

```
[08:03:13] [2022-02-14] exit()
[07:56:12] [2022-02-14] umv(ucryox, 400)
[07:55:41] [2022-02-14] umv(ucryox, 300)
[07:55:37] [2022-02-14] NameError: name 'ucryox' is not defined
[07:55:37] [2022-02-14] umv(ucryox, 300)
[07:55:17] [2022-02-14] wmv(ucryox)
[07:49:25] [2022-02-14] umvr(ustrx, 10)
[07:49:13] [2022-02-14] sc()
[07:48:43] [2022-02-14] umv(ubsy, -100, ucryoy, 150)
[07:48:26] [2022-02-14] umvr(ucryox, 5)
[07:48:02] [2022-02-14] umvr(ubsx, 10)
[07:45:14] [2022-02-14] umv(udetx, -250)
[15:46:25] [2022-02-12] sc()

[11:59:10] [2022-02-12] Starting KmapActor

dataset: holder2_roi12563_14349.h5

steps_x: 200

steps_y: 75

step_size_x: 2.0

step_size_y: 2.0

dwell: 0.1

energy:

[11:59:01] [2022-02-12] Dataset roi12562_14341 (holder2) has been sent to archive. files=8 size=15565811580 bytes
[11:59:01] [2022-02-12] Dataset roi12562_14341 (holder2) has been stored into ICAT successfully

[11:39:33] [2022-02-12] Starting KmapActor

dataset: holder2_roi12562_14341.h5

steps_x: 100

steps_y: 100

step_size_x: 2.0

step_size_y: 2.0

dwell: 0.1

energy:

[11:39:09] [2022-02-12] Dataset roi12561_14337 (holder2) has been sent to archive. files=13 size=32206716727 bytes
[11:39:09] [2022-02-12] Dataset roi12561_14337 (holder2) has been stored into ICAT successfully

[11:01:45] [2022-02-12] Starting KmapActor

dataset: holder2_roi12561_14337.h5

steps_x: 200

steps_y: 100

step_size_x: 2.0

step_size_y: 2.0

dwell: 0.1

energy:

[11:01:31] [2022-02-12] Dataset roi12560_14326 (holder2) has been sent to archive. files=8 size=15572511068 bytes
[11:01:31] [2022-02-12] Dataset roi12560_14326 (holder2) has been stored into ICAT successfully

[10:42:10] [2022-02-12] Starting KmapActor

dataset: holder2_roi12560_14326.h5

steps_x: 100

steps_y: 100

step_size_x: 2.0

step_size_y: 2.0

dwell: 0.1

energy:

[10:41:56] [2022-02-12] Dataset roi12559_14316 (holder2) has been sent to archive. files=8 size=15587697334 bytes
[10:41:56] [2022-02-12] Dataset roi12559_14316 (holder2) has been stored into ICAT successfully

[10:22:35] [2022-02-12] Starting KmapActor

dataset: holder2_roi12559_14316.h5

steps_x: 100

steps_y: 100

step_size_x: 2.0

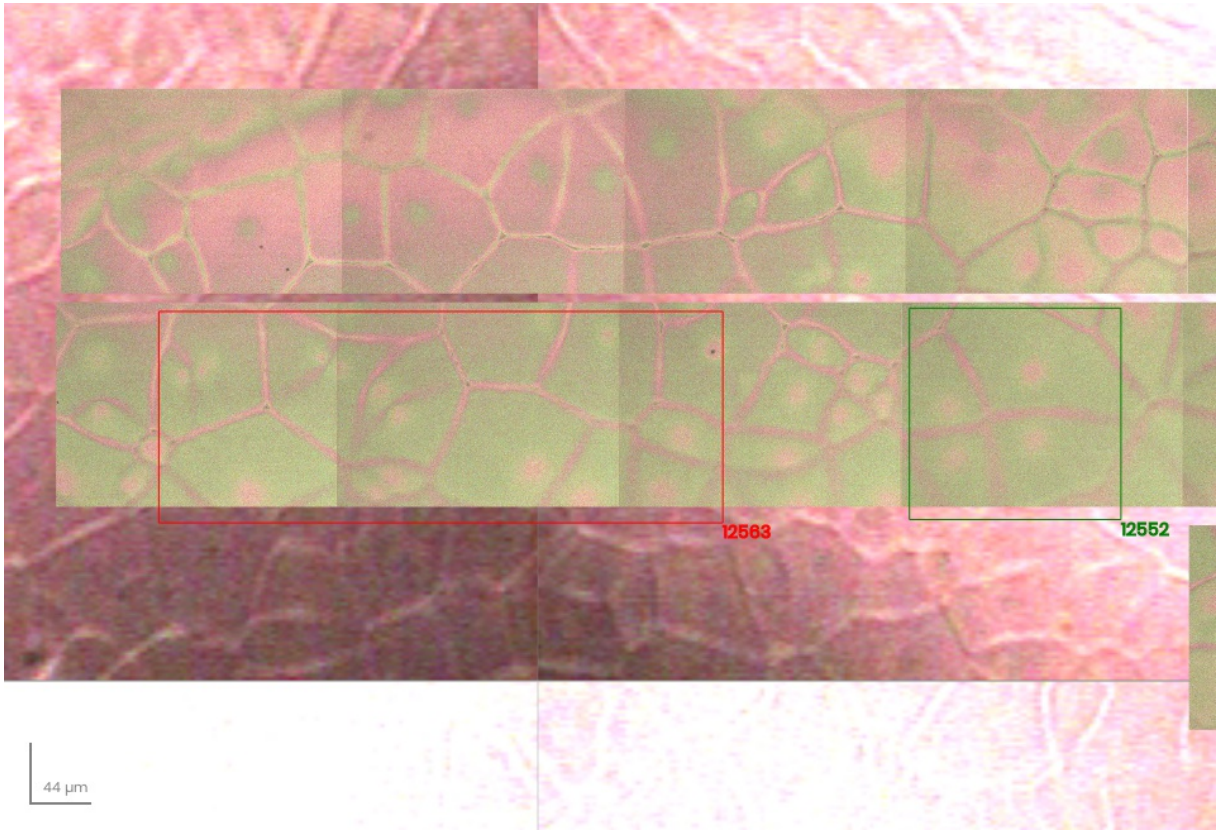
step_size_y: 2.0

dwell: 0.1

energy:

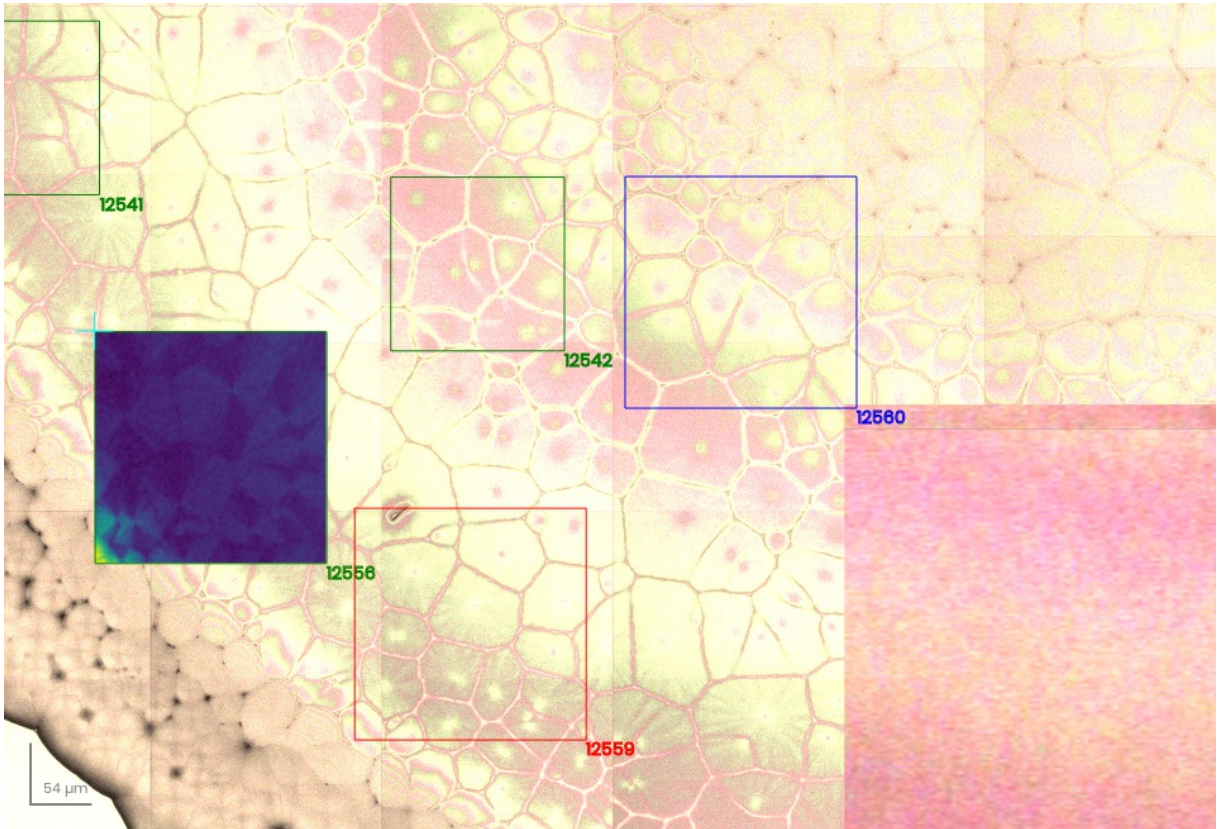
[10:21:59] [2022-02-12] Dataset roi12556_14305 (holder2) has been sent to archive. files=8 size=9512225712 bytes
[10:21:59] [2022-02-12] Dataset roi12556_14305 (holder2) has been stored into ICAT successfully
```

[10:20:04] [2022-02-12]



[10:20:03] [2022-02-12] Saved current acquisition image for sample holder2

[10:15:50] [2022-02-12]



[10:15:50] [2022-02-12] Saved current acquisition image for sample holder2

[10:01:57] [2022-02-12] Starting KmapActor

```
dataset: holder2_roi12556_14305.h5
steps_x: 100
steps_y: 100
step_size_x: 2.0
step_size_y: 2.0
dwell: 0.02
energy:
```

