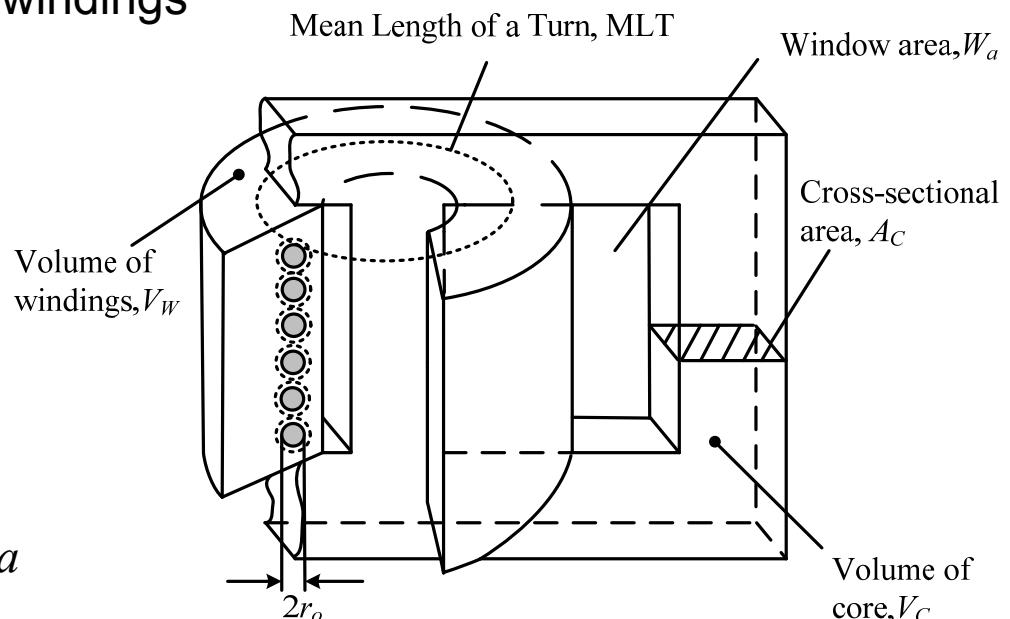
$$P_{cu} = \rho_w V_w k_u J_o^2$$

Core losses

$$P_{fe} = V_c K_c f^\alpha B_{max}^\beta$$

$$A_p = W_a \times A_c$$

Window area \times cross-sectional area



Typical layout of a transformer



Winding losses

Core losses

Total losses

At a given operation frequency,

$$\frac{\partial P}{\partial B_{\max}} = -\frac{2a}{f^2 B_{\max}^3} + \beta b f^\alpha B_{\max}^{\beta-1} = 0$$

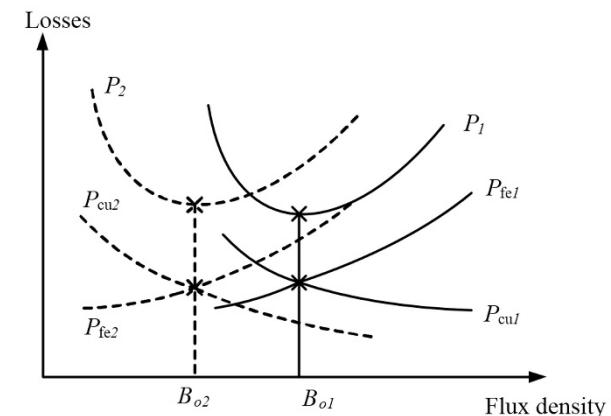
The minimum losses occur when

$$P_{\text{cu}} = \frac{\beta}{2} P_{\text{fe}}$$

$$P_{\text{cu}} = \rho_w V_w k_u \left[\frac{\sum \text{VA}}{K_v f B_{\max} k_f k_u A_p} \right]^2 = \frac{a}{f^2 B_{\max}^2}$$

$$P_{\text{fe}} = V_c K_c f^\alpha B_{\max}^\beta = b f^\alpha B_{\max}^\beta$$

$$P = \frac{a}{f^2 B_m^2} + b f^\alpha B_m^\beta$$



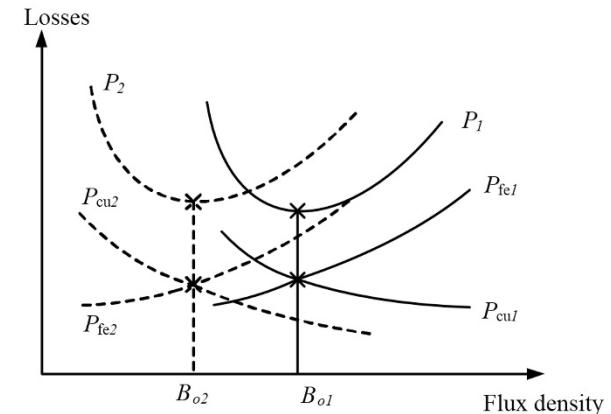
$$P = \frac{a}{f^2 B_m^2} + b f^\alpha B_m^\beta$$

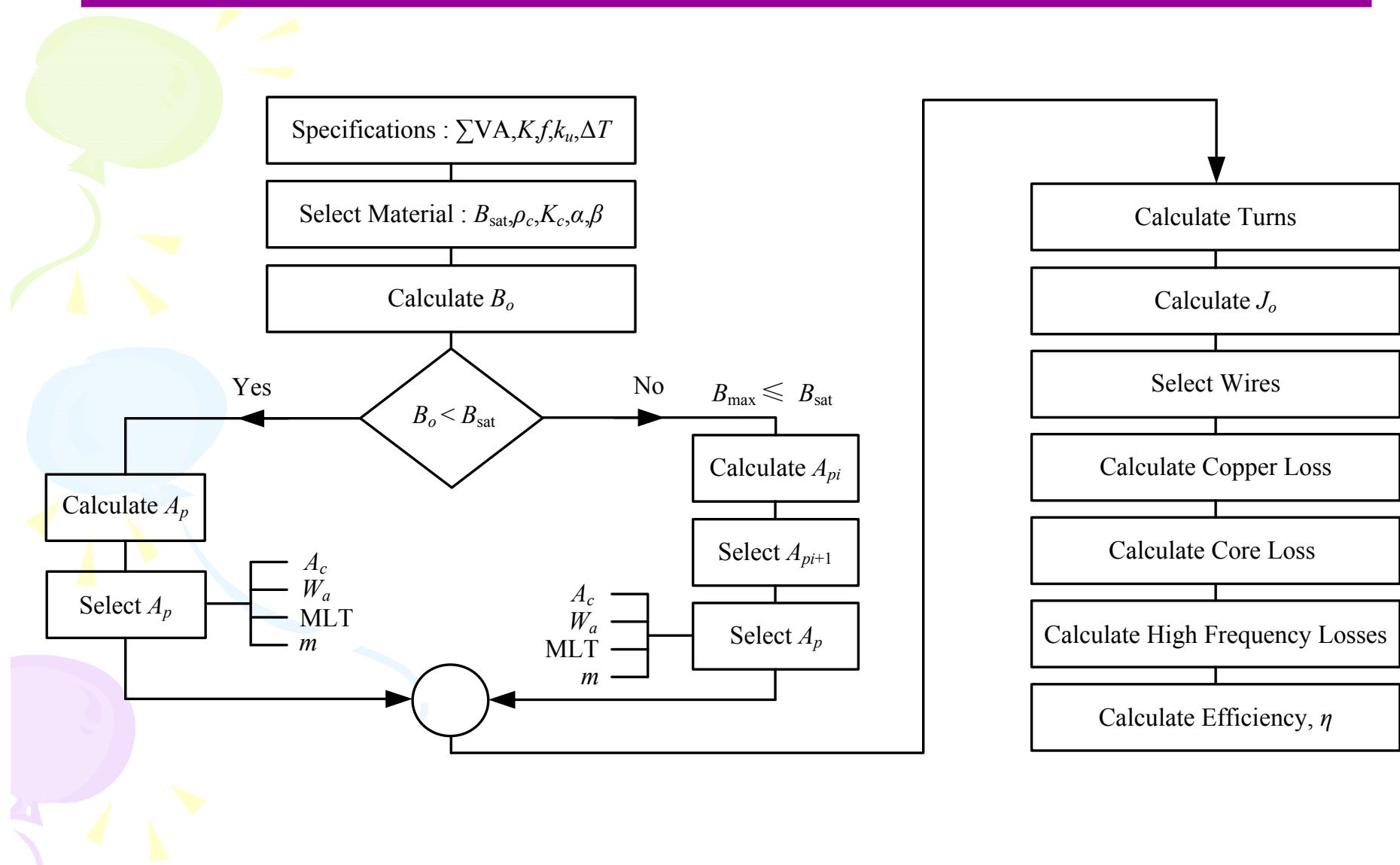
$$B_o^{\frac{7\beta-12}{12}} f^{\frac{7\alpha-12}{12}} = \frac{2^{7/12} \beta^{1/12}}{(\beta+2)^{2/3}} \frac{[hk_t \Delta T]^{2/3}}{[\rho k_w]^{1/12} [k_c K_c]^{7/12}} \left[\frac{K_v \sqrt{k_u}}{\sum \text{VA}} \right]^{1/6}$$

$$A_p = \left[\frac{\beta+2}{\beta} \frac{1}{k_u \Delta T} \right]^{4/7} \left[\frac{\sum \text{VA}}{K_v f B_o K_\theta} \right]^{8/7}$$

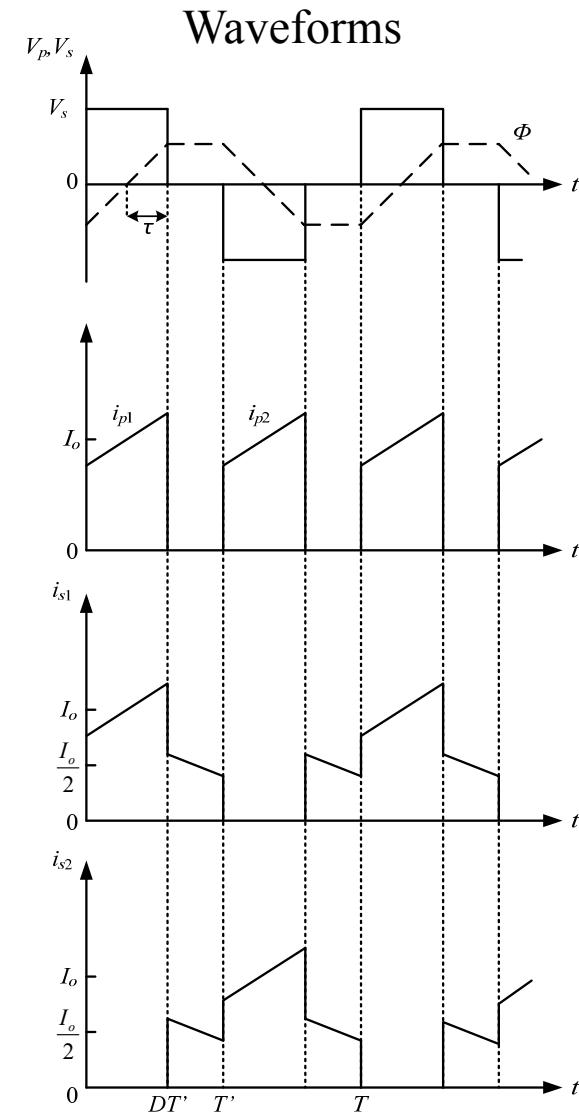
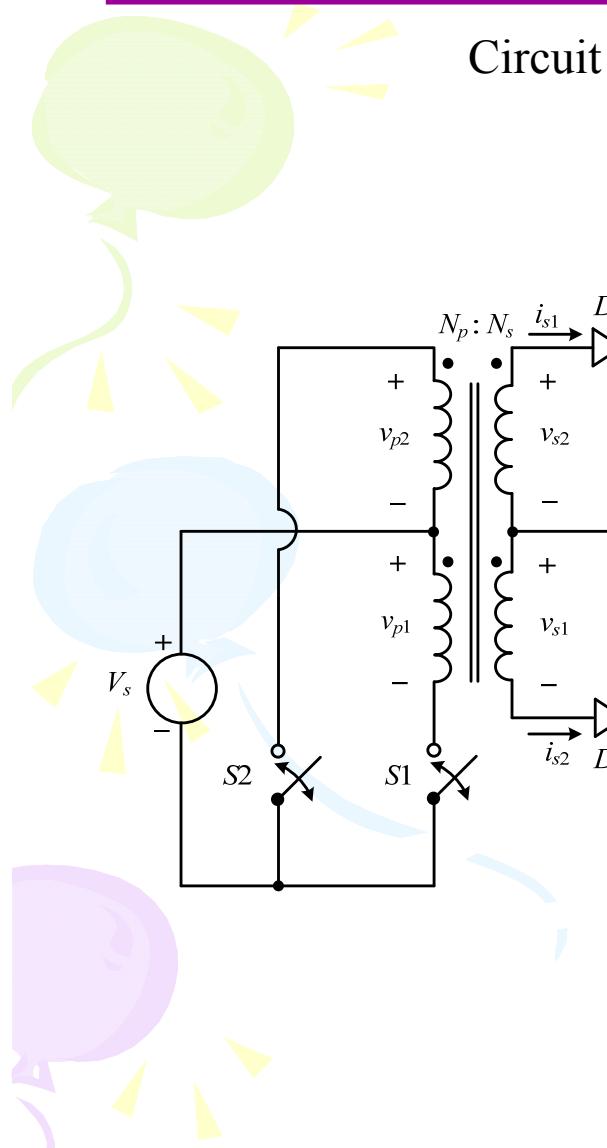
$$J_o = \sqrt{\frac{\beta}{\beta+2}} \frac{hk_t}{\rho k_w} \sqrt{\frac{\Delta T}{k_u}} \frac{1}{A_p^{1/8}} = K_\theta \sqrt{\frac{\beta}{\beta+2}} \sqrt{\frac{\Delta T}{k_u}} \frac{1}{A_p^{1/8}}$$

For $h=10 \text{ W/m}^2 \text{ }^\circ\text{C}$, $k_c=5.6$, $k_w=10$, $k_t=40$, $\rho=1.72 \times 10^{-8} \Omega\text{-m}$, $K_\theta=48.224 \times 10^3$.





Push-pull Converter Transformer



Design specifications

Input	36 → 72 V
Output	24 V, 12.5 A
Frequency, f	50 kHz
Temperature Rise, ΔT	35 °C
Ambient Temperature, T_a	45 °C

Core data: EPCOS N67 Mn-Zn

K_c	9.12
α	1.24
β	2.0
B_{sat}	0.4 T

Core loss

$$P_{fe} = K_c f^\alpha B_m^\beta$$



Calculations:

(3) VA ratings of the windings

$$P_o = (24+1) \times 12.5 = 312.5 \text{ W}$$

$$\begin{aligned} \sum VA &= \left(\frac{1}{k_{pp}} \left(\frac{P_o}{2} + \frac{P_o}{2} \right) + \frac{1}{k_{ps}} \left(\frac{P_o}{2} + \frac{P_o}{2} \right) \right) = \left(\sqrt{2} + \sqrt{\frac{1+D}{D}} \right) P_o \\ &= \left(\sqrt{2} + \sqrt{\frac{1+0.67}{0.67}} \right) (312.5) = 935 \end{aligned}$$

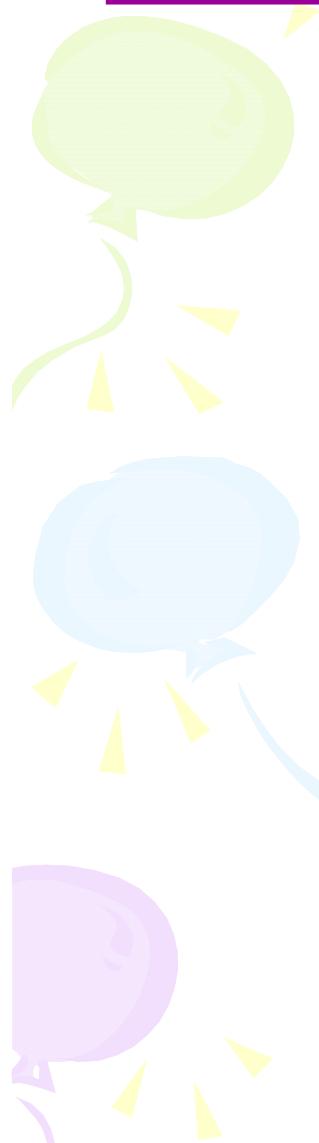
(4) Optimum A_p

$$\begin{aligned} B_o &= \frac{[(10)(40)(35)]^{2/3}}{2^{2/3} [(1.72 \times 10^{-8})(10)(0.4)]^{1/12} [(5.6)(9.12)(50\,000)^{1.24}]^{7/12}} \\ &\cdot \left[\frac{(4.88)(50000)(1.0)(0.4)}{935} \right]^{1/6} = 0.126 \text{ T} \end{aligned}$$

The optimum flux density is less than B_{sat}

$$A_p = \left[\frac{\sqrt{2}(935)}{(4.88)(50\,000)(0.126)(1.0)(0.4)(48.2 \times 10^3) \sqrt{(0.4)(35)}} \right]^{8/7} \times 10^8 = 2.693 \text{ cm}^4$$





A_c	1.73 cm ²
W_a	2.78 cm ²
A_p	4.81 cm ⁴
V_c	17.70 cm ³
k_f	1.0
k_u	0.4
MLT	7.77 cm
ρ_{20}	1.72 $\mu\Omega\text{-cm}$
α_{20}	0.00393

Calculations:

(6) Wire size

$$J_o = K_t \sqrt{\frac{\Delta T}{2k_u}} \frac{1}{\sqrt[8]{A_p}} = (48.2 \times 10^3) \sqrt{\frac{35}{2(0.4)}} \frac{1}{\sqrt[8]{(4.81 \times 10^{-8})}} = 2.620 \times 10^6 \text{ A/m}^2$$

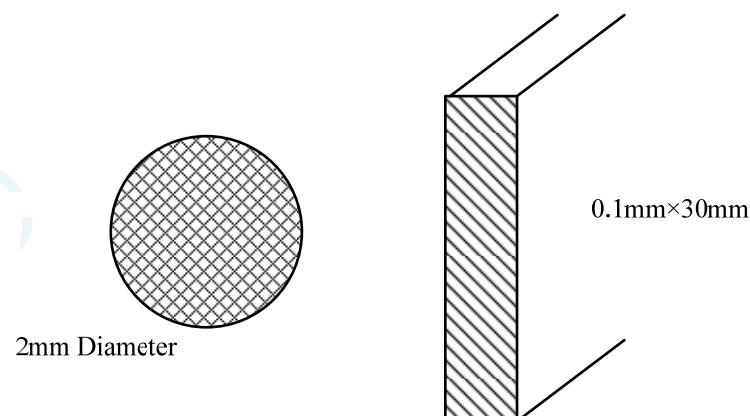
Primary windings:

$$I_p = \frac{P_o / 2}{k_{pp} V_p} = \frac{312.5 / 2}{(0.707)(29.5)} = 7.5 \text{ A}$$

$$A_w = I_p / J_o = 2.863 \text{ mm}^2$$

Skin depth at 50 kHz = 0.295 mm

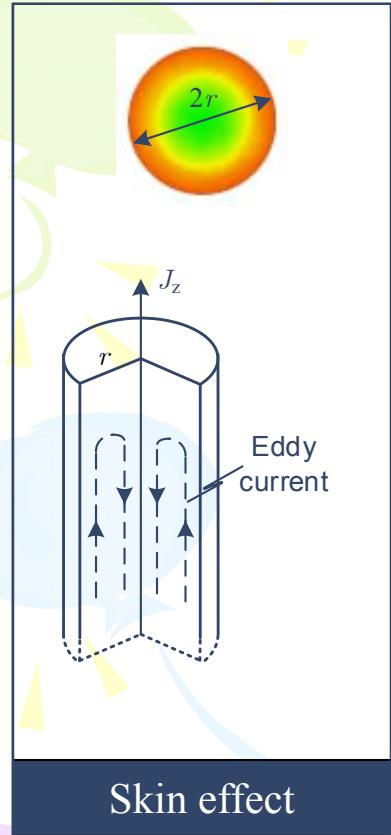
Standard 0.1×30 mm copper foil with a dc resistance of $5.8 \text{ m}\Omega/\text{m}$ @ 20°C meets this requirement or a 2 mm diameter wire.



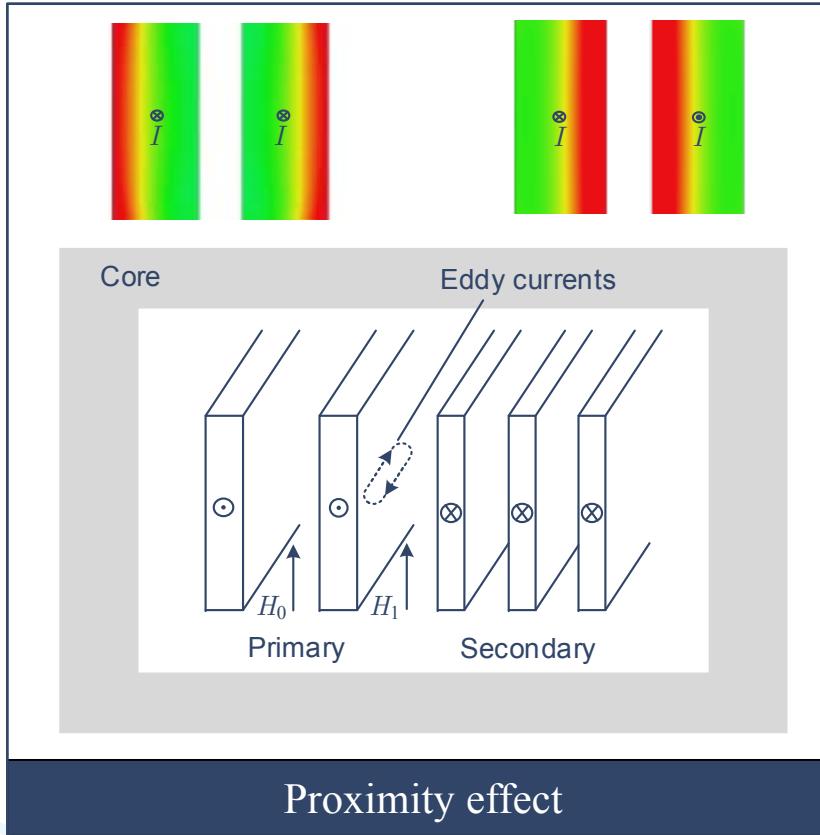


High Frequency Effects in the Windings

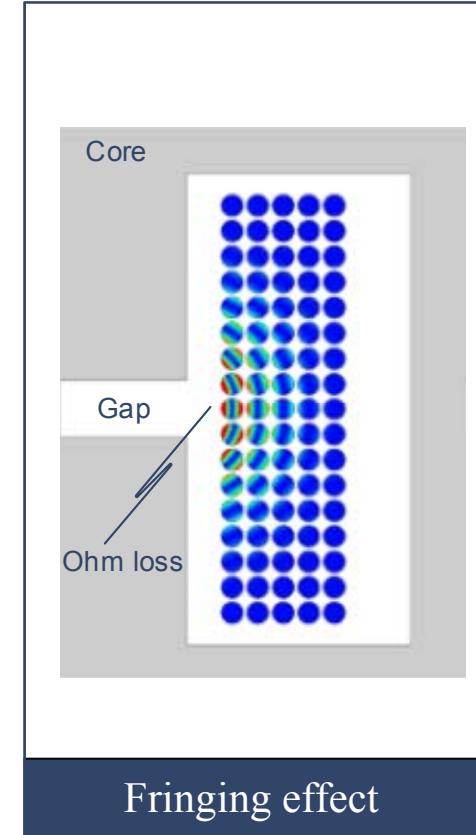
Design Issues for High Frequency



Skin effect

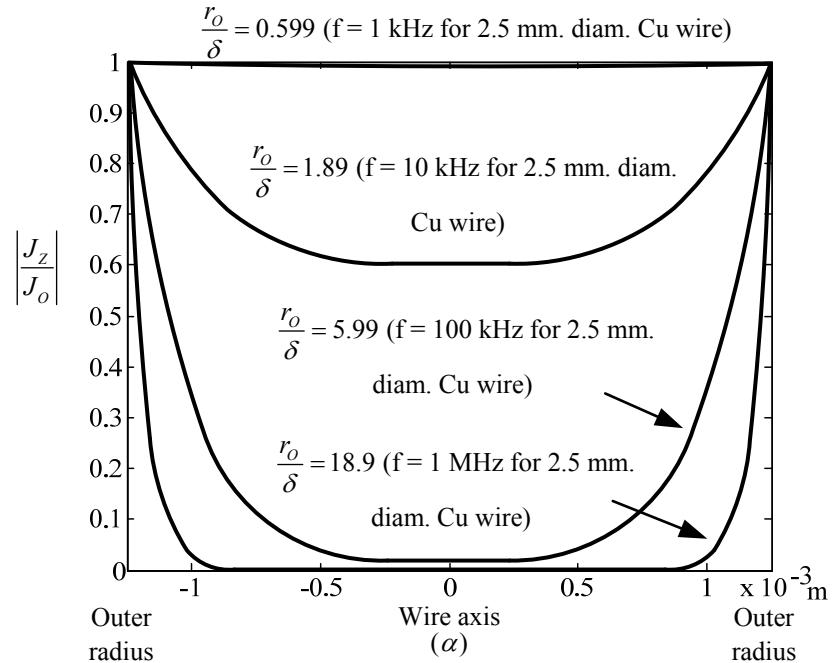
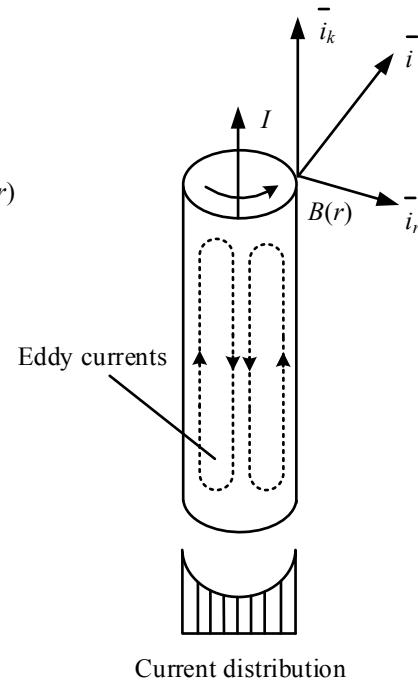
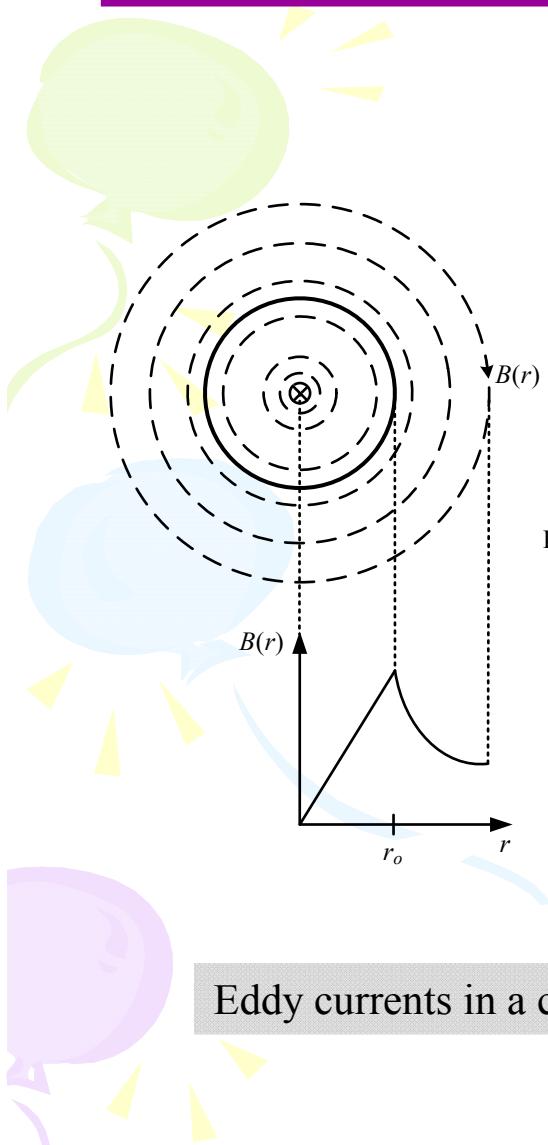


Proximity effect



Fringing effect

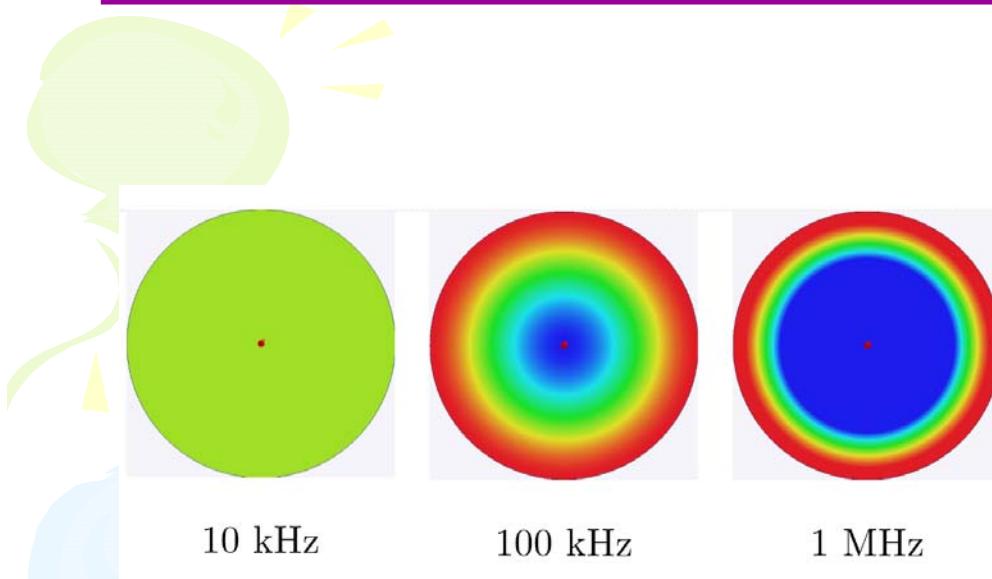
- High frequency winding loss
- Core loss: Steinmetz equation, iGSE.
- Parasitic parameters: leakage inductance, stray capacitance



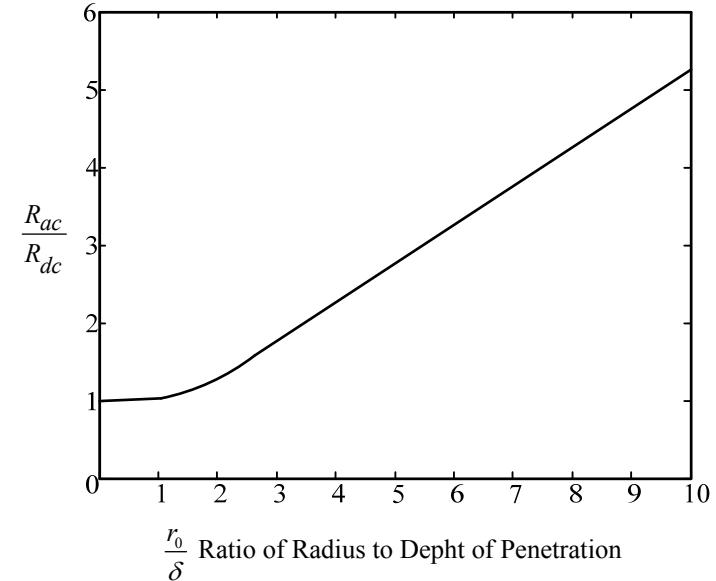
Eddy currents in a circular conductor

Current distribution in a circular conductor





Current distribution in a circular conductor



R_{ac}/R_{dc} due to the skin effect

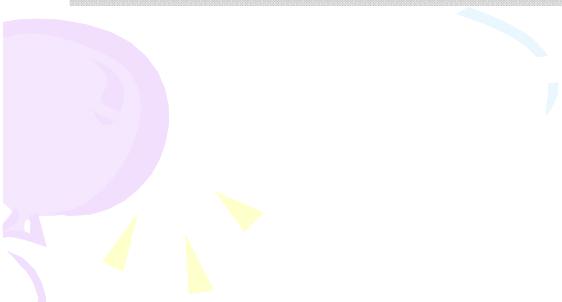
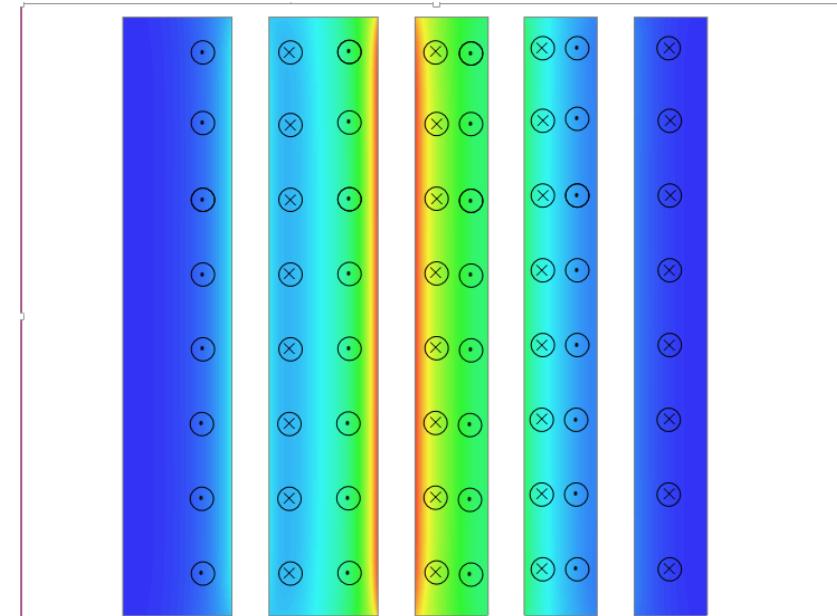
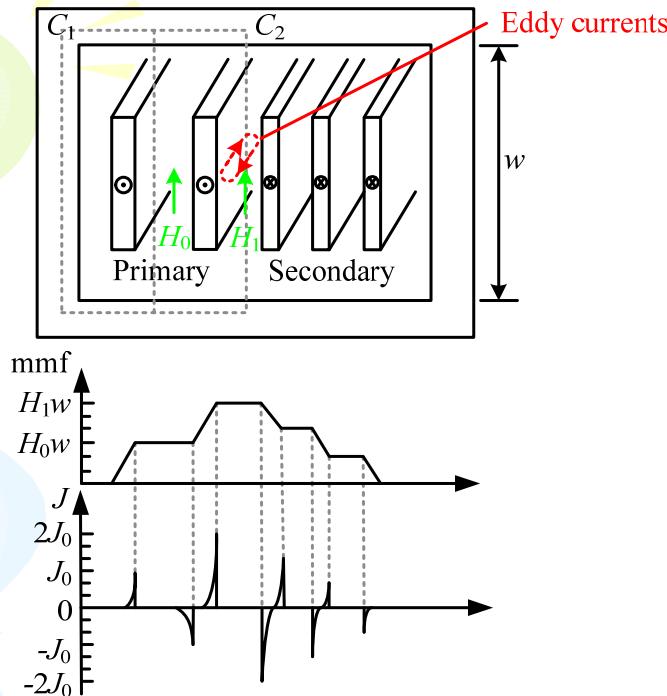
$$\frac{R_{ac}}{R_{dc}} = 1 + \frac{(r_o/\delta)^4}{48 + 0.8(r_o/\delta)^4} \quad r_o/\delta < 2$$

$$\delta = \frac{1}{\sqrt{\pi f \mu \sigma}}$$

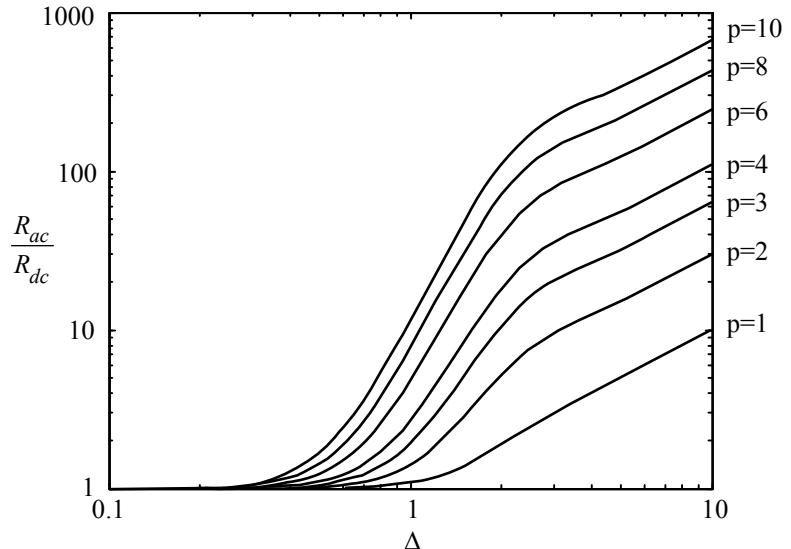
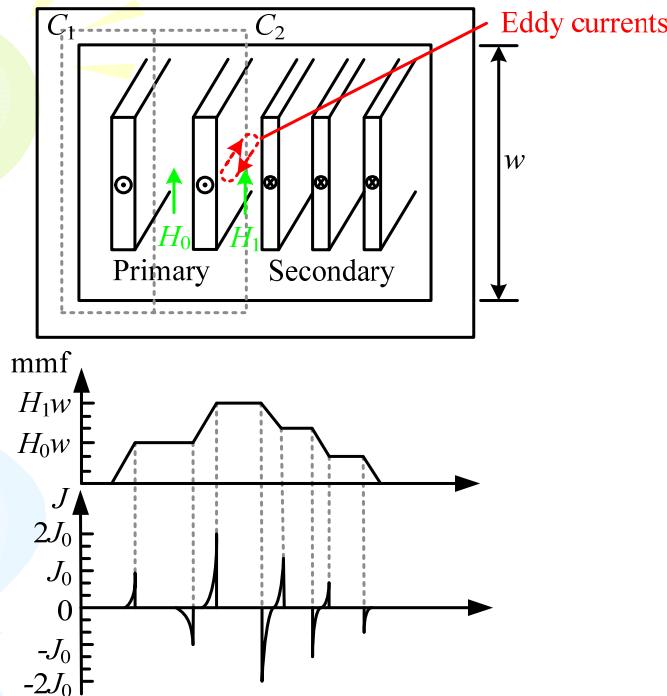
- The ac resistance is proportional to the square root of frequency at very high frequencies.



