

Rubin Observatory

Vera C. Rubin Observatory
Data Management

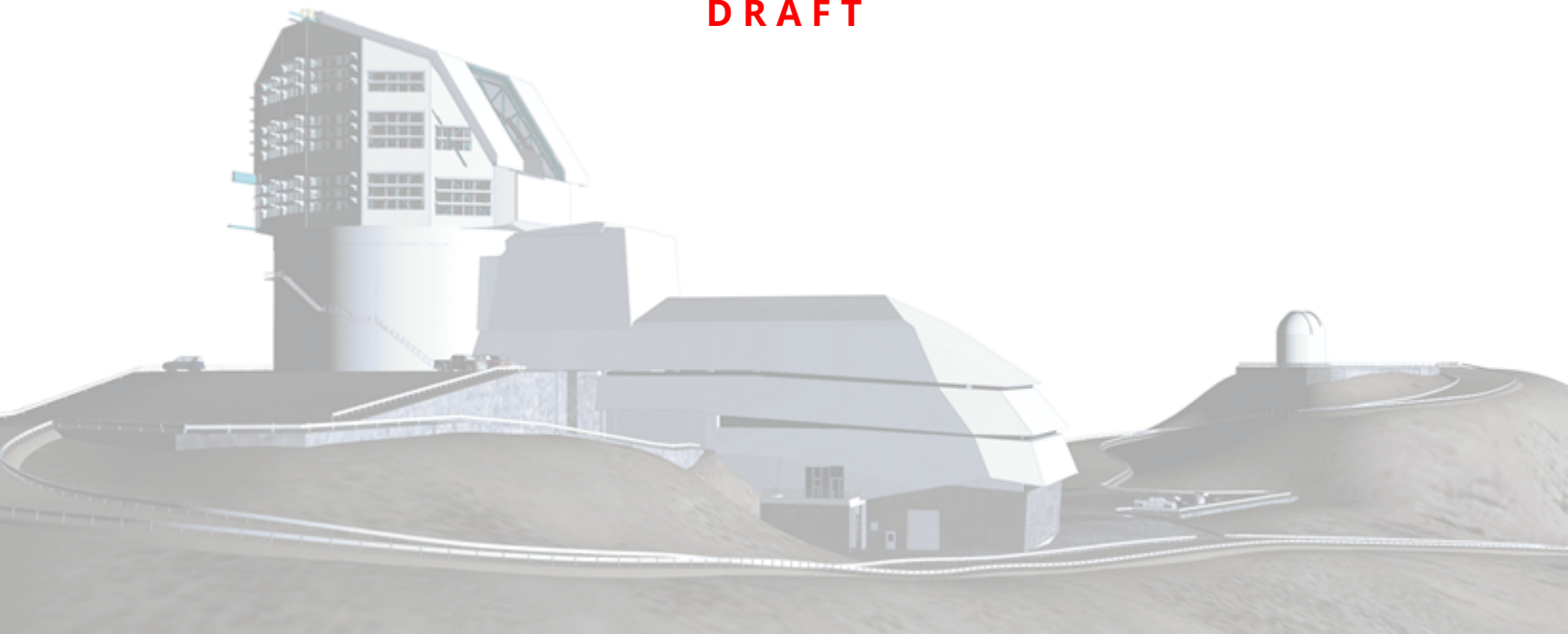
Characterizing DIASource Detection Efficiency

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DMTN-TBD

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Abstract

This document proposes that the Data Management System determine and provide detection efficiencies for DIASources using artificial source injection. The motivation for, and scientific benefits of, this proposal are provided.

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Characterizing DIASource Detection Efficiency

1 Introduction

Any astrophysical question which asks, e.g., "*How often?*" or "*How many?*" about transient phenomena, such as population studies or occurrence rates, needs to know a survey's *detection efficiency*: the probability that a source is detected (or in other words, the fraction of all sources that are detected).

Detection efficiencies are required for many of the core science pillars of the LSST, such as transient phenomena, cosmology, and Solar System studies (Appendix A). Many other surveys use populations of synthetic sources injected into the data in order to characterize the detection efficiency (Appendix A.1).

Rubin Observatory documentation contains no requirements related to producing or serving detection efficiencies for transient DIASources in difference images (Appendix B), but does contain requirements about creating source injection software and using it to characterize detected sources' *spuriousness* parameter (see Appendix C).

As described in Appendix D, leaving synthetic source injection and the derivation of LSST detection efficiencies for transients as a user-generated data product is a moderate risk to LSST science.

This risk could be mitigated with a bit of extra effort on behalf of Data Management (and/or the Rubin Data Production team in Operations) to (1) ensure the artificial sources injected in order to characterize spuriousness cover the range of parameters needed to determine detection efficiencies, and (2) generate and provide a table of detection efficiencies.