[10:01:20] [2022-02-12] Dataset roi12555_14299 (holder2) has been sent to archive. files=13 size=30271976953 bytes
[10:01:20] [2022-02-12] Dataset roi12555_14299 (holder2) has been stored into ICAT successfully

```
[09:52:34] [2022-02-12] Starting KmapActor

dataset: holder2_roi12555_14299.h5

steps_x: 1530

steps_y: 65

step_size_x: 2.0

step_size_y: 2.0

dwell: 0.02

energy:

[09:51:55] [2022-02-12] Dataset roi12553_14297 (holder2) has been sent to archive. files=5 size=2282258991 bytes
[09:51:55] [2022-02-12] Dataset roi12553_14297 (holder2) has been stored into ICAT successfully

[09:50:13] [2022-02-12] Starting KmapActor

dataset: holder2_roi12553_14297.h5

steps_x: 50

steps_y: 50

step_size_x: 2.0

step_size_y: 2.0

dwell: 0.02

energy:

[09:49:55] [2022-02-12] Dataset roi12552_14294 (holder2) has been sent to archive. files=6 size=5449913555 bytes
[09:49:55] [2022-02-12] Dataset roi12552_14294 (holder2) has been stored into ICAT successfully

[09:46:32] [2022-02-12] Starting KmapActor

dataset: holder2_roi12552_14294.h5

steps_x: 75

steps_y: 75

step_size_x: 2.0

step_size_y: 2.0

dwell: 0.02

energy:

[09:46:13] [2022-02-12] Dataset roi12551_14291 (holder2) has been sent to archive. files=6 size=5525936820 bytes
[09:46:13] [2022-02-12] Dataset roi12551_14291 (holder2) has been stored into ICAT successfully

[09:42:50] [2022-02-12] Starting KmapActor

dataset: holder2_roi12551_14291.h5

steps_x: 75

steps_y: 75

step_size_x: 2.0

step_size_y: 2.0

dwell: 0.02

energy:

[09:42:33] [2022-02-12] Dataset roi12549_14288 (holder2) has been stored into ICAT successfully
[09:42:33] [2022-02-12] Dataset roi12549_14288 (holder2) has been sent to archive. files=6 size=5419900844 bytes

[09:39:10] [2022-02-12] Starting KmapActor

dataset: holder2_roi12549_14288.h5

steps_x: 75

steps_y: 75

step_size_x: 2.0

step_size_y: 2.0

dwell: 0.02

energy:

[09:38:52] [2022-02-12] Dataset roi12547_14286 (holder2) has been stored into ICAT successfully
[09:38:53] [2022-02-12] Dataset roi12547_14286 (holder2) has been sent to archive. files=6 size=5664041204 bytes

[09:35:30] [2022-02-12] Starting KmapActor

dataset: holder2_roi12547_14286.h5

steps_x: 75

steps_y: 75

step_size_x: 2.0

step_size_y: 2.0

dwell: 0.02

energy:

[09:35:18] [2022-02-12] Dataset roi12545_14277 (holder2) has been sent to archive. files=19 size=30654114392 bytes
[09:35:18] [2022-02-12] Dataset roi12545_14277 (holder2) has been stored into ICAT successfully
```

```
[09:19:17] [2022-02-12] Starting KmapActor

dataset: holder2_roi12545_14277.h5

steps_x: 175

steps_y: 175

step_size_x: 2.0

step_size_y: 2.0

dwell: 0.02

energy:

[09:18:58] [2022-02-12] Dataset roi12542_14274 (holder2) has been sent to archive. files=6 size=5534723339 bytes
[09:18:58] [2022-02-12] Dataset roi12542_14274 (holder2) has been stored into ICAT successfully

[09:15:36] [2022-02-12] Starting KmapActor

dataset: holder2_roi12542_14274.h5

steps_x: 75

steps_y: 75

step_size_x: 2.0

step_size_y: 2.0

dwell: 0.02

energy:

[09:15:17] [2022-02-12] Dataset roi12541_14271 (holder2) has been stored into ICAT successfully
[09:15:17] [2022-02-12] Dataset roi12541_14271 (holder2) has been sent to archive. files=6 size=5509690478 bytes

[09:11:55] [2022-02-12] Starting KmapActor

dataset: holder2_roi12541_14271.h5

steps_x: 75

steps_y: 75

step_size_x: 2.0

step_size_y: 2.0

dwell: 0.02

energy:

[09:11:36] [2022-02-12] Dataset roi12540_14268 (holder2) has been stored into ICAT successfully
[09:11:36] [2022-02-12] Dataset roi12540_14268 (holder2) has been sent to archive. files=6 size=5862312208 bytes

[09:08:14] [2022-02-12] Starting KmapActor

dataset: holder2_roi12540_14268.h5

steps_x: 75

steps_y: 75

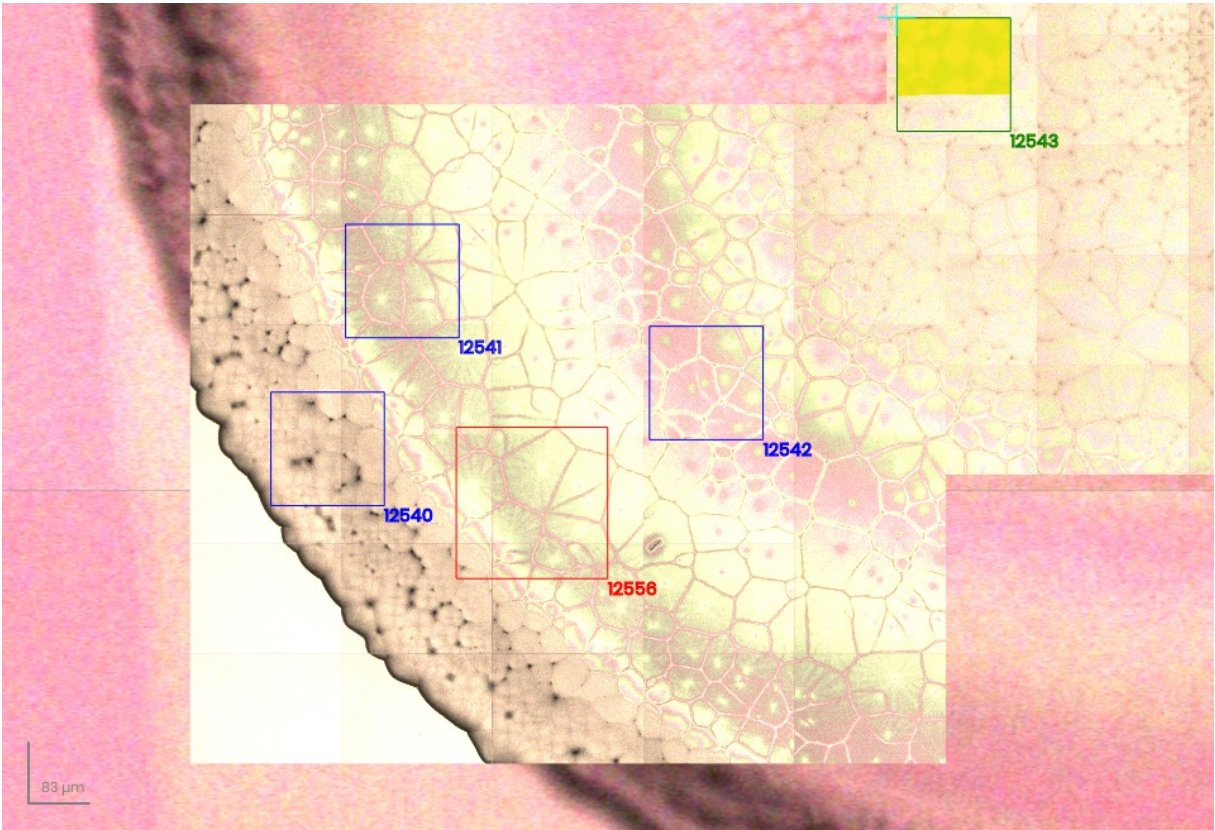
step_size_x: 2.0

step_size_y: 2.0

dwell: 0.02

energy:

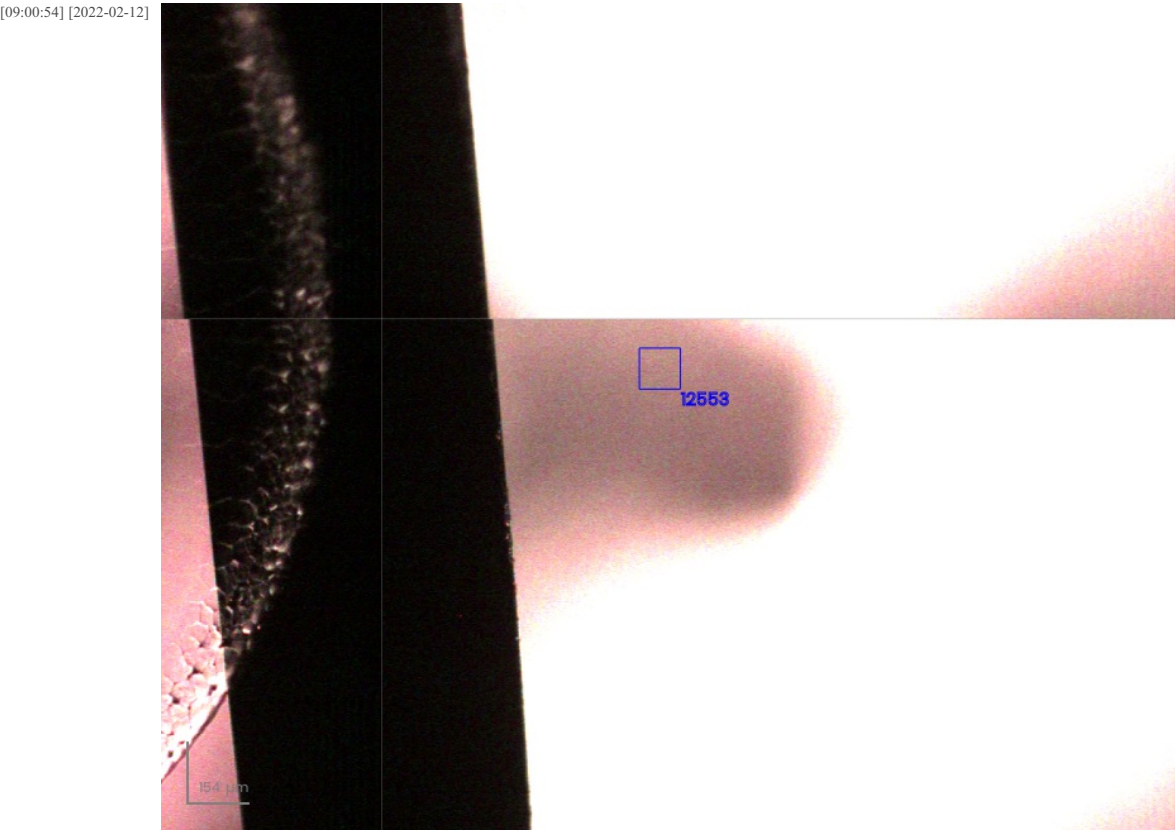
[09:07:39] [2022-02-12] Dataset roi12543_14264 (holder2) has been sent to archive. files=6 size=5633014175 bytes
[09:07:39] [2022-02-12] Dataset roi12543_14264 (holder2) has been stored into ICAT successfully
[09:05:41] [2022-02-12] Saved current acquisition image for sample holder2
```

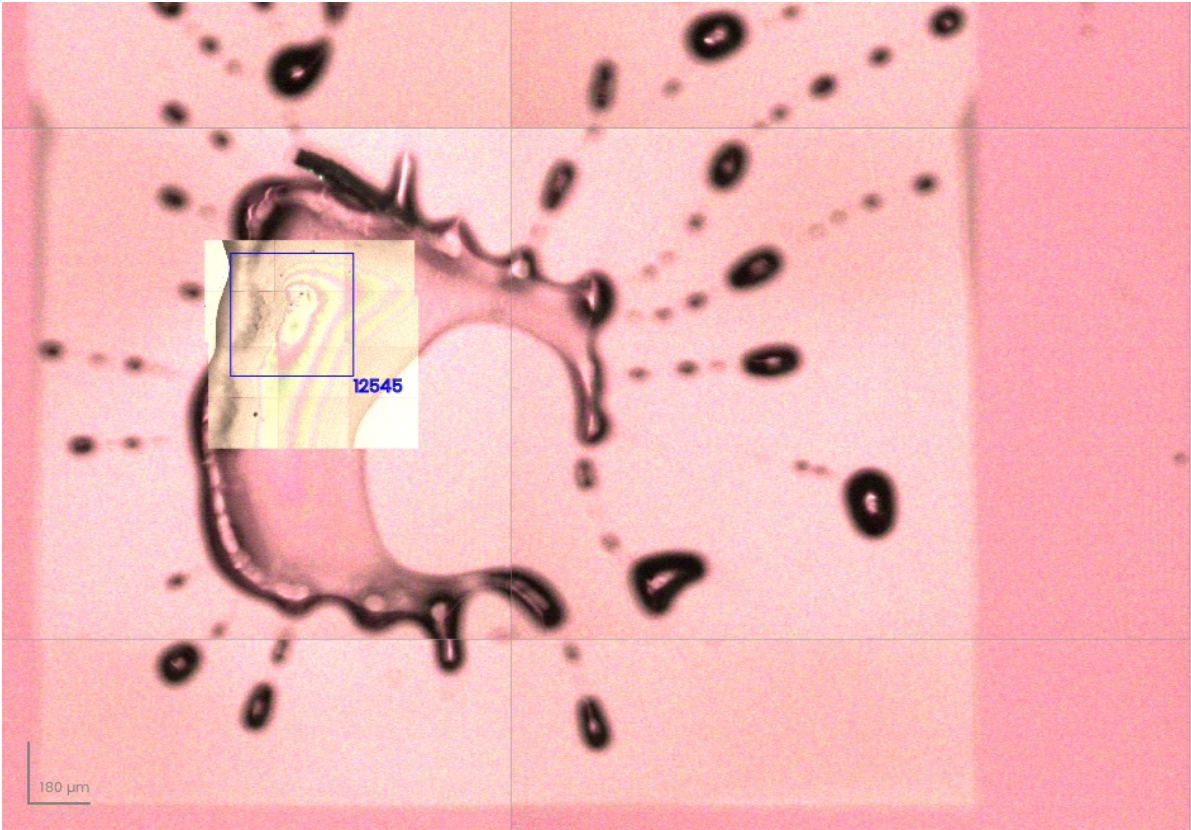
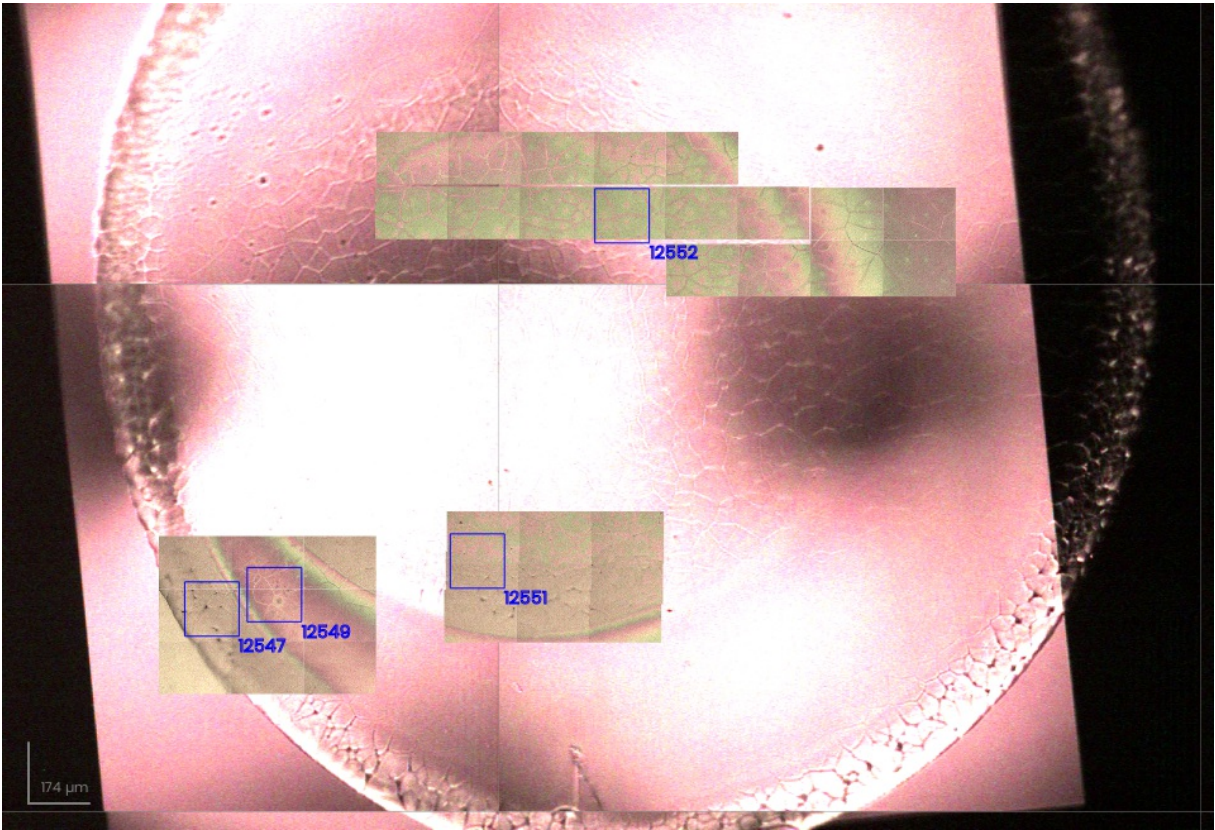
[09:02:11] [2022-02-12] Starting KmapActor