Proximity Effect



Proximity Effect



R_{ac}/R_{dc} due to the proximity effect

$$\frac{R_{ac}}{R_{dc}} = \phi_{prox}(\Delta) = 1 + \frac{5p^2 - 1}{45} \Delta^4 \text{ where } \Delta = \frac{d}{\delta}$$

$$\delta = \frac{1}{\sqrt{\pi f \mu \sigma}}$$

- ❖ As the number of layers p increase there is a substantial increase in the ac resistance for a given layer thickness d and frequency f .



Porosity Factor

A round conductor of diameter D is equivalent to a square conductor of side length

$$d = \sqrt{\frac{\pi}{4}} D$$

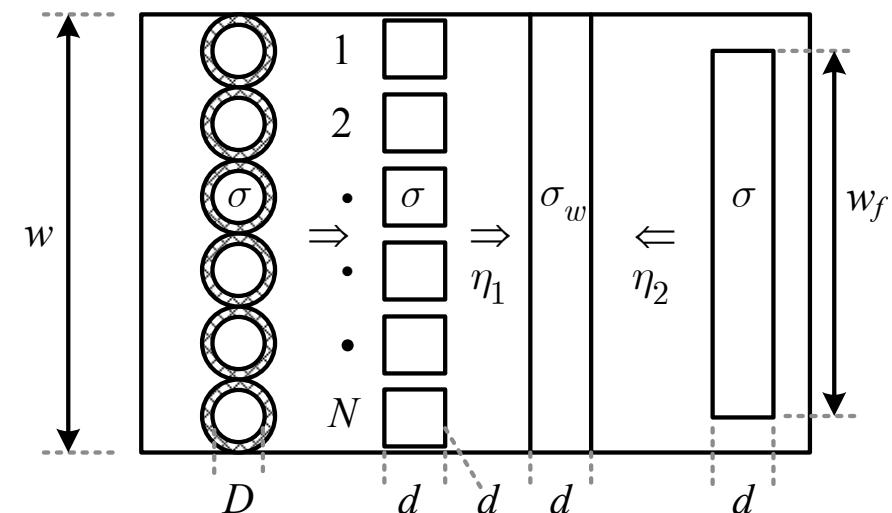
The porosity factor

$$\eta = \frac{Nd}{w}$$

The effective conductivity

$$\sigma_w = \eta \sigma$$

$$\delta = \frac{1}{\sqrt{\pi f \mu \sigma_w}}$$



Porosity factor for foils and round conductors



An arbitrary periodic current waveform may be represented by its Fourier series

$$i(t) = I_{dc} + \sum_{n=1}^{\infty} \hat{I}_n \cos(n \omega t + \varphi_n)$$

The total power loss due to all the harmonics

$$P = R_{dc} I_{dc}^2 + \sum_{n=1}^{\infty} R_{dc} \phi_{prox}(\Delta_n) I_{n,rms}^2$$

so

$$\delta = \frac{1}{\sqrt{\pi f \mu \sigma}} \quad \Delta_n = \frac{d}{\delta_n} = \sqrt{n} \frac{d}{\delta_o} = \sqrt{n} \Delta$$

$$\frac{R_{eff}}{R_{dc}} = \frac{I_{dc}^2 + \sum_{n=1}^{\infty} \phi_{prox}(\Delta_n) I_{n,rms}^2}{I_{rms}^2}$$

$$\phi_{prox}(\Delta_n) = 1 + \frac{5p^2 - 1}{45} \Delta_n^4 = 1 + \frac{5p^2 - 1}{45} n^2 \Delta^4$$

$$= \frac{I_{dc}^2 + \sum_{n=1}^{\infty} I_{n,rms}^2 + \frac{5p^2 - 1}{45} \Delta^4 \sum_{n=1}^{\infty} n^2 I_{n,rms}^2}{I_{rms}^2}$$



$$i(t) = I_{dc} + \sum_{n=1}^{\infty} \hat{I}_n \cos(n \omega t + \varphi_n)$$

$$I_{rms}^2 = I_{dc}^2 + \sum_{n=1}^{\infty} I_{n,rms}^2$$

$$\frac{di(t)}{dt} = I' = -\omega \sum_{n=1}^{\infty} n \hat{I}_n \sin(n \omega t + \varphi_n)$$

$$I'^2_{rms} = \omega^2 \sum_{n=1}^{\infty} n^2 I_{n,rms}^2$$

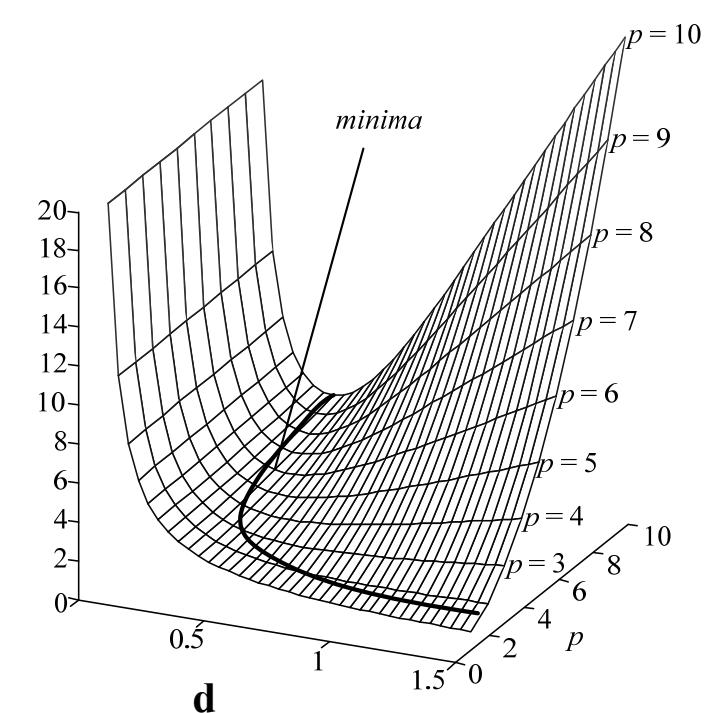
$$\frac{R_{eff}}{R_{dc}} = \frac{I_{dc}^2 + \sum_{n=1}^{\infty} I_{n,rms}^2 + \frac{5p^2-1}{45} \Delta^4 \sum_{n=1}^{\infty} n^2 I_{n,rms}^2}{I_{rms}^2}$$

$$= \frac{I_{rms}^2 + \frac{5p^2-1}{45} \Delta^4 \left[\frac{I'_{rms}}{\omega} \right]^2}{I_{rms}^2}$$

$$= 1 + \frac{5p^2-1}{45} \Delta^4 \left[\frac{I'_{rms}}{\omega I_{rms}} \right]^2$$

$$\Delta = \frac{d}{\delta_o}$$

R_{eff}





The optimum value of Δ

$$\Delta_{opt} = \sqrt{\frac{15}{5p^2 - 1}} \sqrt{\left[\frac{\omega I_{rms}}{\frac{di}{dt}} \right]_{rms}}$$



Finally

$$\frac{R_{eff}}{R_{dc}} = 1 + \frac{1}{3} \left(\frac{\Delta}{\Delta_{opt}} \right)^4$$

$$\left(\frac{R_{eff}}{R_{dc}} \right)_{opt} = \frac{4}{3}$$



$$\Delta_{opt} = \sqrt{\frac{15}{5p^2 - 1}} \sqrt{\frac{\omega I_{rms}}{I'_{rms}}}$$

Skin depth

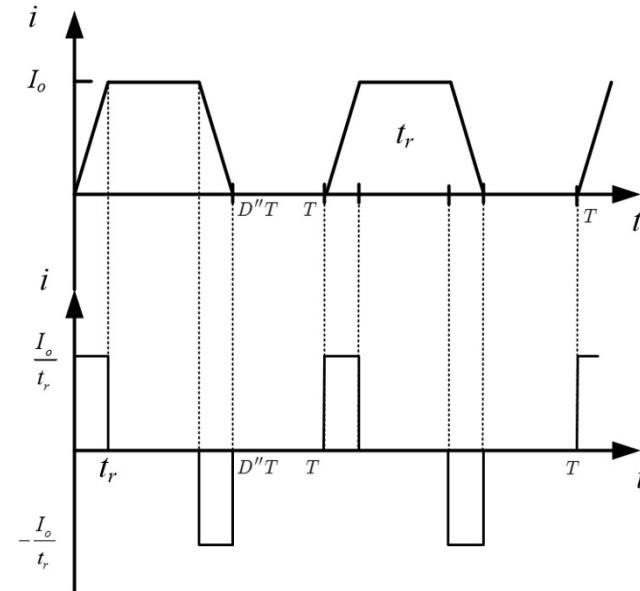
$$\delta_o = \frac{66}{\sqrt{f}} = \frac{66}{\sqrt{(50 \times 10^3)}} = 0.295 \text{ mm}$$

Optimum layer Δ

$$\Delta_{opt} = \sqrt[4]{\frac{\left[D - \frac{8t_r}{3T}\right]\pi^2 \frac{t_r}{T}}{(5p^2 - 1)15}} = \sqrt[4]{\frac{\left[0.67 - \frac{(8)(0.025)}{3}\right]\pi^2(0.025)}{[(5)(6)^2 - 1]/15}} = 0.3342$$

Optimum layer thickness

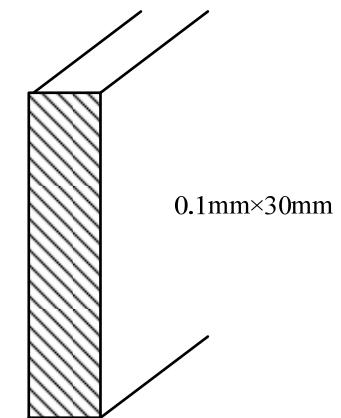
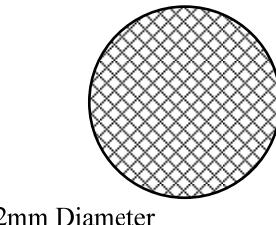
$$d_{opt} = \Delta_{opt} \delta_o = (0.3342)(0.295) = 0.1 \text{ mm}$$



Effective ac resistance: foil $\frac{R_{\text{eff}}}{R_{\text{dc}}} = \frac{4}{3} = 1.3$

AC resistance of round conductor

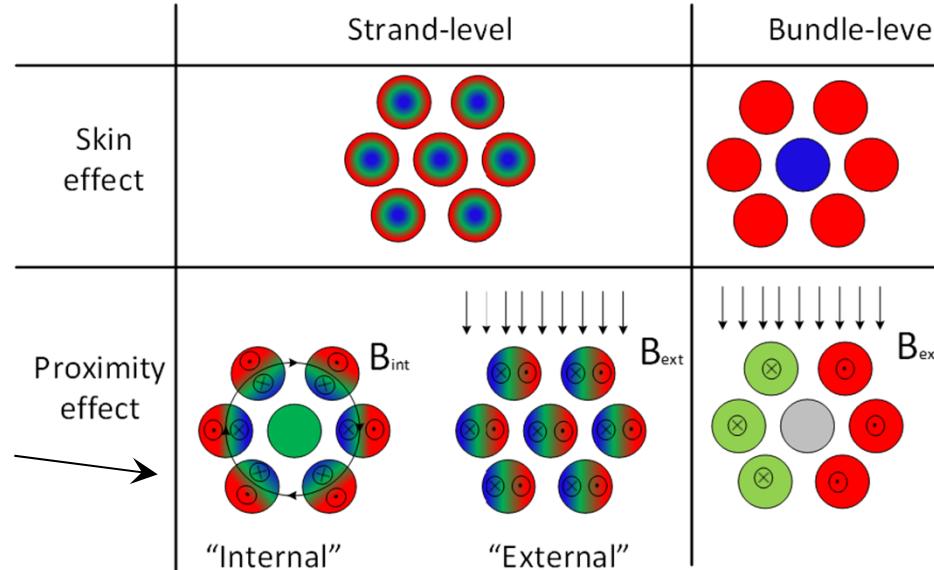
$$\frac{R_{\text{ac}}}{R_{\text{dc}}} = 0.25 + (0.5) \left(\frac{r_o}{\delta_0} \right) = 0.25 + (0.5) \left(\frac{1.0}{0.295} \right) = 1.95$$



Round versus foil conductor

Could replace solid wire with stranded Litz wire





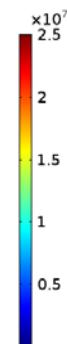
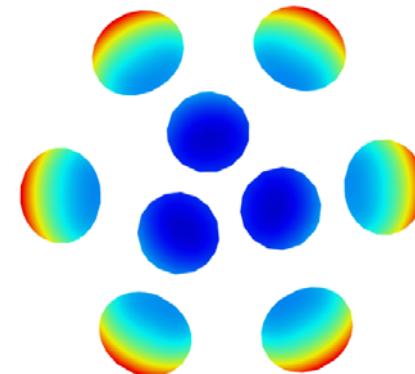
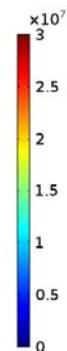
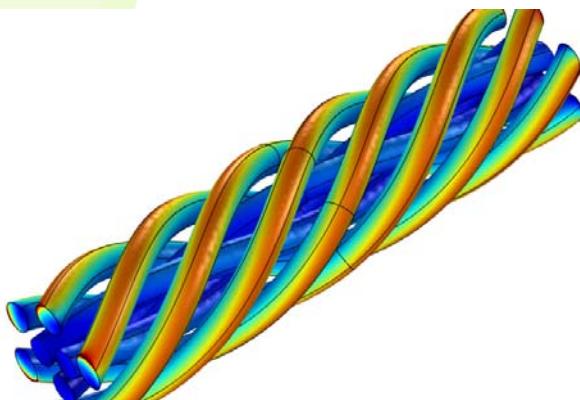
Avoid with radial and angular transposition

Avoid with radial transposition, simple twisting

- Litz wire reduces the window utilisation factor, core may be 30% larger for same temperature rise
- Use strands with diameter less than $\delta/4$
- Proximity effect occurs at strand level when wire is twisted
- Twisting cancels proximity effect at bundle level

Sullivan C. R., Zhang R. Y., "Analytical Model for Effects of Twisting on Litz-wire Losses", IEEE 15th Workshop on Control and Modelling for Power Electronics, (COMPEL), pp. 1-10. 2014

Litz Wire: skin effect

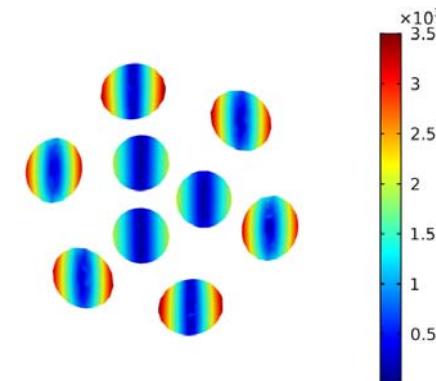
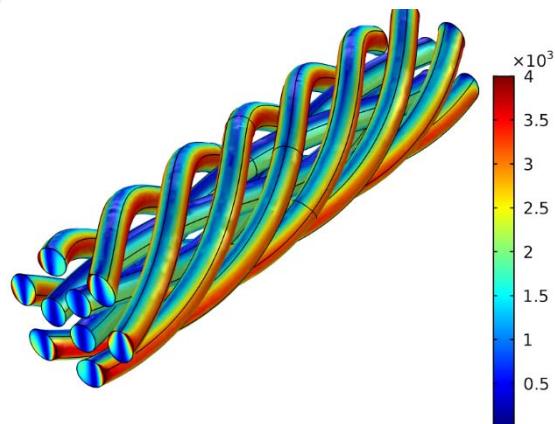
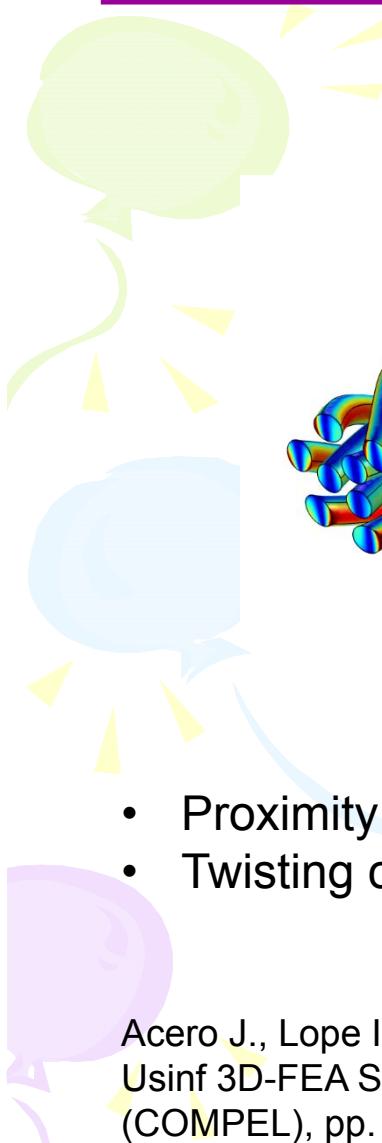


- Skin effect acts like a solid conductor at the bundle level
- Use strands with diameter less than $\delta/4$

Acero J., Lope I., Burdio J.M., Carretero C., Alonso R., "Loss Analysis of Multistranded Twisted Wires by Usinf 3D-FEA Simulation", IEEE 15th Workshop on Control and Modelling for Power Electronics, (COMPEL), pp. 1-6, 2014



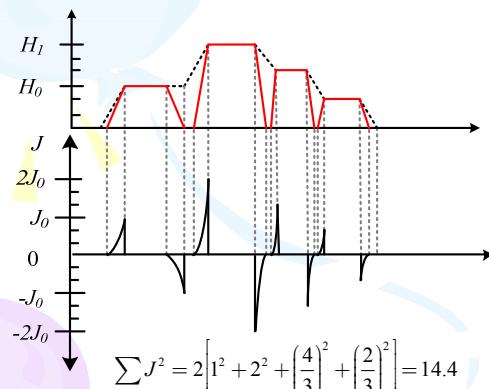
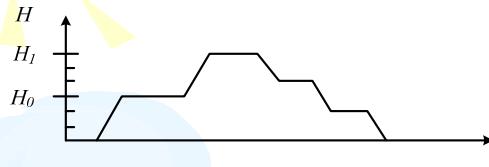
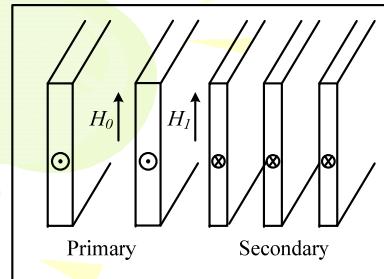
Litz Wire: proximity effect



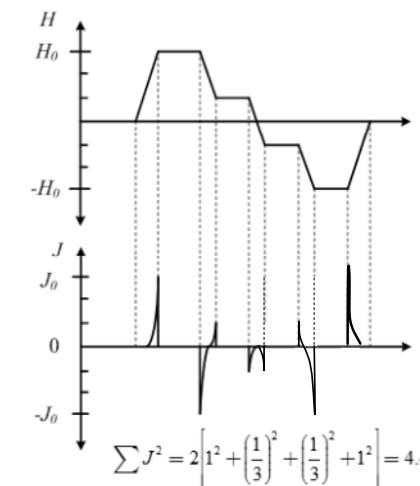
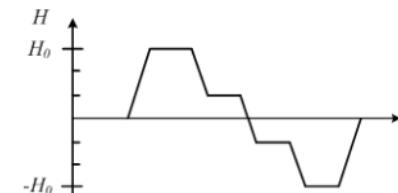
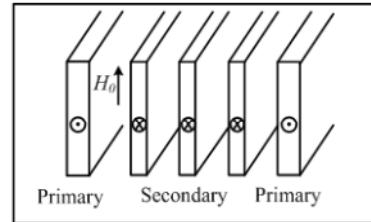
- Proximity effect occurs at strand level when wire is twisted
- Twisting cancels proximity effect at bundle level

Acero J., Lope I., Burdio J.M., Carretero C., Alonso R., "Loss Analysis of Multistranded Twisted Wires by Usinf 3D-FEA Simulation", IEEE 15th Workshop on Control and Modelling for Power Electronics, (COMPEL), pp. 1-6, 2014

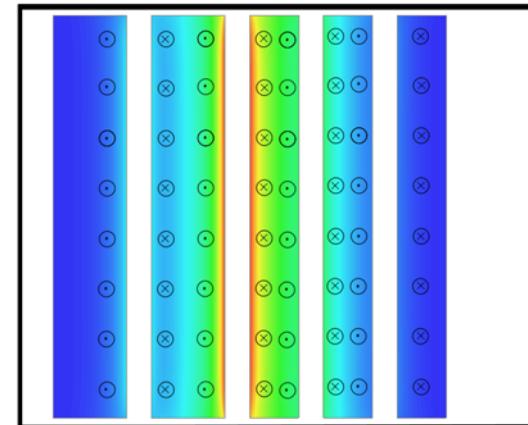
Interleaving the Windings



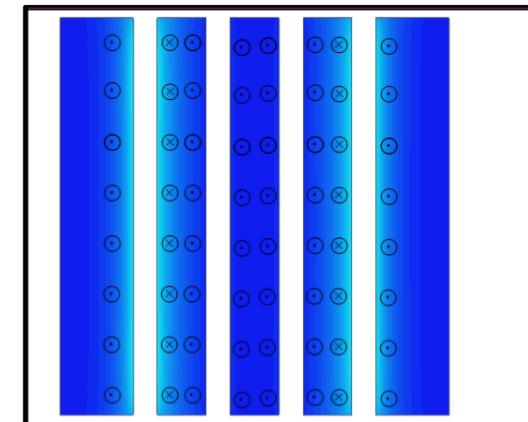
Current density distribution before interleaving



Current density distribution after interleaving



Current density distribution before interleaving in FEA

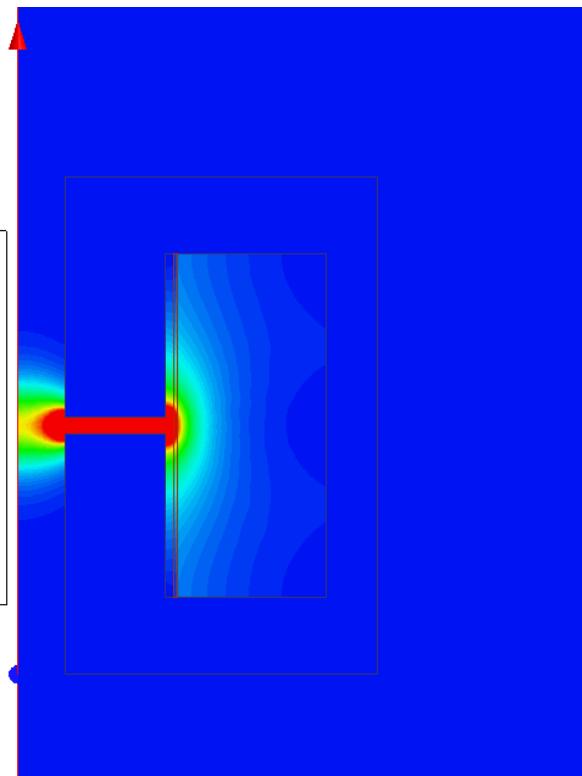
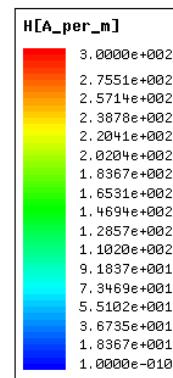


Current density distribution after interleaving in FEA

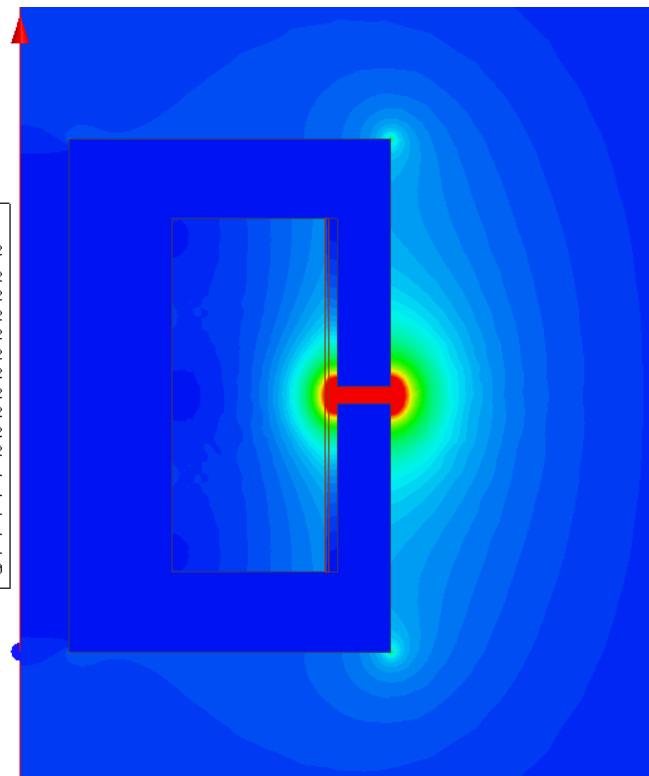
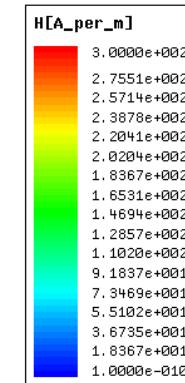
Fringing (Magnetic Field)

Frequency: 100kHz

Core: Magnetics® port core



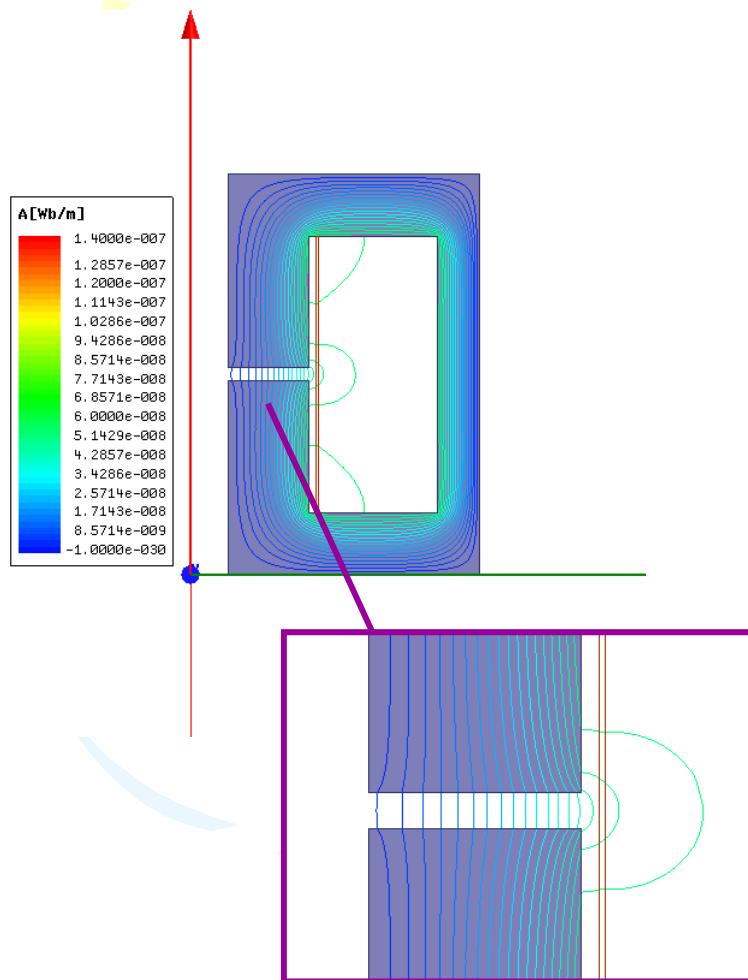
Gap in the centre leg



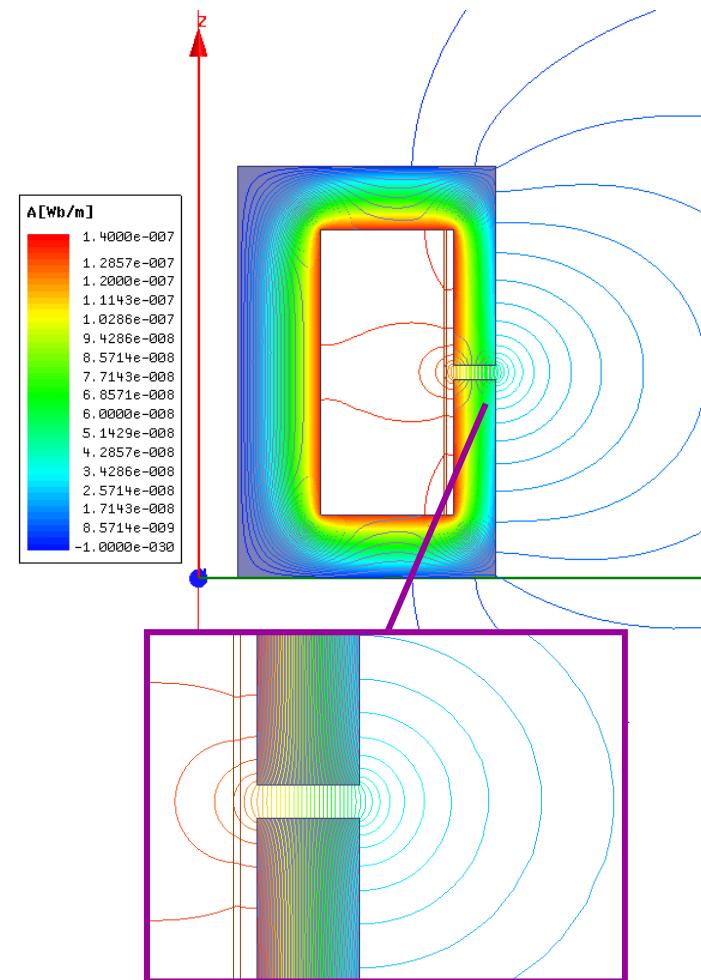
Gap in the outer leg



Fringing (Flux)



Gap in the centre leg



Gap in the outer leg

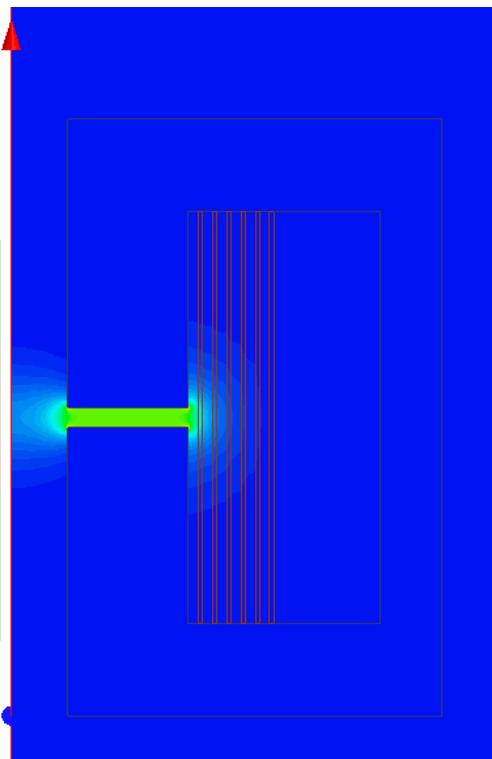
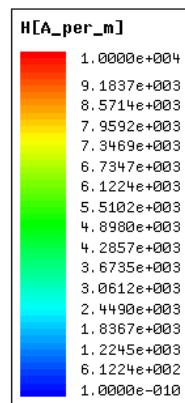


Fringing (Different Frequencies)

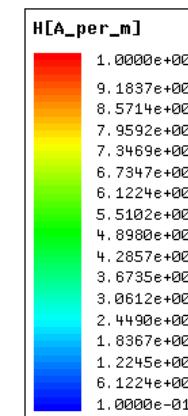
Magnetic Field Intensity

Width of conductor: 0.2mm

Core: Magnetics® port core



Frequency 1kHz

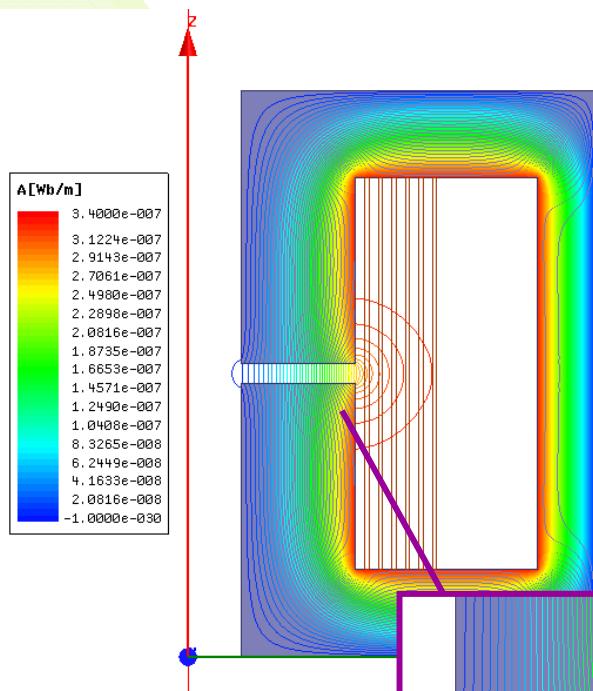


Frequency 100kHz

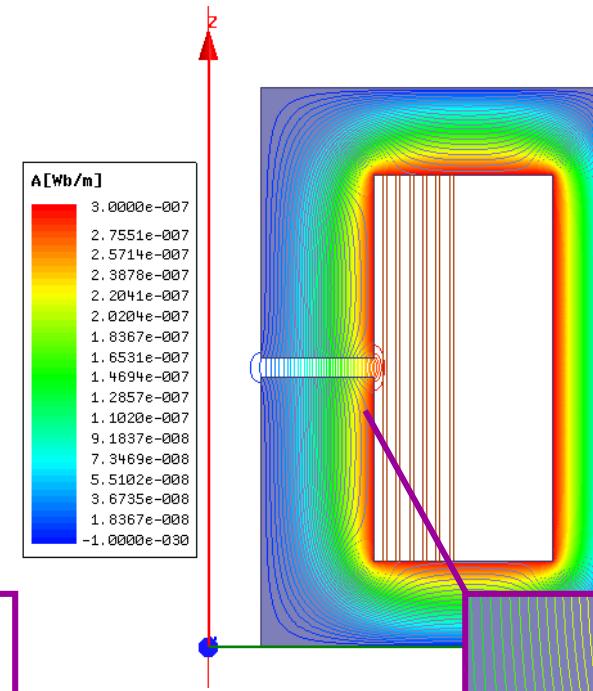


Fringing (Different Frequencies)