The range of parameters that should be covered, and an example use-case of the table of detection efficiencies, is provided in Section 2.

Readers should refer to the Data Products Definitions Document [LSE-163] for more information about DIA, difference images, and DIASources. Detection efficiencies of extended difference-image sources (e.g., light echoes, trailed moving objects), or for variable or static point-sources in direct images, are beyond the scope of this document.

2 Proposed Detection Efficiency Matrix

Detection: as described in the SRD and DPDD, sources in difference images with a signal-to-noise ratio $SNR > transSNR = 5$ will be considered *detected* and will become a DIASource.

Detection Efficiency: The probability that a true astrophysical source of a given magnitude is detected and becomes a DIASource. In other words, the fraction of all true astrophysical sources of a given magnitude that are detected and become DIASources.

Characterizing detection efficiency requires knowing how many sources were in the field of the image (and their brightnesses), which is only possible if “truth” is somehow known from, e.g., co-temporal imaging data of superior quality – which almost never exists because it is inefficient to duplicate data.

Instead, the detection efficiency is typically characterized by simulating and injecting synthetic sources into images, using a point-spread function shape like real astrophysical sources, and then processing the images with the survey’s difference image analysis pipeline and measuring the fraction recovered.

The detection efficiency can be characterized as $\eta(m)$, where m is the apparent magnitude of the time-changing component with respect to the template image, and η is a value between 0 and 1 that represents the probability that the source would be detected in the difference image. As described in Appendix A, η depends on more than just m , and is a function of the parameters (\vec{P}) listed in Table 1.

An accurate measure of $\eta(m, \vec{P})$ for every pixel of every difference image is technologically unfeasible. Instead, an analytic model for $\eta(m, \vec{P})$ can be built, so long as the synthetic sources cover the full range of m and \vec{P} .

As described in Appendix A, for $\eta(m, \vec{P})$ the synthetic sources do *not* need to accurately represent astrophysical transient types in terms of their colors, redshifts, host offsets, durations, light curves, etc. That aspect of the analysis is best left to the user to handle for their particular type of object, as described in Section 2.

A specific example of how users might apply $\eta(m, \vec{P})$ in their analysis is provided in Appendix A.1.3. Generally, it would involve simulating a set of light curves for the object type of interest (e.g.,

normal $0.1 < z < 0.5$ Type Ia supernovae), and then using the detection efficiency table to evaluate the fraction that would be “identified” in a given time-frame (where “identified” might have specific criteria, such as a reliable photometric classification). This is typically done as part of an MC analysis in order to marginalize over intrinsic distributions of, e.g., the brightness or host offsets of the object type of interest.

TABLE 1: A description of the image and source parameters (\vec{P}) that can affect the detection efficiency ($\eta(m)$) of point sources in a difference image (per filter).

Parameter	Description
Surface Brightness	Typically, η decreases for objects embedded in brighter host galaxies.
Static-Source Offset	Sometimes, η decreases for objects that are near (i.e., overlap the point-spread function of) static sources (e.g., stars, galaxy cores, especially if cuspy in profile).
CCD Location	With some instruments, η decreases near the CCD edges due to distortion.
Image FWHM	The value of η can decrease for extreme FWHM differences from the template (i.e., very good or very poor seeing).
Image Airmass	LSST images will experience differential chromatic refraction which affects image subtraction [DMTN-037], and thus potentially also η .
Sky Brightness	Typically, η decreases when the sky background is bright or has a strong gradient (e.g., during twilight, near the moon).
Sky Cloud Cover	Extinction will affect η by degrading the image magnitude limit.

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A Scientific Examples

Detection efficiencies are required for many of the core science pillars of the LSST, as described below. Many other surveys use populations of synthetic sources injected into the data in order to characterize the detection efficiency, as described in the examples provided in A.1.

In consideration of the scientific motivation for detection efficiencies, and what has worked for other surveys, two points are clear.

1. The population of synthetic sources injected in order to characterize the detection efficiency should have similar distributions as real astrophysical phenomena in terms of brightness and location (e.g., proximity to static-sky sources, field crowdedness, surface brightness), and the subset of images used should sample the distributions of, e.g., image quality (seeing), sky brightness, and airmass.
2. The simulated fakes do not need to accurately represent astrophysical transient types, colors, redshifts, durations, light curves, etc., or be planted in sequential images in a correlated way to represent real light curves. That aspect of the analysis is best left to the user to handle during the MC simulation stage for their particular type of object.