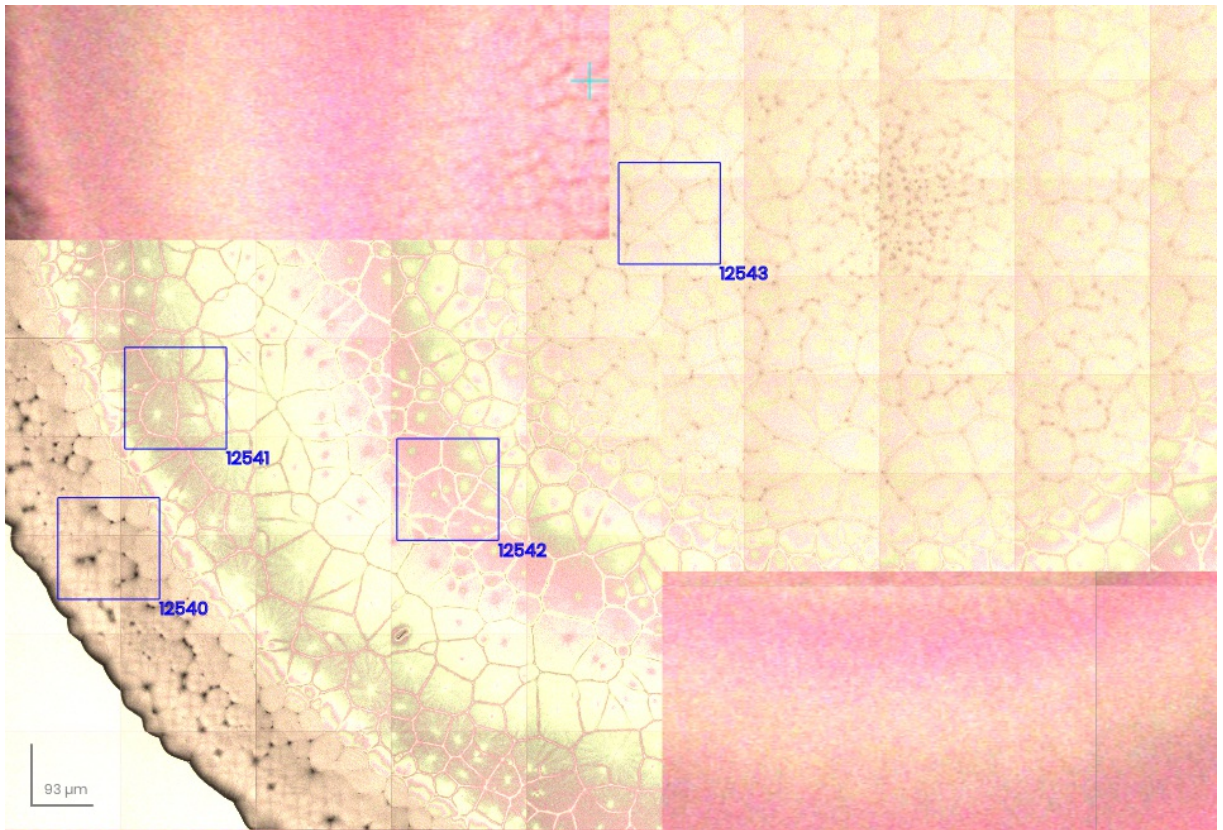
```
dataset: holder2_roi12543_14264.h5
steps_x: 75
steps_y: 75
step_size_x: 2.0
step_size_y: 2.0
dwell: 0.02
energy:
```

[09:00:54] [2022-02-12] Saved current acquisition image for sample holder2



[09:00:29] [2022-02-12] Saved current acquisition image for sample holder2





[08:57:52] [2022-02-12] Saved current acquisition image for sample holder2

```
[08:55:18] [2022-02-12] edit_roi_counters(eiger)
[08:54:58] [2022-02-12] edit_roi_counters(eiger)
[08:54:35] [2022-02-12] eiger.roi_counters
[08:50:00] [2022-02-12] edit_roi_counters(eiger)
[08:49:24] [2022-02-12] ct(0.1)
[08:48:52] [2022-02-12] ct(0.1)
[08:47:20] [2022-02-12] ct(0.1)
[08:46:57] [2022-02-12] ct(0.02)
[08:46:34] [2022-02-12] MG_EH2
[08:46:28] [2022-02-12] so()
[08:46:22] [2022-02-12] dqmgeig()
[08:45:16] [2022-02-12] umv(udetx, -800)
[08:44:10] [2022-02-12] sc()
[08:43:23] [2022-02-12] bsalign()
[08:42:42] [2022-02-12] bsalign()
[08:42:34] [2022-02-12] ct()
[08:42:31] [2022-02-12] fshtrigger()
[08:42:20] [2022-02-12] ct()
[08:41:27] [2022-02-12] bsalign()
[08:41:22] [2022-02-12] umvr(ubxs, 0.1)
[08:41:15] [2022-02-12] umvr(ubxs, -0.1)
[08:41:07] [2022-02-12] umvr(ubxs, -0.1)
[08:41:04] [2022-02-12] umvr(ubxs, -0.1)
[08:41:03] [2022-02-12] umvr(ubxs, -0.1)
[08:41:02] [2022-02-12] umvr(ubxs, -0.1)
[08:41:00] [2022-02-12] umvr(ubxs, -0.1)
[08:40:57] [2022-02-12] lcag(ubxs, -1)
[08:40:53] [2022-02-12] ValueError: ubxs: move to ~-1.861250' would exceed low limit (-0.761250)
[08:40:53] [2022-02-12] umvr(ubxs, -0.1)
[08:40:47] [2022-02-12] lcag(ubxs, 1)
[08:40:44] [2022-02-12] lcag(ubxs, 1)
[08:40:44] [2022-02-12] NameError: name 'ubxs' is not defined
[08:40:29] [2022-02-12] umvr(ubxs, -0.1)
[08:40:29] [2022-02-12] ValueError: ubxs: move to ~-1.861250' would exceed low limit (-1.771250)
[08:40:16] [2022-02-12] umvr(ubxs, -5)
[08:40:03] [2022-02-12] umvr(ubxs, -5)
[08:39:47] [2022-02-12] umvr(ucryox, -0.5)
[08:39:36] [2022-02-12] umvr(ucryox, -1)
[08:39:34] [2022-02-12] umvr(ucryox, -1)
[08:39:31] [2022-02-12] umvr(ucryox, -3)
[08:38:44] [2022-02-12] mgd()
[08:38:41] [2022-02-12] so()
[08:38:15] [2022-02-12] umv(ubsy, 0, ucryoy, 0)
[08:37:03] [2022-02-12] umv(umicroz, 191)
[08:36:46] [2022-02-12] umv(umicroz, 1)
[08:35:51] [2022-02-12] AxisOnLimitError: umicroz: READY (Axis is READY) | LIMPOS (Hardware high limit active) | LIMNEG (Hardware low limit active) | HOME (Home signal active) | SCLIMPOS (positive limitswitch reached) | FAULT (Error from controller) at -0.078125
[08:35:51] [2022-02-12] RuntimeError: Cannot move axis 88: Limit switch - is active (check http://wikiserv.esrf.fr/bliss/index.php/ICETIPS) command sent was: b'MOVE'
[08:35:51] [2022-02-12] RuntimeError: Cannot move axis 88: Limit switch + is active (check http://wikiserv.esrf.fr/bliss/index.php/ICETIPS) command sent was: b'MOVE'
[08:35:51] [2022-02-12] AxisOnLimitError: umicroz: READY (Axis is READY) | LIMPOS (Hardware high limit active) | LIMNEG (Hardware low limit active) | HOME (Home signal active) | SCLINNEG (negative limitswitch reached) | FAULT (Error from controller) at -0.078125
[08:35:51] [2022-02-12] AxisOnLimitError: umicroz: READY (Axis is READY) | LIMPOS (Hardware high limit active) | LIMNEG (Hardware low limit active) | HOME (Home signal active) | SCLIMPOS (positive limitswitch reached) | FAULT (Error from controller) at -0.078125
[08:35:50] [2022-02-12] umvr(umicroz, 5)
[08:35:51] [2022-02-12] RuntimeError: Cannot move axis 88: Limit switch - is active (check http://wikiserv.esrf.fr/bliss/index.php/ICETIPS) command sent was: b'MOVE'
[08:35:51] [2022-02-12] AxisOnLimitError: umicroz: READY (Axis is READY) | LIMPOS (Hardware high limit active) | LIMNEG (Hardware low limit active) | HOME (Home signal active) | SCLINNEG (negative limitswitch reached) | FAULT (Error from controller) at -0.078125
[08:35:51] [2022-02-12] RuntimeError: Cannot move axis 88: Limit switch - is active (check http://wikiserv.esrf.fr/bliss/index.php/ICETIPS) command sent was: b'MOVE'
[08:35:51] [2022-02-12] RuntimeError: Cannot move axis 88: Limit switch + is active (check http://wikiserv.esrf.fr/bliss/index.php/ICETIPS) command sent was: b'MOVE'
[08:35:30] [2022-02-12] wmv(umicroz)
[08:34:57] [2022-02-12] RuntimeError: Cannot move axis 88: Limit switch - is active (check http://wikiserv.esrf.fr/bliss/index.php/ICETIPS) command sent was: b'MOVE'
[08:34:57] [2022-02-12] RuntimeError: Cannot move axis 88: Limit switch - is active (check http://wikiserv.esrf.fr/bliss/index.php/ICETIPS) command sent was: b'MOVE'
[08:34:56] [2022-02-12] RuntimeError: Cannot move axis 88: Limit switch + is active (check http://wikiserv.esrf.fr/bliss/index.php/ICETIPS) command sent was: b'MOVE'
[08:34:57] [2022-02-12] RuntimeError: Cannot move axis 88: Limit switch + is active (check http://wikiserv.esrf.fr/bliss/index.php/ICETIPS) command sent was: b'MOVE'
[08:34:56] [2022-02-12] AxisOnLimitError: umicroz: READY (Axis is READY) | LIMPOS (Hardware high limit active) | LIMNEG (Hardware low limit active) | HOME (Home signal active) | SCLIMPOS (positive limitswitch reached) | FAULT (Error from controller) at -0.078125
[08:34:56] [2022-02-12] AxisOnLimitError: umicroz: READY (Axis is READY) | LIMPOS (Hardware high limit active) | LIMNEG (Hardware low limit active) | HOME (Home signal active) | SCLIMPOS (positive limitswitch reached) | FAULT (Error from controller) at -0.078125
[08:34:56] [2022-02-12] AxisOnLimitError: umicroz: READY (Axis is READY) | LIMPOS (Hardware high limit active) | LIMNEG (Hardware low limit active) | HOME (Home signal active) | SCLINNEG (negative limitswitch reached) | FAULT (Error from controller) at -0.078125
[08:34:56] [2022-02-12] AxisOnLimitError: umicroz: READY (Axis is READY) | LIMPOS (Hardware high limit active) | LIMNEG (Hardware low limit active) | HOME (Home signal active) | SCLINNEG (negative limitswitch reached) | FAULT (Error from controller) at -0.078125
[08:34:56] [2022-02-12] umv(umicroz, 191)
[08:34:56] [2022-02-12] RuntimeError: Cannot move axis 88: Limit switch - is active (check http://wikiserv.esrf.fr/bliss/index.php/ICETIPS) command sent was: b'MOVE'
[08:34:24] [2022-02-12] AxisOnLimitError: umicroz: READY (Axis is READY) | LIMNEG (Hardware low limit active) | HOME (Home signal active) at -0.078125
[08:34:24] [2022-02-12] AxisOnLimitError: umicroz: READY (Axis is READY) | LIMNEG (Hardware low limit active) | HOME (Home signal active) | SCLINNEG (negative limitswitch reached) | FAULT (Error from controller) at -0.078125
[08:34:24] [2022-02-12] AxisOnLimitError: umicroz: READY (Axis is READY) | LIMNEG (Hardware low limit active) | HOME (Home signal active) | SCLINNEG (negative limitswitch reached) | FAULT (Error from controller) at 0.0
[08:34:24] [2022-02-12] RuntimeError: Cannot move axis 88: Limit switch - is active (check http://wikiserv.esrf.fr/bliss/index.php/ICETIPS) command sent was: b'MOVE'
[08:34:24] [2022-02-12] RuntimeError: Cannot move axis 88: Limit switch - is active (check http://wikiserv.esrf.fr/bliss/index.php/ICETIPS) command sent was: b'MOVE'
[08:34:24] [2022-02-12] RuntimeError: Cannot move axis 88: Limit switch + is active (check http://wikiserv.esrf.fr/bliss/index.php/ICETIPS) command sent was: b'MOVE'
[08:34:24] [2022-02-12] AxisOnLimitError: umicroz: READY (Axis is READY) | LIMNEG (Hardware low limit active) | HOME (Home signal active) | SCLINNEG (negative limitswitch reached) | FAULT (Error from controller) at 0.0
```

[08:34:23] [2022-02-12] slil(0); umv(umicroz, 191)

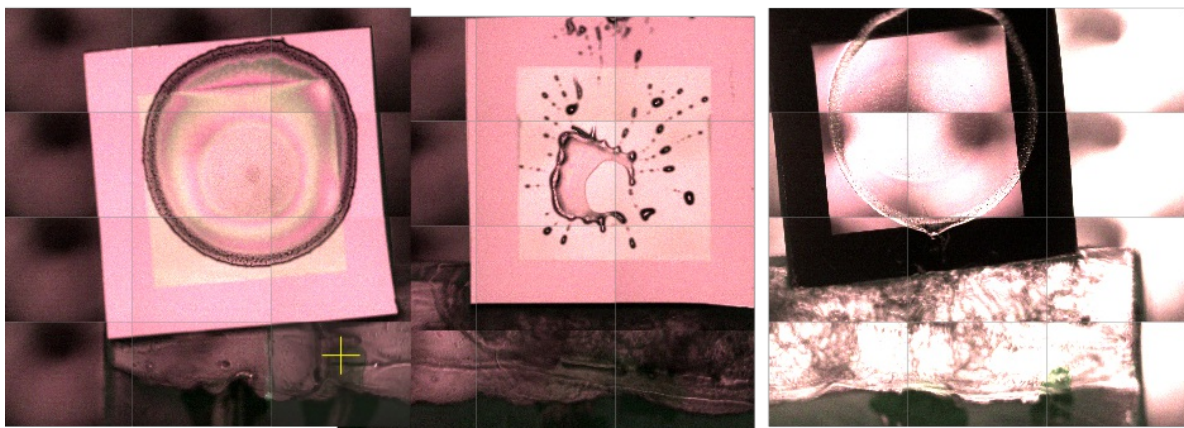
[08:26:32] [2022-02-12] Actor e3d8c9e2-95a2-408e-85d2-95f5c93670e2 failed with exception axis ustrz state is 'MOVING'

Traceback:

```
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/__init__.py", line 838, in execute
    **self.initkwargs
File "/users/blissadm/local/daiquiri/daiquiri_id13/daiquiri_id13/implementors/imageviewer/move.py", line 8, in method
    kwargs["absol"] ["move_to"] (kwargs["absol"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/imageviewer/__init__.py", line 1083, in move_to_absol
    obj["motor"].move(obj["destination"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/motor.py", line 49, in move
    self.call("move", value)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 196, in call
    ret = self._call(function, value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 478, in _call
    ret = getattr(self, "_call_{fn}".format(fn=function))(value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/bliss/motor.py", line 91, in _call_move
    self._object.move(value, wait=False)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 636, in func_wrapper
    return func(self, *args, **kwargs)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 1924, in move
    raise RuntimeError("axis %s state is %r" % (self.name, "MOVING"))
```

[08:25:56] [2022-02-12] sc()