Magnetic Flux



Frequency 1kHz

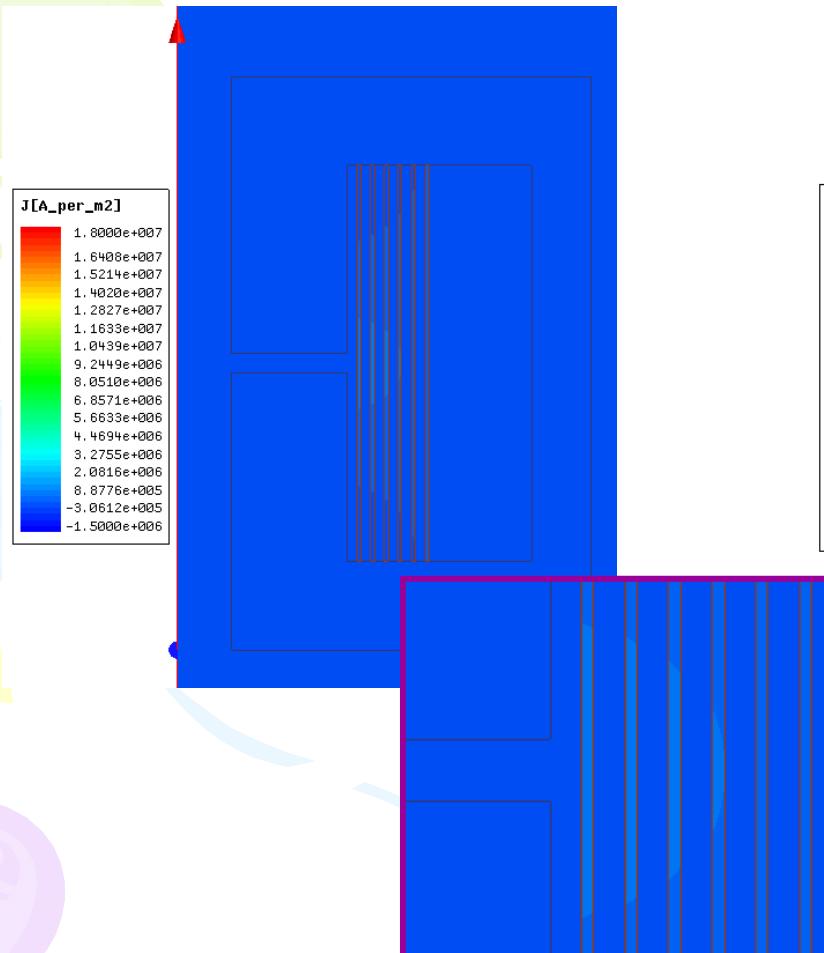


Frequency 100kHz

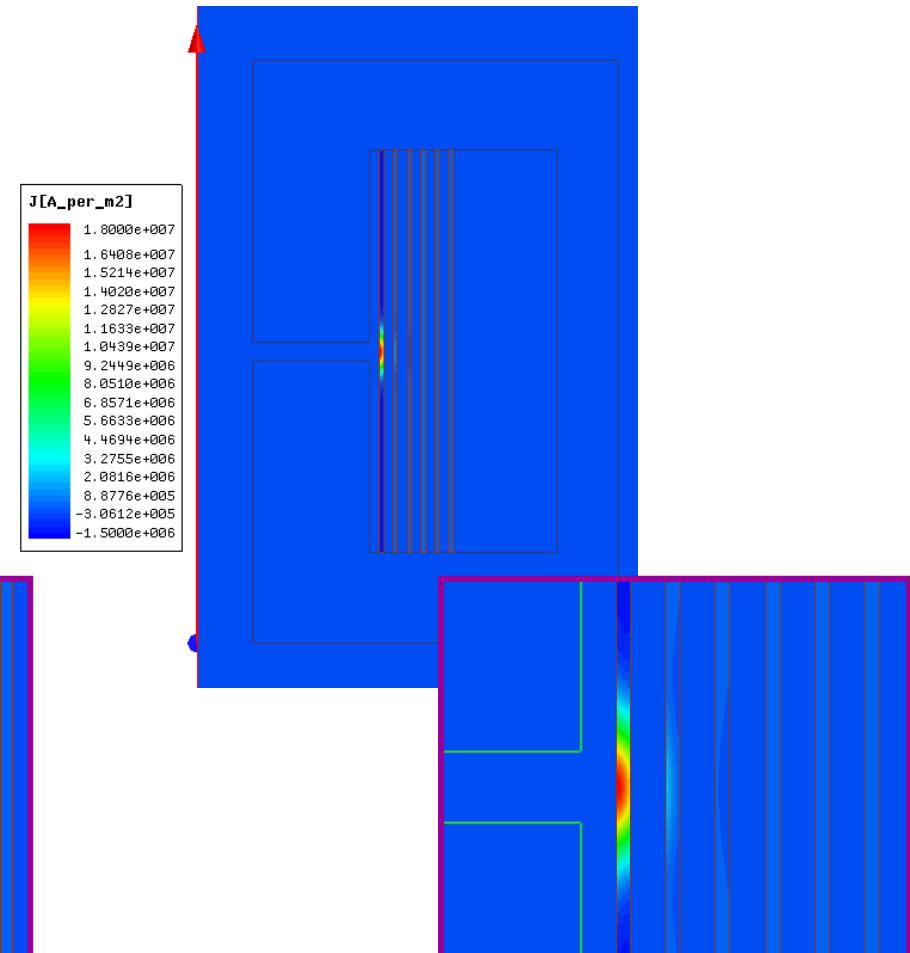


Fringing (Different Frequencies)

Current Density



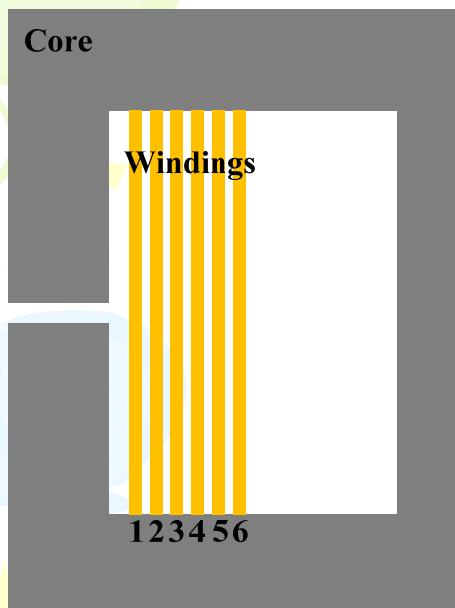
Frequency 1kHz



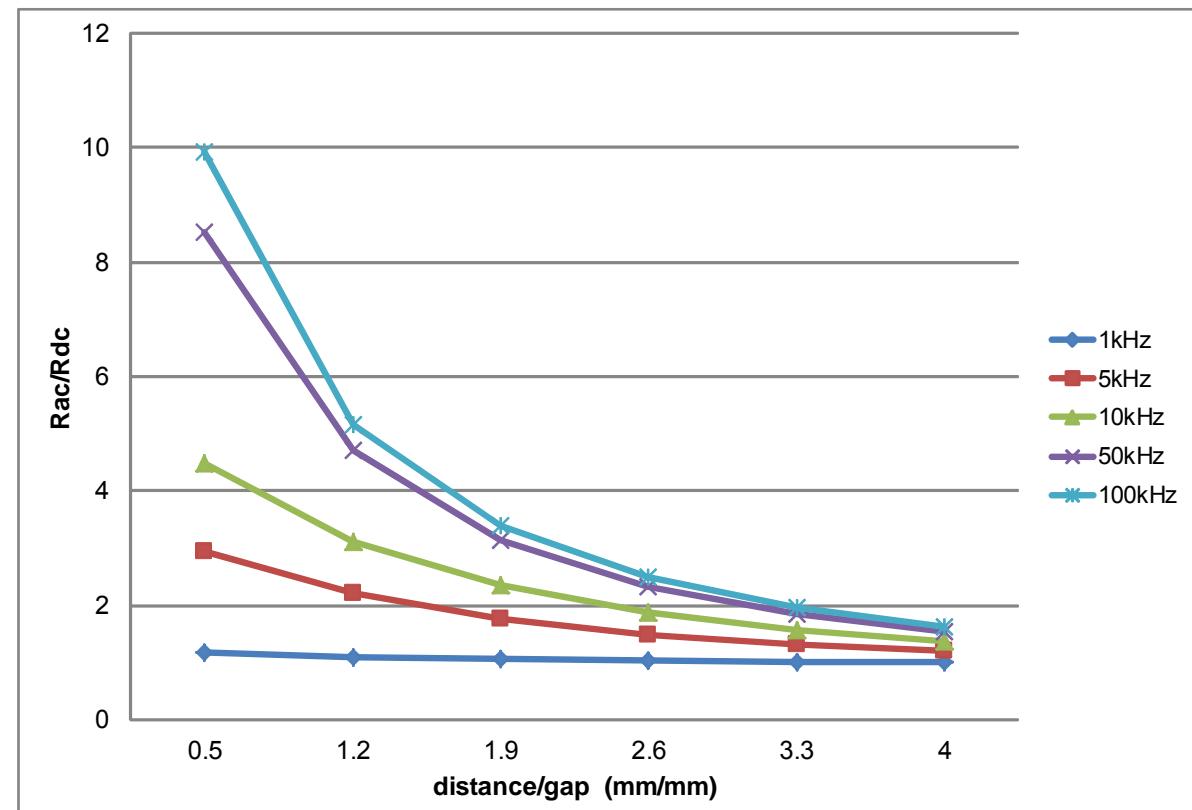
Frequency 100kHz



Winding Resistance related to the fringing effect, $g=1\text{mm}$



Distance 1: 0.5mm
 Distance 2: 1.2mm
 Distance 3: 1.9mm
 Distance 4: 2.6mm
 Distance 5: 3.3mm
 Distance 6: 4.0mm

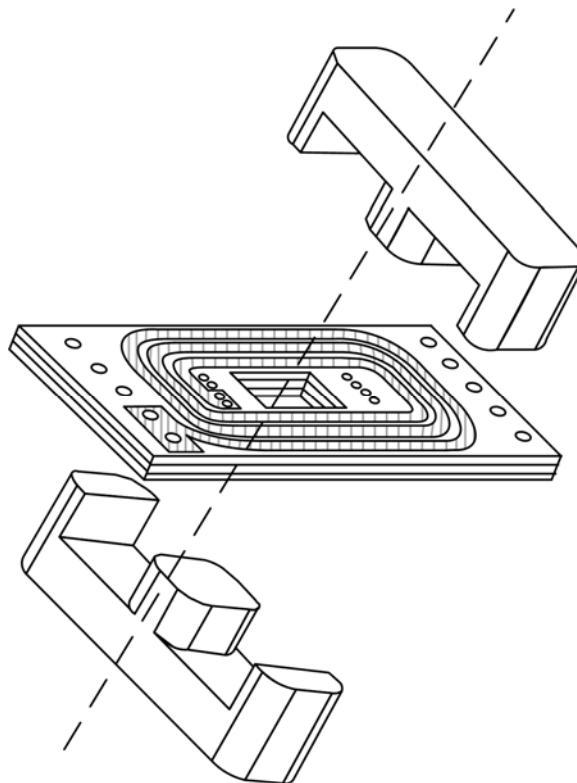
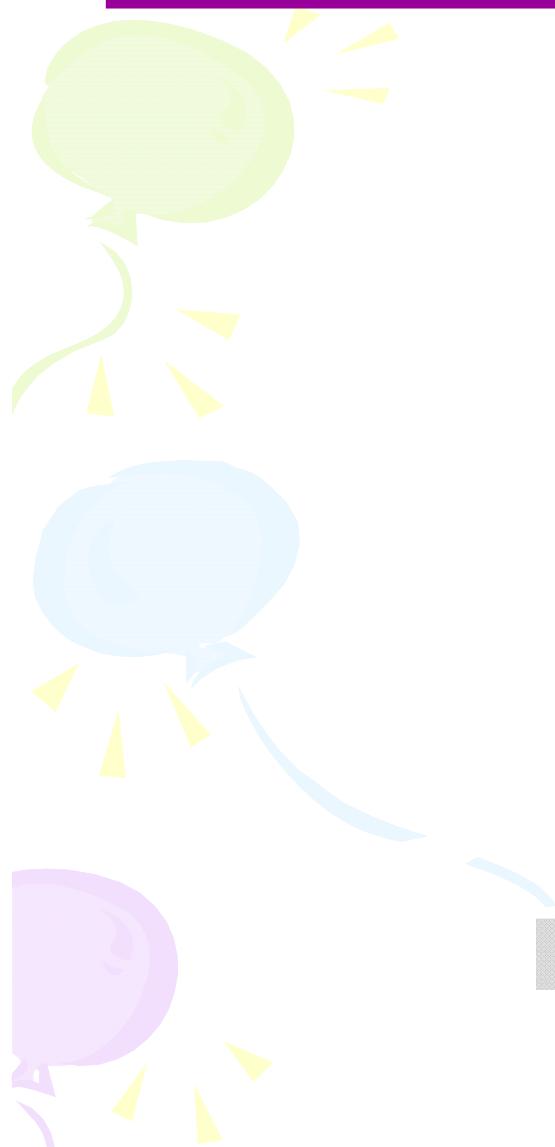




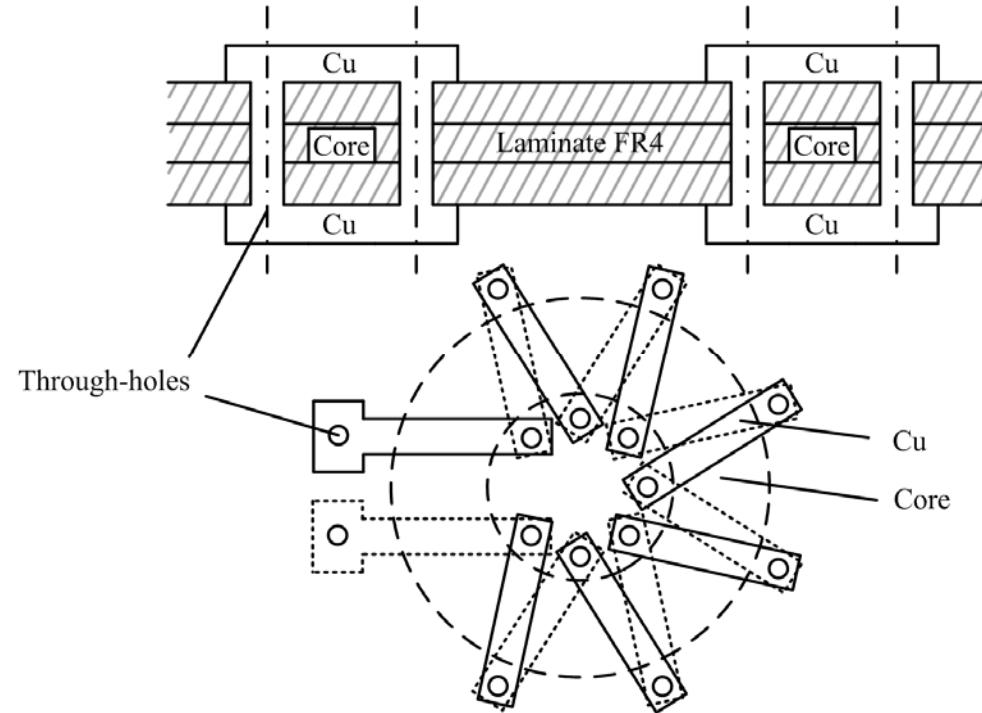
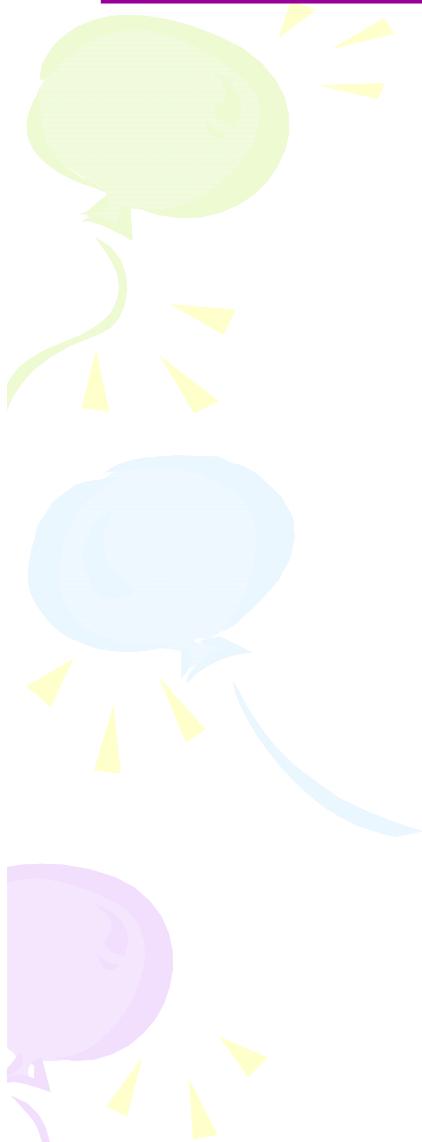
Analytical Models for Planar Magnetics

- ❑ **Low profile** — planar magnetic components has a lower profile than their wire wound counterparts due to the fabrication process;
- ❑ **Automation** — it is difficult to automate the winding of conventional inductors and transformers, the processes used in planar magnetics are based on advanced computer aided manufacturing techniques. Suitable for SMT
- ❑ **High power densities** — planar inductors and transformers are spread out and this gives them a bigger surface-to-volume ratio than conventional components, this enhances the thermal performance;
- ❑ **Predictable parasitics** — with planar magnetics, the windings are precise and consistent, yielding magnetic designs with highly controllable and predictable characteristic parameters.

- ❑ **Turns** — the number of turns in planar device tends to be limited by the manufacturing process;
- ❑ **Footprint** — larger footprint compared with its conventional counterpart;
- ❑ **Capacitance** — interlayer capacitance introduces resonance at high frequencies;
- ❑ **Trade-off** — between magnetic core area and winding window area; between the path length versus the mean length of a turn.

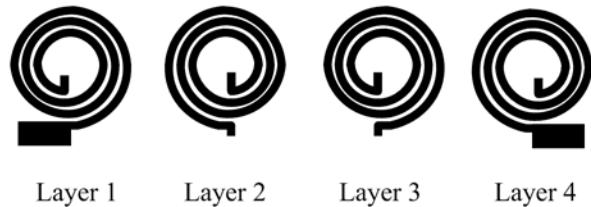


A typical planar transformer with an E-I core



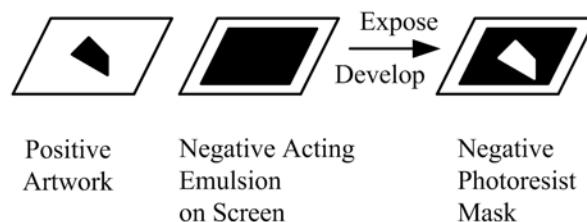
PCB integrated magnetic toroidal transformer

Thick Film Devices: Photoplots



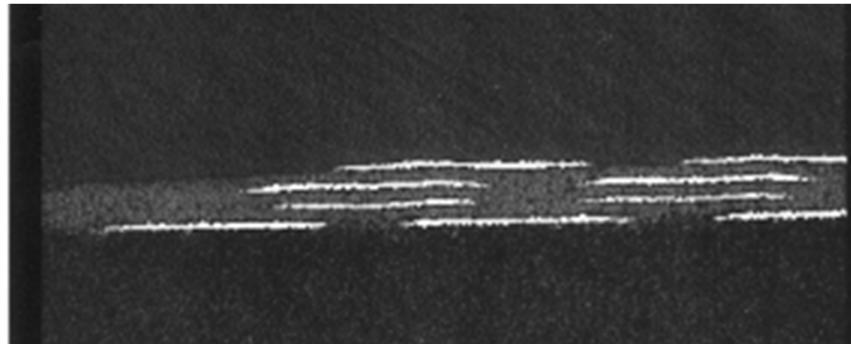
Photoplots of conducting layers

Masks for dielectric layers



Screen generation

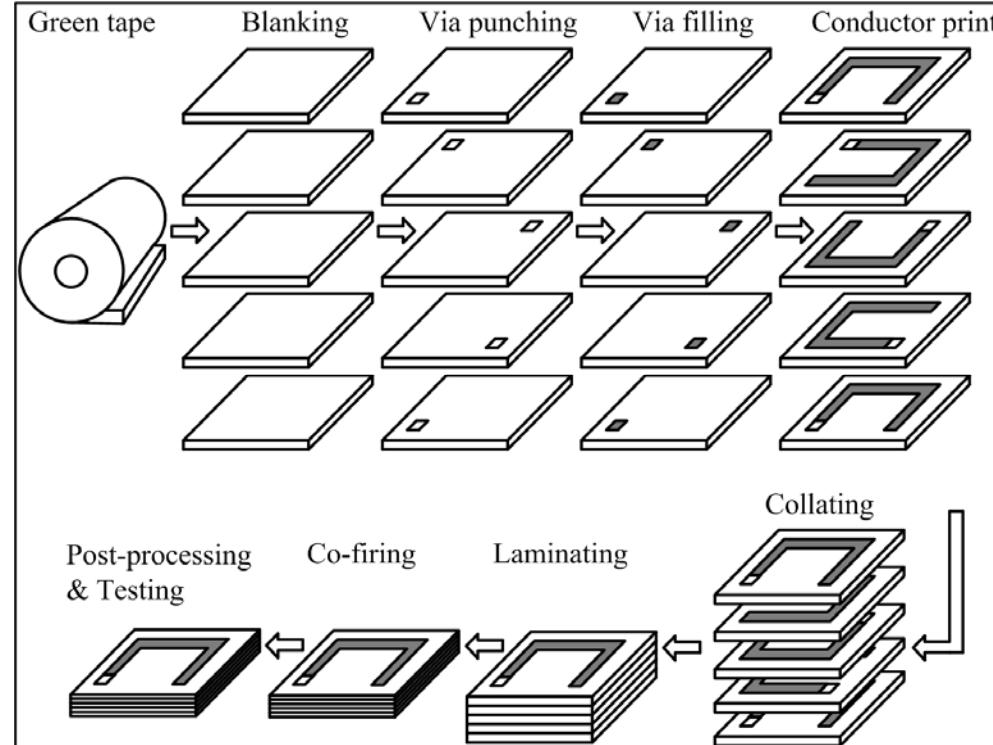
Thick Film Devices: Microsection



Optical photograph of a microsectioned device (scale 30:1) [1] Reproduced with permission from [1]. Copyright 1999 IEEE.

[1] W. G. Hurley, M. C. Duffy, S. O'Reilly, and S. C. O'Mathuna, 'Impedance formulas for planar magnetic structures with spiral windings,' IEEE Transactions on Industrial Electronics, vol. 46(2), pp. 271-278, 1999.

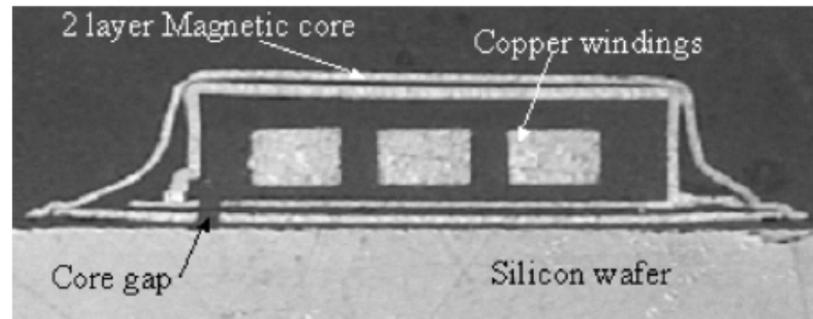
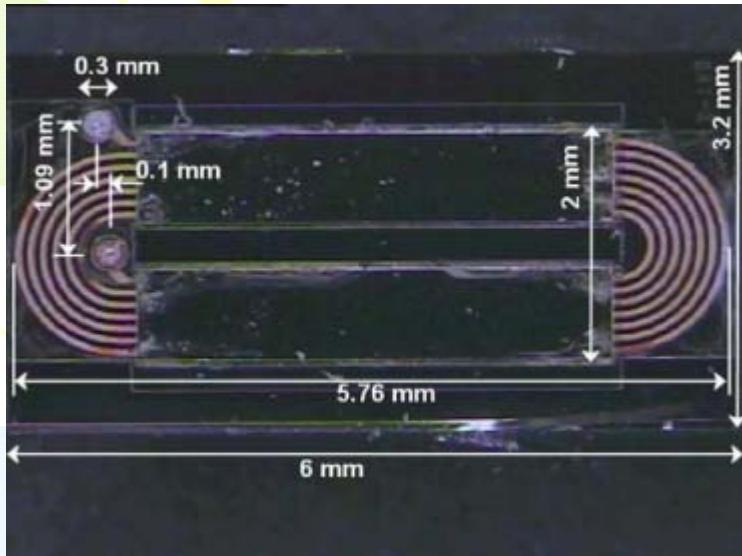
Low Temperature Co-fired Ceramics



LTCC Process flow



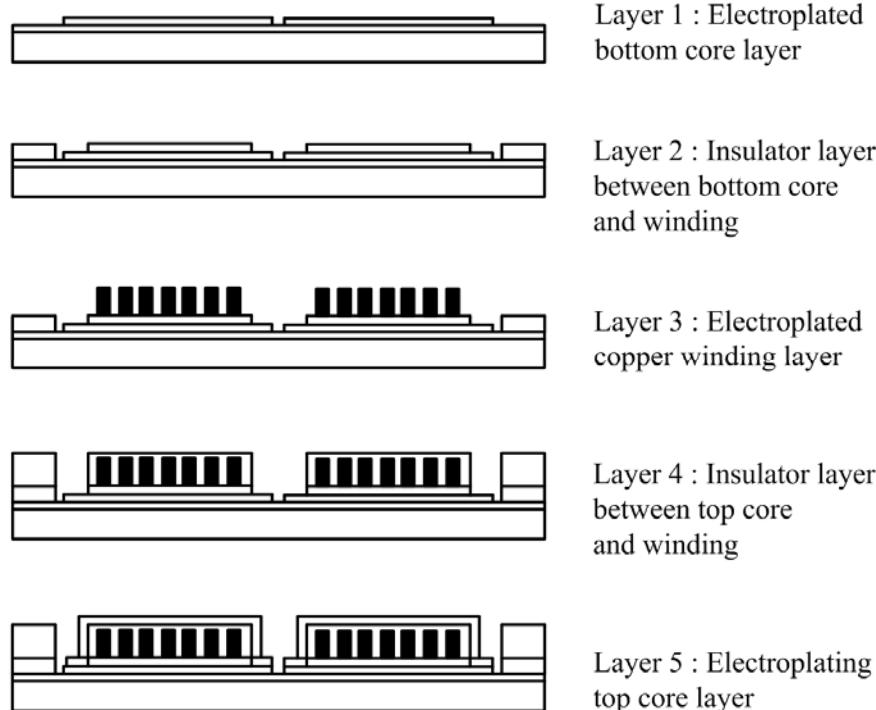
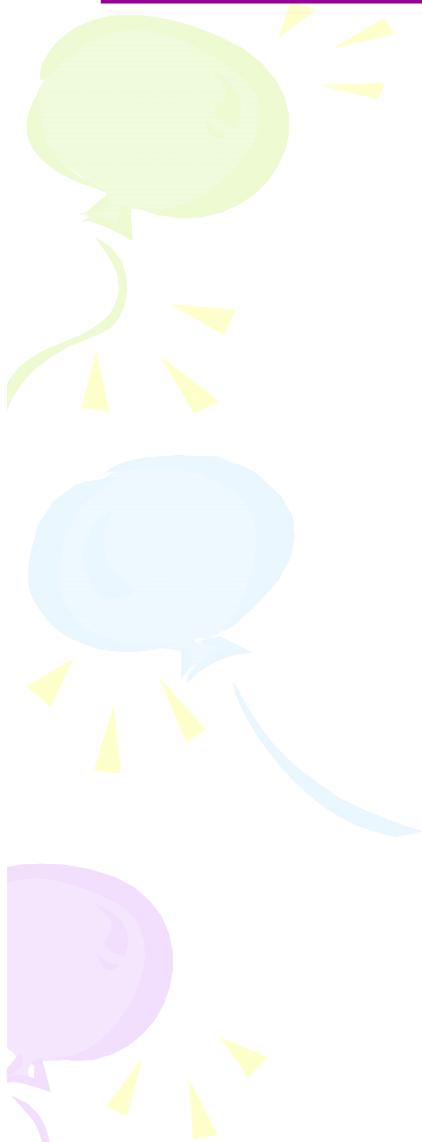
Silicon Integrated Microinductor



Silicon integrated microinductor: (a) Top view. Reproduced with permission from [1]. Copyright 2008 IEEE, (b) Cross-section. Reproduced with permission from [2]. Copyright 2005 IEEE

- [1] W. Ningning, T. O'Donnell, R. Meere, F. M. F. Rhen, S. Roy, and S. C. O'Mathuna, 'Thin-Film-Integrated Power Inductor on Si and Its Performance in an 8-MHz Buck Converter,' *IEEE Transactions on Magnetics*, vol. 44(11), pp. 4096-4099, 2008.
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Thin Film Devices: Microfabrication



Microfabrication process flow for an inductor

Technology Comparison

Technology	Frequency (Typical)	Power (Typical)	Inductance (Typical)	Size (Typical)
PCB magnetics	20 KHz ~ 2 MHz	1 W ~ 5 kW	10 μ H ~ 10 mH	100 mm ² ~ 100's cm ²
Thick Film	< 10 MHz	< 10 W	1 μ H ~ 1 mH	< 1 cm ²
LTCC	200 KHz ~ 10 MHz	< 10W	1 μ H ~ 1 mH	< 1cm ²
Thin Film	> 10 MHz	< 1W	10's ~ 100's nH	< 10mm ²

Advantages and Disadvantages

Technology	Integration method	Advantages	Disadvantage
PCB	Discrete core on laminated structure or integrated core in laminated structure Parallel or sequential process	Low cost Multilayer structure Thick copper High current High inductance	Low resolution (line width 100µm) Relatively low frequency
Thick Film	Screen printed on sintered ceramic Sequential build up of multiple layers	Low cost	Difficult to form Long process time and low yield due to sequential build-up
LTCC	Screen printed on green tapes Parallel multilayer and final cofired structure	Parallel layer process High layer counts Module reliability	Cofireability of materials
Thin Film	Sequential build up of lithographically defined layers	Precision value (line width 5µm) High tolerance High component density High frequency	Low inductance Equipment costly Limited selection on film materials/ material compatibility



Planar Transformer

Planar Core ER41



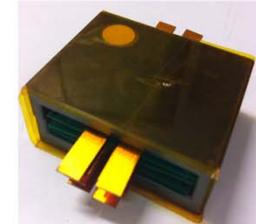
Primary PCB Windings



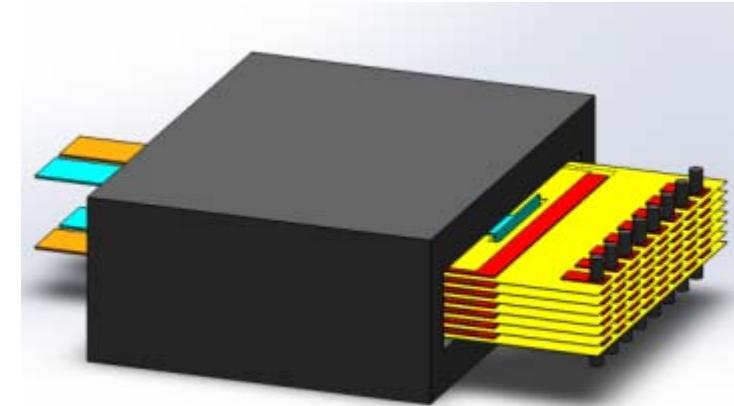
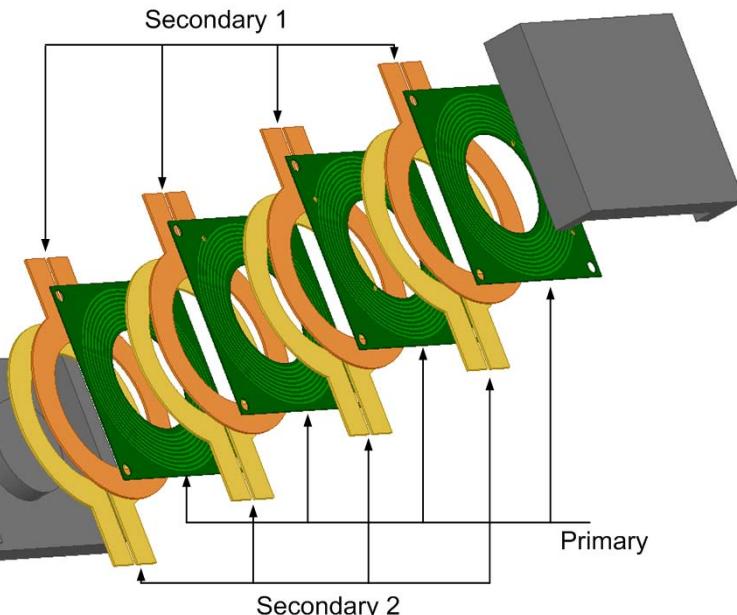
Secondary Foil Windings

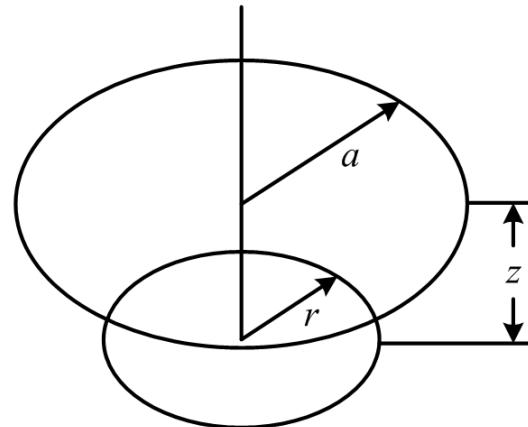
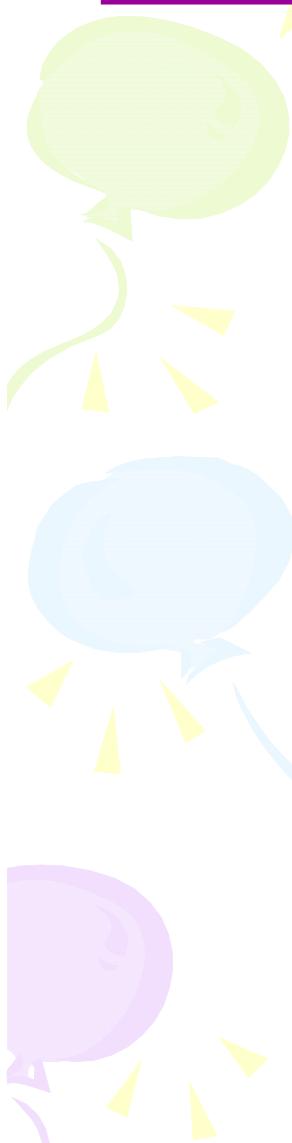


Planar Transformer



Secondary 1





Circular concentric filaments in air

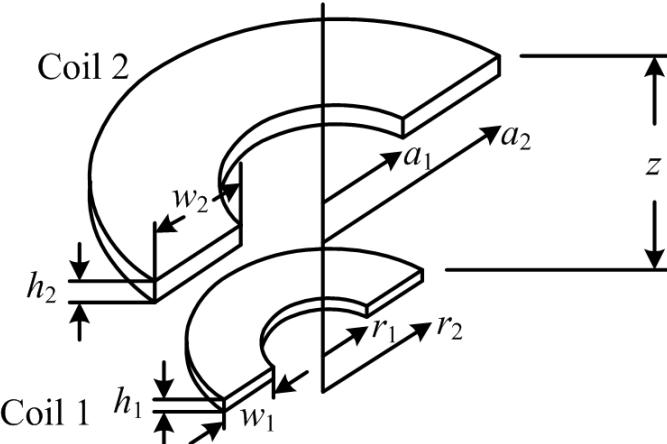
$$M = \mu_0 \sqrt{ar} \frac{2}{f} \left[\left(1 - \frac{f^2}{2}\right) K(f) - E(f) \right]$$

$$f = \sqrt{\frac{4ar}{z^2 + (a+r)^2}}$$

$K(f)$: complete elliptic integrals of the first kind

$E(f)$: complete elliptic integrals of the second kind

Mutual Inductance of Planar Coils



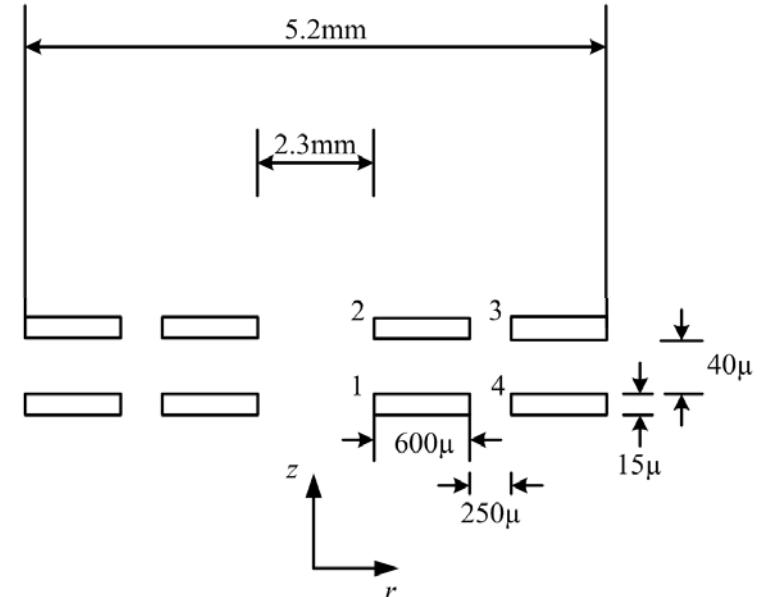
Planar coils of rectangular cross-section

$$M_{12} = \frac{\mu_0 \pi}{h_1 h_2 \ln\left(\frac{r_2}{r_1}\right) \ln\left(\frac{a_2}{a_1}\right)} \int_0^\infty S(kr_2, kr_1) S(ka_2, ka_1) Q(kh_1, kh_2) e^{-k|z|} dk$$

$$S(kx, ky) = \frac{J_0(kx) - J_0(ky)}{k}$$

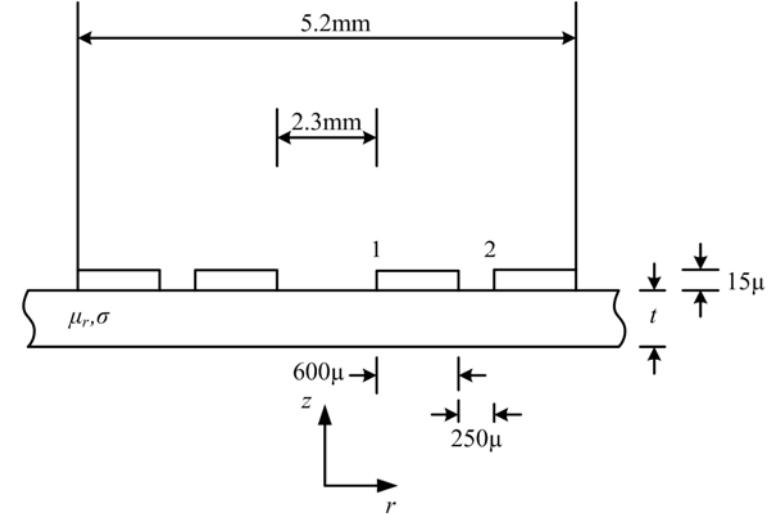
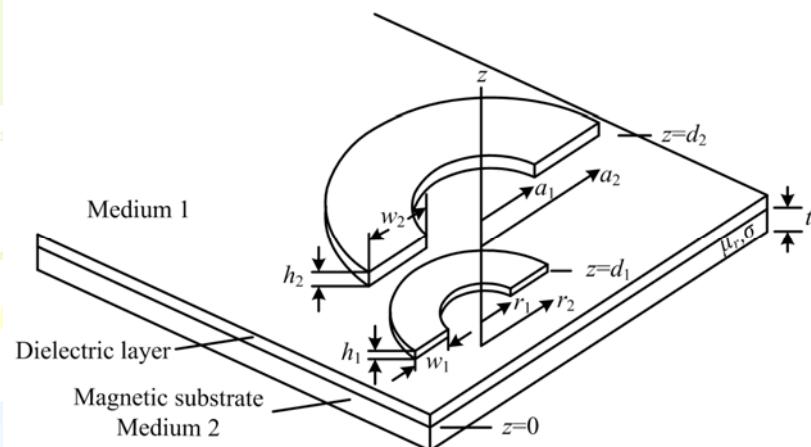
Solve with MATLAB

$$\begin{aligned} Q(kx, ky) &= \frac{2}{k^2} \left[\cosh k \frac{x+y}{2} - \cosh k \frac{x-y}{2} \right] \quad z > \frac{h_1 + h_2}{2} \\ &= \frac{2}{k} \left(h + \frac{e^{-kh} - 1}{k} \right) \quad z = 0, x = y = h \end{aligned}$$



[1] W G Hurley, M C Duffy, J Zhang, I Lope, B Kunz, W H Wölfle, , “A Unified Approach to the Calculation of Self and Mutual Inductance for Coaxial Coils in Air”, IEEE Trans. on Power Electronics, vol. 30, no.11, pp. 6155–6162, November 2015.