A.1 Transients

Transient events such as stellar explosions (supernovae, kilonovae) and tidal disruption events (TDEs; stars destroyed by close passage to a supermassive black hole) occur once and do not repeat. Since most transient progenitors are stars, they are most often found in high surface brightness environments (i.e., galaxies; their spatial distribution “follows the light”) and require difference imaging in order to be discovered, and thus detection efficiencies in order to characterize their occurrence rates.

For example, transient occurrence rates as a function of environment can constrain their progenitor star characteristics, which requires that detection biases be well known, as does understanding selection biases in transient samples (e.g., when using Type Ia supernova as cosmological standard candles).

The four surveys mentioned below have either inserted fakes into all of their live images (SDSS-II and DES) or into a representative set of images at a later time (CFHT and PTF), to ensure that detection efficiencies can be determined for the full range of image parameters. In all cases, the fakes were simulated with parameter distributions (e.g., brightness, location) that roughly mimic the real astrophysical objects of interest for each particular survey (mostly supernovae, for the above examples). Typically, the MC method was then used to simulate light curves for the transient of interest, and then the derived detection efficiencies were applied.

The take-away message is that, for Rubin Observatory to best serve a broad section of the transient community, the simulated population of fake sources need only be representative of true astrophysical sources in a bulk sense, in terms of their brightness and location (i.e., plant more faint sources than bright, and more in high surface-brightness areas than isolated regions). The simulated fakes do not need to accurately represent astrophysical transient types, colors, redshifts, durations, light curves, etc., or be planted in sequential images in a correlated way to represent real light curves. That aspect of the analysis is best left to the user to handle during the MC simulation stage for their particular transient type.

A.1.1 Sloan Digital Sky Survey II (SDSS-II)

In order to calculate the occurrence rates of Type Ia supernovae (SNe Ia) from the SDSS-II, [20] generated a realistic sample of SNe Ia and injected fake point sources into the images as part of the live data processing pipeline to discover SNe Ia. Additional simulations to evaluate on how often the fakes were recovered by the end-to-end SN Ia discovery pipeline were then required to evaluate how assumptions about the simulated population (e.g., the distribution of light curve stretches) contributed to the final uncertainty in the derived rates [5]. The final form of their derived detection efficiency for SNe Ia was $\epsilon(z) = (0.78 \pm 0.01) + (-0.13 \pm 0.14)z$, within which is captured assumptions about the true relative fraction of each SN Ia subtype, such as the under/over-luminous 91bg/91T-likes [5]. The detection efficiency, ϵ , contributed to the final volumetric rate, $r_V = N/\widehat{VT}\epsilon$, where N is the number of SNe Ia detected, and $\widehat{VT}\epsilon$ is the product of the effective survey volume, time, and detection efficiency.

A.1.2 Dark Energy Survey (DES)

In order to determine the SN Ia detection efficiency as a function of redshift, the DES team used a method very similar to SDSS-II: fake sources were injected into their live data, which was run through their real-time DiffImg pipeline used to detect transients [17]. This process also started by simulating a realistic sample of SNe Ia, with parameters such as light curve stretch, host offset, and subtype drawn from established underlying distributions, and then used a Monte Carlo simulation of many more SN light curves, combined with the detection efficiencies for their fakes, to determine the SN Ia detection efficiency as a function of redshift.

A.1.3 A Canada-France-Hawaii Telescope (CFHT) Cluster Survey

In order to calculate the occurrence rate of SNe Ia in galaxy clusters for a CFHT imaging survey, [21] performed DIA to detect SNe in real time, but the fake injection was done separately. Simulated point sources were implanted into a representative subset of their images, and detection efficiencies calculated as a function of the relevant parameters for this survey: apparent magnitude, image quality, and focal plane location (because the survey used single pointings with only small dithers). Their expression for the rate of Type Ia supernovae per unit stellar mass is $R_{\text{Ia}} = (N_{\text{Ia}}/C_{\text{spec}})/(\sum_{j=1}^{j=N_{\text{img}}} \Delta t_j M_j)$, where N_{Ia} is the number of SNe Ia discovered in the survey, C_{spec} is the spectroscopic confirmation rate (determined separately), the denominator's sum is over all images of the survey, M_j is the total stellar mass within the image, and Δt_j is the control time for SNe Ia of that image. The control time is expressed as $\Delta t = \int_{t_1}^{t_2} \eta(m(t)) dt$, where $m(t)$ is a SN Ia light curve, η is the detection efficiency, and the integration limits are the survey's temporal boundaries.