[08:22:05] [2022-02-12]



880 μm

[08:22:05] [2022-02-12] Saved current acquisition image for sample holder2

[08:21:16] [2022-02-12] Actor 128b1d79-8bf8-42c8-a6ae-3d41f0d8c066 failed with exception axis ustrz state is 'MOVING'

Traceback:

```
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/__init__.py", line 838, in execute
    **self.initkwargs
File "/users/blissadm/local/daiquiri/daiquiri_id13/daiquiri_id13/implementors/imageviewer/move.py", line 8, in method
    kwargs["absol"] ["move_to"] (kwargs["absol"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/imageviewer/__init__.py", line 1083, in move_to_absol
    obj["motor"].move(obj["destination"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/motor.py", line 49, in move
    self.call("move", value)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 196, in call
    ret = self._call(function, value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 478, in _call
    ret = getattr(self, "_call_{fn}".format(fn=function))(value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/bliss/motor.py", line 91, in _call_move
    self._object.move(value, wait=False)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 636, in func_wrapper
    return func(self, *args, **kwargs)
```



```

File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 1924, in move
    raise RuntimeError("axis %s state is %r" % (self.name, "MOVING"))

[08:20:13] [2022-02-12] Actor 18d9396d-5ee9-4308-99cc-15a7c22ea8f0 failed with exception axis ustrz state is 'MOVING'
Traceback:
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/__init__.py", line 838, in execute
    **self.initkwargs
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri_id13/daiquiri_id13/implementors/imageviewer/move.py", line 8, in method
    kwargs["absol"] ["move_to"] (kwargs["absol"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/imageviewer/__init__.py", line 1083, in move_to_absol
    obj["motor"].move(obj["destination"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/motor.py", line 49, in move
    self.call("move", value)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 196, in call
    ret = self._call(function, value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 478, in _call
    ret = getattr(self, "_call_{fn}".format(fn=function))(value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/bliss/motor.py", line 91, in _call_move
    self._object.move(value, wait=False)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 636, in func_wrapper
    return func(self, *args, **kwargs)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 1924, in move
    raise RuntimeError("axis %s state is %r" % (self.name, "MOVING"))

[08:20:07] [2022-02-12] Actor 55f0a9a8-3c84-42e2-a83d-9db3ac52e6e6 failed with exception axis ustrz state is 'MOVING'
Traceback:
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/__init__.py", line 838, in execute
    **self.initkwargs
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri_id13/daiquiri_id13/implementors/imageviewer/move.py", line 8, in method
    kwargs["absol"] ["move_to"] (kwargs["absol"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/imageviewer/__init__.py", line 1083, in move_to_absol
    obj["motor"].move(obj["destination"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/motor.py", line 49, in move
    self.call("move", value)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 196, in call
    ret = self._call(function, value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 478, in _call
    ret = getattr(self, "_call_{fn}".format(fn=function))(value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/bliss/motor.py", line 91, in _call_move
    self._object.move(value, wait=False)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 636, in func_wrapper
    return func(self, *args, **kwargs)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 1924, in move
    raise RuntimeError("axis %s state is %r" % (self.name, "MOVING"))

[08:19:36] [2022-02-12] Actor 3ff47c87-ff1b-4b08-abdf-a69b6f39bce2 failed with exception axis ustry state is 'MOVING'
Traceback:
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/__init__.py", line 838, in execute
    **self.initkwargs
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri_id13/daiquiri_id13/implementors/imageviewer/move.py", line 8, in method
    kwargs["absol"] ["move_to"] (kwargs["absol"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/imageviewer/__init__.py", line 1083, in move_to_absol
    obj["motor"].move(obj["destination"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/motor.py", line 49, in move
    self.call("move", value)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 196, in call
    ret = self._call(function, value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 478, in _call
    ret = getattr(self, "_call_{fn}".format(fn=function))(value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/bliss/motor.py", line 91, in _call_move
    self._object.move(value, wait=False)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 636, in func_wrapper
    return func(self, *args, **kwargs)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 1924, in move
    raise RuntimeError("axis %s state is %r" % (self.name, "MOVING"))

[08:19:33] [2022-02-12] Actor 88070f12-4532-4f32-a218-c9c523ed8f48 failed with exception axis ustry state is 'MOVING'
Traceback:
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/__init__.py", line 838, in execute
    **self.initkwargs

```

```

File "/users/blissadm/local/daiquiri/daiquiri_id13/daiquiri_id13/implementors/imageviewer/move.py", line 8, in method
    kwargs["absol"] ["move_to"] (kwargs["absol"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/imageviewer/__init__.py", line 1083, in move_to_absol
    obj["motor"].move(obj["destination"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/motor.py", line 49, in move
    self.call("move", value)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 196, in call
    ret = self._call(function, value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 478, in _call
    ret = getattr(self, "_call_{fn}".format(fn=function))(value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/bliss/motor.py", line 91, in _call_move
    self._object.move(value, wait=False)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 636, in func_wrapper
    return func(self, *args, **kwargs)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 1924, in move
    raise RuntimeError("axis %s state is %r" % (self.name, "MOVING"))

```

[08:19:21] [2022-02-12] Actor 507de8bc-a6ff-4ade-859a-92b6ff930b16 failed with exception axis ustrz state is 'MOVING'

Traceback:

```

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/__init__.py", line 838, in execute
    **self.initkwargs
File "/users/blissadm/local/daiquiri/daiquiri_id13/daiquiri_id13/implementors/imageviewer/move.py", line 8, in method
    kwargs["absol"] ["move_to"] (kwargs["absol"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/imageviewer/__init__.py", line 1083, in move_to_absol
    obj["motor"].move(obj["destination"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/motor.py", line 49, in move
    self.call("move", value)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 196, in call
    ret = self._call(function, value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 478, in _call
    ret = getattr(self, "_call_{fn}".format(fn=function))(value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/bliss/motor.py", line 91, in _call_move
    self._object.move(value, wait=False)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 636, in func_wrapper
    return func(self, *args, **kwargs)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 1924, in move
    raise RuntimeError("axis %s state is %r" % (self.name, "MOVING"))

```

[08:19:16] [2022-02-12] Actor e67ec308-bc84-448e-9c80-3b75f150e4c7 failed with exception axis ustrz state is 'MOVING'

Traceback:

```

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/__init__.py", line 838, in execute
    **self.initkwargs
File "/users/blissadm/local/daiquiri/daiquiri_id13/daiquiri_id13/implementors/imageviewer/move.py", line 8, in method
    kwargs["absol"] ["move_to"] (kwargs["absol"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/imageviewer/__init__.py", line 1083, in move_to_absol
    obj["motor"].move(obj["destination"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/motor.py", line 49, in move
    self.call("move", value)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 196, in call
    ret = self._call(function, value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 478, in _call
    ret = getattr(self, "_call_{fn}".format(fn=function))(value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/bliss/motor.py", line 91, in _call_move
    self._object.move(value, wait=False)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 636, in func_wrapper
    return func(self, *args, **kwargs)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 1924, in move
    raise RuntimeError("axis %s state is %r" % (self.name, "MOVING"))

```

```

[08:17:55] [2022-02-12] umvr(ustrx, 0.01)
[08:17:53] [2022-02-12] umvr(ustrx, 0.01)
[08:17:54] [2022-02-12] umvr(ustrx, 0.01)
[08:17:53] [2022-02-12] umvr(ustrx, 0.01)
[08:17:52] [2022-02-12] umvr(ustrx, 0.01)
[08:17:48] [2022-02-12] umvr(ustrx, -0.01)

```

[08:17:134] [2022-02-12] Actor 07008691-e7e2-4e37-a413-43978a69e681 failed with exception axis ustrz state is 'MOVING'

Traceback:

```

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/__init__.py", line 838, in execute
    **self.initkwargs
File "/users/blissadm/local/daiquiri/daiquiri_id13/daiquiri_id13/implementors/imageviewer/move.py", line 8, in method
    kwargs["absol"] ["move_to"] (kwargs["absol"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/imageviewer/__init__.py", line 1083, in move_to_absol
    obj["motor"].move(obj["destination"])