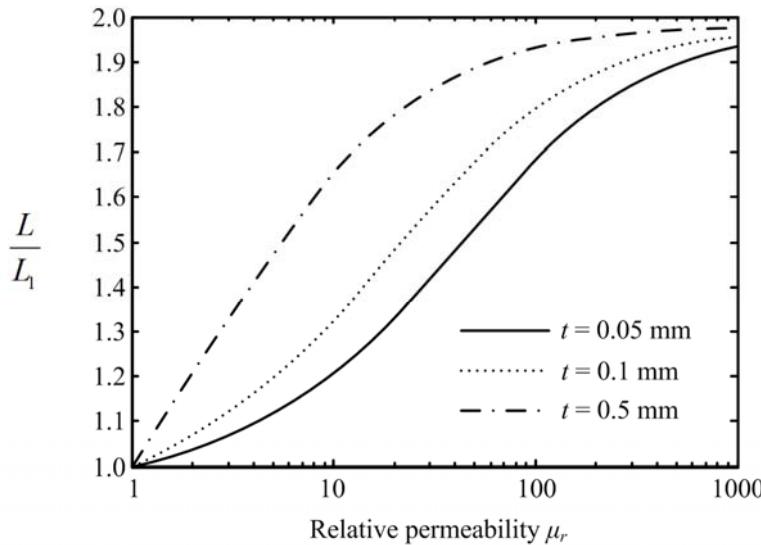
Add a Magnetic Substrate



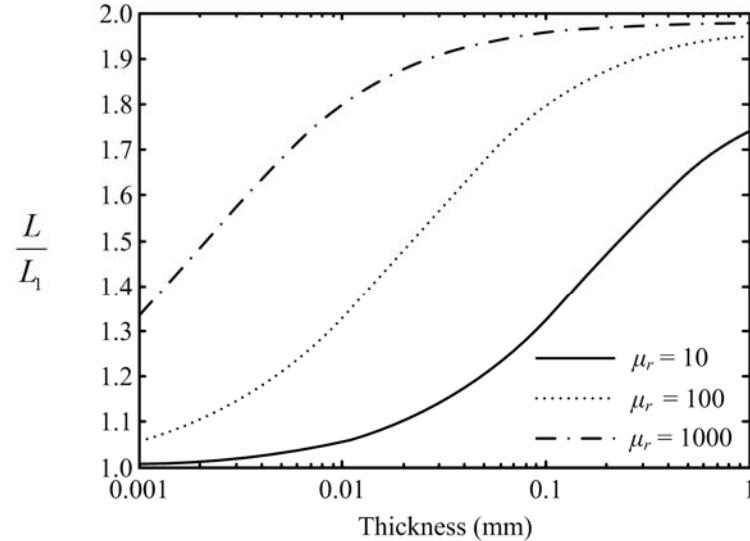
Planar coils on a magnetic substrate

$$Z_t^p = \frac{j\omega\mu_0\pi}{h_1 h_2 \ln(\frac{r_2}{r_1}) \ln(\frac{a_2}{a_1})} \int_0^\infty S(kr_2, kr_1) S(ka_2, ka_1) Q(kh_1, kh_2) \lambda(t) e^{-k(d_1+d_2)} dk$$

Effect of Permeability and Thickness

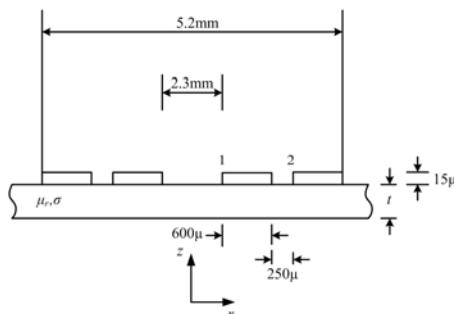


(a)

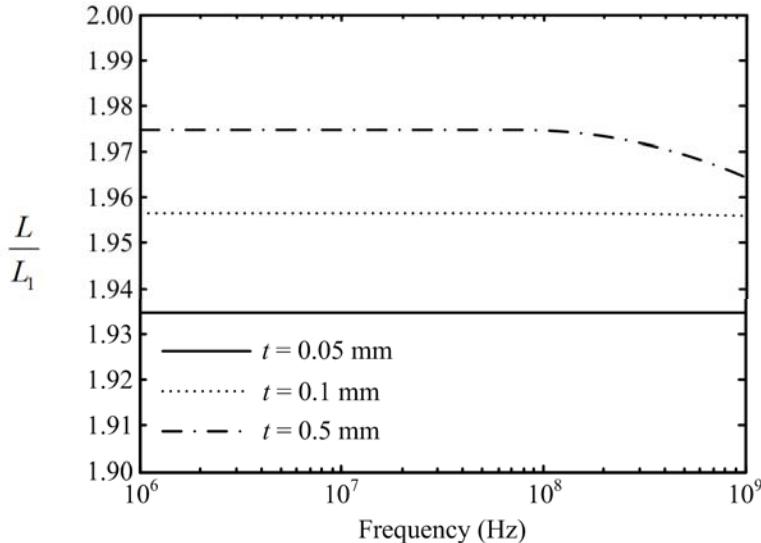


(b)

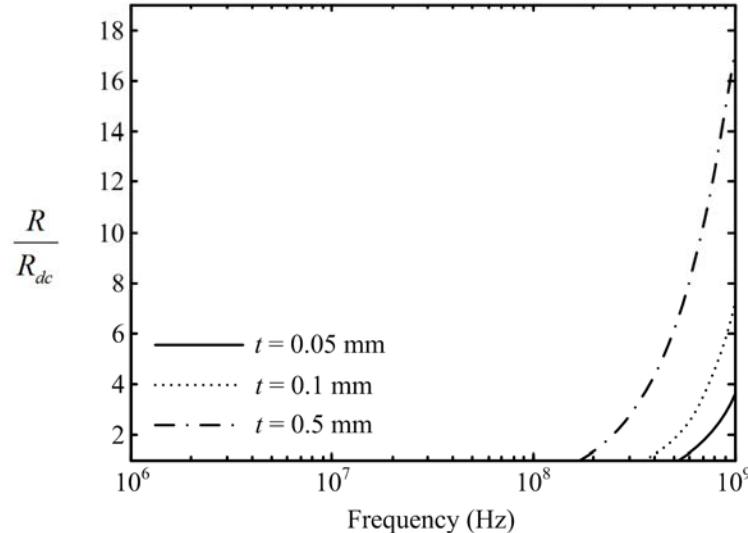
Enhancement of inductance with magnetic substrate: (a) as a function of μ_r , (b) as a function of t .



Effect of Frequency



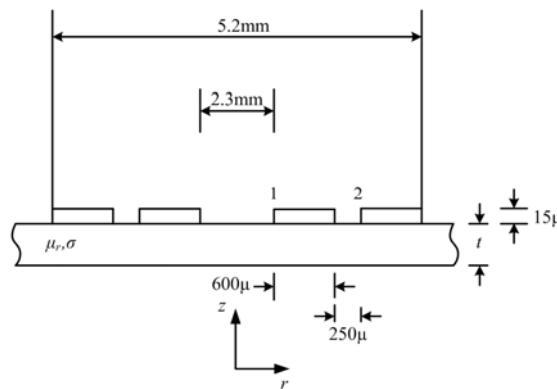
(a)



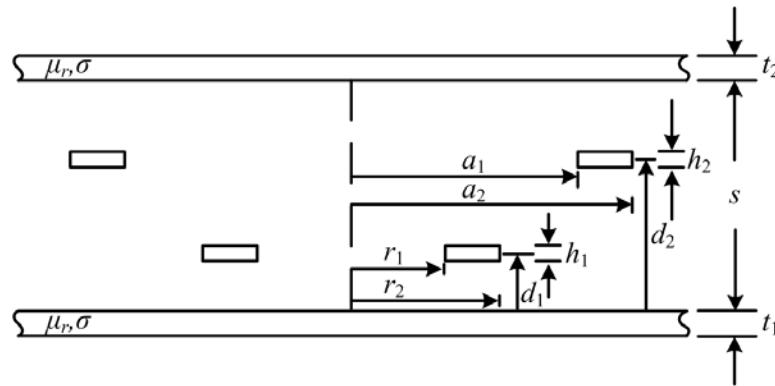
(b)

Self impedance of a planar coil on a finite substrate: (a) inductance, (b) resistance.

$$g(\lambda) = \frac{2\lambda(t_1)\lambda(t_2)e^{-2ks} \cosh[k(d_2 - d_1)]}{1 - \lambda(t_1)\lambda(t_2)e^{-2ks}}$$



Sandwich Structure



Planar coils in a sandwich structure

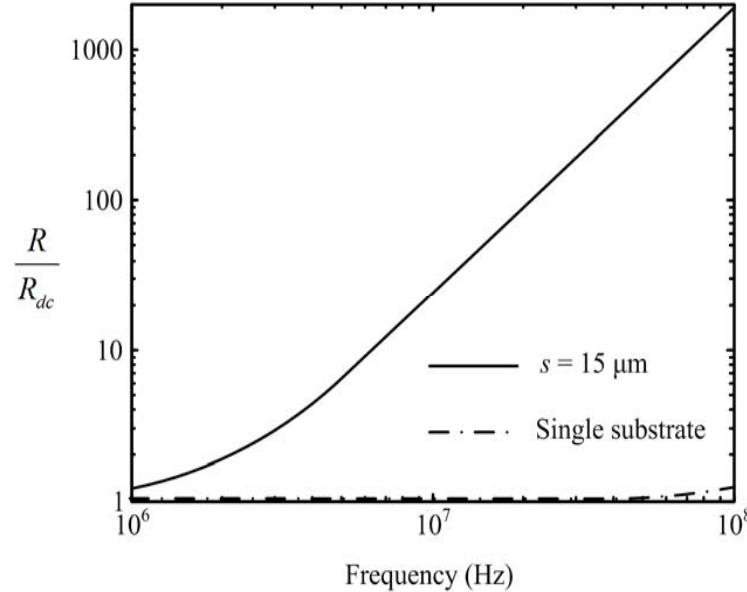
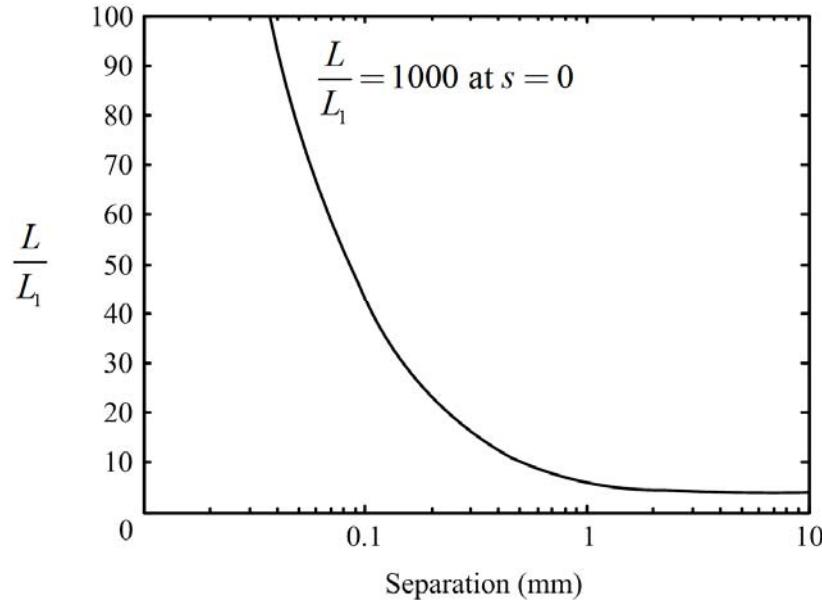
$$Z_{s\omega}^p = \frac{j\omega\mu_0\pi}{h_1 h_2 \ln(\frac{r_2}{r_1}) \ln(\frac{a_2}{a_1})} \int_0^\infty S(kr_2, kr_1) S(ka_2, ka_1) [f(\lambda) + g(\lambda)] Q(kh_1, kh_2) dk$$

$$f(\lambda) = \frac{\lambda(t_1)e^{-k(d_1+d_2)} + \lambda(t_2)e^{-k(d_1'+d_2')}}{1 - \lambda(t_1)\lambda(t_2)e^{-2ks}}$$

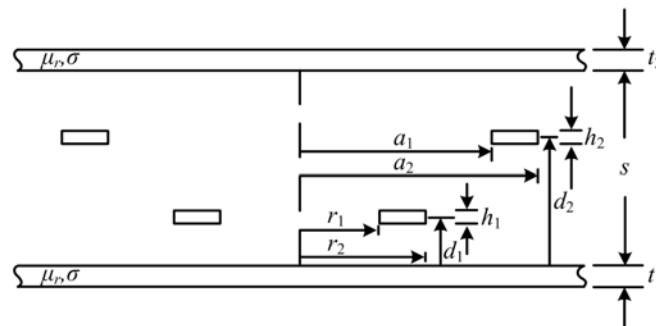
$$g(\lambda) = \frac{2\lambda(t_1)\lambda(t_2)e^{-2ks} \cosh[k(d_2-d_1)]}{1 - \lambda(t_1)\lambda(t_2)e^{-2ks}}$$



Separation and Frequency



Inductance as a function of substrate separation; $L_1=17.14\text{nH}$.



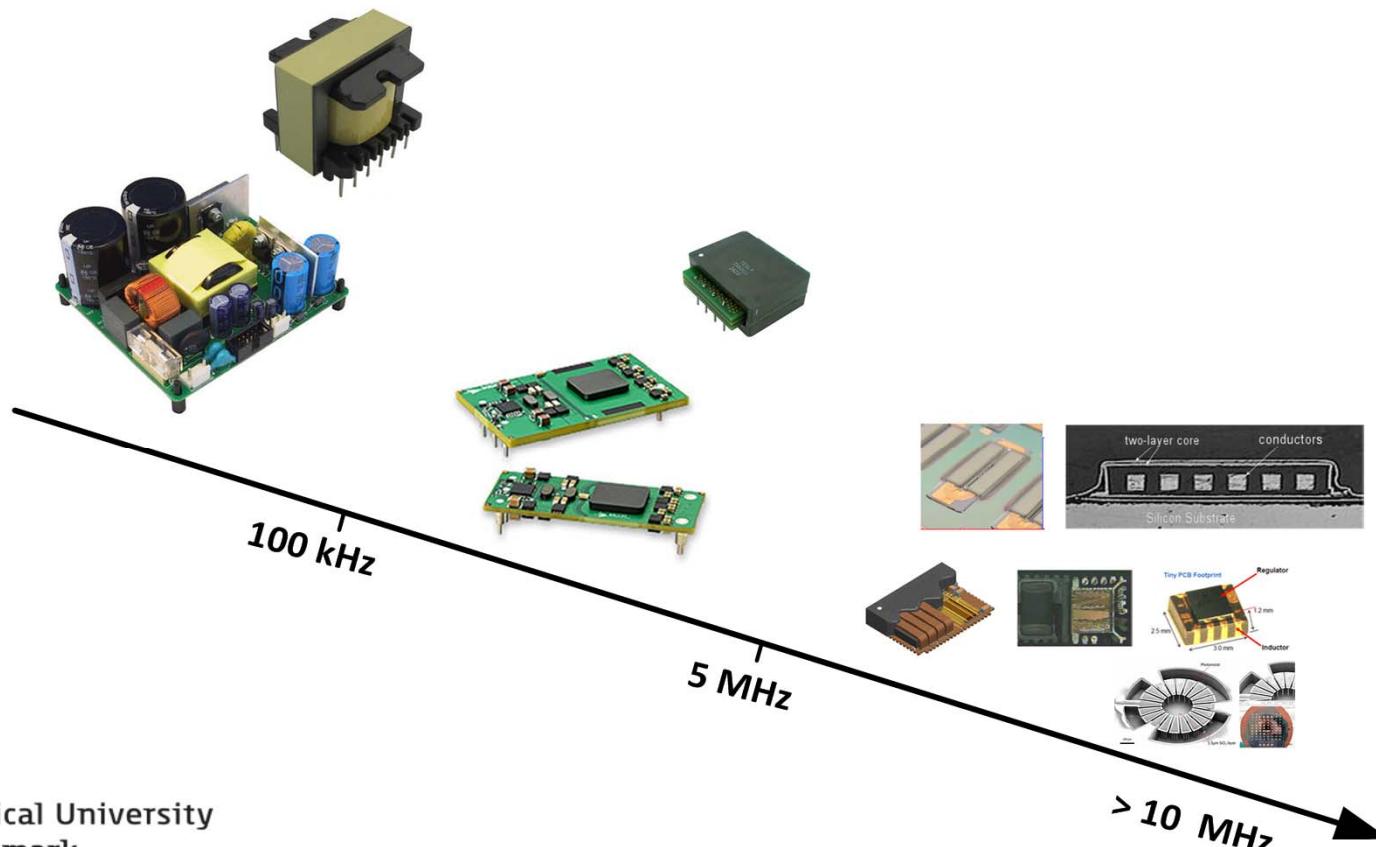
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- [10] F. Judd and D. Kressler, 'Design optimization of small low-frequency power transformers,' *IEEE Transactions on Magnetics*, vol. 13(4), pp. 1058-1069, 1977.
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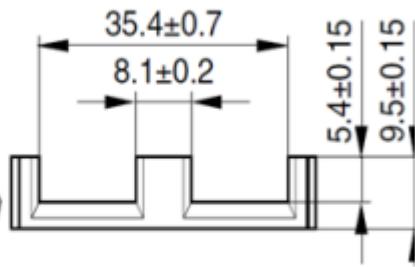
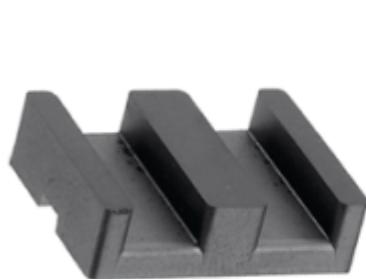


Planar Magnetics – Fundamentals

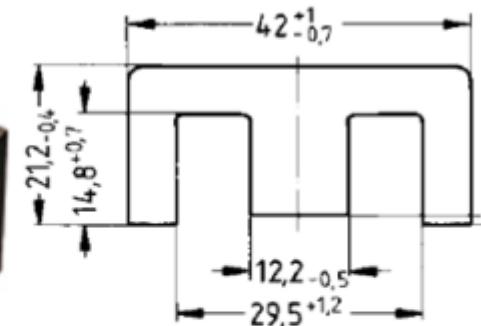
With rapidly increased frequencies, magnetics become **VERY important** factor to achieve high-efficiency and high-power-density converter.



- ❖ **Low profile:** the height of a planar magnetic core is typically 25% to 50% the height of its wire-wound counterpart.

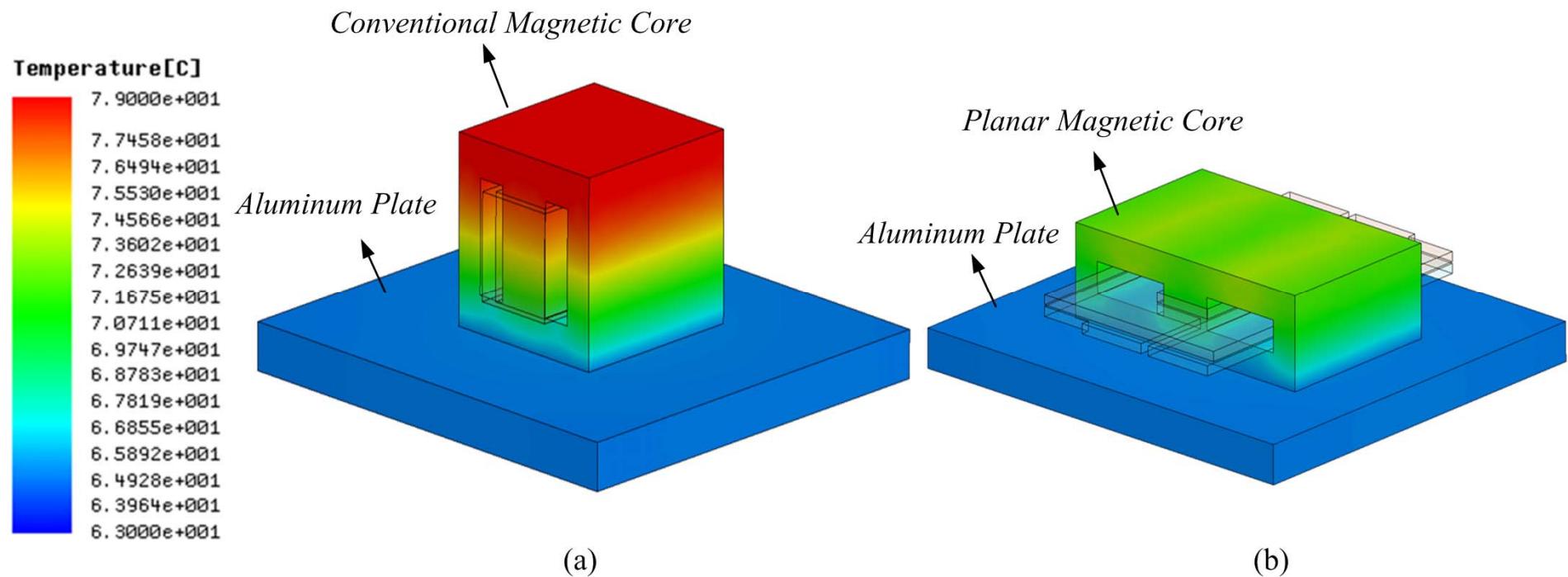
ELP 43/10/28

$$\begin{aligned}A_e &= 229 \text{ mm}^2 \\A_{\min} &= 225 \text{ mm}^2 \\V_e &= 14000 \text{ mm}^3\end{aligned}$$

E 42/21/20

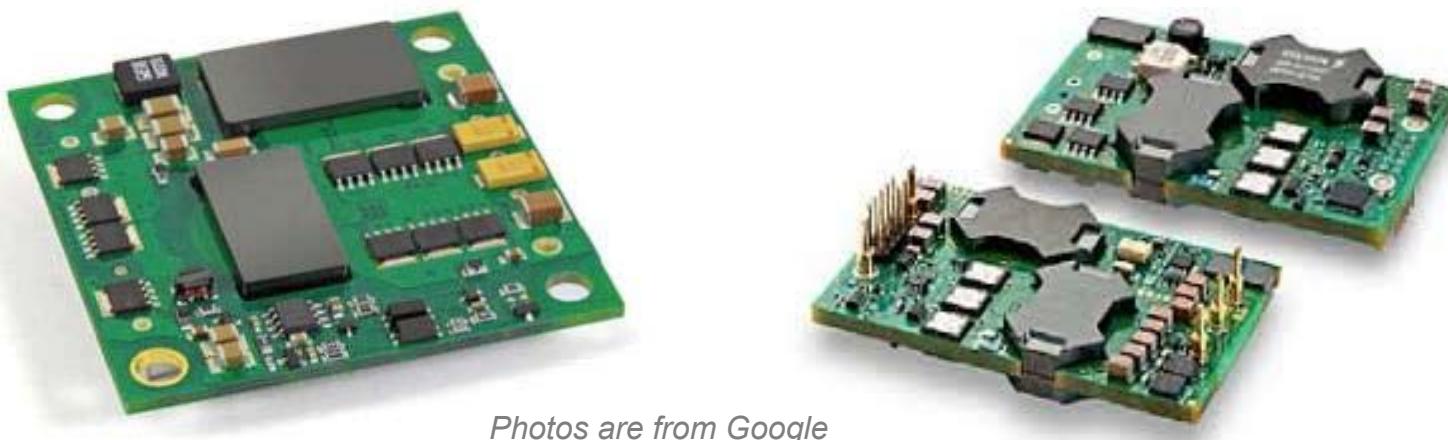
$$\begin{aligned}A_e &= 234 \text{ mm}^2 \\A_{\min} &= 229 \text{ mm}^2 \\V_e &= 22700 \text{ mm}^3\end{aligned}$$

- ❖ **Good thermal characteristic:** planar cores essentially have a higher surface area to volume ratio than conventional magnetic cores.



- ❖ **Ease of manufacturability and cost reduction:** automation process and computer aided.

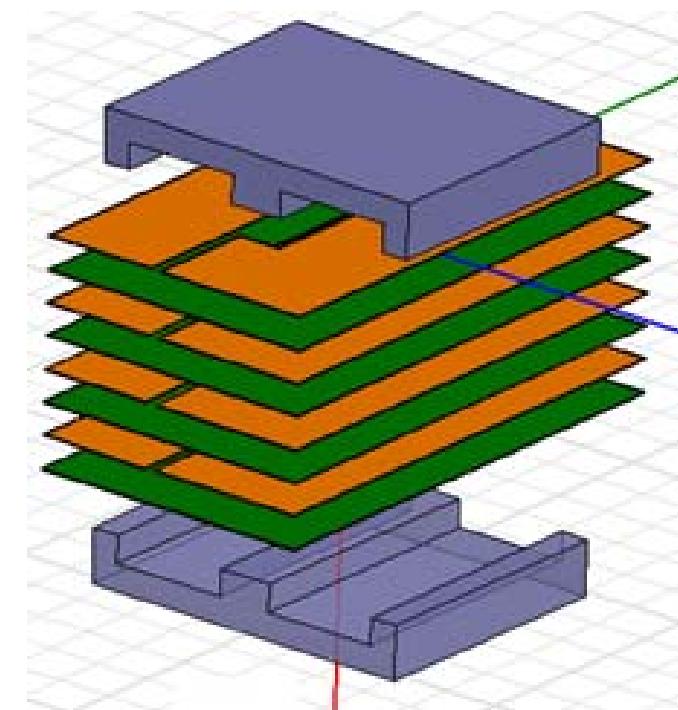
- ❖ **Modularity:** no extra connections are required

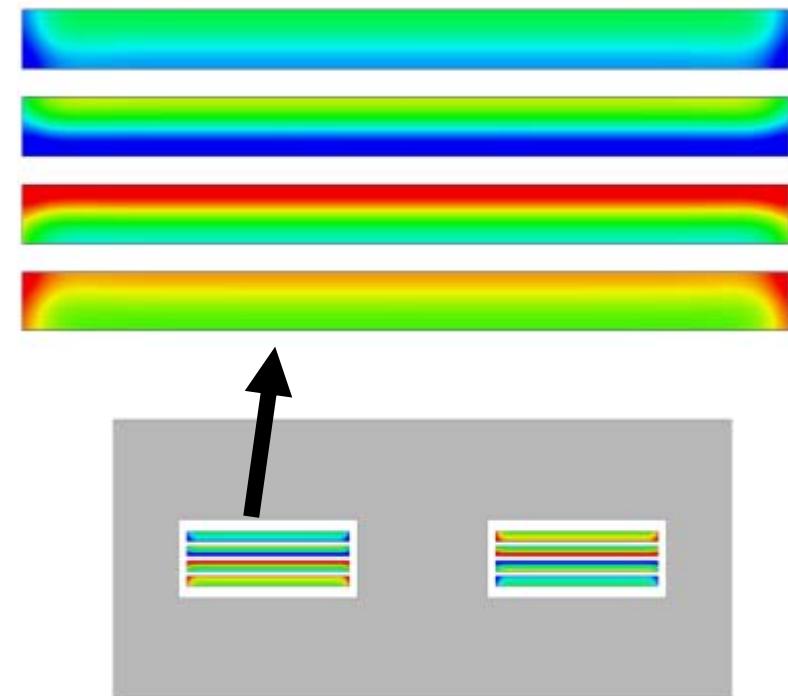
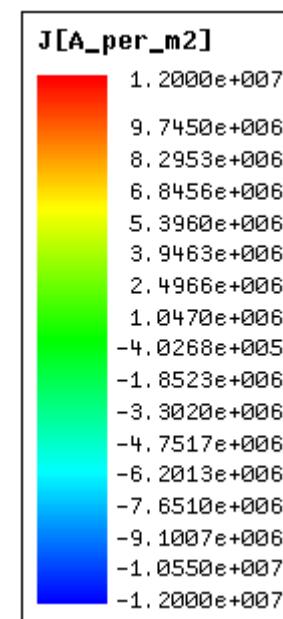
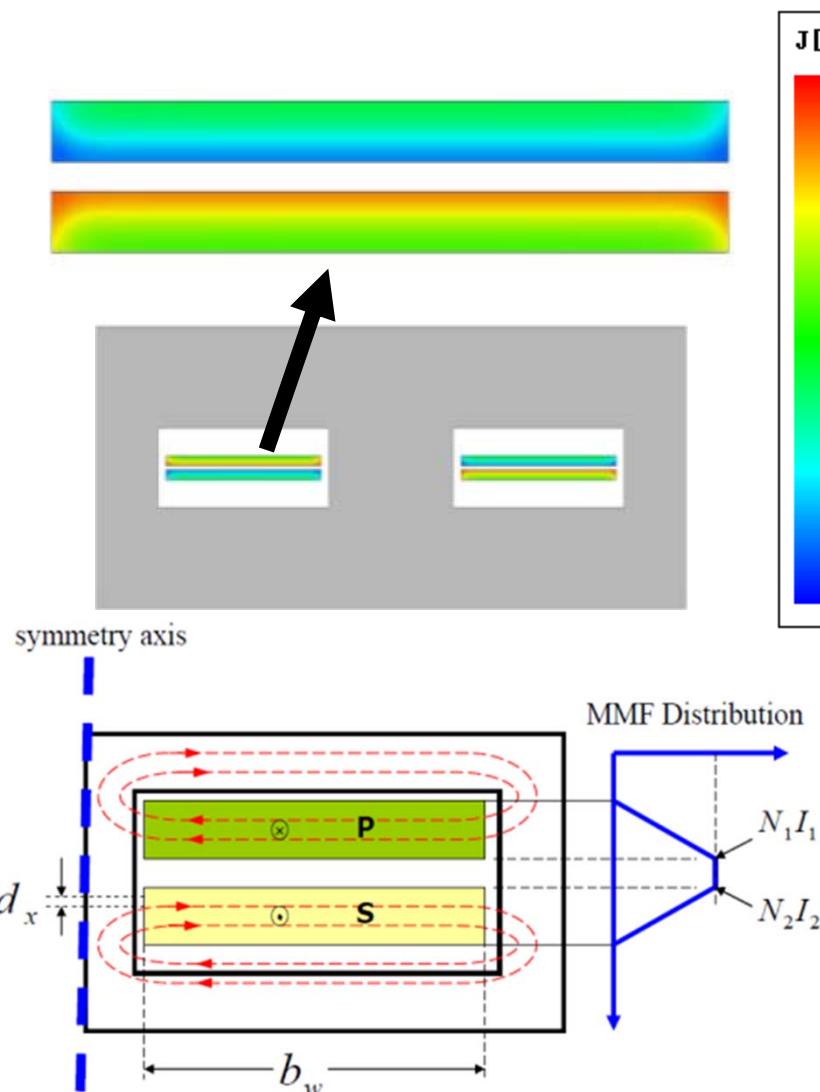


Photos are from Google

- ❖ **Predictable parasitics:** windings manufactured by PCB machines are more precise and consistent, resulting in magnetic designs with highly controllable and predictable parasitic parameters

- ❖ **Ease of implementation on interleaved windings:** multi-layer PCBs allow for interconnection between arbitrary layers.





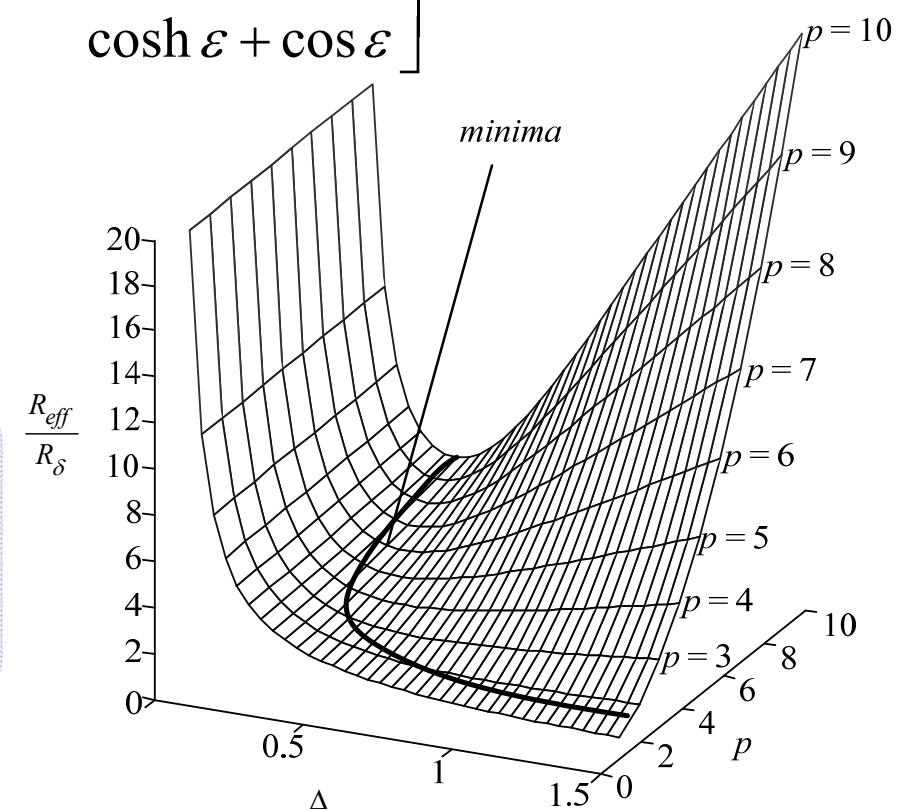
In typical planar transformers, most of external flux (leakage flux) is parallel to the surface of the conductors

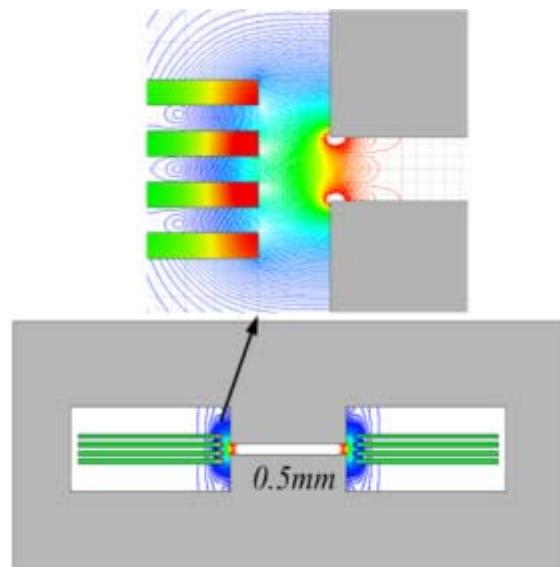
Modelling ac resistance in planar transformer is the same with traditional one-dimensional Dowell's analysis:

$$\frac{R_{ac}}{R_{dc}} = \varepsilon \left[\frac{\sinh 2\varepsilon + \sin 2\varepsilon}{\cosh 2\varepsilon - \cos 2\varepsilon} + \frac{2(p^2 - 1)}{3} \frac{\sinh \varepsilon - \sin \varepsilon}{\cosh \varepsilon + \cos \varepsilon} \right]$$

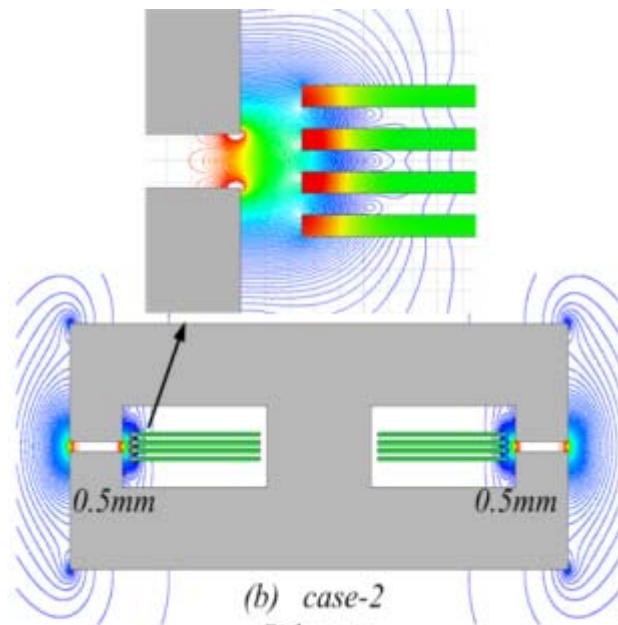
where ε is the ratio of the conductor thickness to the skin depth. p is the number of layers

Note: “**radial current distribution**” in planar structures may affect the dc resistance, but no effect on the ratio of ac resistance to dc resistance.