The Monte Carlo method was then used to calculate R_{Ia} for the survey many times while sampling over a realistic distribution of SN Ia light curve properties for $m(t)$ and the errors in N_{Ia} , M_j , and *etc.* During this MC, an *effective* detection efficiency was used, which accounts for the possibility that the simulated SN Ia was detected in the previous two images: $\eta = \eta_j - \eta_j \eta_{(j-1)} - \eta_j \eta_{(j-2)} - \eta_j \eta_{(j-1)} \eta_{(j-2)}$ (as was appropriate for this survey's monthly cadence). The final result was quoted as the median of the MC rates with 1σ errors. A similar methodology was applied to this survey's cluster SNe II in [11].

A.1.4 Palomar Transient Factory (PTF)

The PTF covered 8000 square degrees with a three-to-five day cadence and generated over 1 PB of data. As detailed by [8], inserting fake sources into all of these images was both impractical and unnecessary. Instead, they chose a single representative *field* and planted fake sources in all images of that field. The fakes were given a uniform distribution in apparent magnitude, distributed in each image such that most of them are located within a galaxy, and then the PTF detection efficiencies were determined as a function of the apparent magnitude, the local surface brightness, and image parameters such as FWHM, airmass, moon illumination fraction, and sky background. These detection efficiencies were used to derive the volumetric rate of normal SNe Ia [10], of Ca-rich transients by [9], and of tidal disruption events (TDEs) by [13]. However, note that some rates analyses for TDEs have used aperture photometry and not difference imaging, and thus did not need fake injection for difference-image detection efficiencies (e.g., [12]).

A.2 Active Galactic Nuclei

Active Galactic Nuclei (AGN) are powered by a supermassive black hole in the center of a galaxy, surrounded by a gas disk. Their energy output is non-thermal emission from X-ray through to mid-infrared, including emission lines in the optical spectrum, and many (or most) AGN exhibit optical variability. As such, they appear as a variable point source in the cores of galaxies. Many studies of AGN use aperture photometry on direct images, and not difference imaging, because it is desirable to have the *entire* flux of the AGN's point source, not just the flux in its variable component.

AGN samples have typically identified using spectroscopic emission lines, optical colors, or by looking for excesses of radio, X-ray, or mid-infrared emission, but selection by optical variability is also an option and in particular it may be better at including low-luminosity AGN, as described by [e.g., 24, 25]. The detection method of [24] uses image subtraction for the initial detection of AGN candidates, mainly because difference imaging was already done to find supernovae in the survey. Aperture photometry is then performed on the candidates, and a variability threshold applied to form their final sample for spectroscopic follow-up. [25] skip the difference imaging step and use aperture photometry and a statistical analysis true variability to identify AGN. Neither use the injection of fake point sources to evaluate their detection efficiencies, and instead use objects with spectra and/or X-ray detections to esti-

mate their completeness. However, using spectra or X-ray to characterize the sample selection function of AGN identified by optical variability might not be possible in the LSST era, when optical variability becomes a more efficient and prolific way to discover a AGN [e.g., 2], generating significantly larger, lower-luminosity, and/or higher-redshift samples, for which spectroscopic confirmation is more difficult.

Furthermore, TDE and SNe also occur in the cores of galaxies [e.g., 19, 16], causing contamination of the AGN samples, and quantifying the rate of missed transients in the cores of galaxies remains an open problem.

Considering the needs of the AGN, TDE, and SN communities suggests that a population of fake injected transients to characterize the difference-image detection efficiency of point sources in galaxy cores would be scientifically beneficial.

A.3 Variable Stars

A star's luminosity might exhibit intrinsic variability (e.g., RR Lyrae, Cepheids) and/or extrinsic variability (e.g., eclipsing binaries, exoplanet transits, or microlensing events). In uncrowded fields, using direct images and the total flux is preferable to difference-imaging analysis for scientific studies that aim to identify and characterize variable stars. However, in crowded fields such as the Galactic plane, identifying variable stars in difference images can be much easier because the difference image is not as (or not at all) crowded, compared to the direct image.

For example, the census of variable stars in crowded fields by [7] describes how difference imaging is used, although it does not appear that injecting fake sources or deriving detection efficiencies was needed for their analysis.

It also seems that difference-image detection efficiencies are not needed for microlensing studies, for which it is a common methodology to fit a PSF to every pixel of a difference image, concoct a "light curve", and then statistically assess whether it is consistent with the expected shape of a microlensing event [18]¹.

Despite difference-image detection efficiencies not playing a role in past variable star studies,

¹Although [18] does mention that detection efficiencies would be used in a paper in preparation.

they might still be needed for LSST analyses. For example, injecting new fake sources in crowded stellar fields might be useful for detection efficiencies for stars which are too faint to have a counterpart in the template, but whose variable component makes them detectable by LSST for a short while. This would apply to e.g., M-dwarf flares (a common contaminant in searches for young SNe) and microlensing events.

Simulating variability of stars that *are* present in the template image is beyond the scope of this document.