```

```
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/motor.py", line 49, in move
    self.call("move", value)

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 196, in call
    ret = self._call(function, value, **kwargs)

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 478, in _call
    ret = getattr(self, "_call_{fn}".format(fn=function))(value, **kwargs)

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/bliss/motor.py", line 91, in _call_move
    self._object.move(value, wait=False)

File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 636, in func_wrapper
    return func(self, *args, **kwargs)

File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 1924, in move
    raise RuntimeError("axis %s state is %r" % (self.name, "MOVING"))

[08:16:38] [2022-02-12] umvr(ustrx, 0.1)
[08:16:37] [2022-02-12] umvr(ustrx, 0.1)
[08:16:36] [2022-02-12] umvr(ustrx, 0.1)
[08:16:35] [2022-02-12] umvr(ustrx, 0.1)
[08:16:34] [2022-02-12] umvr(ustrx, 0.1)
[08:16:33] [2022-02-12] umvr(ustrx, 0.1)
[08:16:32] [2022-02-12] umvr(ustrx, 0.1)
[08:16:16] [2022-02-12] umvr(ustrx, -0.1)
[08:16:15] [2022-02-12] umvr(ustrx, -0.1)
[08:16:14] [2022-02-12] umvr(ustrx, -0.1)
[08:16:13] [2022-02-12] umvr(ustrx, -0.1)
[08:16:10] [2022-02-12] umvr(ustrx, 0.1)
[08:16:09] [2022-02-12] umvr(ustrx, 0.1)
[08:16:08] [2022-02-12] umvr(ustrx, 0.1)
[08:16:07] [2022-02-12] umvr(ustrx, 0.1)
[08:16:05] [2022-02-12] umvr(ustrx, 0.1)
[08:16:04] [2022-02-12] umvr(ustrx, 0.1)
[08:14:59] [2022-02-12] sll(24)
[08:14:56] [2022-02-12] sll(0)
[08:14:52] [2022-02-12] AxisOnLimitError: umicroz: READY (Axis is READY) | LIMNEG (Hardware low limit active) | HOME (Home signal active) at 0.0
[08:14:52] [2022-02-12] AxisOnLimitError: umicroz: READY (Axis is READY) | LIMNEG (Hardware low limit active) | HOME (Home signal active) at 0.0
[08:14:44] [2022-02-12] umv(umicroz, 0)
[08:14:26] [2022-02-12] AxisOnLimitError: umicroz: READY (Axis is READY) | LIMNEG (Hardware low limit active) | HOME (Home signal active) at 50.0
[08:14:26] [2022-02-12] AxisOnLimitError: umicroz: READY (Axis is READY) | LIMNEG (Hardware low limit active) | HOME (Home signal active) at 50.0
[08:14:19] [2022-02-12] umv(umicroz, 50)
[08:13:50] [2022-02-12] AxisOnLimitError: umicroz: READY (Axis is READY) | LIMNEG (Hardware low limit active) | HOME (Home signal active) at 100.0
[08:13:50] [2022-02-12] AxisOnLimitError: umicroz: READY (Axis is READY) | LIMNEG (Hardware low limit active) | HOME (Home signal active) at 100.0
[08:13:37] [2022-02-12] umv(umicroz, 100)
[08:12:16] [2022-02-12] wvn(umicroz)
[08:12:00] [2022-02-12] AxisOnLimitError: umicroz: READY (Axis is READY) | LIMNEG (Hardware low limit active) | HOME (Home signal active) at 190.0
[08:12:00] [2022-02-12] AxisOnLimitError: umicroz: READY (Axis is READY) | LIMNEG (Hardware low limit active) | HOME (Home signal active) at 190.0
[08:11:59] [2022-02-12] umvr(umicroz, -1)
[08:11:47] [2022-02-12] wvn(umicroz)
[08:10:14] [2022-02-12] last_error
[08:09:58] [2022-02-12] RuntimeError: Cannot move axis 88: Limit switch + is active (check http://wikiserv.esrf.fr/bliss/index.php/ICETIPS) command sent was: b'MOVE'
[08:09:58] [2022-02-12] RuntimeError: Cannot move axis 88: Limit switch + is active (check http://wikiserv.esrf.fr/bliss/index.php/ICETIPS) command sent was: b'MOVE'
[08:09:58] [2022-02-12] AxisOnLimitError: umicroz: READY (Axis is READY) | LIMPOS (Hardware high limit active) | LIMNEG (Hardware low limit active) | HOME (Home signal active) | SCLIMPOS (positive limitswitch reached) | FAULT (Error from controller) at 191.0
[08:09:57] [2022-02-12] RuntimeError: Cannot move axis 88: Limit switch + is active (check http://wikiserv.esrf.fr/bliss/index.php/ICETIPS) command sent was: b'MOVE'
[08:09:58] [2022-02-12] AxisOnLimitError: umicroz: READY (Axis is READY) | LIMPOS (Hardware high limit active) | LIMNEG (Hardware low limit active) | HOME (Home signal active) | SCLIMPOS (positive limitswitch reached) | FAULT (Error from controller) at 191.0
[08:09:57] [2022-02-12] umv(umicroz, 100)
[08:09:46] [2022-02-12] RuntimeError: Synchronization error for axis 'uhum_sp'
[08:09:40] [2022-02-12] RuntimeError: Synchronization error for axis 'uhexrz'
[08:09:39] [2022-02-12] RuntimeError: Synchronization error for axis 'uhexry'
[08:09:39] [2022-02-12] RuntimeError: Synchronization error for axis 'uhexty'
[08:09:39] [2022-02-12] RuntimeError: Synchronization error for axis 'uhextz'
[08:09:39] [2022-02-12] RuntimeError: Synchronization error for axis 'uhextx'
[08:09:39] [2022-02-12] RuntimeError: Synchronization error for axis 'uhexrx'
[08:09:39] [2022-02-12] sync()
[08:09:28] [2022-02-12] wvn(umicroz)
[08:09:24] [2022-02-12] wa(umicroz)
[08:09:24] [2022-02-12] TypeError: wa() takes 0 positional arguments but 1 was given
[08:01:29] [2022-02-12] AxisOnLimitError: umicroz: READY (Axis is READY) | LIMPOS (Hardware high limit active) | LIMNEG (Hardware low limit active) | HOME (Home signal active) | SCLIMPOS (positive limitswitch reached) | FAULT (Error from controller) at 191.0
[08:01:29] [2022-02-12] AxisOnLimitError: umicroz: READY (Axis is READY) | LIMPOS (Hardware high limit active) | LIMNEG (Hardware low limit active) | HOME (Home signal active) | SCLIMPOS (positive limitswitch reached) | FAULT (Error from controller) at 191.0
[08:01:29] [2022-02-12] RuntimeError: Cannot move axis 88: Limit switch + is active (check http://wikiserv.esrf.fr/bliss/index.php/ICETIPS) command sent was: b'MOVE'
[08:01:29] [2022-02-12] RuntimeError: Cannot move axis 88: Limit switch + is active (check http://wikiserv.esrf.fr/bliss/index.php/ICETIPS) command sent was: b'MOVE'
[08:01:29] [2022-02-12] RuntimeError: Cannot move axis 88: Limit switch + is active (check http://wikiserv.esrf.fr/bliss/index.php/ICETIPS) command sent was: b'MOVE'
[08:01:29] [2022-02-12] umv(umicroz, 100)
[07:57:46] [2022-02-12] RuntimeError: Cannot move axis 88: Limit switch + is active (check http://wikiserv.esrf.fr/bliss/index.php/ICETIPS) command sent was: b'MOVE'
[07:57:46] [2022-02-12] RuntimeError: Cannot move axis 88: Limit switch + is active (check http://wikiserv.esrf.fr/bliss/index.php/ICETIPS) command sent was: b'MOVE'
[07:57:46] [2022-02-12] AxisOnLimitError: umicroz: READY (Axis is READY) | LIMPOS (Hardware high limit active) | LIMNEG (Hardware low limit active) | HOME (Home signal active) | SCLIMPOS (positive limitswitch reached) | FAULT (Error from controller) at 191.0
[07:57:46] [2022-02-12] AxisOnLimitError: umicroz: READY (Axis is READY) | LIMPOS (Hardware high limit active) | LIMNEG (Hardware low limit active) | HOME (Home signal active) | SCLIMPOS (positive limitswitch reached) | FAULT (Error from controller) at 191.0
[07:57:46] [2022-02-12] umv(umicroz, 100)
[07:57:46] [2022-02-12] RuntimeError: Cannot move axis 88: Limit switch + is active (check http://wikiserv.esrf.fr/bliss/index.php/ICETIPS) command sent was: b'MOVE'
[07:54:36] [2022-02-12] RuntimeError: Cannot move axis 88: Limit switch + is active (check http://wikiserv.esrf.fr/bliss/index.php/ICETIPS) command sent was: b'MOVE'
[07:54:36] [2022-02-12] RuntimeError: Cannot move axis 88: Limit switch + is active (check http://wikiserv.esrf.fr/bliss/index.php/ICETIPS) command sent was: b'MOVE'
[07:54:36] [2022-02-12] umv(umicroz, 100)
[07:54:36] [2022-02-12] RuntimeError: Cannot move axis 88: Limit switch + is active (check http://wikiserv.esrf.fr/bliss/index.php/ICETIPS) command sent was: b'MOVE'
[07:54:36] [2022-02-12] AxisOnLimitError: umicroz: READY (Axis is READY) | LIMPOS (Hardware high limit active) | LIMNEG (Hardware low limit active) | HOME (Home signal active) | SCLIMPOS (positive limitswitch reached) | FAULT (Error from controller) at 191.0
[07:54:36] [2022-02-12] AxisOnLimitError: umicroz: READY (Axis is READY) | LIMPOS (Hardware high limit active) | LIMNEG (Hardware low limit active) | HOME (Home signal active) | SCLIMPOS (positive limitswitch reached) | FAULT (Error from controller) at 191.0
[07:54:12] [2022-02-12] umvr(ustry, -7)
[07:53:14] [2022-02-12] sapalign()
[07:52:45] [2022-02-12] bapalign()
[07:52:08] [2022-02-12] sapalign()
[07:52:04] [2022-02-12] umvr(ustry, 2)
[07:52:01] [2022-02-12] umvr(ustry, 2)
[07:51:57] [2022-02-12] umvr(ustry, 5)
[07:50:44] [2022-02-12] sapalign()
[07:50:41] [2022-02-12] fshtrigger()
[07:50:35] [2022-02-12] mgd()
[07:50:24] [2022-02-12] sapalign()

[07:50:24] [2022-02-12] DevFailed: DevFailed[

DevError[

    desc = Failed to connect to device idl3/limaccd/frelonid131a

    The connection request was delayed.

    The last connection request was done less than 1000 ms ago

    origin = Connection::reconnect

    reason = API_CantConnectToDevice

severity = ERR]

]

[07:50:08] [2022-02-12] so()

[07:44:37] [2022-02-12] DevFailed: DevFailed[
```



```
DevError[
    desc = Failed to connect to device id13/limaccd/frelonid131a
        The connection request was delayed.
        The last connection request was done less than 1000 ms ago
    origin = Connection::reconnect
    reason = API_CantConnectToDevice
severity = ERR]
]

[07:44:37] [2022-02-12]  sapalign()

[07:44:32] [2022-02-12]  DevFailed: DevFailed[
DevError[
    desc = Failed to connect to device id13/limaccd/frelonid131a
        The connection request was delayed.
        The last connection request was done less than 1000 ms ago
    origin = Connection::reconnect
    reason = API_CantConnectToDevice
severity = ERR]
]

[07:44:31] [2022-02-12]  bapalign()
[07:44:18] [2022-02-12]  exit()
[07:44:01] [2022-02-12]  sapalign()

[07:44:02] [2022-02-12]  DevFailed: DevFailed[
DevError[
    desc = Failed to connect to device id13/limaccd/frelonid131a
        The connection request was delayed.
        The last connection request was done less than 1000 ms ago
    origin = Connection::reconnect
    reason = API_CantConnectToDevice
severity = ERR]
]

[07:43:50] [2022-02-12]  DevFailed: DevFailed[
DevError[
    desc = Failed to connect to device id13/limaccd/frelonid131a
        The connection request was delayed.
        The last connection request was done less than 1000 ms ago
    origin = Connection::reconnect
    reason = API_CantConnectToDevice
severity = ERR]
]

[07:43:49] [2022-02-12]  bapalign()
[07:41:59] [2022-02-12]  wa()
[07:38:38] [2022-02-12]  umv(ucryoy, 150, ubsy, -100)
[07:38:18] [2022-02-12]  umvr(ucryox, 5)
[07:37:53] [2022-02-12]  umvr(ubsx, 10)
[07:36:38] [2022-02-12]  umv(udetx, -250)
[07:36:06] [2022-02-12]  sc()
[22:44:44] [2022-02-11]  sc()

[22:42:52] [2022-02-11]  Starting KmapActor

    dataset: holder1_roi12271_14073.h5

    steps_x: 25

    steps_y: 25

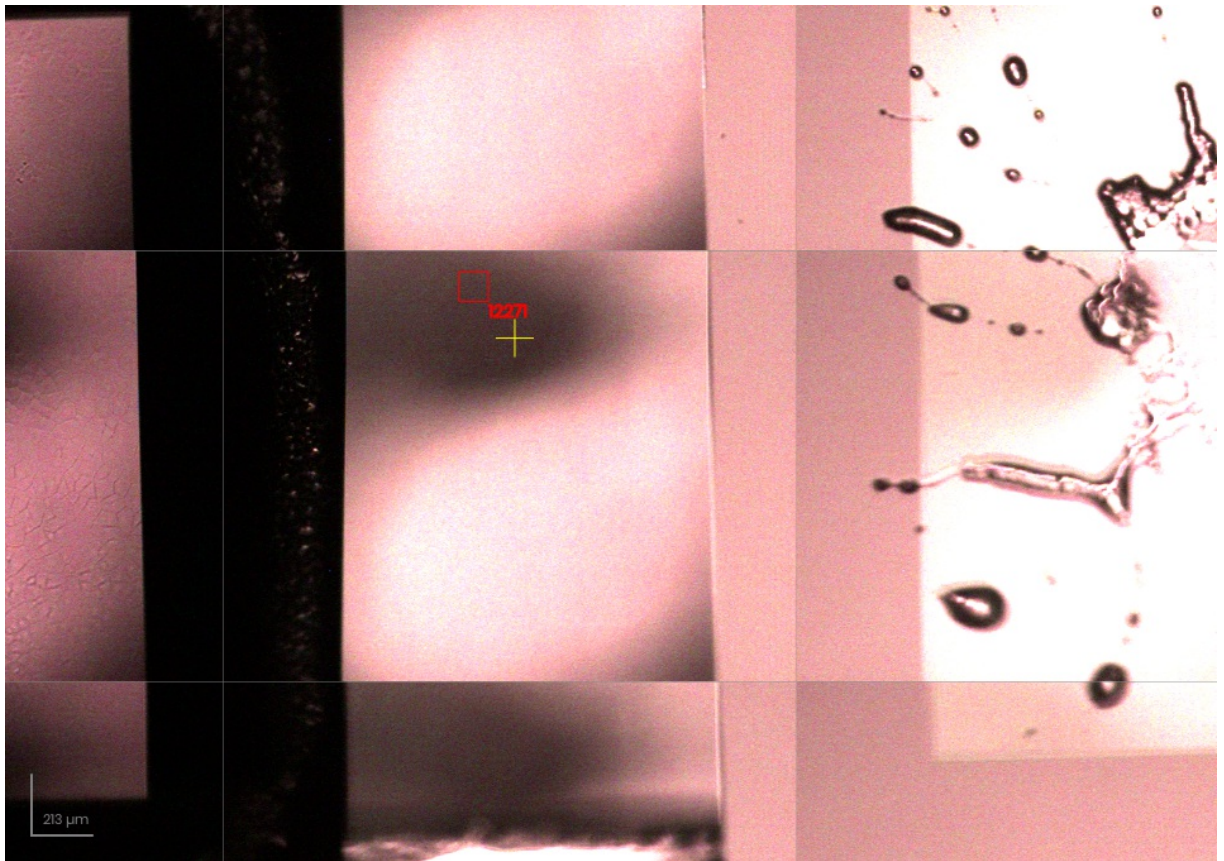
    step_size_x: 4.0

    step_size_y: 4.0

    dwell: 0.02

    energy:
```

[22:42:31] [2022-02-11]



[22:42:31] [2022-02-11] Saved current acquisition image for sample holder1
[22:42:17] [2022-02-11] Dataset roi12270_14020 (holder1) has been stored into ICAT successfully
[22:41:03] [2022-02-11] so()
[20:54:02] [2022-02-11] sc()

[20:47:00] [2022-02-11] Starting KmapActor

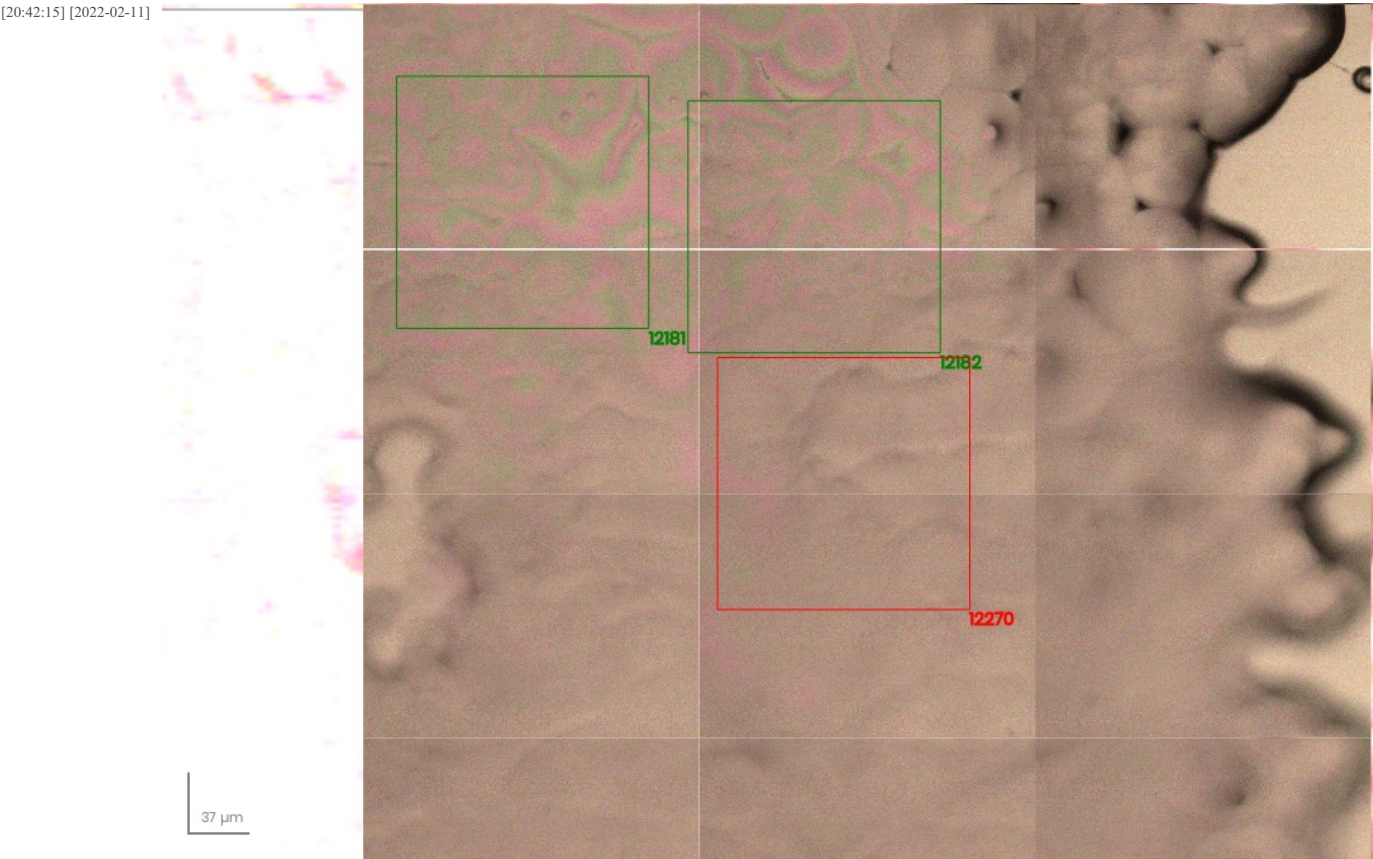
```
dataset: holder1_roi12270_14020.h5  
steps_x: 75  
steps_y: 75  
step_size_x: 2.0  
step_size_y: 2.0  
dwell: 0.02  
energy:
```

[20:46:42] [2022-02-11] Dataset roi12268_14017 (holder1) has been stored into ICAT successfully

[20:43:19] [2022-02-11] Starting KmapActor

```
dataset: holder1_roi12268_14017.h5  
steps_x: 75  
steps_y: 75  
step_size_x: 2.0  
step_size_y: 2.0  
dwell: 0.02  
energy:
```