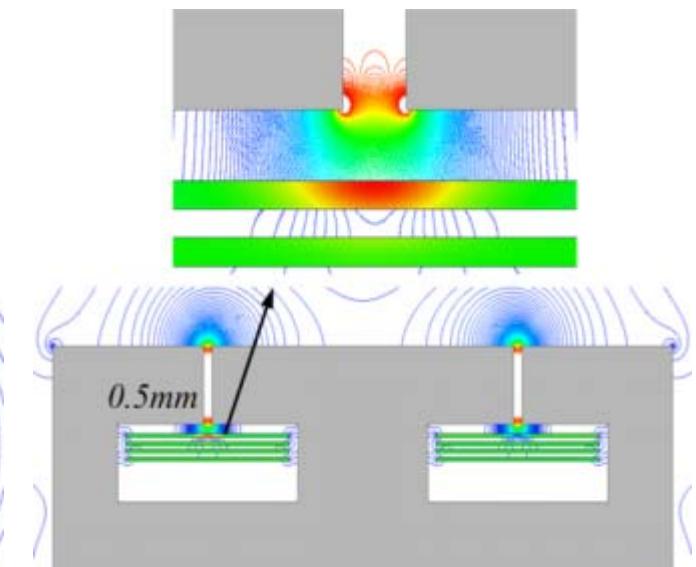




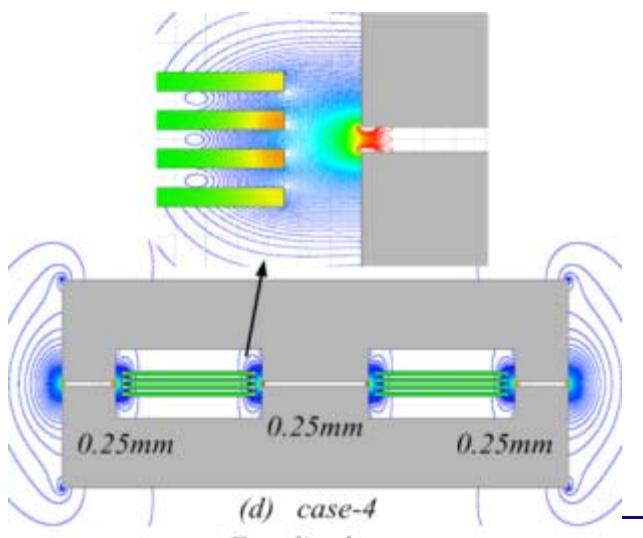
(a) case-1
Center gap



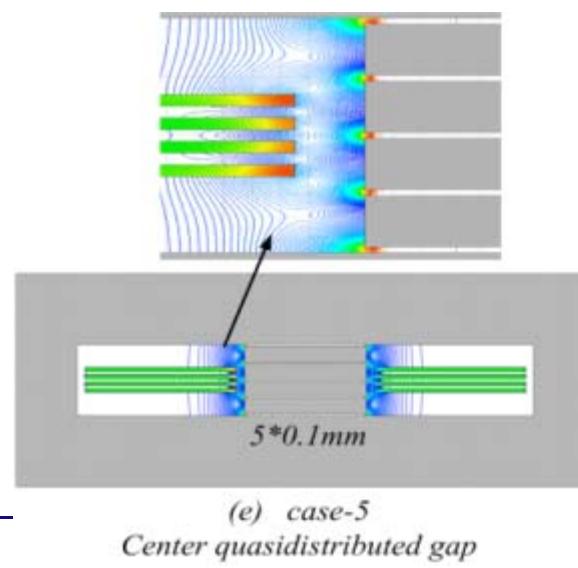
(b) case-2
Side gap



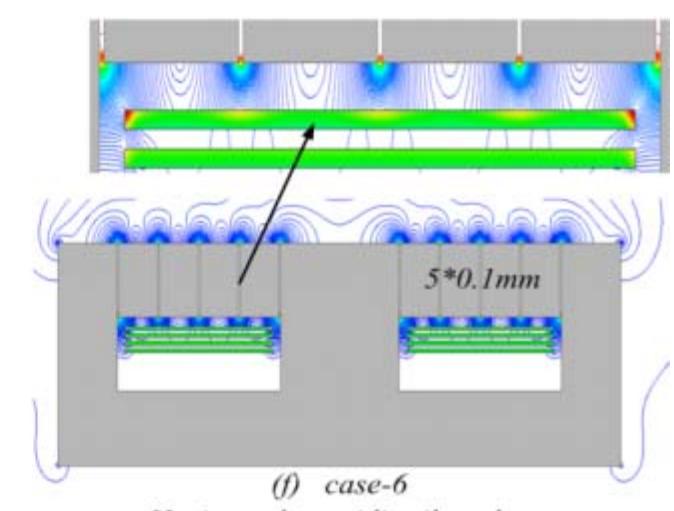
(c) case-3
Horizontal gap



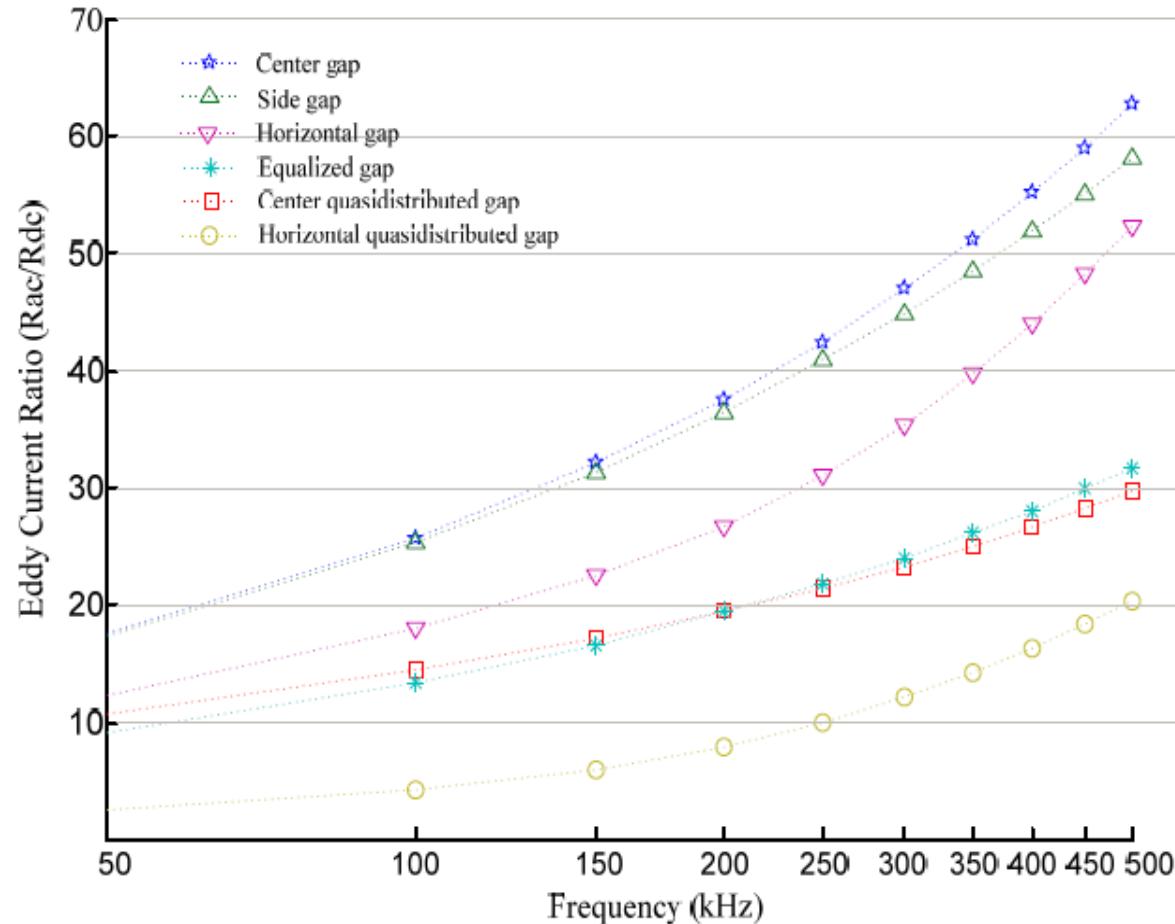
(d) case-4
Equalized gap



(e) case-5
Center quasidistributed gap

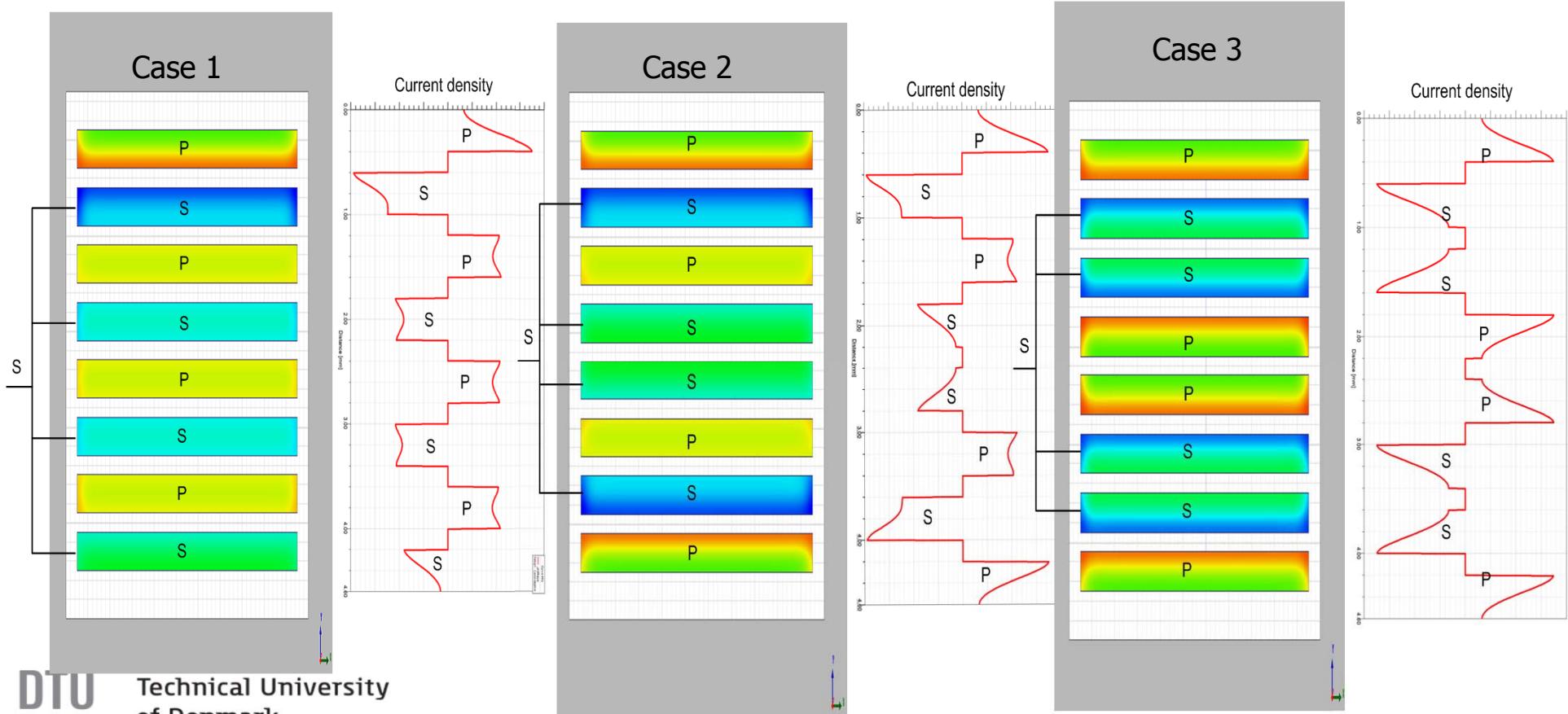


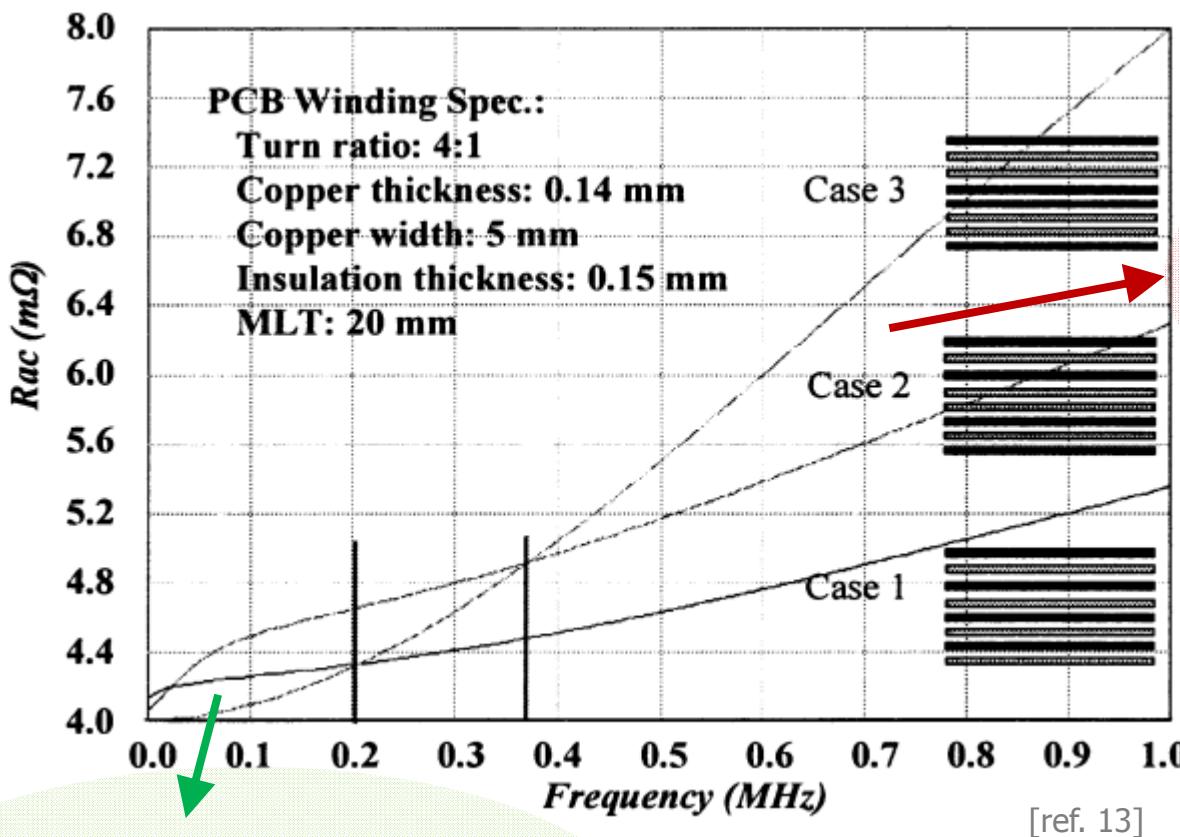
(f) case-6
Horizontal quasidistributed gap



	Fringing effect on winding loss	Fringing effect on external magnetic field
Case 1: Center gap	Highest	Low
Case 2: Side gap	High	High
Case 3: Horizontal gap	Medium	High
Case 4: Equalized gap	Low	Medium
Case 5: Center quasi-distributed gap	Low	Low
Case 6: Horizontal quasi-distributed gap	Lowest	Medium

- ❖ High current applications
- ❖ Currents may not be equally distributed in the paralleled winding layers



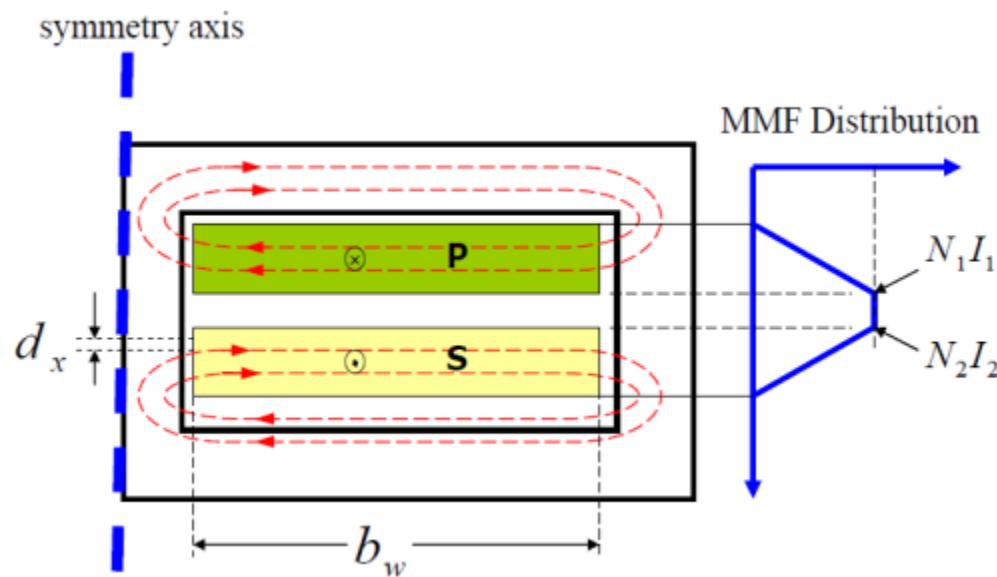


At high frequency,
eddy current effect
losses dominate.

At low frequency, "parallel
effect losses" or "circulating
currents losses" dominates

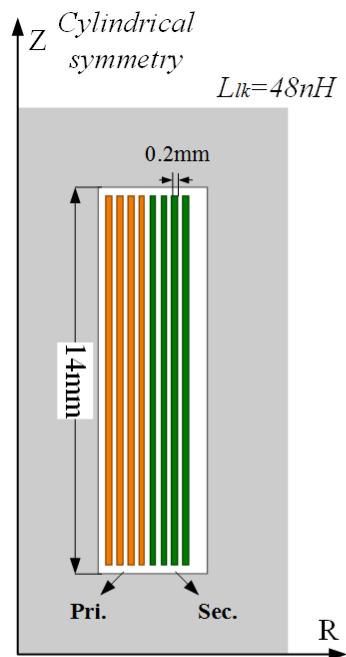
[ref. 13]

Leakage inductance is simply dependent on the energy stored in core window area:

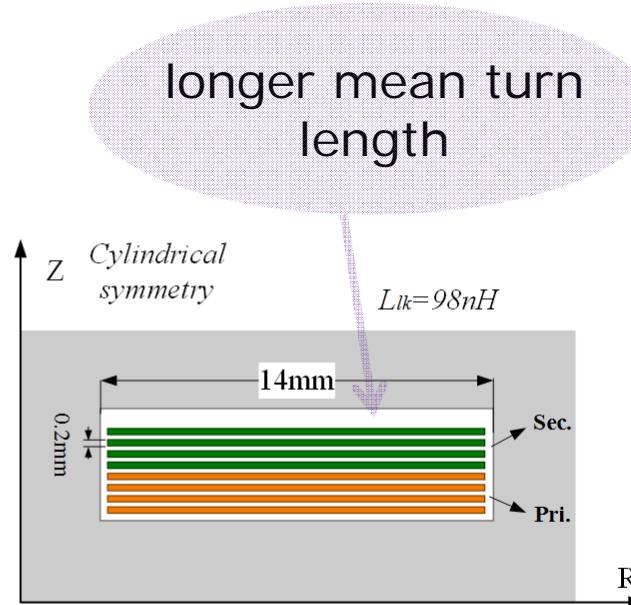


Leakage energy stored in each elementary layer:

$$E_{energy} = \frac{\mu_0}{2} \sum \int_0^h H^2 \cdot l_w \cdot b_w \cdot dx$$



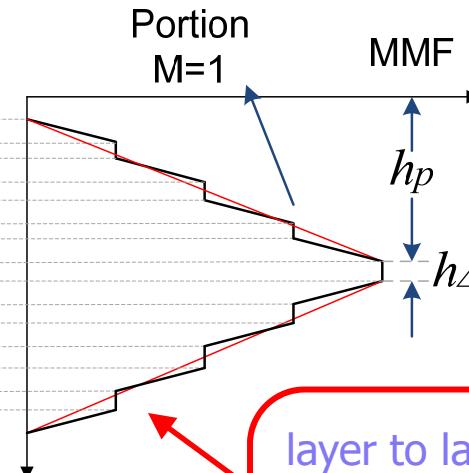
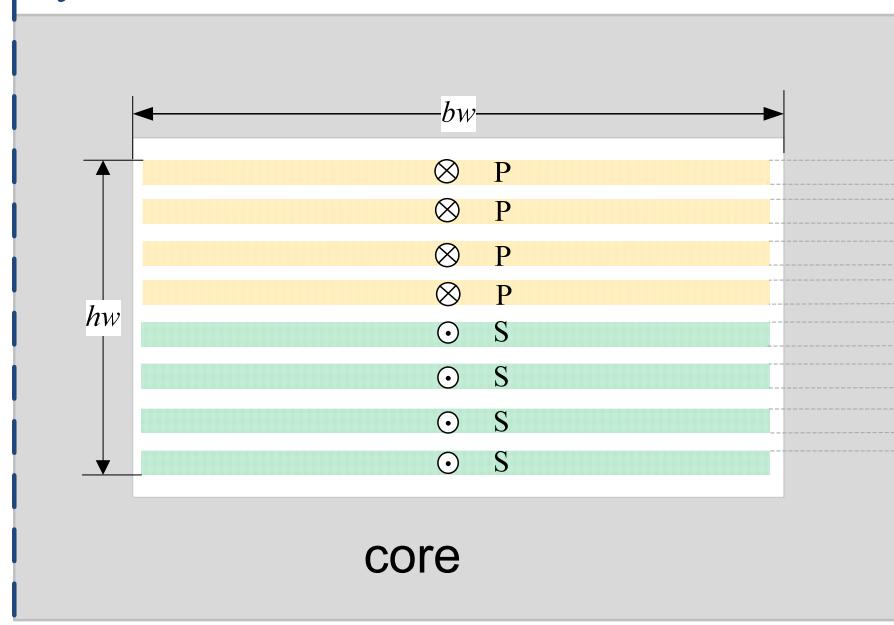
(a) conventional core geometry
with vertical-winding



(b) planar core geometry
with horizontal-winding

- ❖ Planar structure is not intrinsically a low leakage inductance construction.
- ❖ The benefit of planar PCB transformers in this regard is the relative ease with which primary and secondary windings can be heavily interleaved

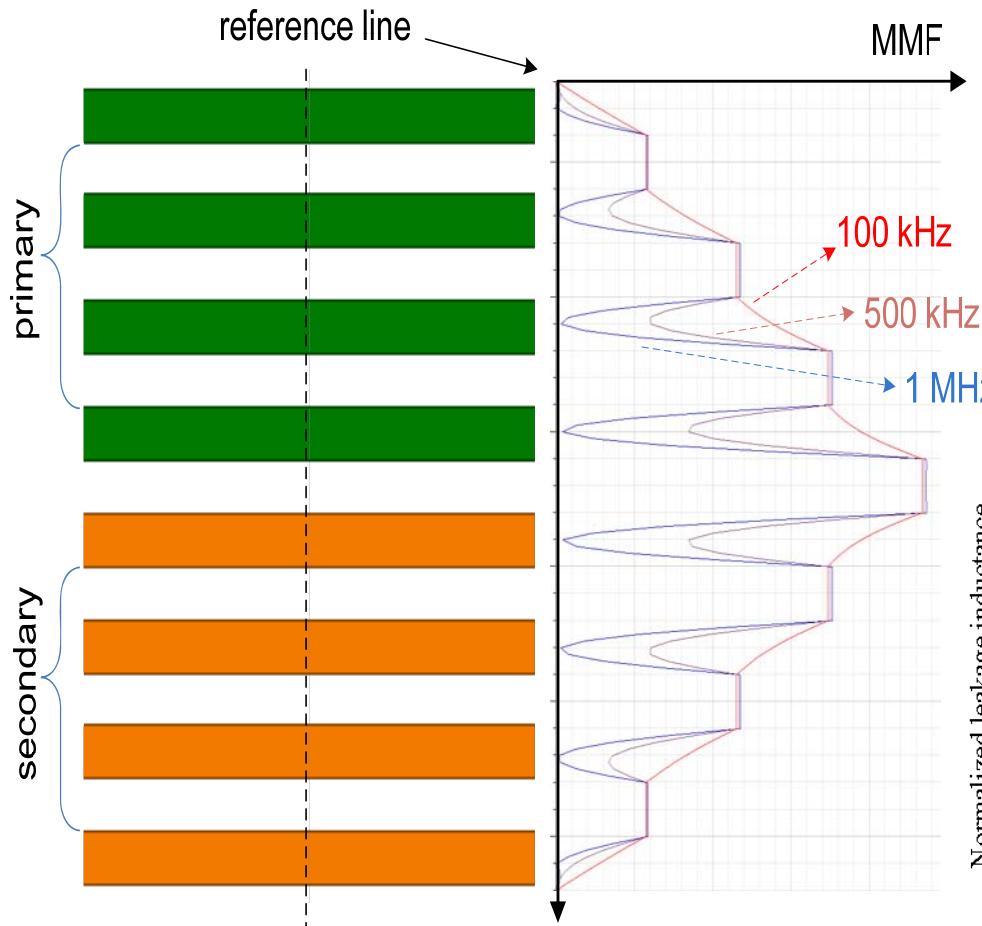
symmetric



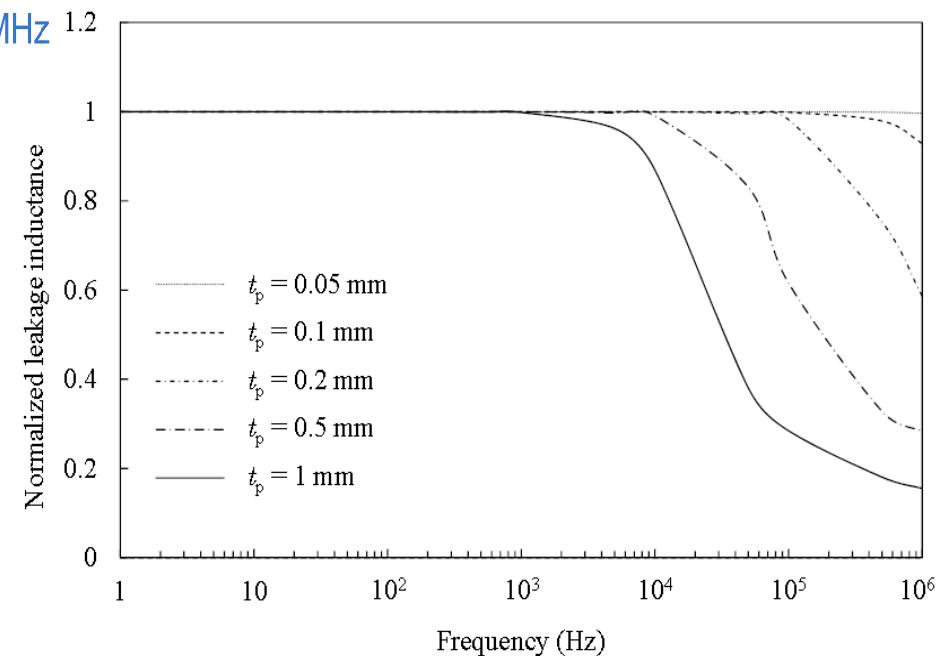
layer to layer insulation thickness has not been considered, which in PCB windings (usually have a thicker dielectric layer) may make a significant error

Traditional analytical expression:

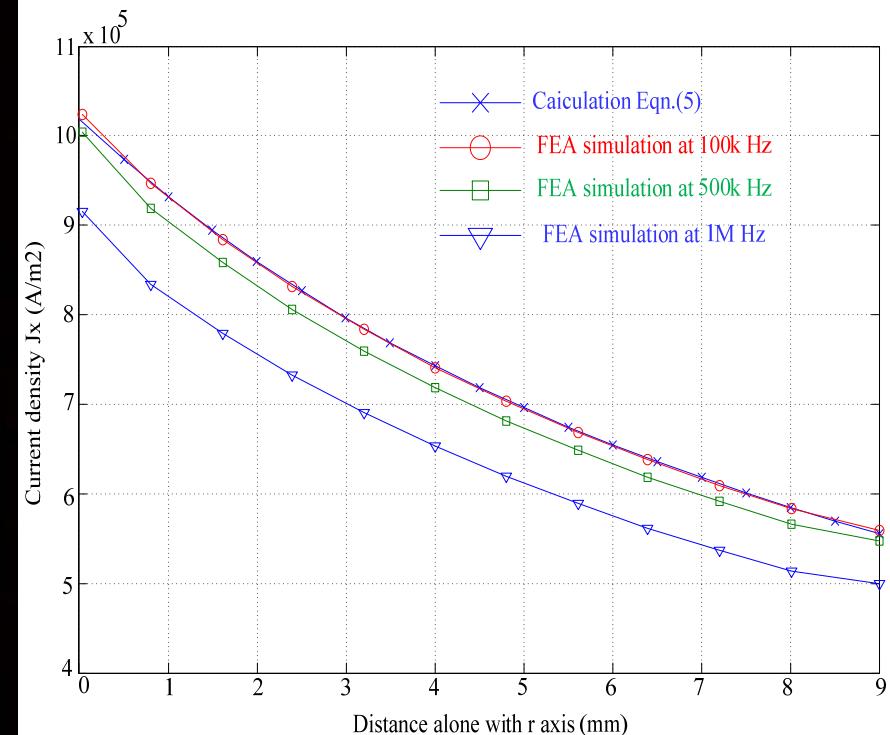
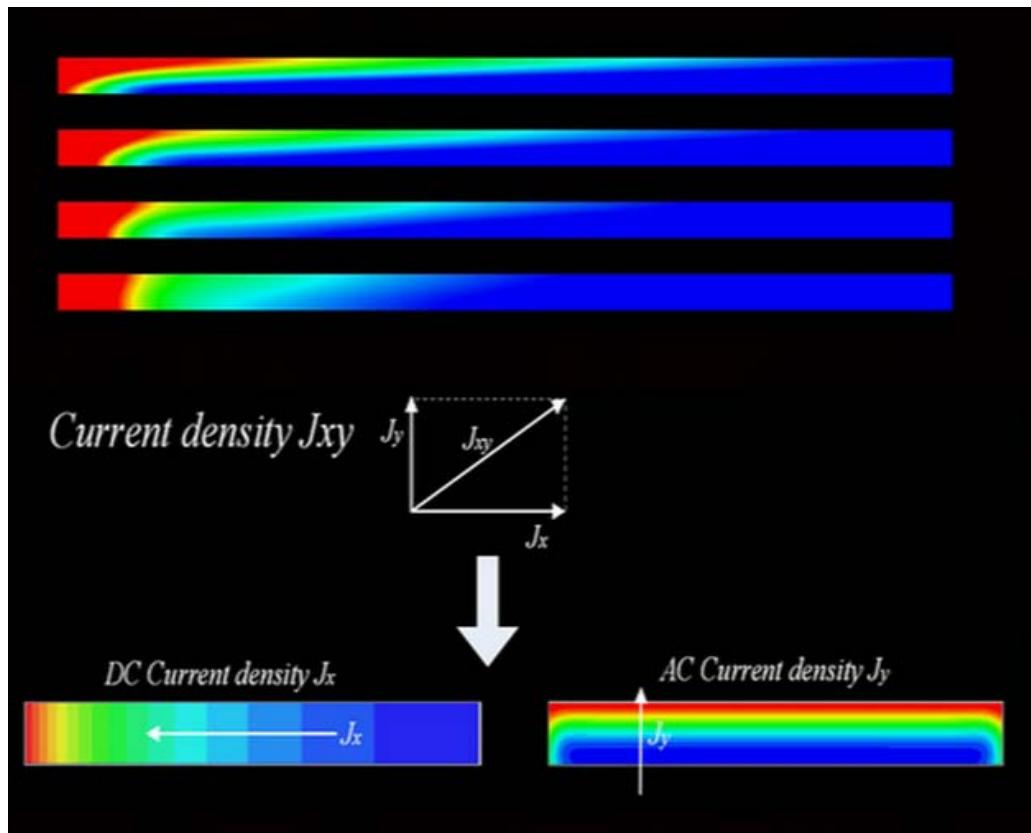
$$L_{lk} = \mu_0 \frac{N^2 l_w}{M^2 b_w} \left(\frac{1}{3} \sum_{P=1}^{2M} h_P + \sum_{\Delta=1}^M h_{\Delta} \right)$$



Leakage Inductance is frequency dependent



- ❖ “radial current distribution” due to high aspect ratio of width to height of a section, b_w/h_w .