A.4 Moving Objects

All of the moving objects identified by LSST will first be detected as difference-image sources, and detection efficiencies would be useful for population studies. In epochs of non-detection, being able to obtain the detection efficiency at a predicted location (i.e., as a function of local surface brightness and image qualities) would be a useful quantity for science goals related to moving object populations. The probability of, e.g., a faint asteroid's chance alignment over bright galaxies is small, and so fake injected point sources in empty locations may be more useful for moving object science — these would be needed to simulate very high-redshift transients, as well.

A consideration of whether the injection of trailed sources is scientifically useful is left for other work.

B Requirements Review

There are no requirements related to producing or serving detection efficiencies for transient DIASources in difference images.

However, the SRD specifies the definition for “detection” as $SNR > 5$, the OSS specifies that spuriousness characterization be done “*by insertion and recovery of artificial sources*”, and the DMSR specifies that *software* for fake injection is a deliverable of the DMS (§ B.3). These specifications suggest that use of artificial source injection to determine a detection efficiency matrix for transient DIASources would not require a large expansion of scope for DM.

The DPDD and LPM-151 also contain some discussion relevant to detection efficiencies.

As a final note, the DMS computational system is sized to accommodate the (re)processing of all images with fake sources implanted (**from KT**).

B.1 Science Requirements Document (SRD, LPM-17)

The SRD [LPM-17], V5.2.4 (Jan 30 2018), does not contain any requirements related to detection efficiencies.

The SRD does describe how the Prompt pipeline should provide “*the fast release of data on likely optical transients will include measurements of position, flux, size and shape, using appropriate weighting functions, for all the objects detected above transSNR signal-to-noise ratio in difference images*”, where $\text{transSNR} = 5$ (page 41).

The SRD thus specifies that all sources with $SNR \geq 5$ in a difference image are considered “detected”, and it is the efficiency (or completeness) of detected transients (i.e., new sources which were not present in the template) that this document is concerned with.

B.2 Observatory System Specifications (OSS, LSE-30)

The OSS [LSE-30], V19.1 (July 30 2021) does not contain any requirements related to the determination of detection efficiencies.

However, it does contain several specifications related to characterizing the spuriousness (also referred to as the “real/bogus” parameter), completeness, and purity of LSST sources detected in difference images. See Appendix C for a description of these terms.

The “insertion and recovery of artificial sources” that are mentioned as a means towards achieving requirements 0351, 0353, and 0354 could also be used to determine detection efficiencies.

- OSS-REQ-0351, *Difference Source Spurious Probability Metric*, specifies that “the Observatory shall develop a metric to characterize the probability of each reported difference source being spurious” (Section 3.1.5.2.1.7.5). The discussion further clarifies that “the performance of this metric will be assessed by simulations, by insertion and recovery of artificial sources, and comparisons to ground truth where known”. OSS-REQ-0351
- OSS-REQ-0352, *Difference Source Sample Completeness*, specifies that “for each visit, the Observatory shall estimate the detected difference source sample completeness and purity as a function of the spuriousness metric threshold cut” (Section 3.1.5.2.1.7.6). The discussion further clarifies that “this information will aid the end users in selecting the spuriousness threshold appropriate for their particular science case”. OSS-REQ-0352
- OSS-REQ-0353, *Difference Source Spuriousness Threshold - Transients*, specifies that “there shall exist a spuriousness threshold τ for which the completeness and purity of selected difference sources are higher than `transCompletenessMin` (90%) and `transPurityMin` (95%), respectively, at the SNR detection threshold `transSampleSNR` (6). This requirement is to be interpreted as an average over the entire survey” (Section 3.1.5.2.1.7.7). As for OSS-REQ-0351, the discussion further clarifies that “the performance of this metric will be assessed by simulations, by insertion and recovery of artificial sources, and comparisons to ground truth where known”. OSS-REQ-0353
`transCompletenessMin`
`transPurityMin`
`transSampleSNR`
- OSS-REQ-0354, is similar to OSS-REQ-0353 but defines a threshold for moving objects. OSS-REQ-0354

Regarding spuriousness, the discussion for OSS-REQ-0351 further describes that the “spuriousness metric be prior free to the extent possible. For example, while it may make use of information from the source and image characterization (e.g., comparison of source to PSF morphology), as well as the information on the Telescope and Camera system (e.g., ghost maps, defect maps, etc.), it will not use any information about the astrophysical neighborhood of the source, whether

it has been previously observed or not, etc. The intent is to avoid introducing a bias against unusual sources or sources discovered in unusual environments".

B.3 Data Management System Requirements (DMSR, LSE-61)

The DMSR [LSE-61], V9.0 (Feb 12 2021) does contain a few statements relevant to detection efficiencies.