[20:42:43] [2022-02-11] Dataset roi12267_14011 (holder1) has been stored into ICAT successfully
[20:42:35] [2022-02-11] Saved current acquisition image for sample holder1
[20:42:15] [2022-02-11] Saved current acquisition image for sample holder1



[20:33:35] [2022-02-11] Starting KmapActor

dataset: holder1_roi12267_14011.h5

steps_x: 75

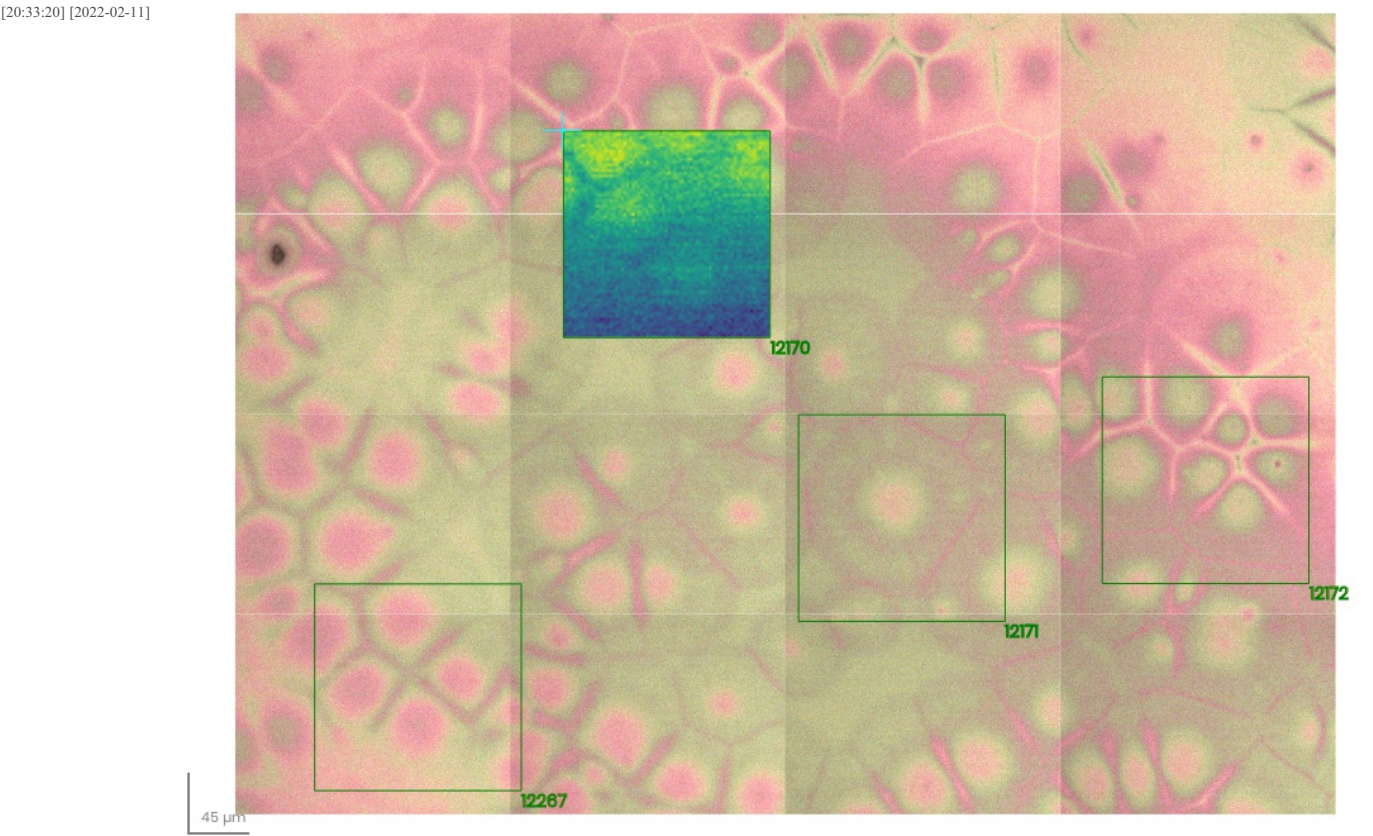
steps_y: 75

step_size_x: 2.0

step_size_y: 2.0

dwell: 0.02

energy:



[20:33:20] [2022-02-11] Saved current acquisition image for sample holder1

[20:31:38] [2022-02-11] so()

[20:27:10] [2022-02-11] exit()


```
[20:05:42] [2022-02-11]  se()

[19:04:35]  [2022-02-11]  Starting KmapActor

    dataset: holder1_roi12182_13985.h5

    steps_x: 75

    steps_y: 75

    step_size_x: 2.0

    step_size_y: 2.0

    dwell: 0.1

    energy:

[19:04:23] [2022-02-11]  Dataset roi12181_13982 (holder1) has been stored into ICAT successfully
[19:04:23] [2022-02-11]  Dataset roi12181_13982 (holder1) has been sent to archive. files=6 size=8645840171 bytes

[18:53:12]  [2022-02-11]  Starting KmapActor

    dataset: holder1_roi12181_13982.h5

    steps_x: 75

    steps_y: 75

    step_size_x: 2.0

    step_size_y: 2.0

    dwell: 0.1

    energy:

[18:53:00] [2022-02-11]  Dataset roi12180_13975 (holder1) has been stored into ICAT successfully
[18:53:00] [2022-02-11]  Dataset roi12180_13975 (holder1) has been sent to archive. files=6 size=8607901221 bytes

[18:41:50]  [2022-02-11]  Starting KmapActor

    dataset: holder1_roi12180_13975.h5

    steps_x: 75

    steps_y: 75

    step_size_x: 2.0

    step_size_y: 2.0

    dwell: 0.1

    energy:

[18:41:40] [2022-02-11]  Dataset roi12179_13969 (holder1) has been stored into ICAT successfully
[18:41:40] [2022-02-11]  Dataset roi12179_13969 (holder1) has been sent to archive. files=6 size=8645055047 bytes

[18:30:29]  [2022-02-11]  Starting KmapActor

    dataset: holder1_roi12179_13969.h5

    steps_x: 75

    steps_y: 75

    step_size_x: 2.0

    step_size_y: 2.0

    dwell: 0.1

    energy:

[18:30:15] [2022-02-11]  Dataset roi12174_13962 (holder1) has been sent to archive. files=6 size=8719251085 bytes
[18:30:14] [2022-02-11]  Dataset roi12174_13962 (holder1) has been stored into ICAT successfully

[18:19:05]  [2022-02-11]  Starting KmapActor

    dataset: holder1_roi12174_13962.h5

    steps_x: 75

    steps_y: 75

    step_size_x: 2.0

    step_size_y: 2.0

    dwell: 0.1

    energy:

[18:18:50] [2022-02-11]  Dataset roi12172_13955 (holder1) has been sent to archive. files=6 size=8720851167 bytes
[18:18:50] [2022-02-11]  Dataset roi12172_13955 (holder1) has been stored into ICAT successfully

[18:07:43]  [2022-02-11]  Starting KmapActor

    dataset: holder1_roi12172_13955.h5

    steps_x: 75

    steps_y: 75

    step_size_x: 2.0

    step_size_y: 2.0

    dwell: 0.1

    energy:

[18:07:29] [2022-02-11]  Dataset roi12171_13948 (holder1) has been stored into ICAT successfully
[18:07:29] [2022-02-11]  Dataset roi12171_13948 (holder1) has been sent to archive. files=6 size=8678082308 bytes
```

```

[17:56:22] [2022-02-11] Starting KmapActor

dataset: holder1_roi12171_13948.h5

steps_x: 75

steps_y: 75

step_size_x: 2.0

step_size_y: 2.0

dwell: 0.1

energy:

[17:55:46] [2022-02-11] Dataset roi12170_13938 (holder1) has been sent to archive. files=6 size=8568786740 bytes
[17:55:46] [2022-02-11] Dataset roi12170_13938 (holder1) has been stored into ICAT successfully

[17:38:12] [2022-02-11] Starting KmapActor

dataset: holder1_roi12170_13938.h5

steps_x: 75

steps_y: 75

step_size_x: 2.0

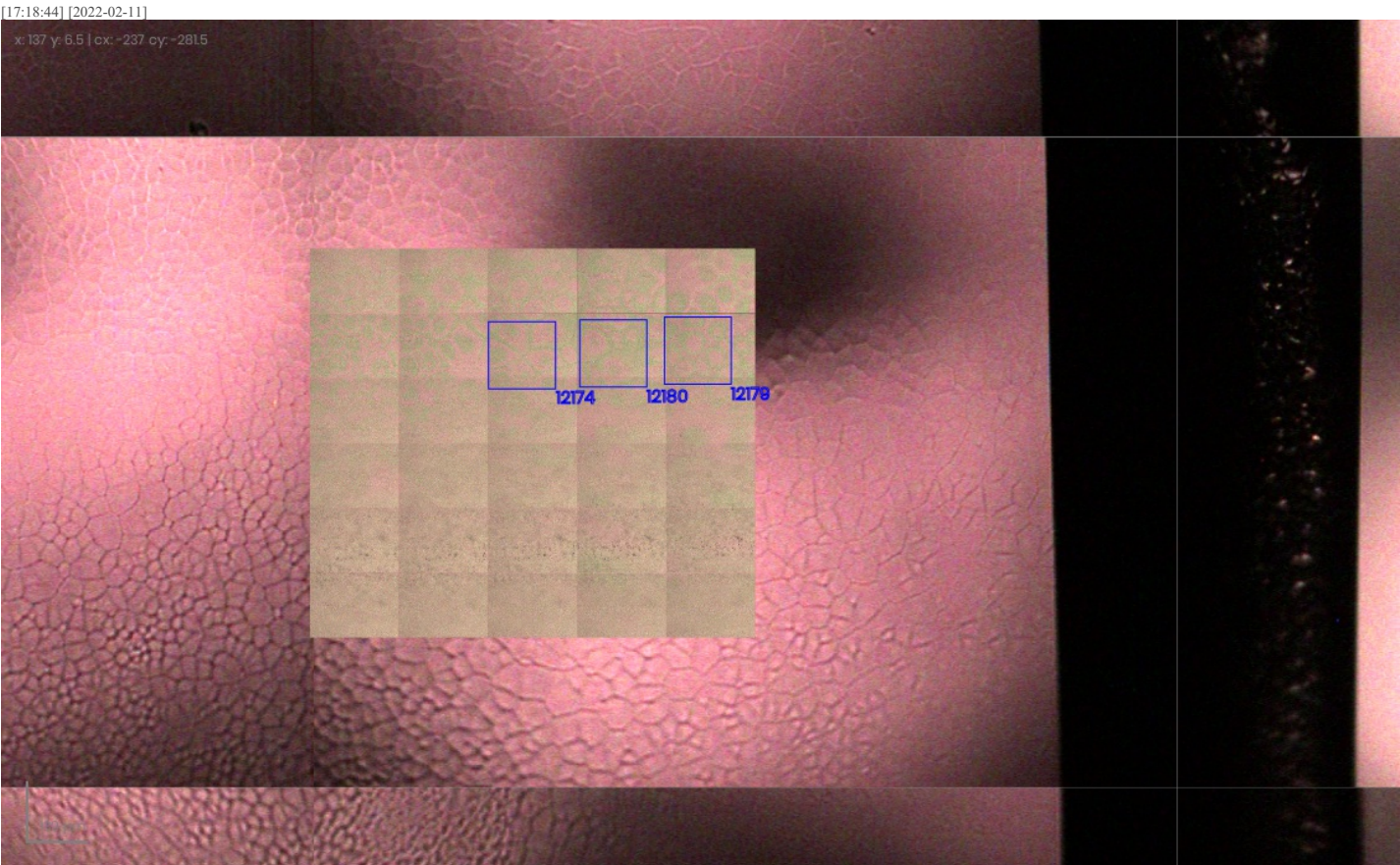
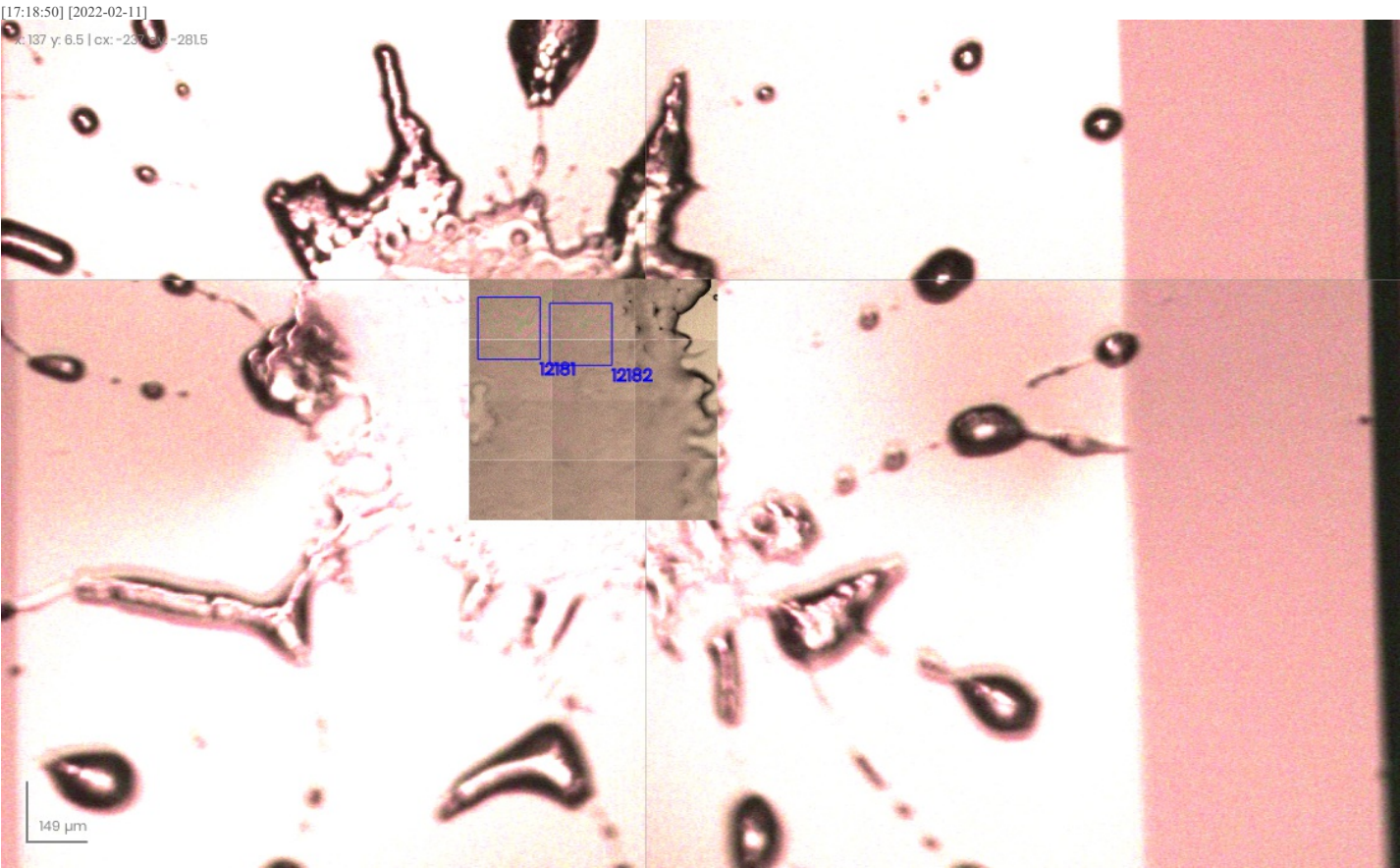
step_size_y: 2.0

dwell: 0.1

energy:

[17:36:16] [2022-02-11] edit_roi_counters(eiger)
[17:35:30] [2022-02-11] edit_roi_counters(eiger)
[17:35:23] [2022-02-11] eiger.roi_counters.clear()
[17:35:07] [2022-02-11] edit_roi_counters
[17:35:02] [2022-02-11] eiger.roi_counters
[17:34:18] [2022-02-11] ctt(0.1)
[17:34:00] [2022-02-11] ctt(0.1)
[17:33:42] [2022-02-11] umvr(ubsx, -0.05)
[17:33:41] [2022-02-11] umvr(ubsx, -0.05)
[17:33:38] [2022-02-11] lcag(ubsx, 0.11)
[17:33:27] [2022-02-11] umvr(ubsx, -0.05)
[17:33:24] [2022-02-11] lcag(ubsx, 0.06)
[17:33:01] [2022-02-11] ctt(0.1)
[17:32:56] [2022-02-11] umvr(ubsx, -0.05)
[17:32:53] [2022-02-11] lcag(ubsx, 0.06)
[17:32:45] [2022-02-11] ValueError: ubsx: move to '-1.611250' would exceed low limit (-1.561250)
[17:32:44] [2022-02-11] umvr(ubsx, -0.05)
[17:32:40] [2022-02-11] umvr(ubsx, -0.05)
[17:32:28] [2022-02-11] ctt(0.1)
[17:32:24] [2022-02-11] umvr(ubsx, 0.05)
[17:32:14] [2022-02-11] ValueError: ubsx: move to '-1.611250' would exceed low limit (-1.561250)
[17:32:14] [2022-02-11] umvr(ubsx, -0.05)
[17:31:40] [2022-02-11] ctt(0.1)
[17:31:18] [2022-02-11] ctt(0.02)
[17:29:51] [2022-02-11] ctt(0.02)
[17:29:45] [2022-02-11] MG_EH2
[17:29:37] [2022-02-11] so()
[17:29:31] [2022-02-11] dumpgeig()
[17:28:26] [2022-02-11] umv(udetx, -800)
[17:26:57] [2022-02-11] sc()
[17:26:06] [2022-02-11] bsalign()
[17:25:15] [2022-02-11] so()
[17:24:59] [2022-02-11] umvr(ubsx, -5)
[17:24:39] [2022-02-11] umvr(ubsx, -10)
[17:24:26] [2022-02-11] umvr(ubsx, 5)
[17:24:06] [2022-02-11] wm(ucryox)
[17:23:56] [2022-02-11] umvr(ucryox, -0.5)
[17:23:48] [2022-02-11] lcag(ucryox, -1.1)
[17:23:35] [2022-02-11] umvr(ucryox, -0.5)
[17:23:35] [2022-02-11] ValueError: ucryox: move to '134.000000' would exceed low limit (135.100000)
[17:23:11] [2022-02-11] lcag(ucryox, 0.6)
[17:23:03] [2022-02-11] lcag(ucryox, -0.6)
[17:22:59] [2022-02-11] NameError: name 'ucroyx' is not defined
[17:22:59] [2022-02-11] lcag(ucryox, -0.6)
[17:22:32] [2022-02-11] umvr(ucryox, -0.5)
[17:22:04] [2022-02-11] wm(ucryox)
[17:21:42] [2022-02-11] ValueError: ucryox: move to '134.000000' would exceed low limit (134.100000)
[17:21:42] [2022-02-11] umvr(ucryox, -1)
[17:21:35] [2022-02-11] umvr(ucryox, -1)
[17:21:31] [2022-02-11] umvr(ucryox, -3)
[17:20:47] [2022-02-11] umv(ubsy, 0, ucryoy, 0)
[17:19:48] [2022-02-11] umv(umicroz, 191)
[17:19:39] [2022-02-11] slil(0)
[17:18:50] [2022-02-11] Saved current acquisition image for sample holder1

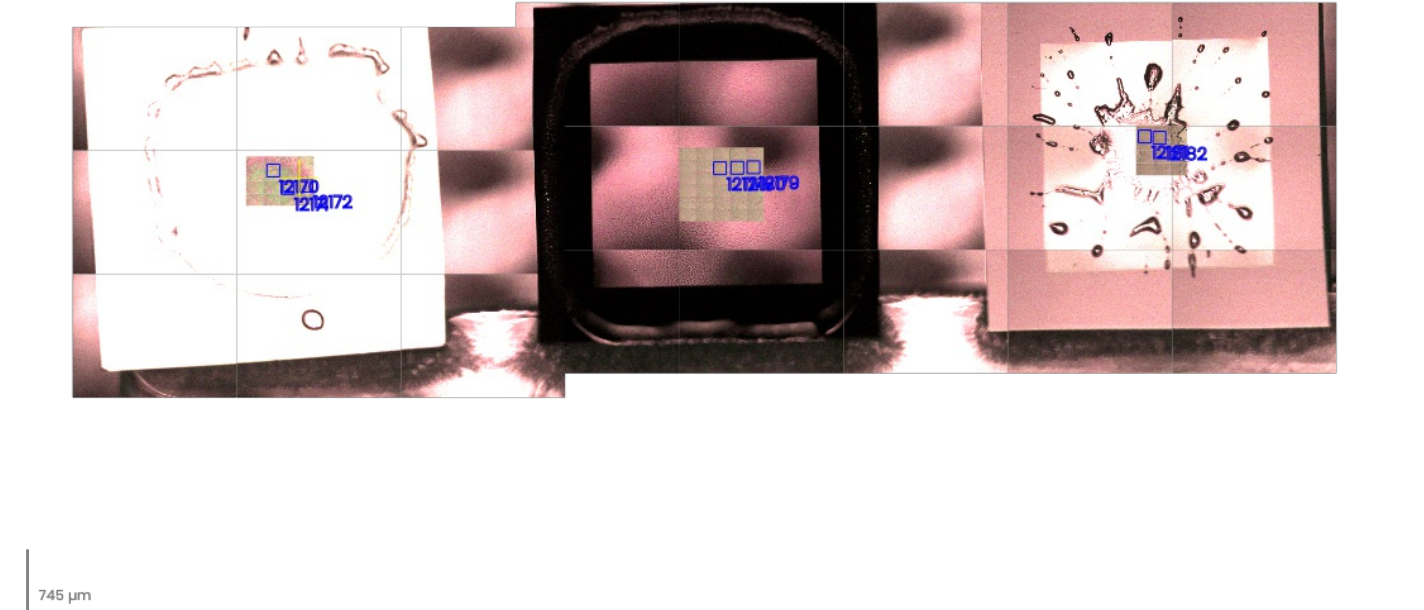
```