New model for planar transformer leakage inductance:

- ❖ The energy stored in the primary/secondary winding is:

$$E_p = \sum_{i=1}^{n_p} E_i = \frac{\mu_0 \cdot \pi \cdot I_p^2 \cdot n_p [k_1(2n_p^2 + 1) + 4k_2(n_p^2 - 1)]}{In(\frac{r_2}{r_1}) \cdot 12 \cdot \gamma \sinh^2(\gamma h_p)}$$

where,

$$\begin{aligned} k_1 &= \sinh(2\gamma h_p) - 2\gamma h_p \\ k_2 &= \gamma h_p \cosh(\gamma \cdot h_p) - \sinh(\gamma \cdot h_p) \end{aligned}$$

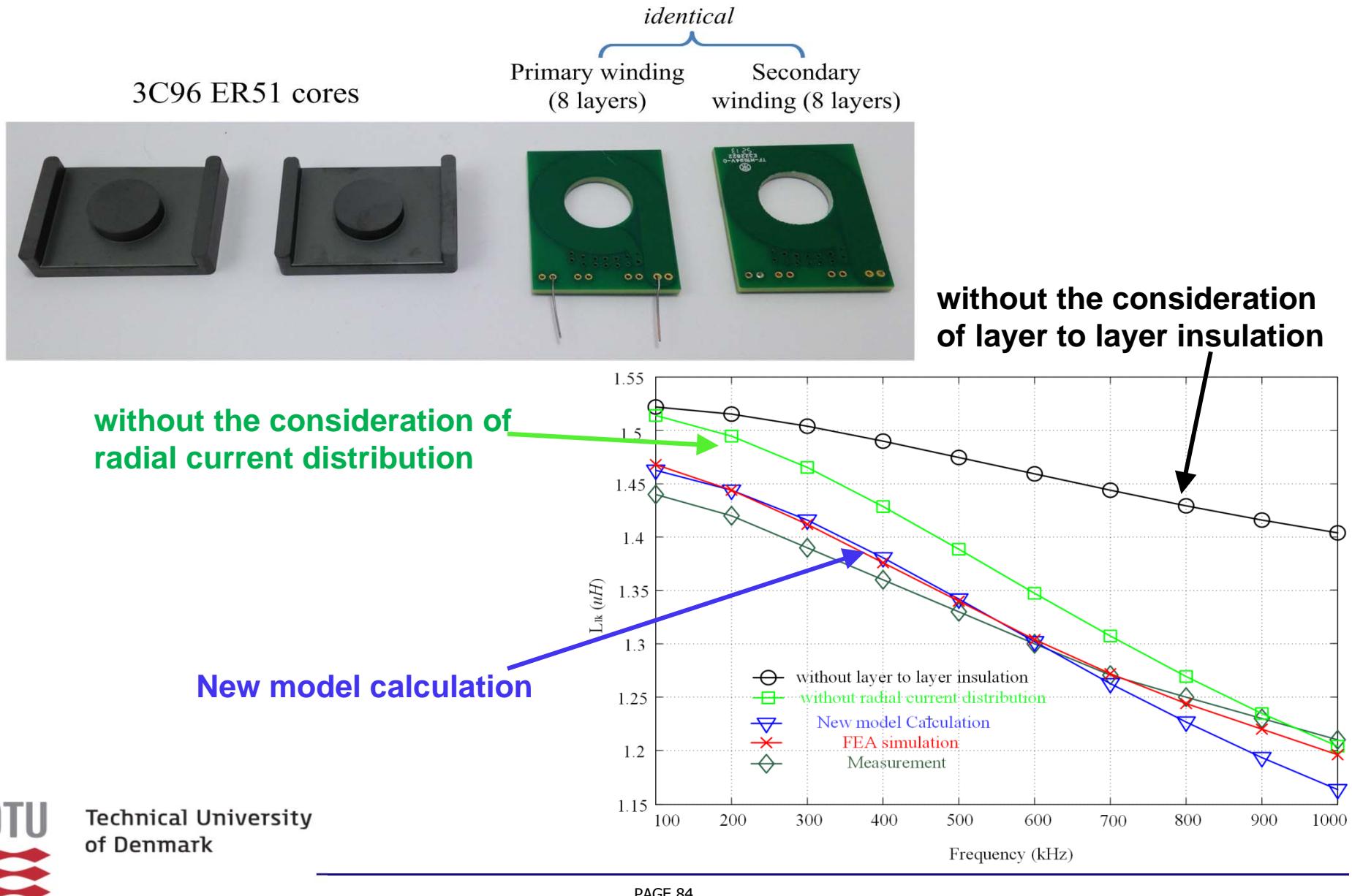
- ❖ The energy stored in the dielectric layer is:

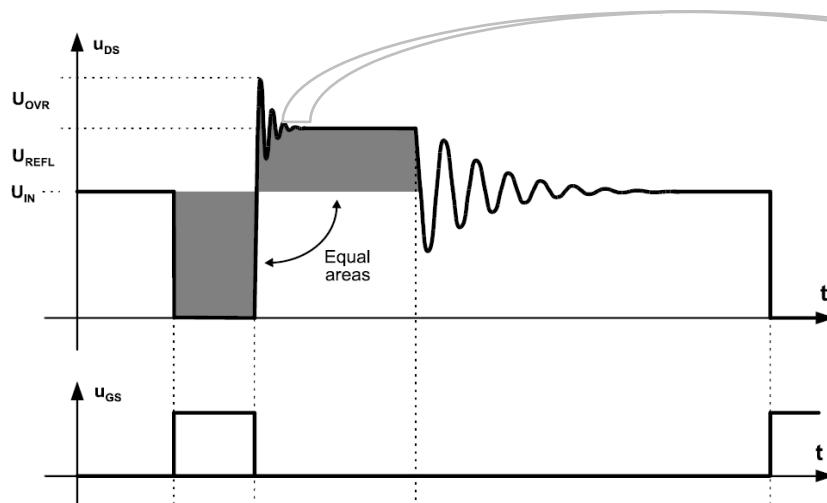
$$\begin{aligned} E_d &= \frac{1}{2} \cdot \mu_0 \cdot h_i \cdot \int_{r_1}^{r_2} H(r, h)^2 \cdot 2\pi r \cdot dr = \frac{\mu_0 \cdot \pi \cdot h_i}{In(\frac{r_2}{r_1})} \left[I_p^2 \sum_{i=1}^{n_p} i^2 + I_s^2 \sum_{i=1}^{n_s-1} i^2 \right] \\ &= \frac{\mu_0 \cdot \pi \cdot h_i}{6In(\frac{r_2}{r_1})} [I_p^2 \cdot n_p(n_p + 1)(2n_p + 1) + I_s^2 \cdot n_s(n_s - 1)(2n_s - 1)] \end{aligned}$$

Giving an example that has only one turn in each layer, the turns ratio $n = \frac{n_s}{n_p}$ is defined, and all windings' thickness are the same ($h_p = h_s$), then the total leakage inductance is:

$$L_{lk} = \frac{\mu_0 \cdot \pi \cdot n_p}{3In\left(\frac{r_2}{r_1}\right)} \left\{ \frac{n_p^2(k_1 + 2k_2)(n + 1)}{\gamma \sinh^2(\gamma h_p)} + \frac{(k_1 - 4k_2)(n + 1)}{2n\gamma \sinh^2(\gamma h_p)} \right. \\ \left. + \left[2(1 + n) \cdot n_p^2 + \frac{1}{n} + 1 \right] h_i \right\}$$

not applicable to complex interleaved cases such as primary and secondary windings on the same layer where 2-D consideration may be needed.

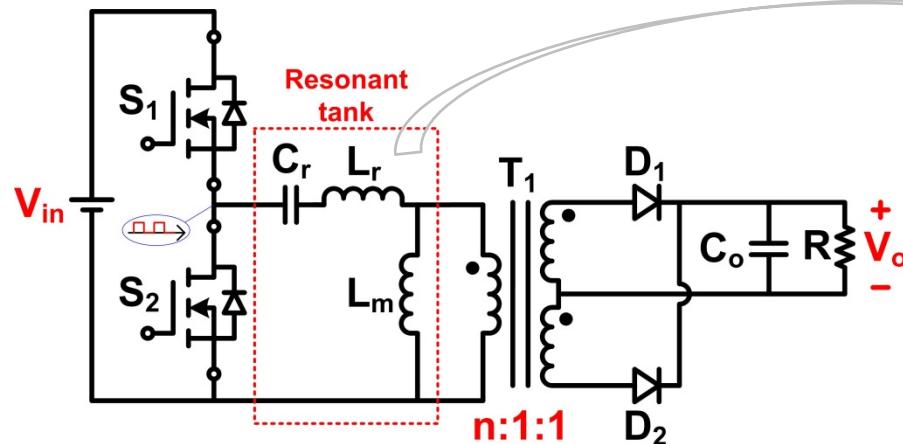




Small Leakage Inductance is expected in most of power converters

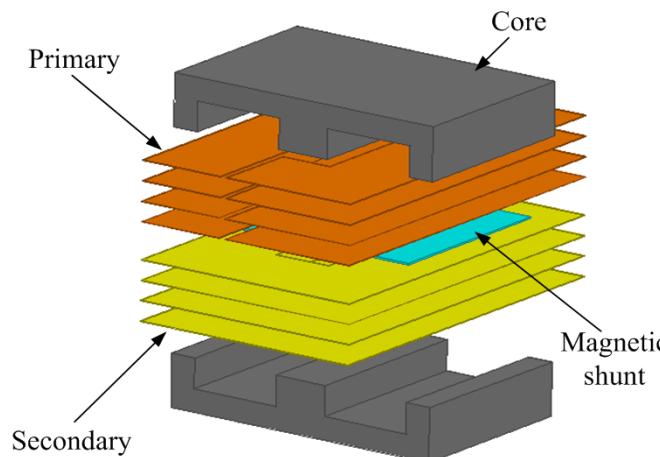
- ❖ Reduce the number of turns. (core saturation and higher core loss)
- ❖ Reduce the thickness of conductors and insulators. (high winding resistance and high interwinding capacitance)
- ❖ Reduce the mean turn length.
- ❖ Increase the window width. (high interwinding capacitance)
- ❖ Interleaving winding arrangement.

Note: “trade-off”

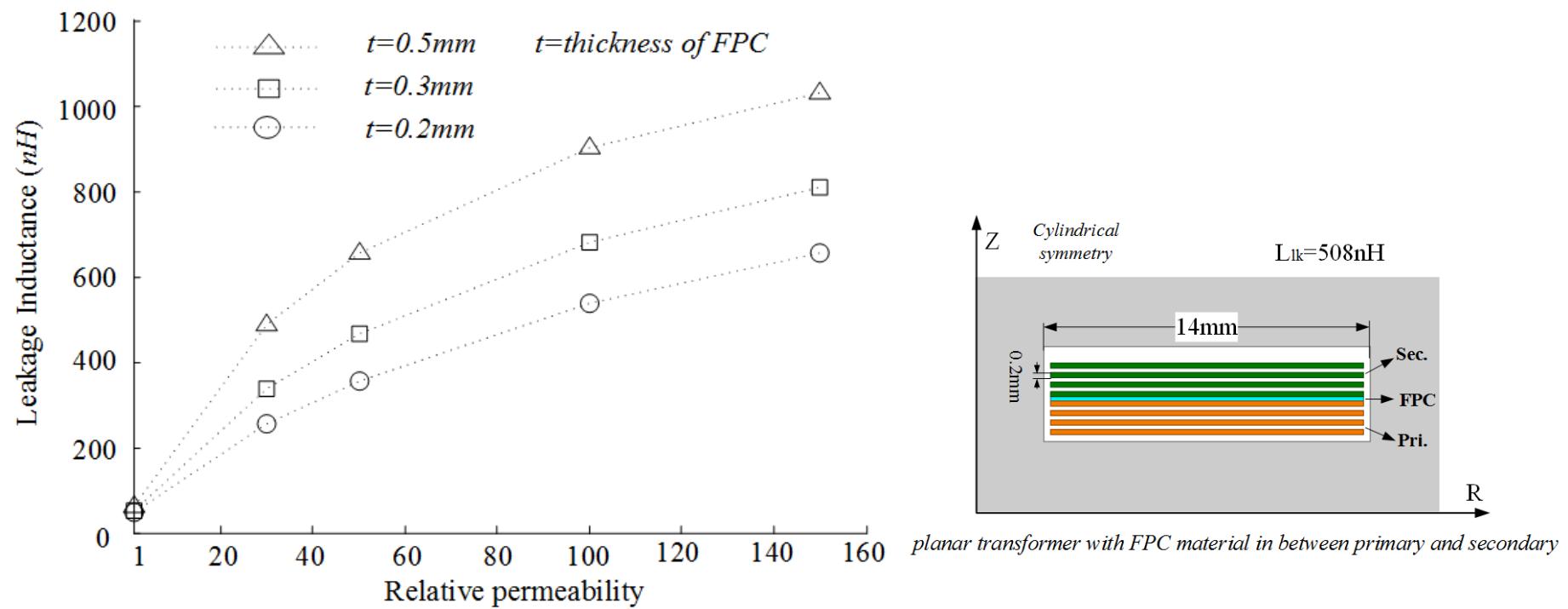


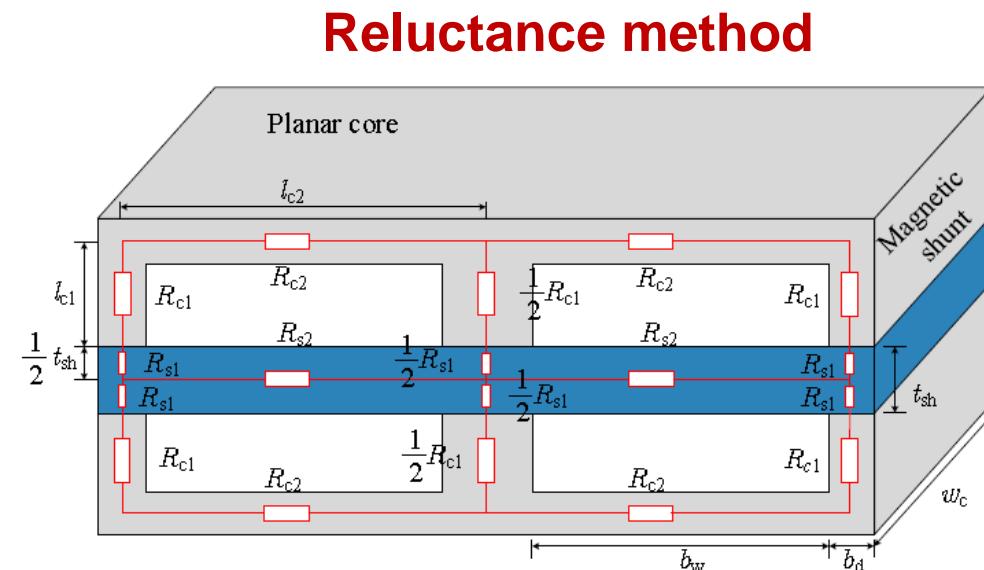
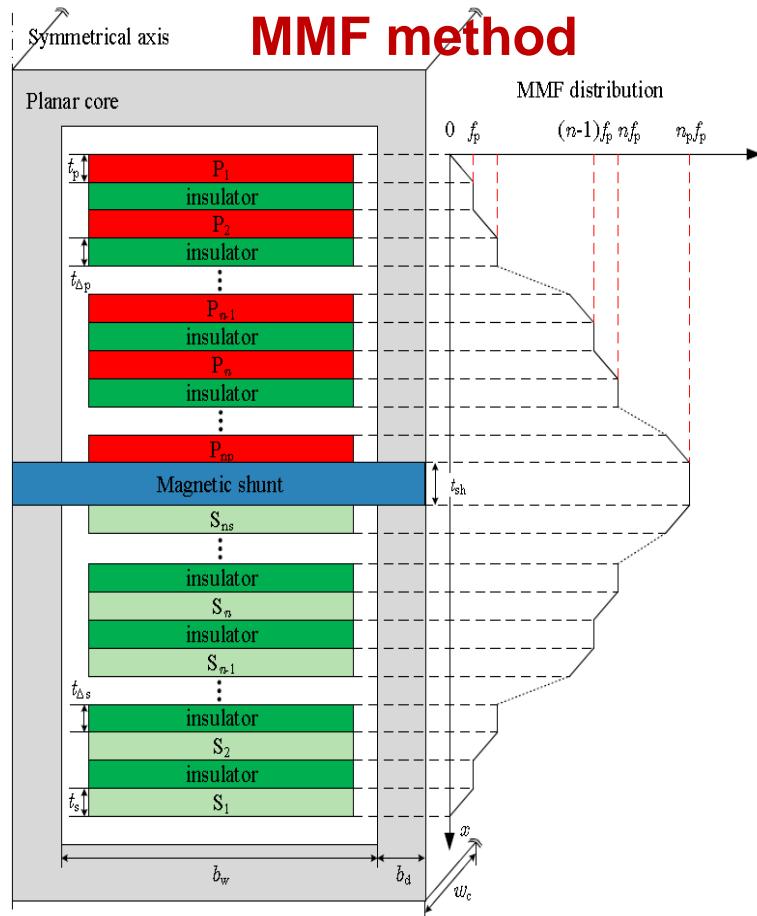
Higher Leakage Inductance is expected in resonant converters such as LLC, DAB etc.

- ❖ Insertion of **magnetic shunt** (f.x. ferrite polymer composites FPC)



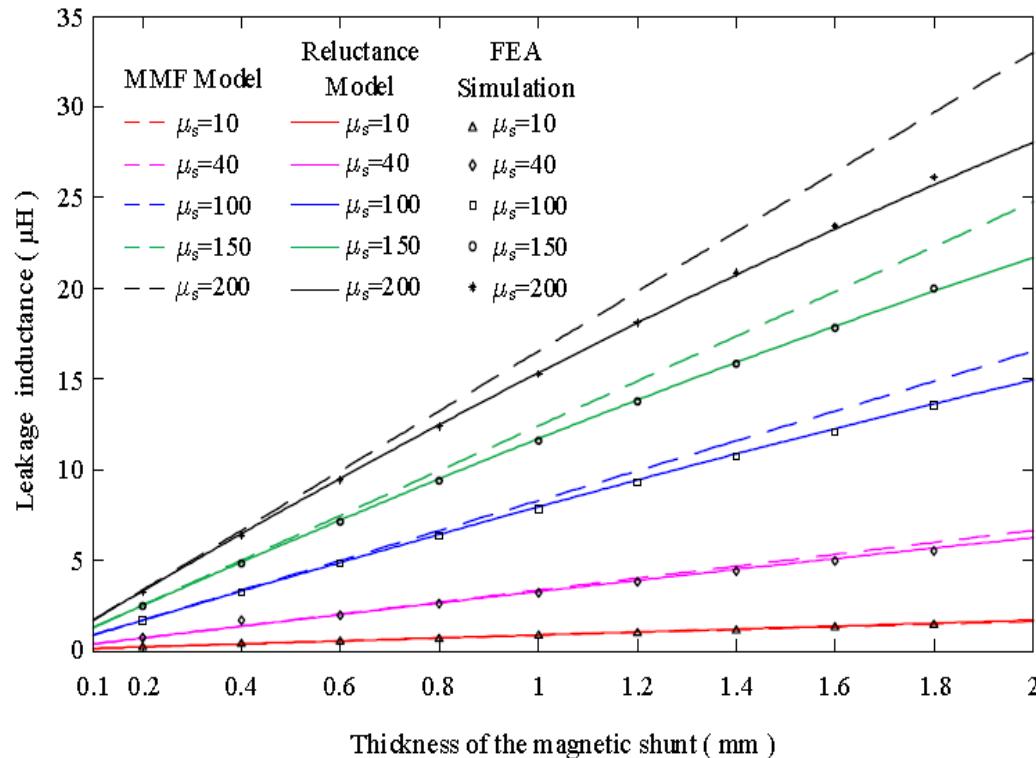
- ❖ Thickness of magnetic sheet
- ❖ Permeability of magnetic sheet



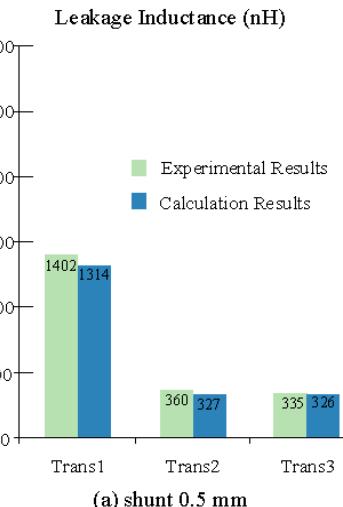


$$L_{lk} = \frac{1}{3} \mu_0 n_{Lp}^2 n_p^2 \frac{w_c}{b_w} \left\{ 6\mu_s a_R^2 \left(t_{sh} + \frac{2b_d b_w R_{s1}^2}{t_{sh} R_{s2}^2} \right) + \frac{3}{4} \mu_r a_R^2 \frac{b_w A_c}{w_c l_c R_{s2}^2} \left(R_{c1} + \frac{1}{2} R_{c2} \right)^2 \right\}.$$

$$L_{lk} = \frac{\mu_0 w_c n_{Lp}^2 n_p^2}{3b_w} \left\{ \sum_{i=p,s} \left[2n_i(t_i + t_{\Delta i}) - 3t_{\Delta i} + \frac{t_{\Delta i}}{n_i} \right] + 6\mu_s t_{sh} \right\}.$$

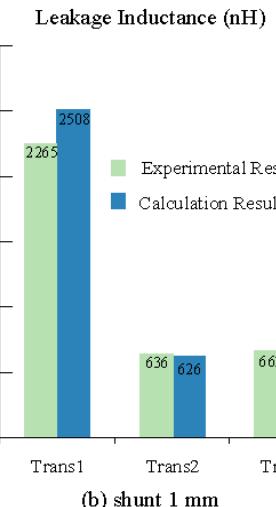


Leakage Inductance (nH)



(a) shunt 0.5 mm

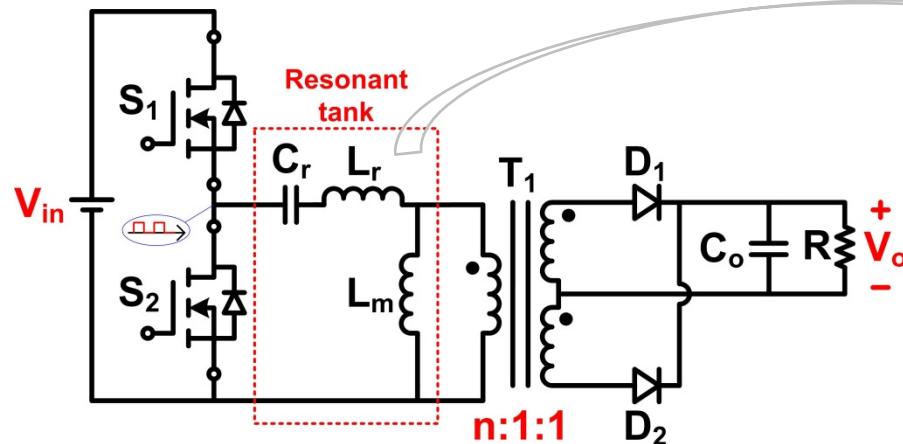
Leakage Inductance (nH)



(b) shunt 1 mm

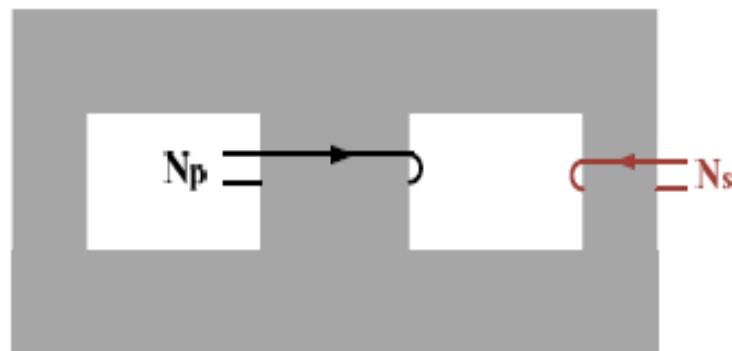


Reluctance method provides a better prediction

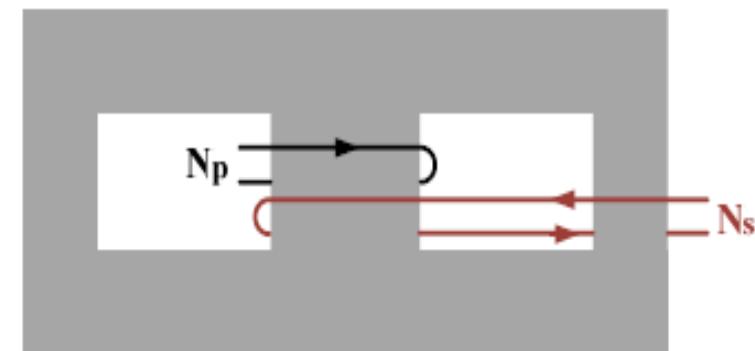


Higher Leakage Inductance is expected in resonant converters such as LLC, DAB etc.

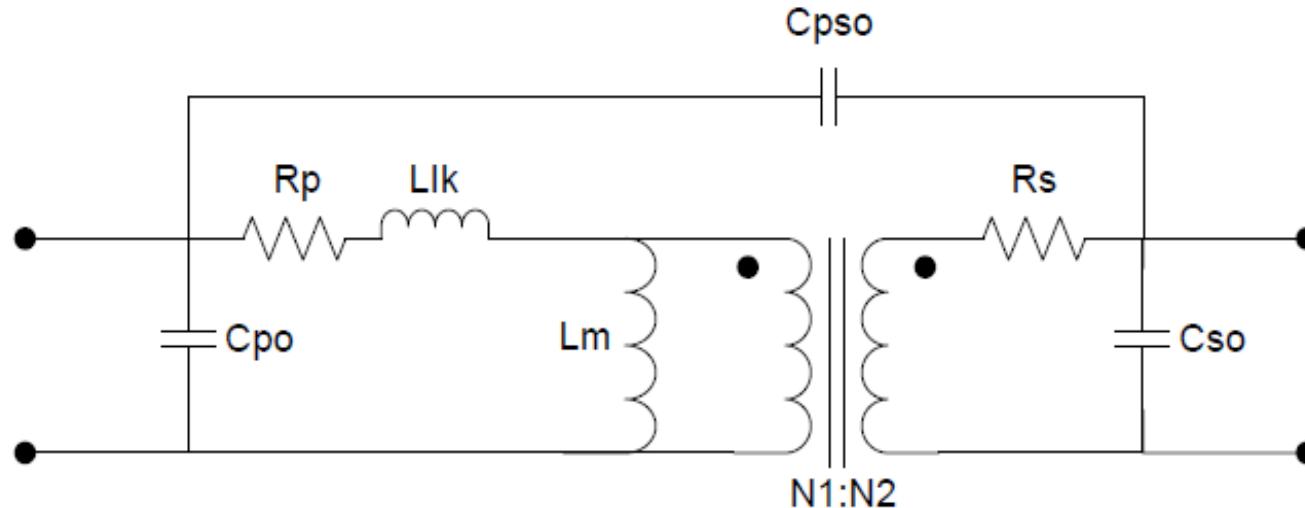
❖ Fractional turn



(a)

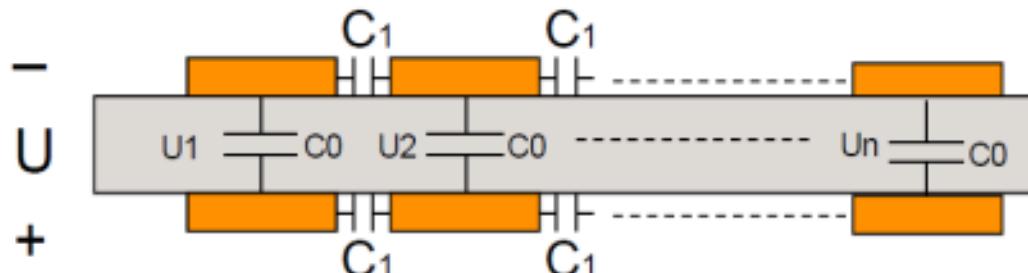


(b)

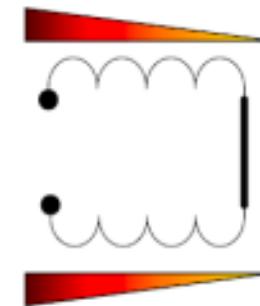
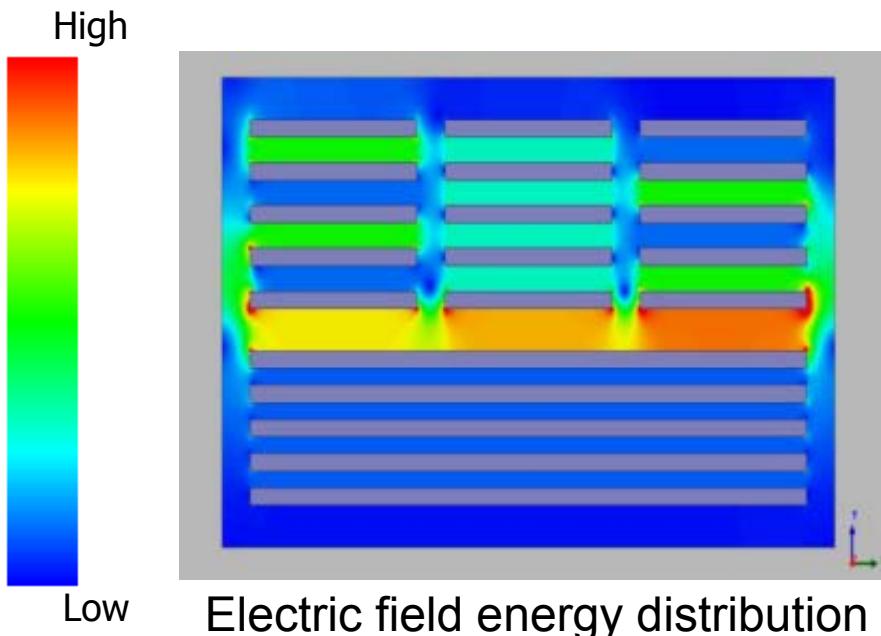


C_{po} , C_{so} are self-capacitances of the primary and the secondary windings, respectively.

C_{ps0} is the mutual capacitance between the two windings.



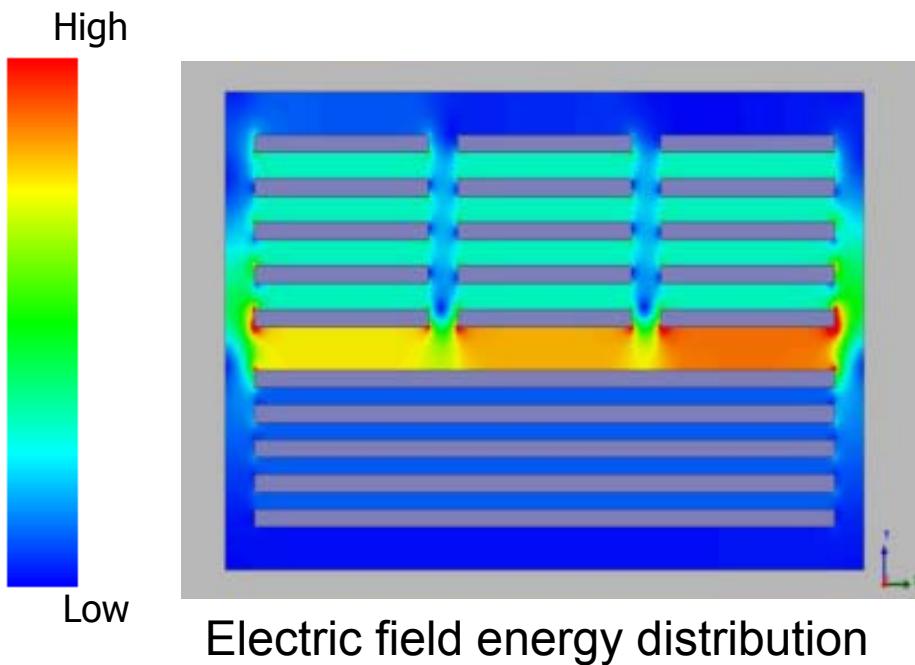
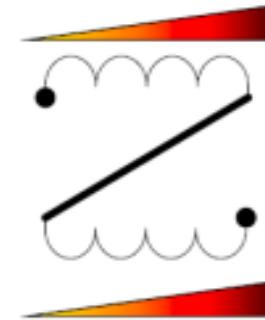
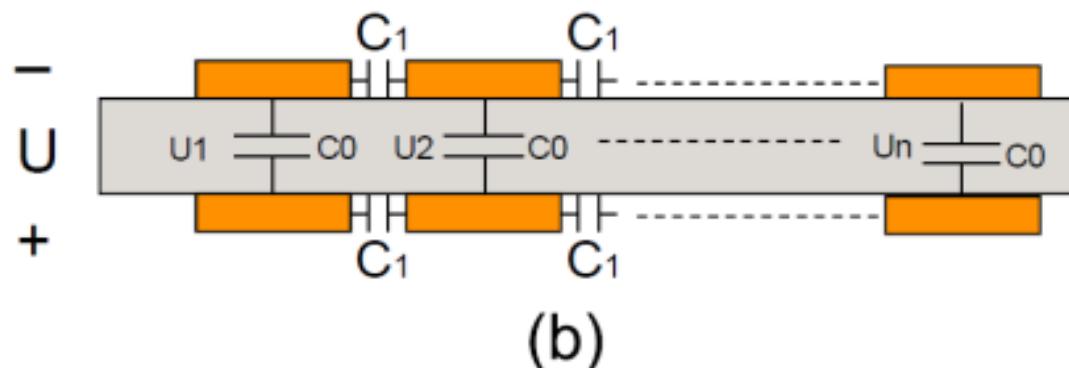
(a)

**U-type winding scheme**

Electric field energy distribution

$$\begin{aligned} E &= \sum_{i=1}^n E_i = \frac{1}{2} C_0 U^2 \sum_{i=1}^n \left(\frac{n+1-i}{n} \right)^2 \\ &= \frac{(n+1)(2n+1)}{12n} C_0 U^2. \end{aligned}$$

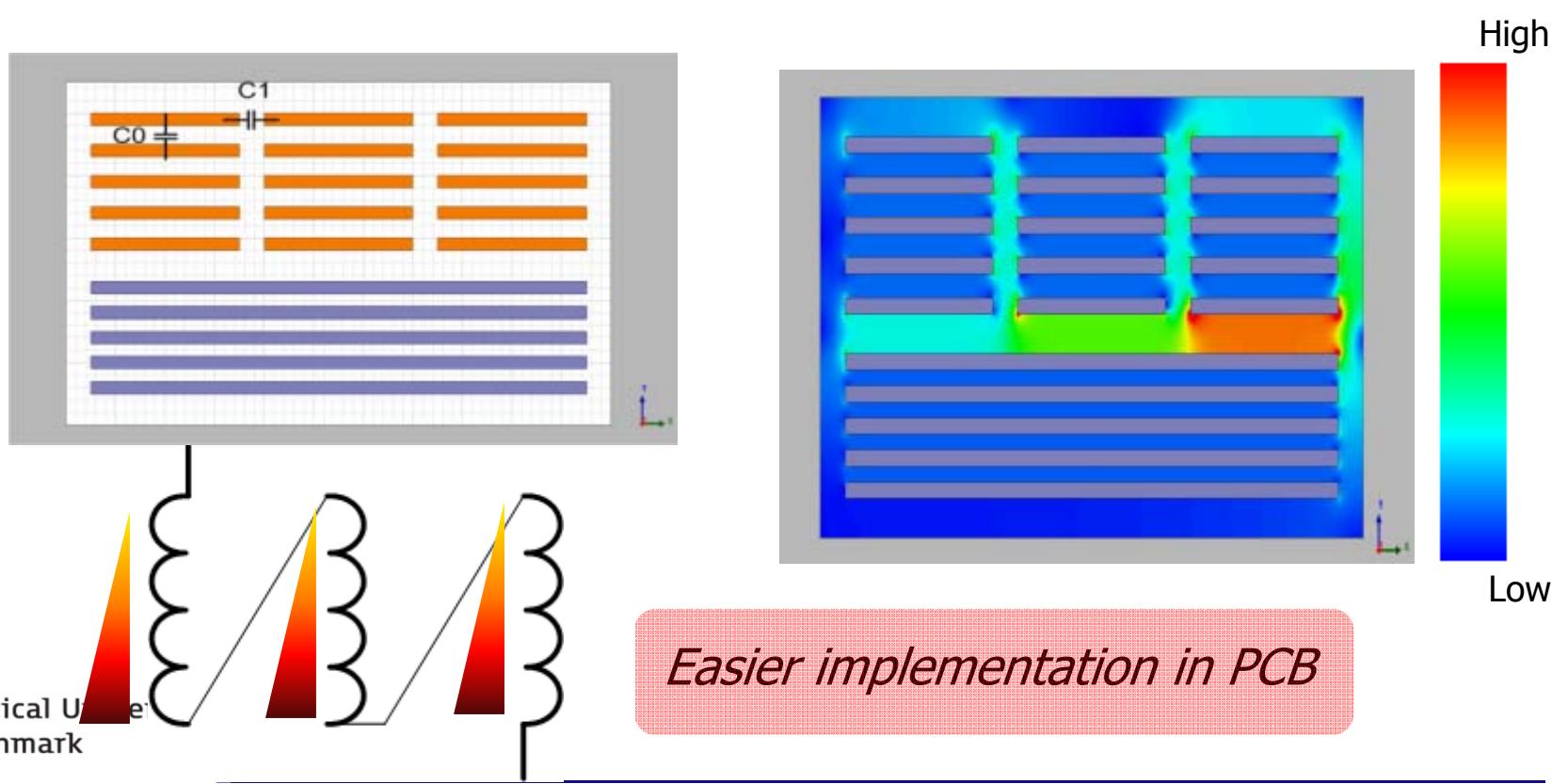
$$C_d = \frac{2E}{U^2} = \frac{(n+1)(2n+1)}{6n} C_0.$$



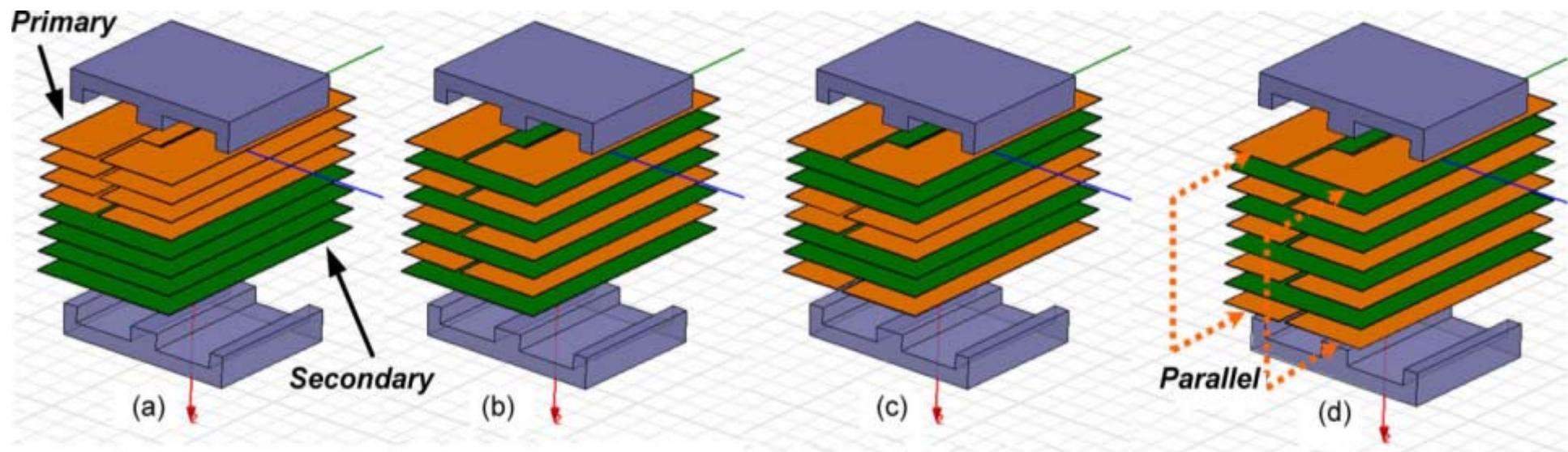
Z-type winding scheme

$$C_d = (n/4) \cdot C_o$$

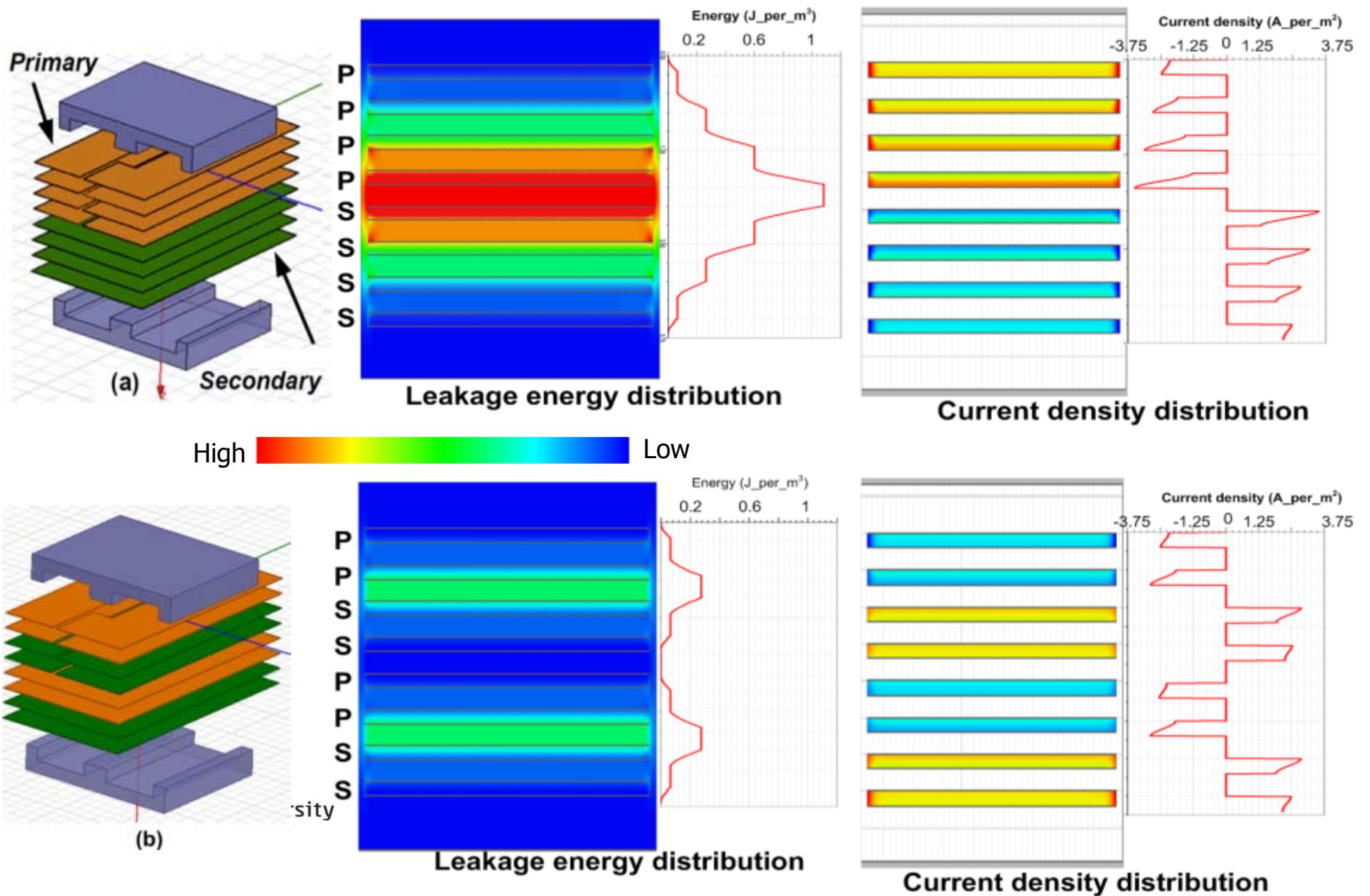
Due to a higher ratio of the width to the thickness of the conductors (intrinsic property of PCB magnetics), C_1 is much lower than C_0 . So, vertical winding scheme leads to a lower electric potential energy.