- DMS-REQ-0097, *"Level 1 Data Quality Report Definition"*, specifies that the Data Management System (DMS) *"shall produce ... indicators of data quality that result from running the DMS pipelines, including ... detection efficiency for point sources vs. mag for each utilized filter"* (Section 1.3.14). However, DMS-REQ-0097 is derived from OSS-REQ-0131, *"Nightly Summary Products"*, and is clearly intended to produce a nightly summary of the general performance of the observatory and the DMS, not to provide the scientifically useful detection efficiencies that are the topic of this document. DMS-REQ-0097
- DMS-REQ-0009, *"Simulated Data"*, specifies that *"the DMS shall provide the ability to inject artificial or simulated data into data products to assess the functional and temporal performance of the production processing software"* (Section 3.2.1). This requirement is derived in part from OSS requirements 0351, 0353, and 0354 discussed above. DMS-REQ-0009

B.4 Data Products Definitions Document (DPDD, LSE-163)

The DPDD [LSE-163], V3.6 (Dec 17 2021) is not a requirements document but does have some information relevant to detection efficiencies.

Table 1 lists a single float is also reserved for SNR in the DPDD's DIASource table, defined as the *"signal-to-noise ratio at which this source was detected in the difference image"*.

Table 1 also lists a single float is reserved in the DIASource table for the spuriousness parameter. The DPDD's definition and description of spuriousness match the OSS requirement (i.e., this is a direct flow-down of OSS-REQ-0351). OSS-REQ-0351

The DIASource catalog table has three other relevant parameters listed that might be scientifically useful for analyses involving detection efficiencies:

- `psLnL [float]` – *Natural log likelihood of the observed data given the point source model.* This represents the probability that a detected source is a point source; detection efficiencies would not apply to non-point sources.
- `fpBkgd [float] nJy/asec2` – *Estimated background at the position (centroid) of the object in the template image.* This will be useful to provide detection efficiencies in difference images as a function of the background at that location.
- `fpBkgdErr [float] nJy/asec2` – *Estimated uncertainty of fpBkgd.* Useful in the same way as fpBkgd.

B.5 Data Management Science Pipelines Design (LDM-151)

LDM-151, V4.3 (Nov 10 2020), details the scientific design and implementation of the requirements set by the SRD, OSS, and DMSR, and the generation of the data products described in the DPDD.

Section 3, “Alert Production”, states that “*In this document we do not address estimation of the selection function for alert generation through the injection of simulated sources. Such a process could be undertaken in batch mode as part of the DRP.*”

However, LDM-151 does make two relevant statements about the spuriousness parameter which describe how the real-bogus algorithm will likely “*be based on a trained random forest classifier ... conditioned on the image quality and airmass*” (Section 3.2.4) and that it “*may use machine learning on other measurements or pixels*” (Section 6.7.2).

C A Primer on Spuriousness (Real/Bogus)

The completeness, purity, and spuriousness of samples of detected sources are all related to detection efficiencies.

When source detection is performed on a difference image, both true astrophysical sources and artifact sources can be detected with $SNR > transSNR = 5$ and become DIASources. Examples of artifacts include, e.g., sources caused by telescope hardware, or incompletely removed cosmic rays (despite the fact that cosmic rays are real astrophysical messengers).

Spuriousness (S): a parameter, typically between 0 and 1, which represents the probability that a source is astrophysical (values closer to 1) or artifact (values closer to 0).

The spuriousness is sometimes also called the *real/bogus score*. It is typically determined by machine learning on many sources that were pre-classified as astrophysical (real) or artifact (bogus), and usually considers factors like the shape of the point source in the difference image (e.g., symmetry, sharpness).

Spuriousness Threshold (τ_S): a lower limit on spuriousness, S , which can be applied to DIASources to separate the "real" from the "bogus", and to thereby obtain a subset of DIASources with a lower fraction of artifacts.

The following definitions describe the classification of detected DIASources, which were either truly real (astrophysical source) or truly false (artifact), as real or bogus by an applied spuriousness threshold τ_S :

- True Positive (TP) A detected astrophysical source that was classified as real.
- False Positive (FP) A detected artifact that was classified as real.
- True Negative (TN) A detected artifact that was classified as bogus.
- False Negative (FN) A detected astrophysical source that was classified as bogus.

Completeness (C): the fraction of all detected astrophysical sources which are classified as real. This is also called the true positive rate, $TPR = \frac{TP}{TP+FN}$.

Purity (P): the fraction of all detected sources that were classified as real which are astrophysical in nature: $\frac{TP}{TP+FP}$. This is also called the *precision* or the *positive predictive value (PPV)*.

of a survey.