[17:18:44] [2022-02-11] Saved current acquisition image for sample holder1

[17:18:36] [2022-02-11]
x: 137 y: 6.5 | cx: -237 cy: -281.5

[17:18:35] [2022-02-11] Saved current acquisition image for sample holder1
[17:18:32] [2022-02-11] Saved current acquisition image for sample holder1
[17:18:32] [2022-02-11]
x: 388.1 y: 433.4 | cx: 14.1 cy: 145.4



[17:13:22] [2022-02-11] Actor ac647b9e-84b4-4f7e-99de-a0bc09c38ac8 failed with exception axis ustrz state is 'MOVING'
Traceback:
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/__init__.py", line 838, in execute
**self.initkwargs
File "/users/blissadm/local/daiquiri/daiquiri_id13/daiquiri_id13/implementors/imageviewer/move.py", line 8, in method
kwargs["absol"] ["move_to"] (kwargs["absol"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/imageviewer/__init__.py", line 1081, in move_to_absol
obj["motor"].move(obj["destination"] [0])

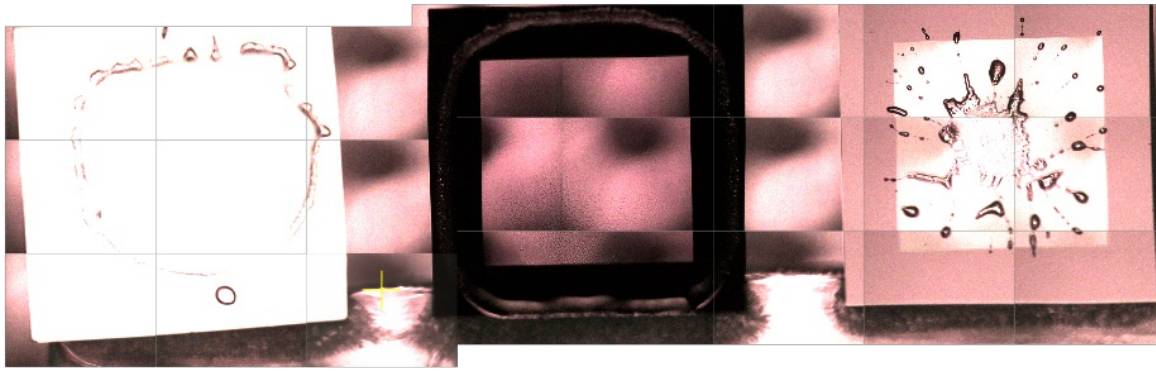
```

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/motor.py", line 49, in move
    self.call("move", value)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 196, in call
    ret = self._call(function, value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 478, in _call
    ret = getattr(self, "_call_{fn}".format(fn=function))(value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/bliss/motor.py", line 91, in _call_move
    self._object.move(value, wait=False)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 636, in func_wrapper
    return func(self, *args, **kwargs)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 1924, in move
    raise RuntimeError("axis %s state is %r" % (self.name, "MOVING"))

```

[17:01:52] [2022-02-11]

x: 3612 y: 543.5 | cx: -128 cy: 255.5



[17:01:52] [2022-02-11] Saved current acquisition image for sample holder1

[17:00:42] [2022-02-11] Dataset roi2092_13907 (mro_calib) has been stored into ICAT successfully

[17:00:43] [2022-02-11] Dataset roi2092_13907 (mro_calib) has been sent to archive. files=4 size=3219406766 bytes

[16:59:49] [2022-02-11] Actor f9e39268-fff3-410b-aal5-4733376fe86b failed with exception axis ustry state is 'MOVING'

Traceback:

```

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/__init__.py", line 838, in execute
    **self.initkwargs
File "/users/blissadm/local/daiquiri/daiquiri_id13/daiquiri_id13/implementors/imageviewer/move.py", line 8, in method
    kwargs["absol"](["move_to"] (kwargs["absol"]))
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/imageviewer/__init__.py", line 1083, in move_to_absol
    obj["motor"].move(obj["destination"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/motor.py", line 49, in move
    self.call("move", value)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 196, in call
    ret = self._call(function, value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 478, in _call
    ret = getattr(self, "_call_{fn}".format(fn=function))(value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/bliss/motor.py", line 91, in _call_move
    self._object.move(value, wait=False)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 636, in func_wrapper
    return func(self, *args, **kwargs)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 1924, in move
    raise RuntimeError("axis %s state is %r" % (self.name, "MOVING"))

```

[16:59:42] [2022-02-11] Actor 7d246508-bdc0-4717-9ba3-babbf7b0b4d8 failed with exception axis ustry state is 'MOVING'

Traceback:

```

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/__init__.py", line 838, in execute
    **self.initkwargs

```

```
File "/users/blissadm/local/daiquiri/daiquiri_id13/daiquiri_id13/implementors/imageviewer/move.py", line 8, in method
    kwargs["absol"] ["move_to"] (kwargs["absol"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/imageviewer/__init__.py", line 1083, in move_to_absol
    obj["motor"].move(obj["destination"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/motor.py", line 49, in move
    self.call("move", value)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 196, in call
    ret = self._call(function, value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 478, in _call
    ret = getattr(self, "_call_{fn}".format(fn=function))(value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/bliss/motor.py", line 91, in _call_move
    self._object.move(value, wait=False)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 636, in func_wrapper
    return func(self, *args, **kwargs)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 1924, in move
    raise RuntimeError("axis %s state is %r" % (self.name, "MOVING"))
```

[16:59:41] [2022-02-11] Actor 143d04b3-f352-4f45-9f3d-174549eddf28 failed with exception axis ustry state is 'MOVING'

Traceback:

```
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/__init__.py", line 838, in execute
    **self.initkwargs
File "/users/blissadm/local/daiquiri/daiquiri_id13/daiquiri_id13/implementors/imageviewer/move.py", line 8, in method
    kwargs["absol"] ["move_to"] (kwargs["absol"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/imageviewer/__init__.py", line 1083, in move_to_absol
    obj["motor"].move(obj["destination"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/motor.py", line 49, in move
    self.call("move", value)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 196, in call
    ret = self._call(function, value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 478, in _call
    ret = getattr(self, "_call_{fn}".format(fn=function))(value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/bliss/motor.py", line 91, in _call_move
    self._object.move(value, wait=False)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 636, in func_wrapper
    return func(self, *args, **kwargs)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 1924, in move
    raise RuntimeError("axis %s state is %r" % (self.name, "MOVING"))
```

[16:59:39] [2022-02-11] Actor e7b9ea5c-535d-4ec9-b84d-8e5d6c9538fe failed with exception axis ustry state is 'MOVING'

Traceback:

```
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/__init__.py", line 838, in execute
    **self.initkwargs
File "/users/blissadm/local/daiquiri/daiquiri_id13/daiquiri_id13/implementors/imageviewer/move.py", line 8, in method
    kwargs["absol"] ["move_to"] (kwargs["absol"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/imageviewer/__init__.py", line 1083, in move_to_absol
    obj["motor"].move(obj["destination"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/motor.py", line 49, in move
    self.call("move", value)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 196, in call
    ret = self._call(function, value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 478, in _call
    ret = getattr(self, "_call_{fn}".format(fn=function))(value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/bliss/motor.py", line 91, in _call_move
    self._object.move(value, wait=False)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 636, in func_wrapper
    return func(self, *args, **kwargs)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 1924, in move
    raise RuntimeError("axis %s state is %r" % (self.name, "MOVING"))
```