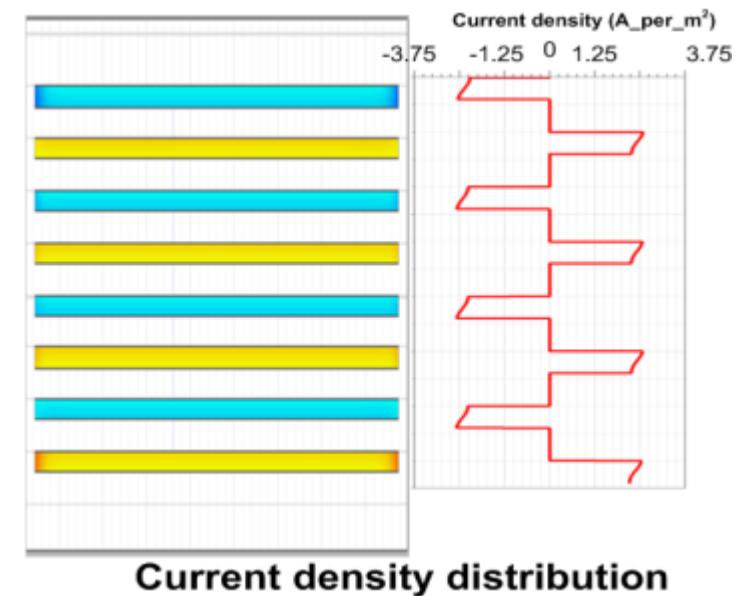
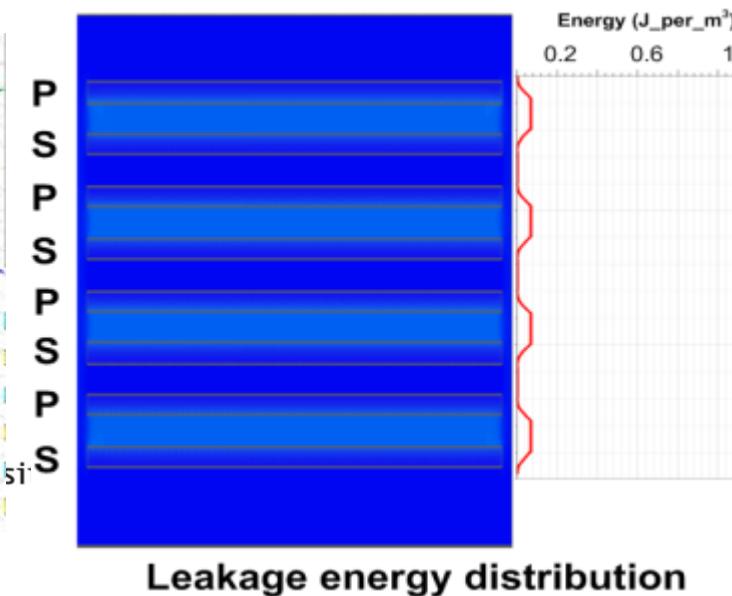
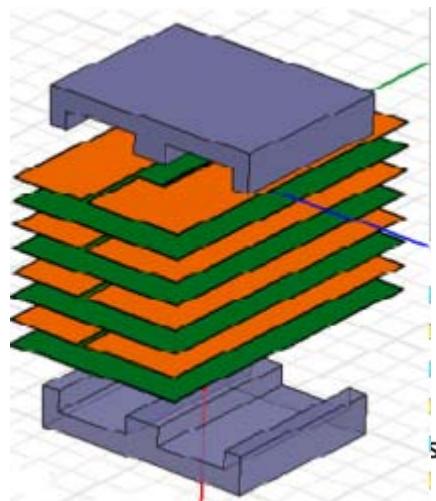
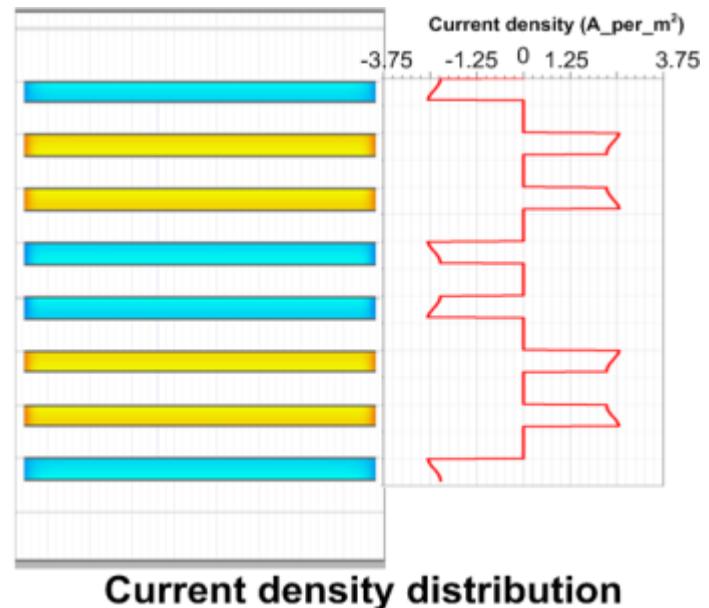
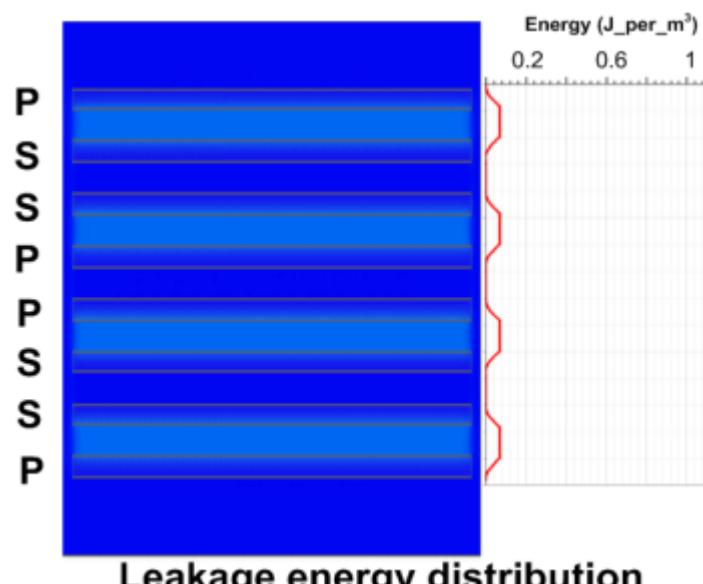
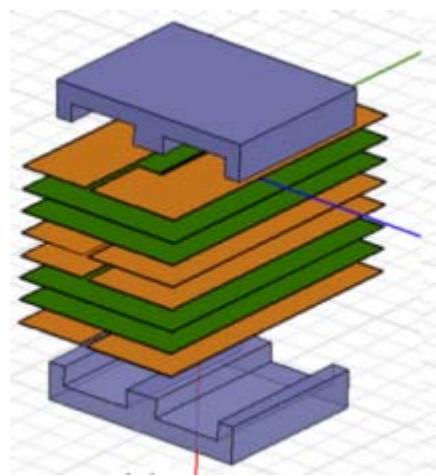
- ❖ Reduce the ac winding resistance;
(not for the flyback converter)
- ❖ Reduce the leakage inductance;
- ❖ Increase the interwinding capacitance.

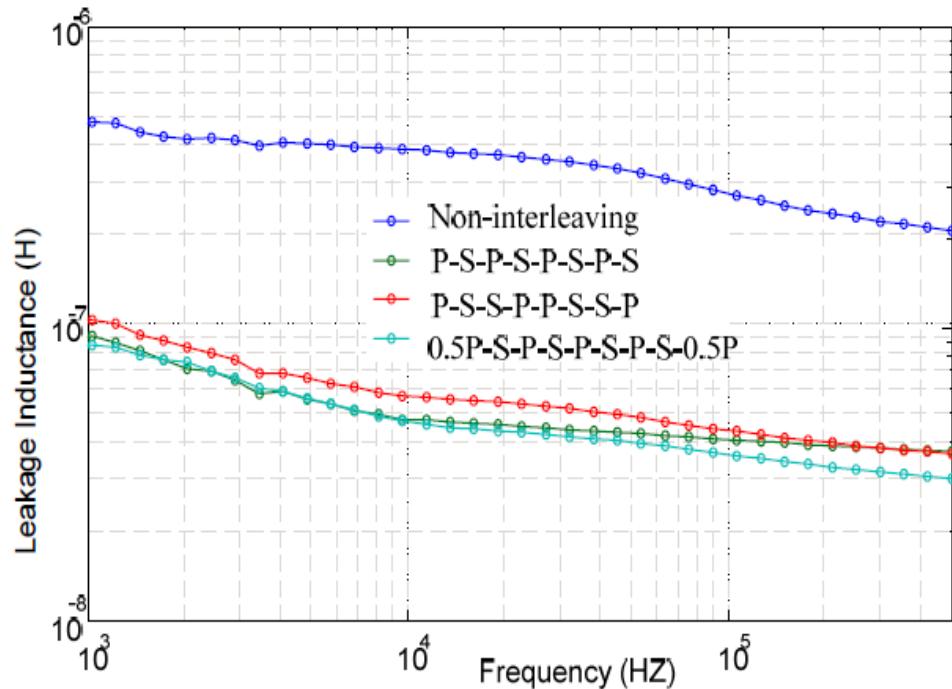
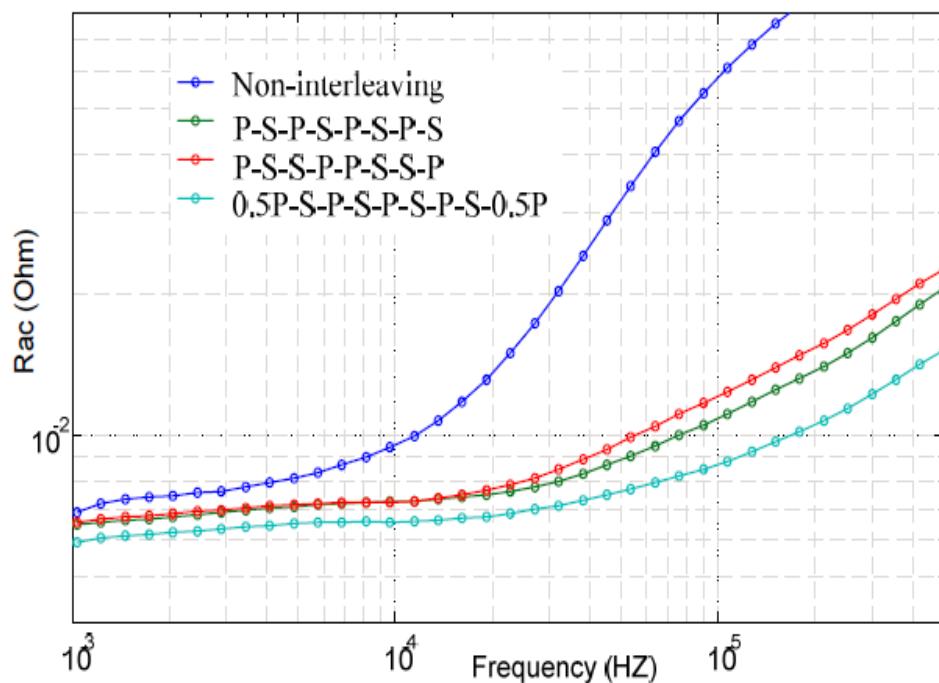
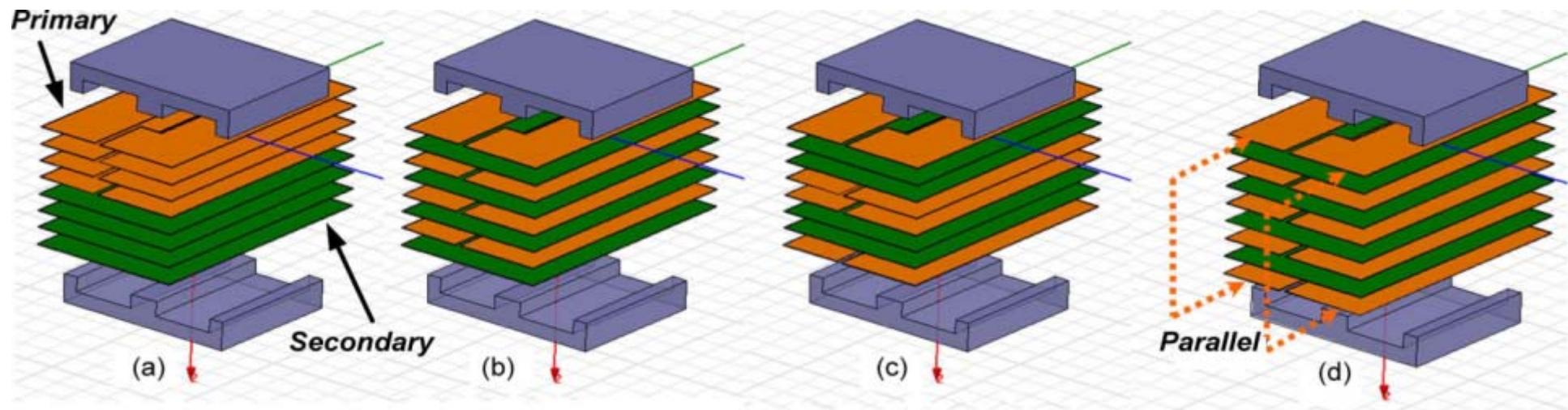


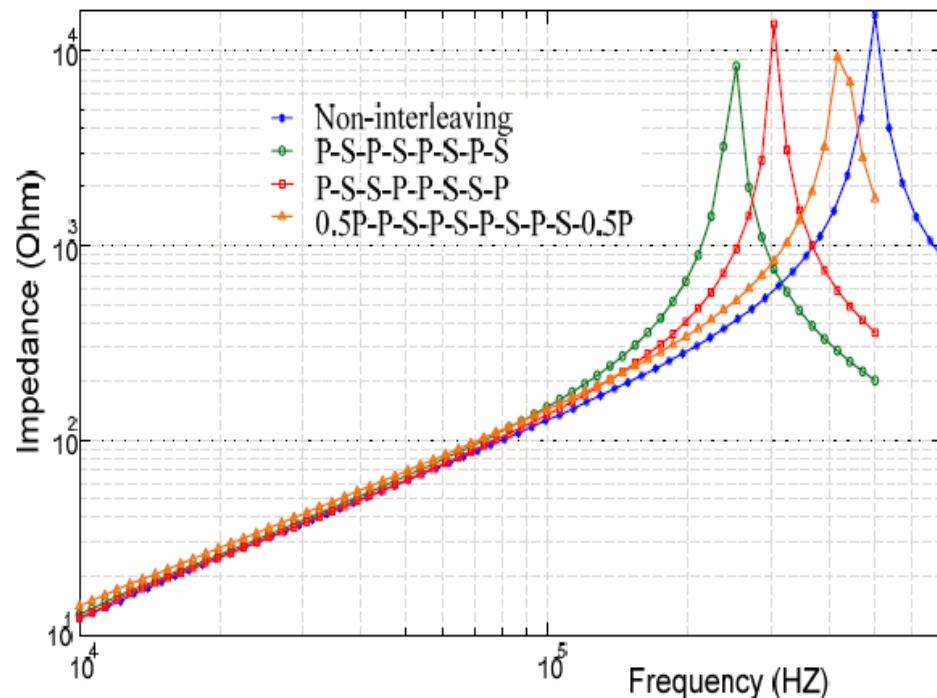
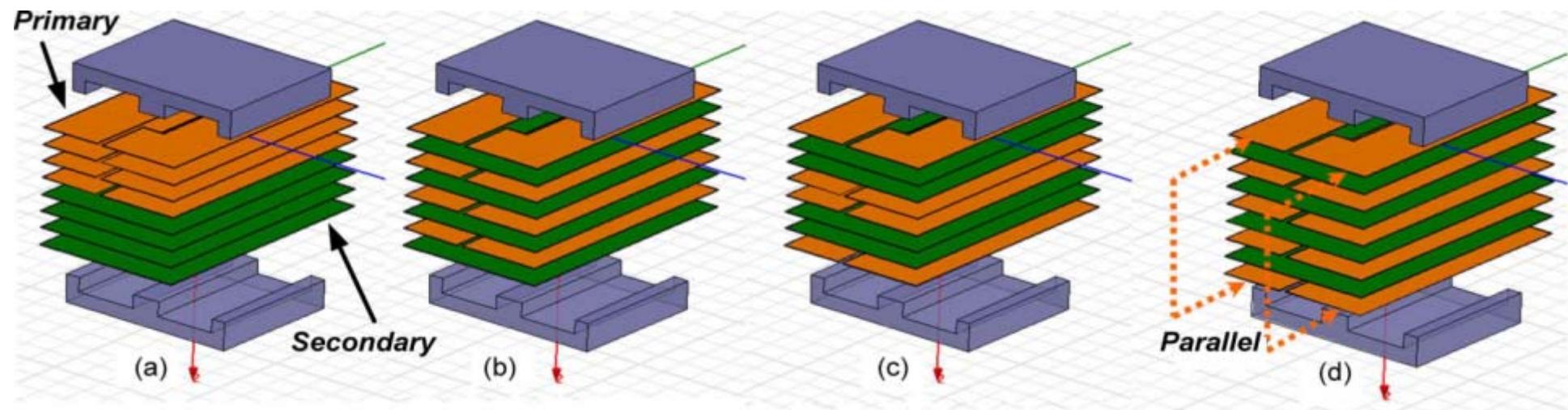
Interleaved Winding



Interleaved Winding







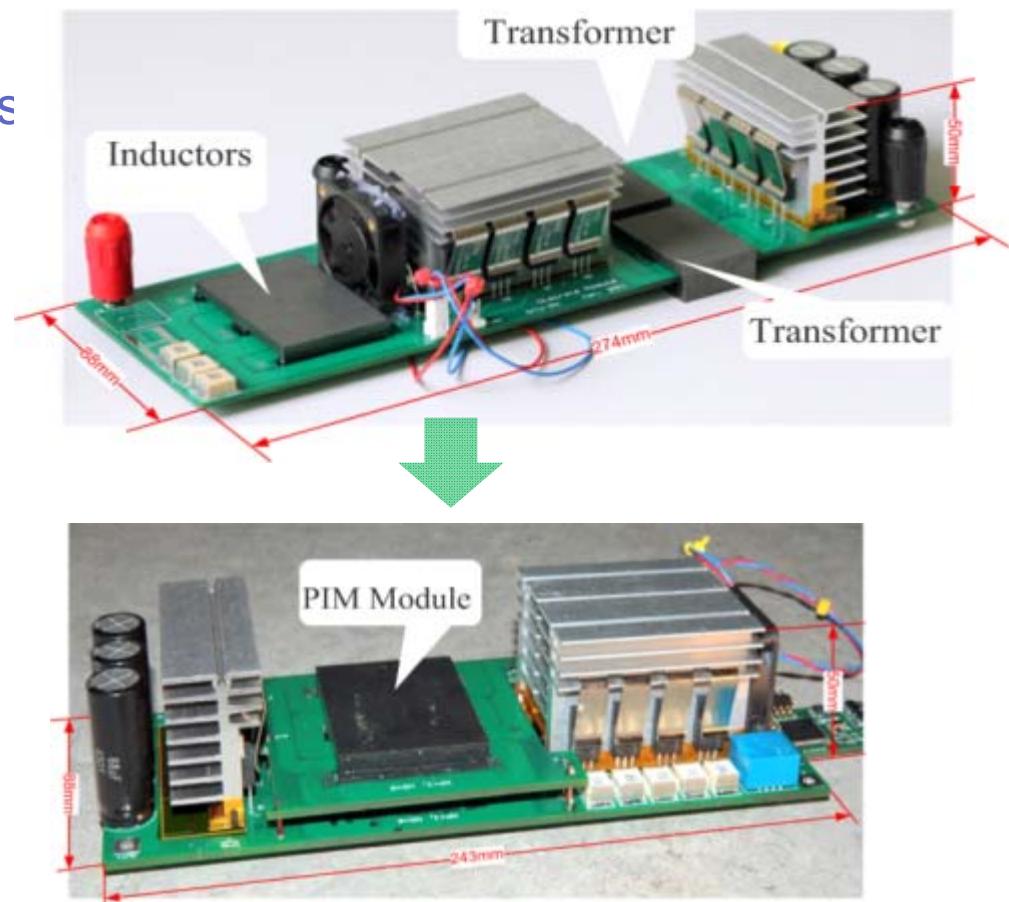
Frequency is 50 kHz	R _{ac} /R _{dc} (mOhm)	L _{leak} (nH)	C _{str} (nF)
Non-interleaving	32.2/6.55	324	1.15
P-S-P-S-P-S-P-S	9.14/6.14	43.8	9.41
P-S-S-P-P-S-S-P	10.1/6.21	47.4	4.24
P/2-S-P-S-P-S-P-S-P/2	7.68/5.69	40.6	3.89

Planar Magnetic Components Integration

functional devices integration, in which discrete magnetic devices with different functions are assembled as one integrated magnetic device.

Mixing the functions of transformers and inductors in:

- Current doubler rectifiers
- LLC resonant converters
- Integrated EMI filters etc.



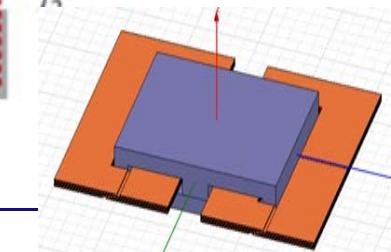
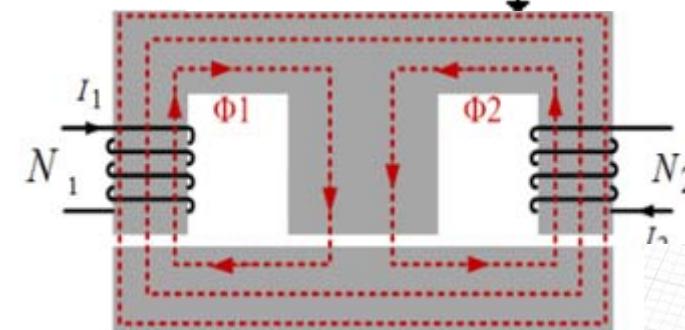
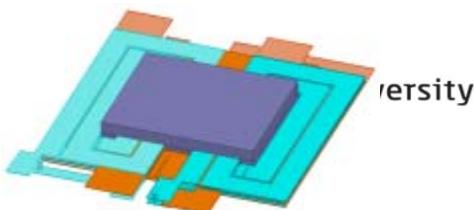
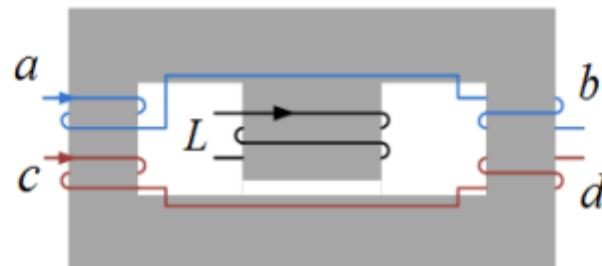
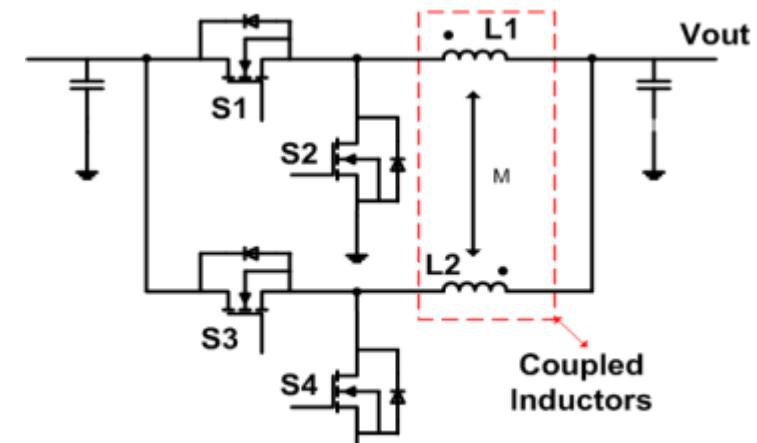
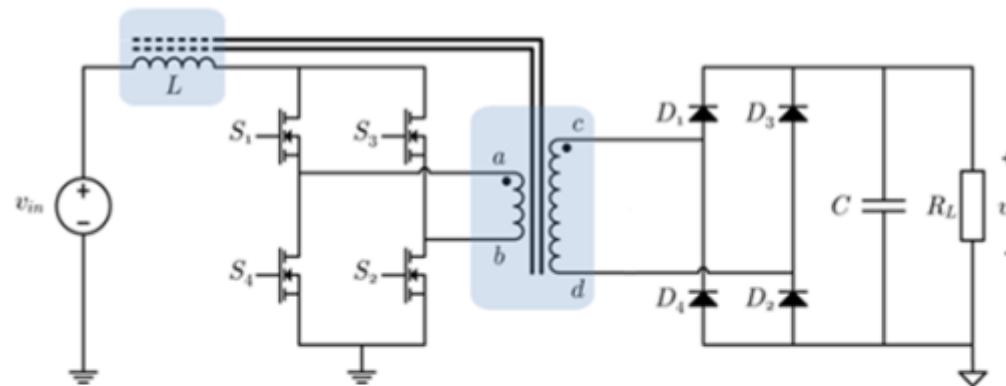
Major advantage:

- ❖ Smaller size
- ❖ higher power efficiency
- ❖ lower core loss (spark interest into the light load conditions with the integrated magnetics)

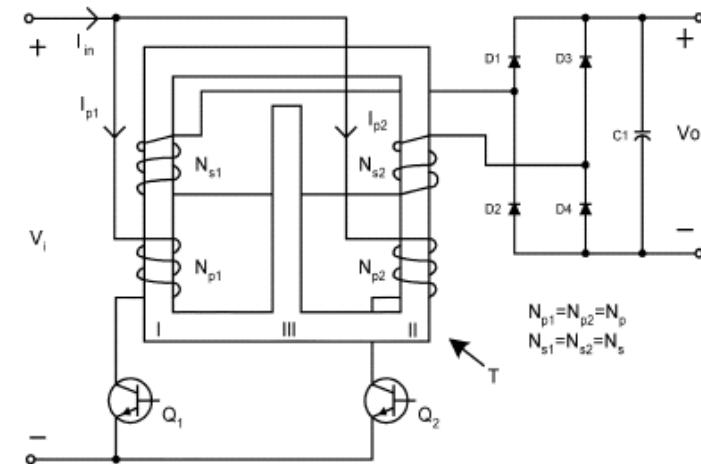
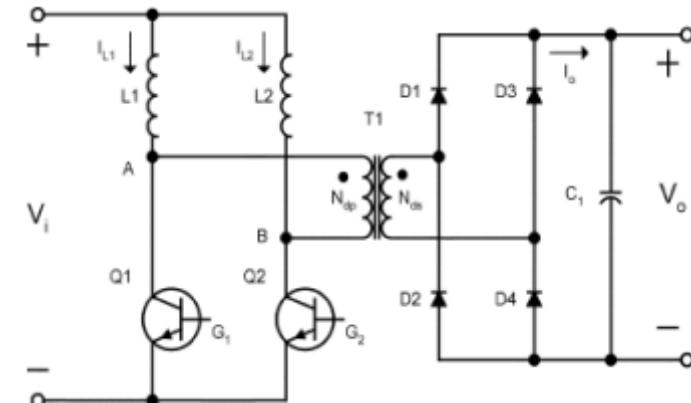
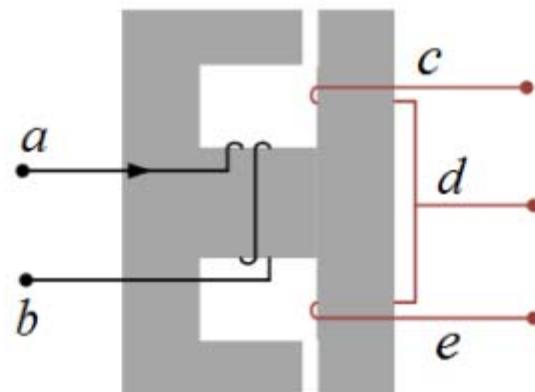
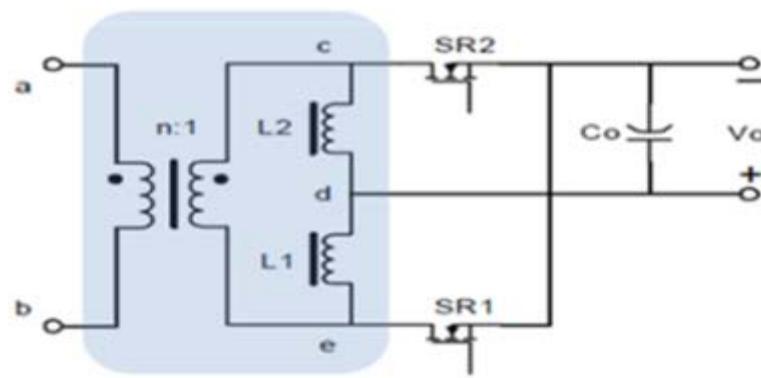
It is often used in applications where space is highly restricted such as computer systems, data center, automotive electrical systems and space applications.

❖ Magnetic core sharing

(Only the core is shared, and the windings are not shared)

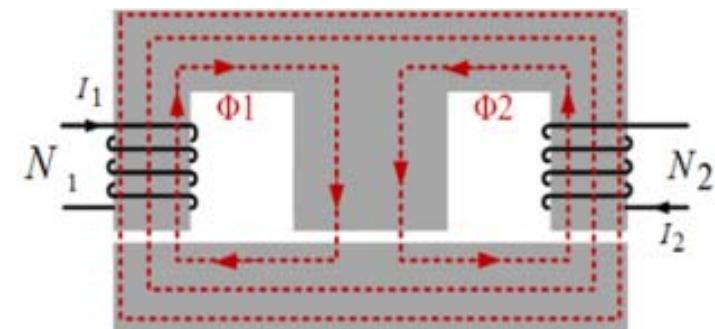
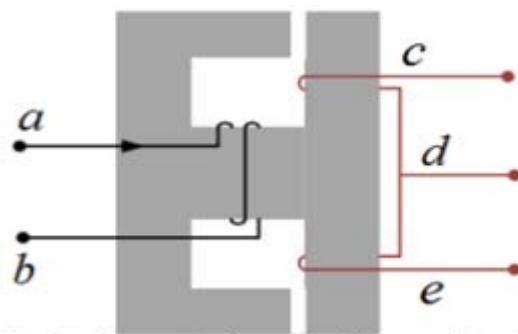


- ❖ **Both winding and magnetic core sharing**
(Fully integration)



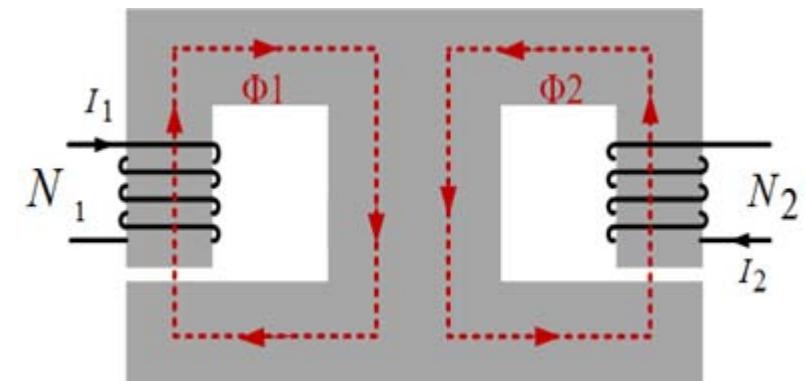
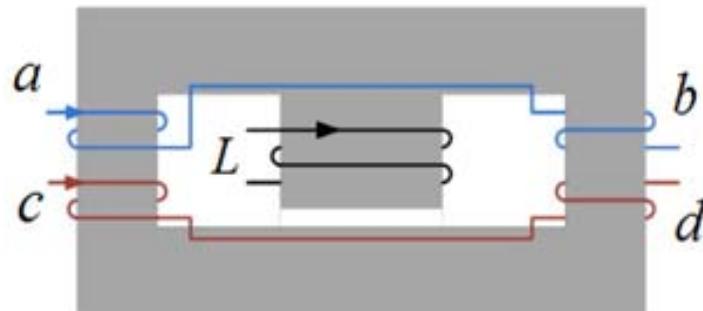
The magnetic field produced by one coil passes through the other coil, changing their effective inductances due to the mutual relationship:

- Coupled Inductors
- Multi-winding transformers
- ...