The false positive rate² is the fraction of all detected sources that were classified as real but which are artifacts: $FPR = 1 - PPV = \frac{FP}{TP+FP}$.

The relationship between the completeness and purity of a sample of DIASources classified as real can be traced out by varying τ_S .

In Figure 1 we show, as an example, the relationship between the false positive rate (FPR ; purity) and the missed detection rate (MDR ; completeness) for different types of source classification (i.e., real/bogus) algorithms from the Palomar Transient Factory [PTF; 1]. This relationship is formally known as the Receiver Operating Characteristic (ROC) curve when it is plotted as the true positive rate vs. the false positive rate for a given transSNR.

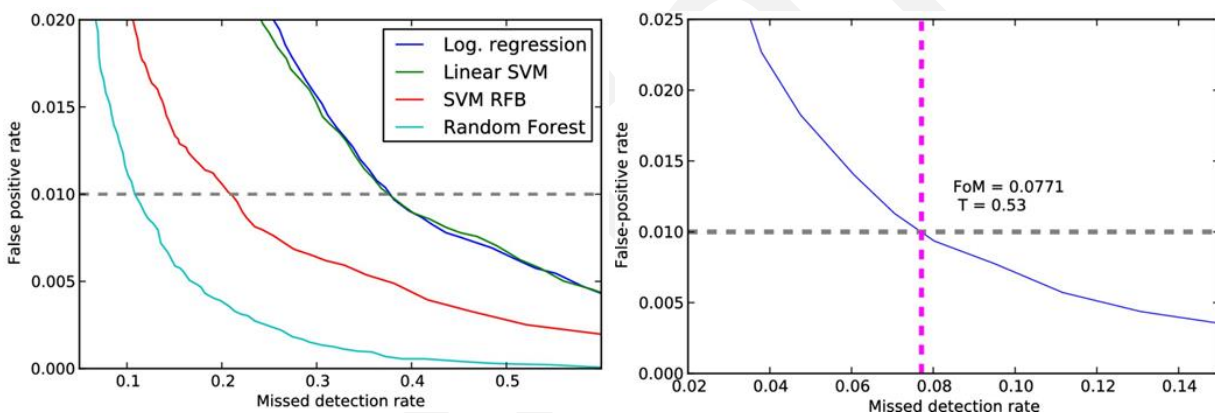


FIGURE 1: *Left:* An example of the relationship between the false positive rate (FPR ; purity) vs. the missed detection rate (MDR ; completeness) for different types of source classification (real/bogus) algorithms considered by the Palomar Transient Factory [1]. *Right:* The relationship between FPR and MDR for the RB2 (real-bogus version 2) classifier (blue line) developed by the PTF and introduced in [1]. Dashed lines show how $FPR = 0.01$ is achieved with a spuriousness (real-bogus score value) threshold of $\tau = 0.53$, which results in $MDR = 0.077$.

Characterizing spuriousness requires knowing which of the detected DIASources are astrophysical (truly real) and which are artifacts (truly bogus). Synthetic source injection is best for simulating astrophysical (real) sources because artifacts (bogus) can be a very diverse group; source injection cannot reveal which DIASources in an image are artifacts. Instead, characterizing spuriousness is achieved by building a training set of point sources that have been confirmed as astrophysical and artifact, using that training set for the spuriousness (S ; re-

²Note that in some published literature the false positive rate is instead defined as the fraction of all detected artifacts that were classified as real, $FPR = \frac{FP}{TN+FP}$.

al/bogus) assignments by the machine learning algorithm. Then, since $transSNR \propto m$, the ROC curve yields $C(m, \tau_S)$ and $\mathcal{P}(m, \tau_S)$.

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D Options Regarding Detection Efficiencies

Options are discussed in terms of the DM effort they require, the risks involved, and the science impact.

The option in D.4, which requires a bit of extra DM effort to (1) ensure that the artificial sources synthesized and injected into images in order to characterize spuriousness cover the parameters needed for scientific analyses, \vec{P} (Table 1), and (2) to generate and provide a table of detection efficiencies, would moderately benefit LSST science.

D.1 Do Nothing

The science community would have access to only the software for synthetic source injection (DMS-REQ-0009, B.3).

DM Effort – None.

Risk – Major. Multiple user groups may then attempt wide-scale source injection and image re-processing, leading to redundant use of limited computational and human resources.

Science Impact – Negative. Lack of detection efficiencies might prohibit science investigations of transient phenomena, Solar System objects, and cosmology, or limit them to research groups able to put effort towards deriving detection efficiencies.

D.2 Make Available the Artificial Sources Use for Spuriousness Characterization

In this scenario, the science community would be given access to the tables of the synthetic sources that are injected into imaging data in order to meet the requirements to characterize the spuriousness parameter (OSS-REQ-0351, B.2).