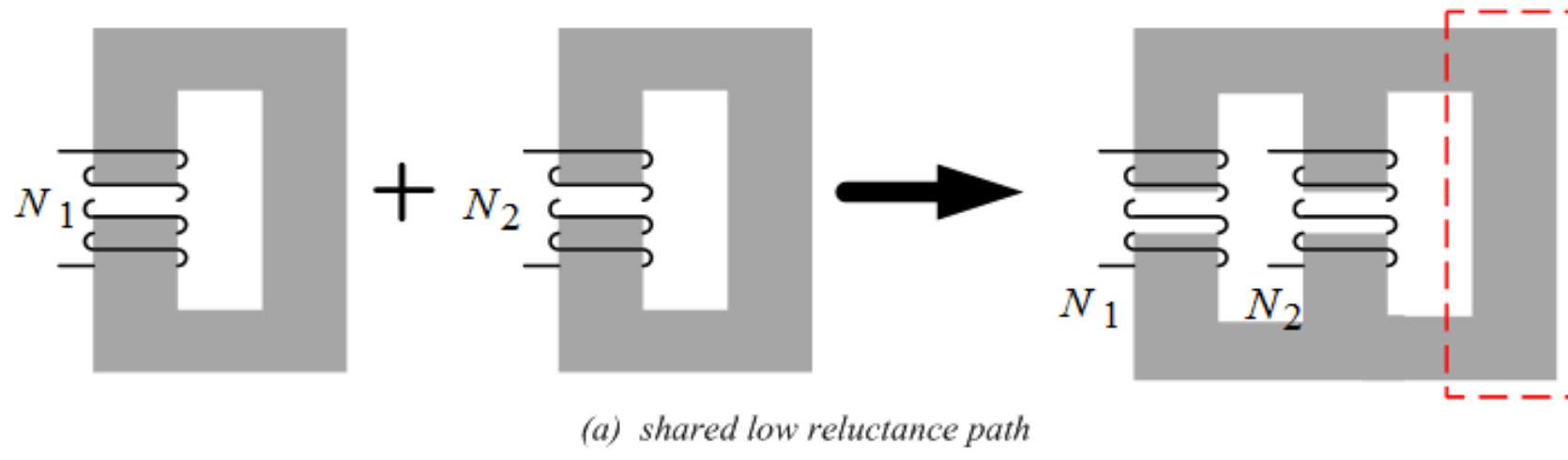
many advantages,...
but can **NOT** be applied in all circuit topologies

The magnetic field produced by one coil does not pass through the other coil or cancel in the other coil.

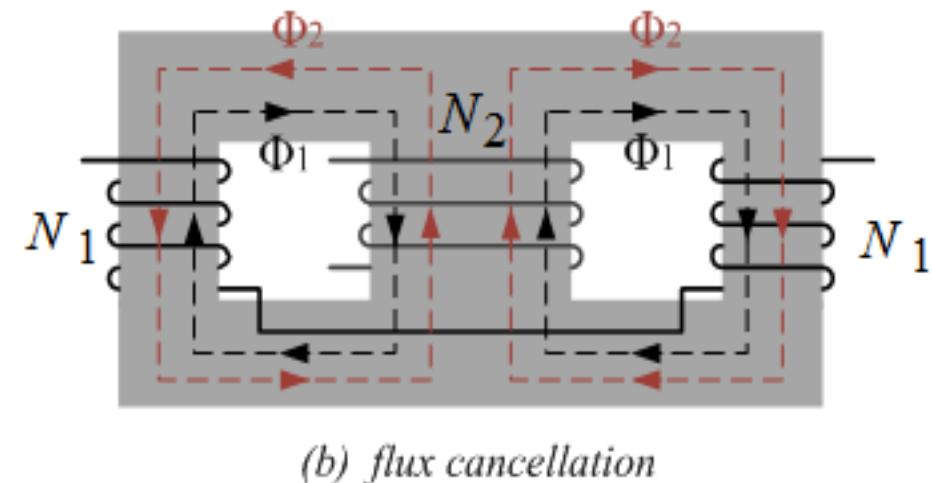


can be used in nearly all circuit topologies due to their independent operation behaviors

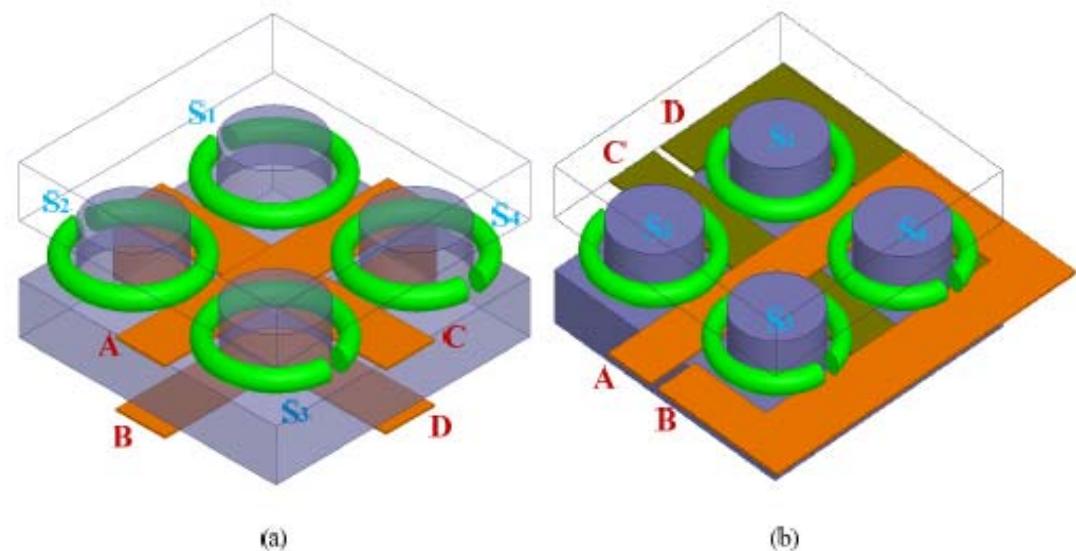
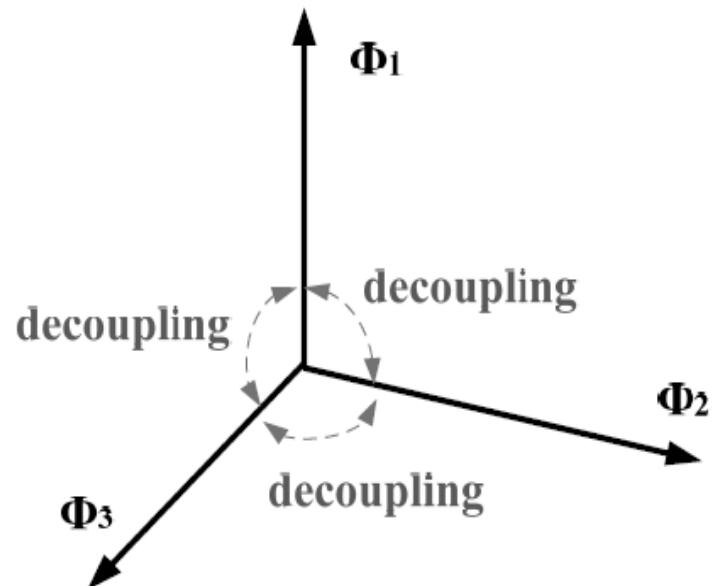
❖ Shared low core reluctance path

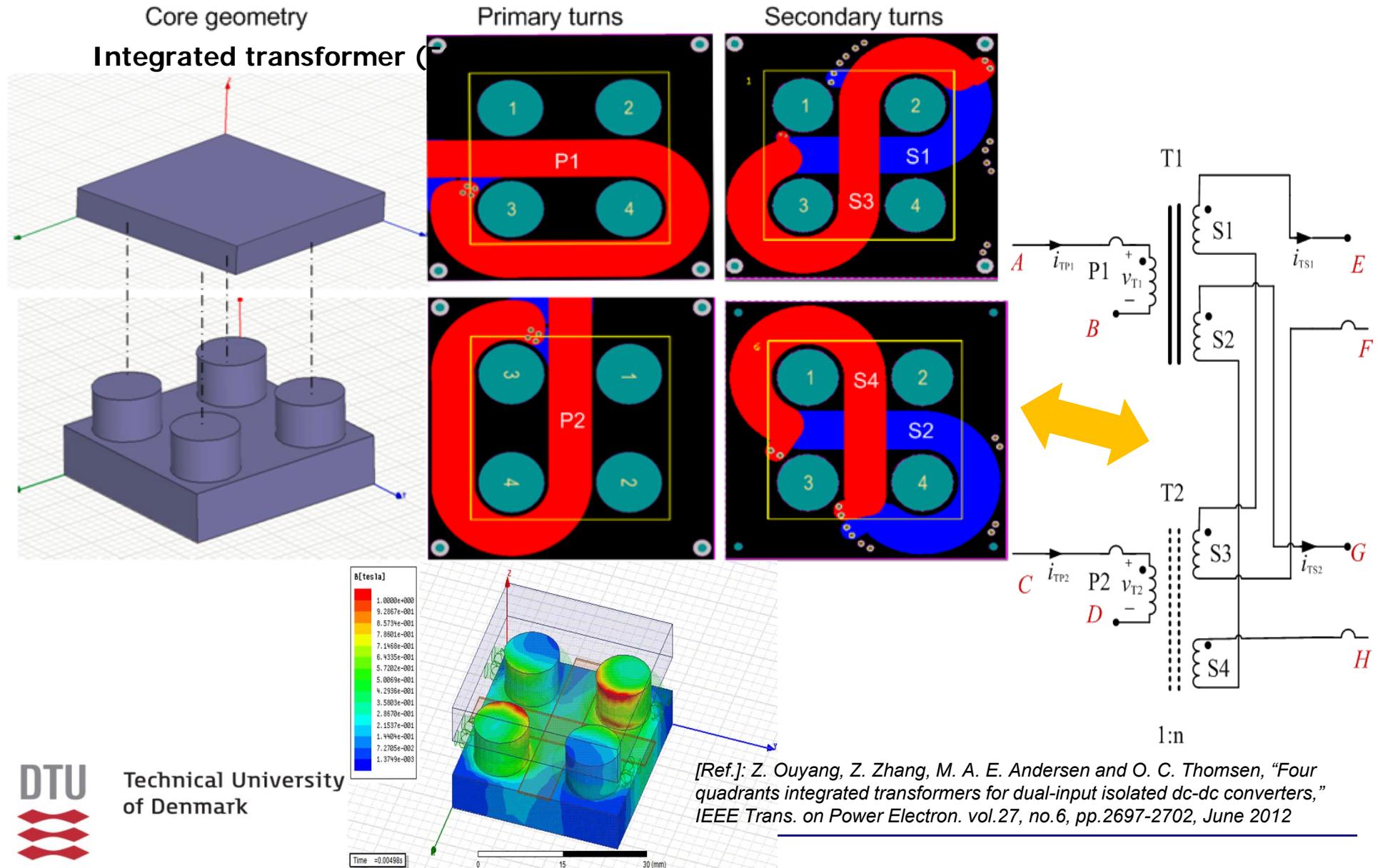


❖ Flux cancellation

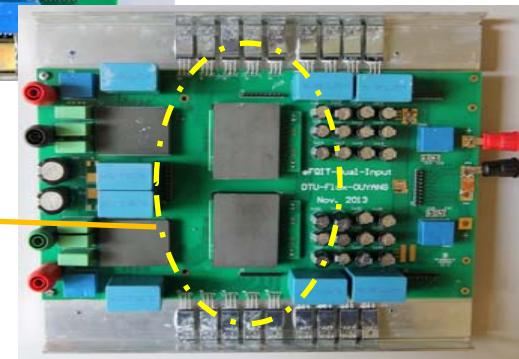
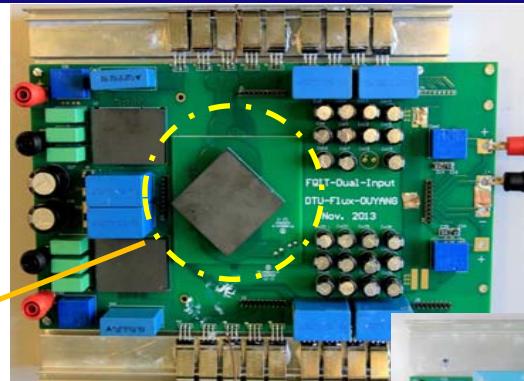
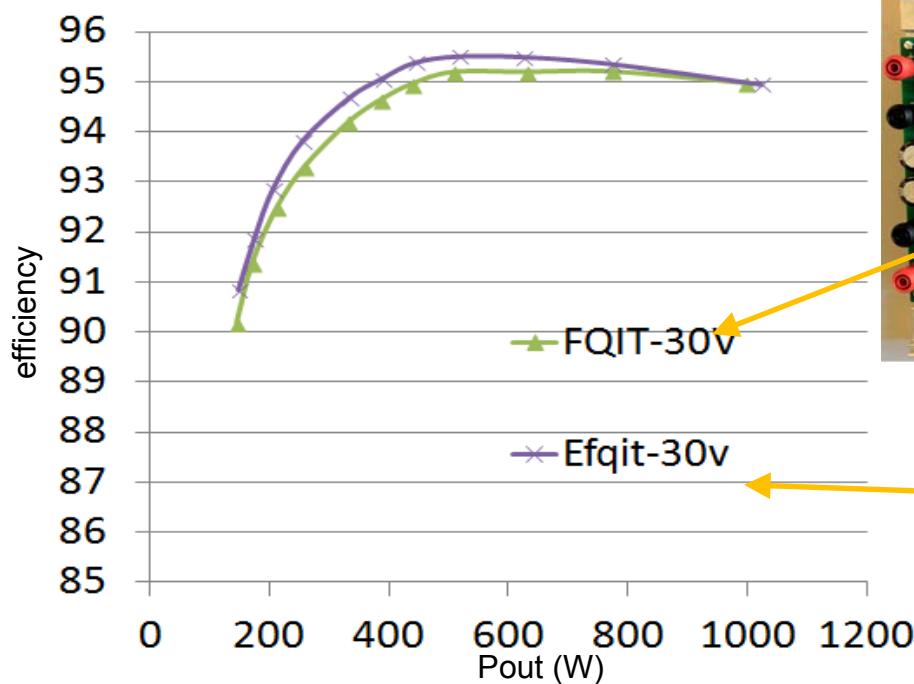


❖ Orthogonal flux path

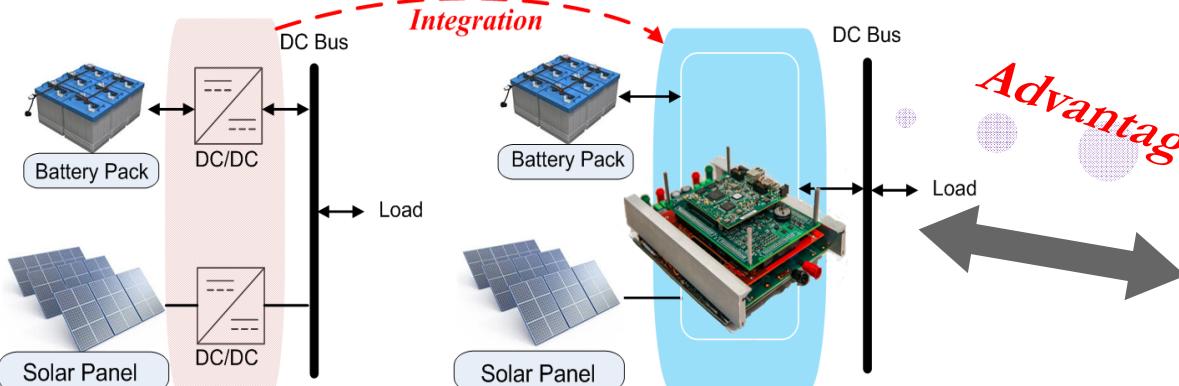




Four Quadrants Integrated Transformer

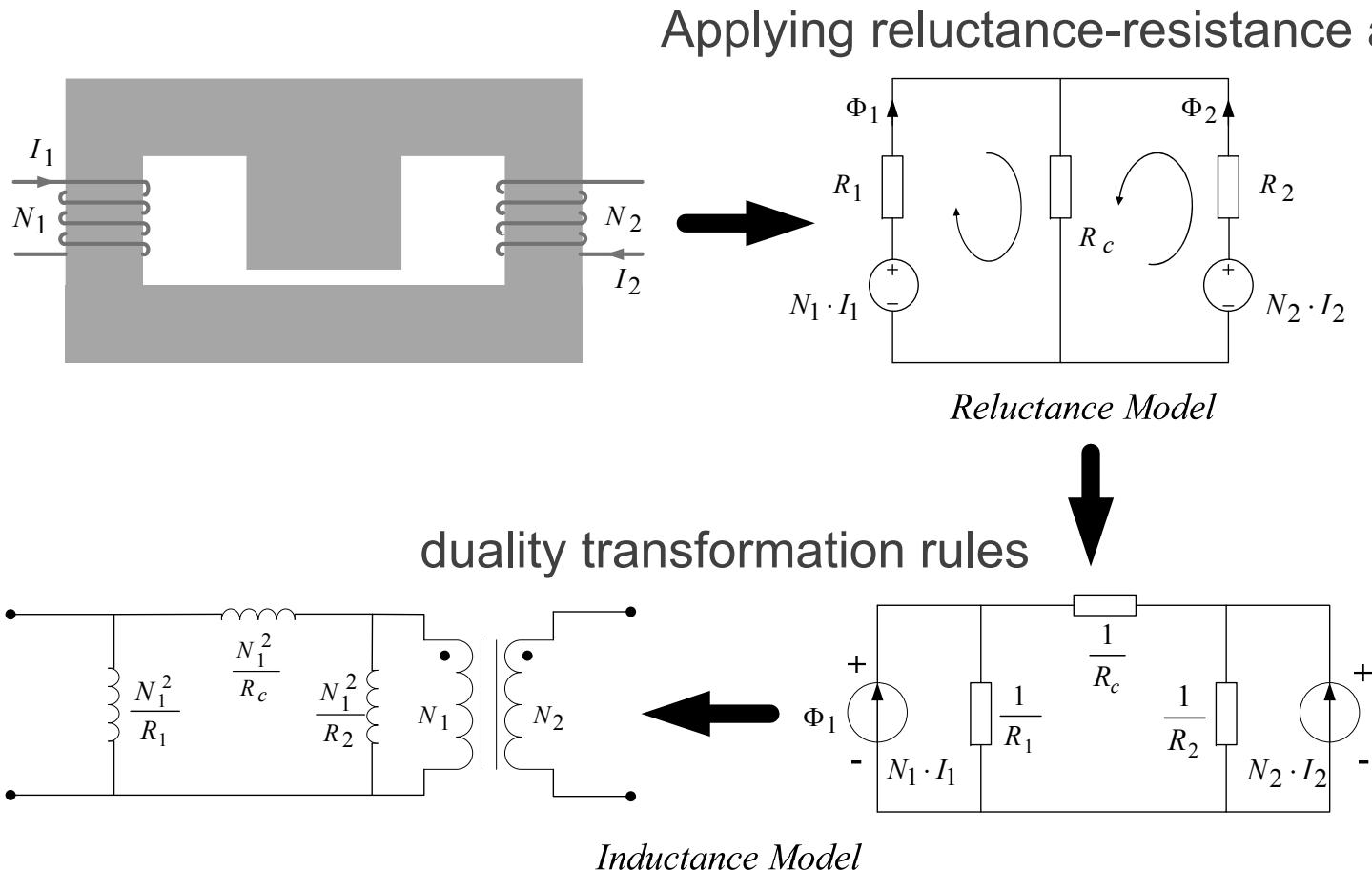


half size of
transformer



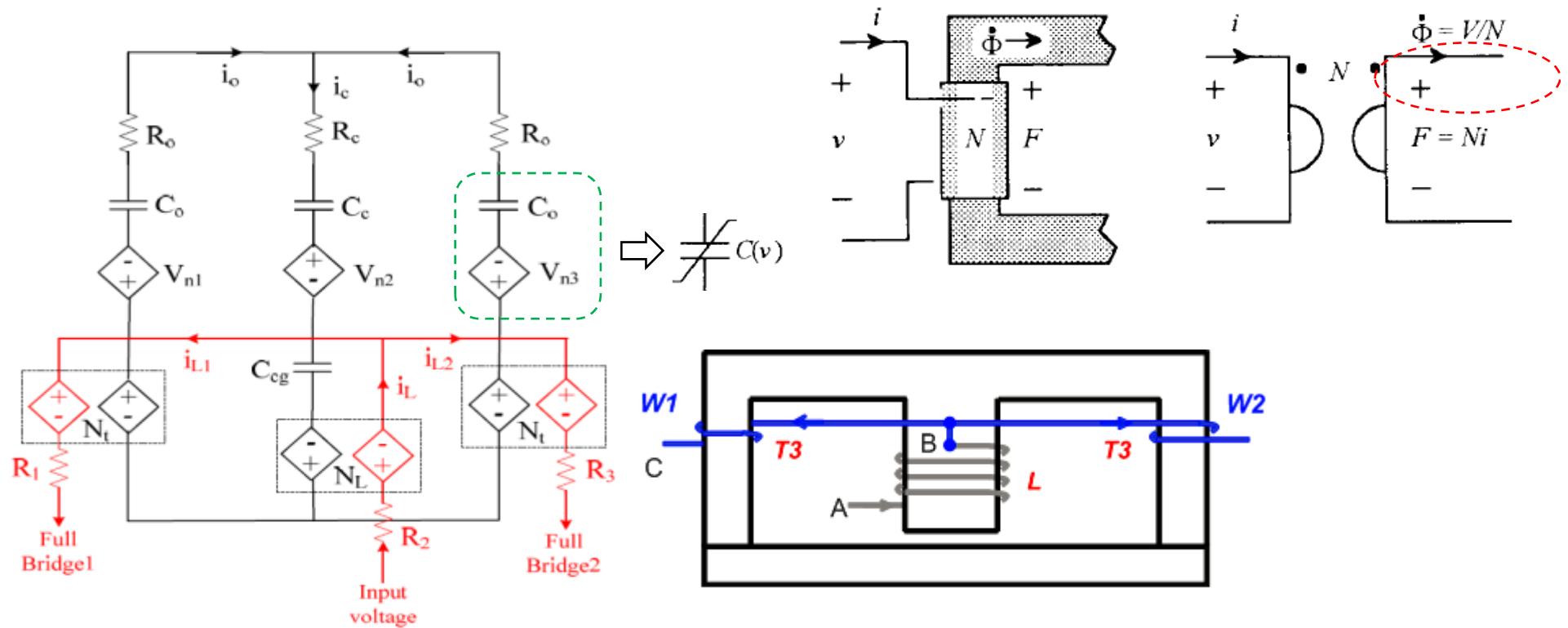
Advantages

- ✓ wide input range
- ✓ simple control and communication
- ✓ high reliability
- ✓ low overall system cost
- ✓ efficient thermal management
- ✓ compact packaging

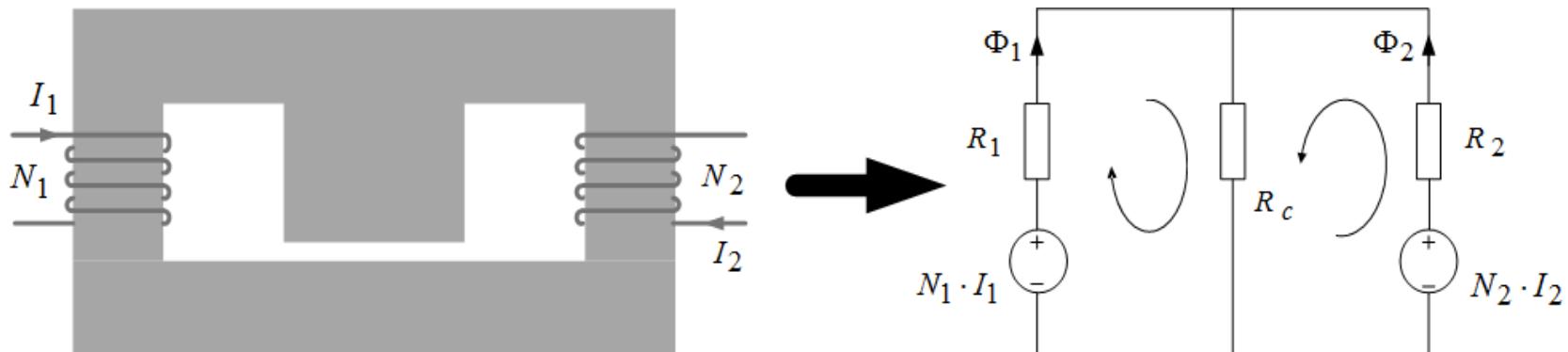


For a practical interest that the magnetic and electrical circuits interact

- ❖ Energy interchange between windings and cores
- ❖ Understand energy relations and dynamics in the context of power electronics



Applying reluctance-model:



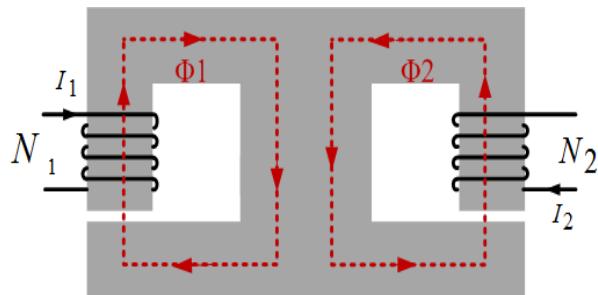
Since Kirchhoff's laws and Faraday's law,

$$\begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} \frac{N_1^2 \cdot (R_2 + R_c)}{\Delta} & -\frac{N_1 \cdot N_2 \cdot R_c}{\Delta} \\ -\frac{N_1 \cdot N_2 \cdot R_c}{\Delta} & \frac{N_2^2 \cdot (R_1 + R_c)}{\Delta} \end{bmatrix} \cdot \begin{bmatrix} \frac{di_1}{dt} \\ \frac{di_2}{dt} \end{bmatrix} = \begin{bmatrix} L_{11} & L_M \\ L_M & L_{22} \end{bmatrix} \cdot \begin{bmatrix} \frac{di_1}{dt} \\ \frac{di_2}{dt} \end{bmatrix}$$

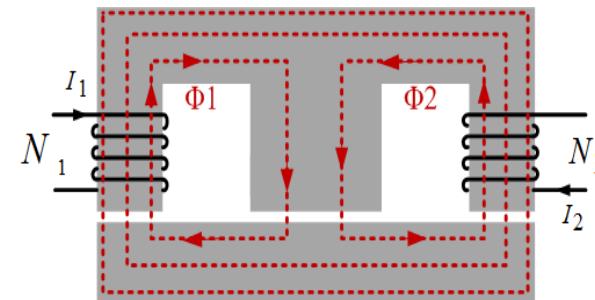
where, $\Delta = R_1 \cdot R_2 + R_1 \cdot R_c + R_2 \cdot R_c$

Coupling coefficient: (assuming $N_1 = N_2$)

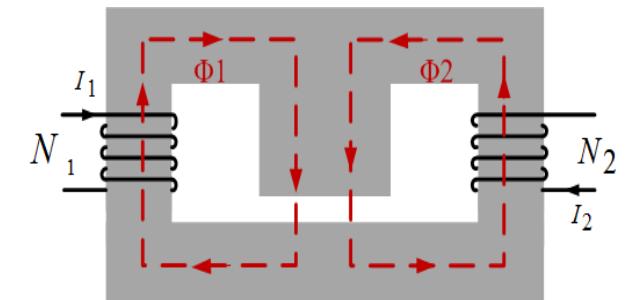
$$k = \frac{L_M}{\sqrt{L_{11} \cdot L_{22}}} \quad L_{11} = L_{22} \rightarrow k = \frac{L_M}{L_{11}} = -\frac{N_2 \cdot R_c}{N_1 \cdot (R_2 + R_c)}$$



(a)



(b)



(c)

$$R_2 \gg R_c$$

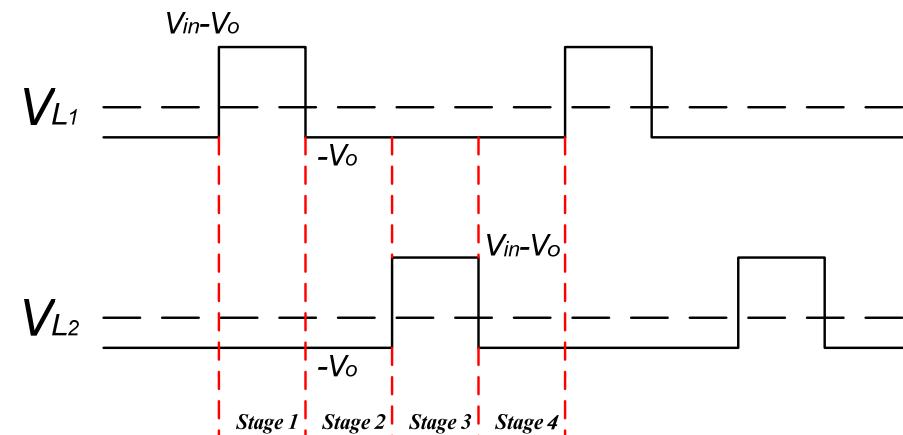
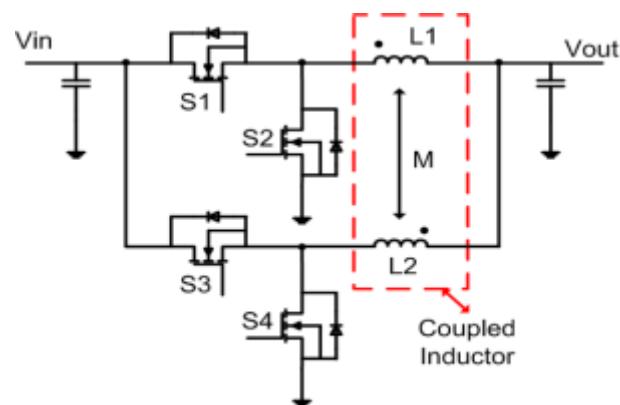
$$\downarrow \\ k \approx 0$$

$$R_2 = 2 * R_c$$

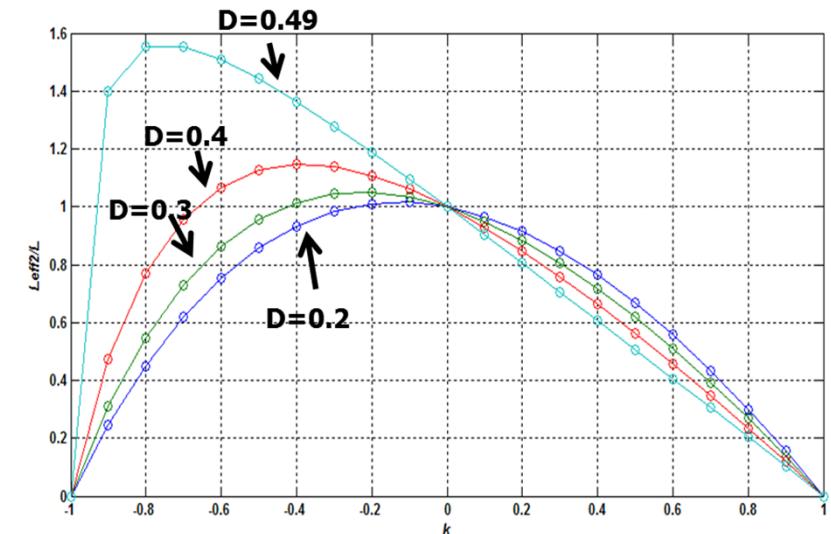
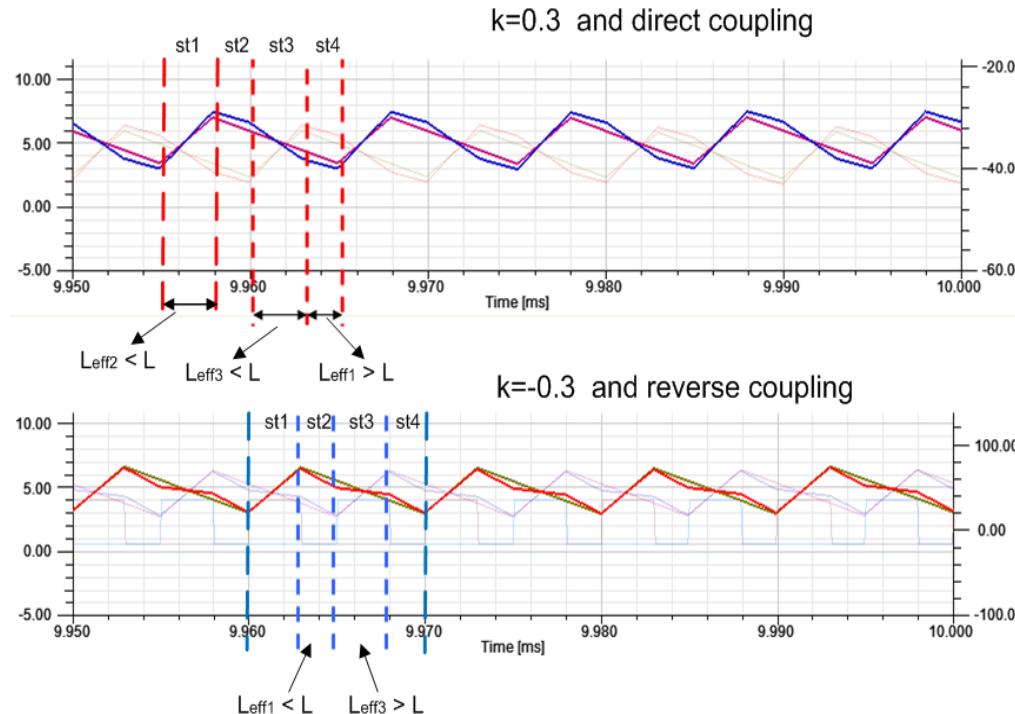
$$\downarrow \\ k = \frac{1}{3}$$

$$R_2 \ll R_c$$

$$\downarrow \\ k \approx 1$$

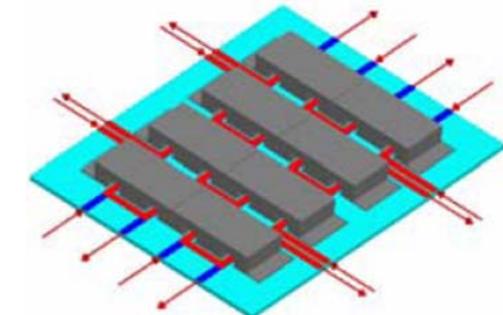
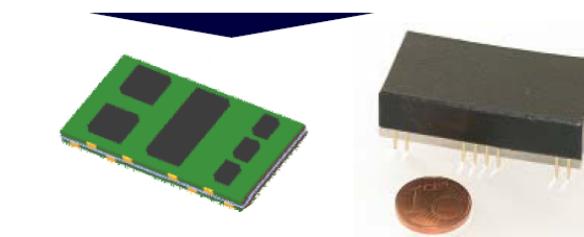
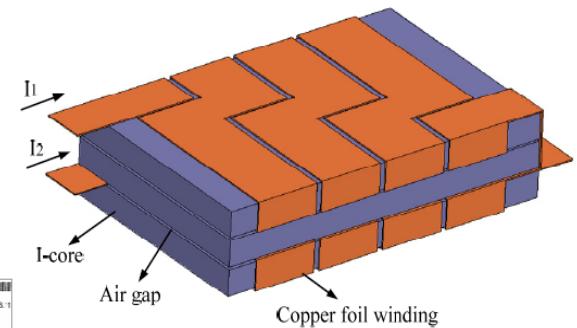
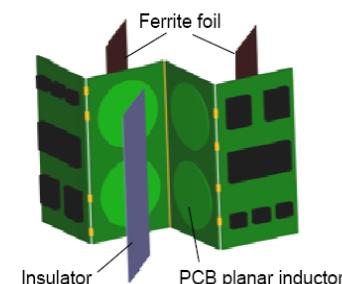
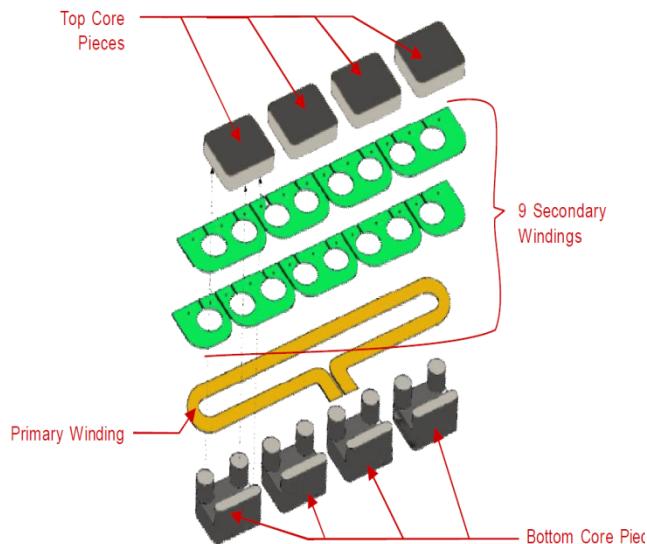


Effective inductances are dependent of circuit operation



[ref.]: P.-L. Wong, Q.-Q. Wu, P. Xu, B. Yang, and F. C. Lee,
“Investigating coupling inductors in the interleaving QSW VRM,” in
Proc. IEEE Appl. Power Electron. Conf. Expo., 2000, pp. 973–978.

- ❖ Integrated magnetics is actually an “open” technology, and may create “innovation” ideas.



Thin isolating low-power converters with folded planar transformer,
e.g. for gate drive applications (patent pending DE 10 2004 026 052)

- ❖ Integrated magnetics has advantages **less number of components, smaller size, and potentially higher power efficiency.**
- ❖ Integrated magnetics are not all advantageous. The main issue is to produce **unwanted parasitic capacitances** among the inductive elements, and a **limited power capability.**
- ❖ Must understand the principle of circuit operation.
- ❖ **New geometry core** may create something interesting.

Conclusion and Trends

- ❖ Planar magnetics still gain its popularity due to low profile and easy manufacture
- ❖ Planar magnetics towards very high frequency (so-called micro-inductor/transformer) would be interesting. Accurate 2D/3D models are emergency
- ❖ High frequency magnetic materials are emergency
- ❖ New winding and core geometries may create something innovative

Thank you very much!

Questions?