For example, this might take the form of a DIASource-like catalog for the synthetic point sources (without the $SNR > 5$ restriction), which users could bin by the \vec{P} relevant to their science and generate $\eta(\vec{P})$. Since the current OSS requirements are to characterize the relationship between spuriousness and sample completeness *only as a function of visit image*

qualities for DIASources with $\text{SNR} > 5$ (§ B), this scenario does not guarantee that these artificial sources would be adequate for all science use-cases.

DM Effort – Minor. E.g., ingesting the synthetic source catalogs to qserv or the Butler.

Risk – Moderate. It is unlikely that the synthetic sources injected for spuriousness characterization would adequately cover \vec{P} . The DM effort to release the tables might not be worth it.

Science Impact – Minor Benefit. Allowing users to build detection efficiency matrices from the same artificial sources as are used to characterize spuriousness might enable some scientific analyses.

D.3 ... And Optimize the Artificial Sources for Detection Efficiencies

This scenario builds on the above, adding a bit of extra effort dedicated to ensuring the simulated sources that are injected and recovered in order to meet the requirements to characterize the spuriousness parameter cover the parameters needed for scientific analyses, \vec{P} , as listed in Table 1.

DM Effort – Minor. E.g., the extra time and effort to ensure the synthetic sources cover an adequate range of parameter space, \vec{P} (plus the effort described above).

Risk – Minor. With sufficient effort to make sure the synthetic sources are broadly useful, DM's efforts here would be worth it and be likely to benefit science.

Science Impact – Moderate Benefit. Allowing users to build detection efficiency matrices from a scientifically-validated set of artificial sources would enable more scientific analyses.

D.4 ... And Generate and Provide Detection Efficiencies

This scenario builds on the above, adding a bit of extra effort to generate and provide the detection efficiency matrix, $\eta(\vec{P})$.

DM Effort – Moderate. E.g., the extra time and effort to generate the detection efficiency matrix and provide examples of how to use it (plus the efforts described above).

Risk – Minor. It is very likely that this goal would be achievable and that this effort would be successful.

Science Impact – Moderate Benefit Enables everyone in the science community to engage in the many different types of scientific analyses that require detection efficiencies.

D.5 Further Considerations

Detection efficiencies should be generated on an annual timescale. – The characterization of detection efficiencies is something that could (and should) only be done as part of the Data Release processing, on an annual timescale. Generally, the science investigations that require detection efficiencies would be done with the Data Release DIASource catalog because they require a well-defined sample, and the Prompt DIASource catalog will be constantly growing. If needed, the DR-derived detection efficiencies could be used on the Prompt data products for the following year.

Separate Image Processing Required – This may seem obvious, but: although some past surveys have injected synthetic sources into their raw data, allowing them to only process their images once and to conserve their total computational budget, this is not feasible for the LSST due to its wide variety of science use cases for the processed images and the high risk involved in contaminating the data.

In order to generate detection efficiencies, artificial sources do not need to be injected into *every* LSST image, only a representative sample.

Avoid Contamination – Artificial sources should not be injected at random locations because it is important to sample regions with higher surface brightness and to avoid the locations of known DIAObjects. If 1000 artificial sources are assigned random locations and injected into a 3.2 Gp image, and we assume that image has 10000 (randomly-distributed) true sources in it, then the probability that none of the artificial sources are coincident with one of the true sources is 0.9968. However, over a full night of 1000 visits, the probability that none of the artificial sources ever landed on a true source in any image is 0.0437, and it is most likely ($P = 0.2218$) that 3 artificial sources would have interfered with true sources.

E Artificial Source Injection Techniques

Describing the technique for artificial source injection that the LSST Science Pipelines will use is left for the Data Management Science Pipelines Design document, [LDM-151].

Typically, artificial sources are added to the direct image *before* that image enters the difference imaging pipeline, so that the detection efficiency captures the end-to-end pipeline efficiency for detecting difference-image sources.

Model PSF – A 2D model for the PSF is added to the direct image in order to simulate a new point source. The shape of the PSF is derived from known trends with, e.g., the focal plane location or airmass (DCR), and the brighter/fatter effect.

Clone-Stamping – A nearby star is cut out and rescaled, and used as the simulated point source. One of the main drawbacks of using clone-stamping with LSST images is that incorporating the brighter/fatter effect into the simulation requires either that a star which is both nearby and of a similar brightness be used or that a model component added to the clone star to appropriately change the shape for the simulated brightness. Another drawback of clone-stamping is that very sparse/crowded fields might not have enough nearby/isolated point sources to use.

Techniques to simulate the variability of real astrophysical objects, such as stars with a time-variable component, are considered beyond the scope of this document.