[16:59:38] [2022-02-11] Actor 379eebebe-64f4-4637-ab2a-55ce9bb5d031 failed with exception axis ustry state is 'MOVING'

Traceback:

```
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/__init__.py", line 838, in execute
    **self.initkwargs
File "/users/blissadm/local/daiquiri/daiquiri_id13/daiquiri_id13/implementors/imageviewer/move.py", line 8, in method
    kwargs["absol"] ["move_to"] (kwargs["absol"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/imageviewer/__init__.py", line 1083, in move_to_absol
    obj["motor"].move(obj["destination"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/motor.py", line 49, in move
    self.call("move", value)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 196, in call
```



```

    ret = self._call(function, value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 478, in _call
    ret = getattr(self, "_call_{fn}".format(fn=function))(value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/bliss/motor.py", line 91, in _call_move
    self._object.move(value, wait=False)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 636, in func_wrapper
    return func(self, *args, **kwargs)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 1924, in move
    raise RuntimeError("axis %s state is %r" % (self.name, "MOVING"))

[16:53:53] [2022-02-11] Actor 69c28390-027d-43e7-9994-6ed3afa9fd46 failed with exception axis ustrz state is 'MOVING'
Traceback:
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/__init__.py", line 838, in execute
    **self.initkwargs
File "/users/blissadm/local/daiquiri/daiquiri_id13/daiquiri_id13/implementors/imageviewer/move.py", line 8, in method
    kwargs["absol"]["move_to"](kwargs["absol"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/imageviewer/__init__.py", line 1083, in move_to_absol
    obj["motor"].move(obj["destination"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/motor.py", line 49, in move
    self.call("move", value)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 196, in call
    ret = self._call(function, value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 478, in _call
    ret = getattr(self, "_call_{fn}".format(fn=function))(value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/bliss/motor.py", line 91, in _call_move
    self._object.move(value, wait=False)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 636, in func_wrapper
    return func(self, *args, **kwargs)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 1924, in move
    raise RuntimeError("axis %s state is %r" % (self.name, "MOVING"))

[16:53:52] [2022-02-11] Actor 3778df55-cb9f-4c0d-8166-4e87ebddel3b failed with exception axis ustrz state is 'MOVING'
Traceback:
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/__init__.py", line 838, in execute
    **self.initkwargs
File "/users/blissadm/local/daiquiri/daiquiri_id13/daiquiri_id13/implementors/imageviewer/move.py", line 8, in method
    kwargs["absol"]["move_to"](kwargs["absol"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/imageviewer/__init__.py", line 1083, in move_to_absol
    obj["motor"].move(obj["destination"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/motor.py", line 49, in move
    self.call("move", value)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 196, in call
    ret = self._call(function, value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 478, in _call
    ret = getattr(self, "_call_{fn}".format(fn=function))(value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/bliss/motor.py", line 91, in _call_move
    self._object.move(value, wait=False)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 636, in func_wrapper
    return func(self, *args, **kwargs)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 1924, in move
    raise RuntimeError("axis %s state is %r" % (self.name, "MOVING"))

[16:53:27] [2022-02-11] Actor 9e695e6d-253d-4974-a2dc-a5a204e03c5f failed with exception axis ustrz state is 'MOVING'
Traceback:
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/__init__.py", line 838, in execute
    **self.initkwargs
File "/users/blissadm/local/daiquiri/daiquiri_id13/daiquiri_id13/implementors/imageviewer/move.py", line 8, in method
    kwargs["absol"]["move_to"](kwargs["absol"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/imageviewer/__init__.py", line 1083, in move_to_absol
    obj["motor"].move(obj["destination"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/motor.py", line 49, in move
    self.call("move", value)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 196, in call
    ret = self._call(function, value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 478, in _call
    ret = getattr(self, "_call_{fn}".format(fn=function))(value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/bliss/motor.py", line 91, in _call_move
    self._object.move(value, wait=False)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 636, in func_wrapper
    return func(self, *args, **kwargs)

```

```

File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 1924, in move
    raise RuntimeError("axis %s state is %r" % (self.name, "MOVING"))

[16:53:24] [2022-02-11] Actor c0ae7369-b9b2-49a6-9e8f-b6d4c30f3654 failed with exception axis ustrz state is 'MOVING'

Traceback:

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/__init__.py", line 838, in execute
    **self.initkwargs

File "/users/blissadm/local/daiquiri/daiquiri_id13/daiquiri_id13/implementors/imageviewer/move.py", line 8, in method
    kwargs["absol"]("move_to")(kwargs["absol"])

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/imageviewer/__init__.py", line 1083, in move_to_absol
    obj["motor"].move(obj["destination"])

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/motor.py", line 49, in move
    self.call("move", value)

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 196, in call
    ret = self._call(function, value, **kwargs)

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 478, in _call
    ret = getattr(self, "_call_{fn}".format(fn=function))(value, **kwargs)

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/bliss/motor.py", line 91, in _call_move
    self._object.move(value, wait=False)

File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 636, in func_wrapper
    return func(self, *args, **kwargs)

File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 1924, in move
    raise RuntimeError("axis %s state is %r" % (self.name, "MOVING"))

[16:52:48] [2022-02-11] slil(25)
[16:52:31] [2022-02-11] umv(umicroz, 0)
[16:52:20] [2022-02-11] umv(umicroz, 50)
[16:52:03] [2022-02-11] umv(umicroz, 100)
[16:46:04] [2022-02-11] umv(ucryoy, 150, ubsy, -100)
[16:45:12] [2022-02-11] umvr(ucryox, 5)
[16:44:37] [2022-02-11] umvr(ubsx, 5)
[16:44:27] [2022-02-11] umvr(ubsx, 5)
[16:42:58] [2022-02-11] umv(udetx, -255)
[16:42:33] [2022-02-11] sc()
[16:38:44] [2022-02-11] dkmapyz_2(-0.1, 0.1, 30, -0.1, 0.1, 30, 0.02)
[16:38:06] [2022-02-11] #kmap.akmap(ustry, -0.1, 0.1, 30, ustrz, -0.1, 0.1, 30, 0.02)
[16:37:27] [2022-02-11] kmap.dkmap(ustry, -0.1, 0.1, 30, ustrz, -0.1, 0.1, 30, 0.02)
[16:37:27] [2022-02-11] RuntimeError: musst doesn't have channel (ustrz) in his config
[16:36:25] [2022-02-11] MG_EH2
[16:36:22] [2022-02-11] fshtrigger()
[16:36:14] [2022-02-11] dmqgeigt()

[16:30:52] [2022-02-11] Starting KmapActor

    dataset: mro_calib_rol12092_13907.h5

    steps_x: 45

    steps_y: 35

    step_size_x: 5.0

    step_size_y: 5.0

    dwell: 0.02

    energy:

[16:27:47] [2022-02-11] fshtrigger()
[16:27:38] [2022-02-11] dmqgeigt()
[16:26:03] [2022-02-11] ct(0.02)
[16:25:56] [2022-02-11] ct(0.01)
[16:25:33] [2022-02-11] umv(udetx, -800)
[16:25:04] [2022-02-11] dscan(ustry, -0.2, 0.2, 50, 0.01)
[16:24:57] [2022-02-11] fshtrigger()
[16:24:31] [2022-02-11] dscan(ustry, -0.2, 0.2, 50, 0.01)
[16:23:37] [2022-02-11] ct(0.01)
[16:21:05] [2022-02-11] ct(0.01)
[16:20:48] [2022-02-11] ct(0.1)
[16:20:28] [2022-02-11] umv(udetx, -700)
[16:20:10] [2022-02-11] umv(udetx, -600)
[16:19:23] [2022-02-11] umv(udetx, -500)
[16:19:04] [2022-02-11] wm(udetx)
[16:17:19] [2022-02-11] ct(0.01)
[16:17:11] [2022-02-11] MG_EH2
[16:17:05] [2022-02-11] mgeigt()
[16:16:57] [2022-02-11] MG_EH2
[16:16:39] [2022-02-11] so(); ct(0.01)
[16:16:35] [2022-02-11] fshtrigger()
[16:16:16] [2022-02-11] so(); ct(0.01)
[16:15:54] [2022-02-11] so(); ct(0.001)
[16:15:35] [2022-02-11] fshtrigger()
[16:15:25] [2022-02-11] MG_EH2
[16:15:16] [2022-02-11] dmqgeigt()
[16:14:42] [2022-02-11] MG_EH2
[16:14:34] [2022-02-11] mgeigt()
[16:12:06] [2022-02-11] sc()
[16:11:25] [2022-02-11] bsalign()
[16:10:42] [2022-02-11] bsalign()
[16:10:37] [2022-02-11] where()
[16:10:32] [2022-02-11] gopt(38)
[16:09:34] [2022-02-11] bsalign()
[16:09:29] [2022-02-11] where()
[16:09:27] [2022-02-11] goc(ubsy)
[16:08:52] [2022-02-11] dscan(ubsy, -1, 1, 100, 0.1)
[16:08:33] [2022-02-11] umvr(ubsy, -2)
[16:08:21] [2022-02-11] where()
[16:08:10] [2022-02-11] goc(ubsz)
[16:06:31] [2022-02-11] dscan(ubsz, -1, 1, 100, 0.1)
[16:05:50] [2022-02-11] umvr(ubsy, 2)
[16:05:04] [2022-02-11] MG_EH2
[16:04:47] [2022-02-11] wm(ubsy)
[16:03:56] [2022-02-11] bsalign()
[16:03:49] [2022-02-11] ct()
[16:03:45] [2022-02-11] mgld()
[16:03:42] [2022-02-11] fshtrigger()
[16:02:55] [2022-02-11] bsalign()
[16:02:32] [2022-02-11] so()
[16:02:19] [2022-02-11] lcag(ubsx, 0)
[16:01:32] [2022-02-11] umvr(ubsx, -0.1)
[16:01:31] [2022-02-11] umvr(ubsx, -0.1)
[16:01:16] [2022-02-11] umvr(ubsx, -0.5)

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[16:01:11] [2022-02-11] umvr(ubsx, -1)
[16:01:08] [2022-02-11] umvr(ubsx, -1)
[16:01:06] [2022-02-11] lcag(ubsx, -3)
[16:00:43] [2022-02-11] umvr(ubsx, -1)
[16:00:43] [2022-02-11] ValueError: ubsx: move to '0.138750' would exceed low limit (0.858750)
[16:00:35] [2022-02-11] umvr(ubsx, -2)
[16:00:21] [2022-02-11] umvr(ubsx, -3)
[15:59:57] [2022-02-11] umvr(ubsx, -10)
[15:59:39] [2022-02-11] umvr(ubsx, -10)
[15:56:36] [2022-02-11] lcag(ucryox, 0.1)
[15:56:33] [2022-02-11] lcage(ucryox, 0.1)
[15:56:33] [2022-02-11] NameError: name 'lcage' is not defined
[15:56:09] [2022-02-11] wvr(ucryox)
[15:55:48] [2022-02-11] umvr(ucryox, -1)
[15:55:32] [2022-02-11] umvr(ucryox, -1)
[15:55:27] [2022-02-11] umvr(ucryox, -3)
[15:55:22] [2022-02-11] umvr(ucryox, -5)
[15:55:18] [2022-02-11] umvr(ucryox, -5)
[15:55:18] [2022-02-11] ValueError: ucryox: move to '-5.000000' would exceed low limit (134.000000)
[15:54:50] [2022-02-11] umv(ubsy, 0)
[15:53:59] [2022-02-11] umv(ucryoy, 0)
[15:52:04] [2022-02-11] umvr(umicroz, 191)
[15:51:55] [2022-02-11] slil(0)
[15:50:45] [2022-02-11] umvr(ustrx, -0.01)
[15:50:43] [2022-02-11] umvr(ustrx, -0.01)
[15:50:40] [2022-02-11] umvr(ustrx, 0.01)
[15:50:39] [2022-02-11] umvr(ustrx, 0.01)
[15:50:38] [2022-02-11] umvr(ustrx, 0.01)
[15:50:37] [2022-02-11] umvr(ustrx, 0.01)
[15:50:32] [2022-02-11] umvr(ustrx, 0.1)
[15:50:30] [2022-02-11] umvr(ustrx, 0.1)
[15:50:29] [2022-02-11] umvr(ustrx, 0.1)
[15:50:28] [2022-02-11] umvr(ustrx, 0.1)
[15:50:27] [2022-02-11] umvr(ustrx, 0.1)
[15:50:26] [2022-02-11] umvr(ustrx, 0.1)
[15:50:18] [2022-02-11] umvr(ustrx, -0.01)
[15:50:19] [2022-02-11] umvr(ustrx, -0.01)
[15:50:18] [2022-02-11] umvr(ustrx, -0.01)
[15:50:14] [2022-02-11] umvr(ustrx, -0.01)
[15:50:12] [2022-02-11] umvr(ustrx, -0.01)
[15:50:12] [2022-02-11] umvr(ustrx, -0.01)
[15:50:11] [2022-02-11] umvr(ustrx, -0.01)
[15:50:10] [2022-02-11] umvr(ustrx, -0.01)
[15:50:09] [2022-02-11] umvr(ustrx, -0.01)
[15:50:08] [2022-02-11] umvr(ustrx, -0.01)
[15:50:07] [2022-02-11] umvr(ustrx, -0.01)
[15:50:06] [2022-02-11] umvr(ustrx, -0.01)
[15:50:05] [2022-02-11] umvr(ustrx, -0.01)
[15:50:04] [2022-02-11] umvr(ustrx, -0.01)
[15:50:03] [2022-02-11] umvr(ustrx, -0.01)
[15:50:02] [2022-02-11] umvr(ustrx, -0.01)
[15:50:02] [2022-02-11] umvr(ustrx, -0.01)
[15:50:01] [2022-02-11] umvr(ustrx, -0.01)
[15:49:56] [2022-02-11] slil(30)
[15:49:51] [2022-02-11] umvr(ustrx, -0.01)
[15:49:49] [2022-02-11] umvr(ustrx, -0.01)
[15:49:48] [2022-02-11] umvr(ustrx, -0.01)
[15:49:47] [2022-02-11] umvr(ustrx, -0.01)
[15:49:46] [2022-02-11] umvr(ustrx, -0.01)
[15:49:45] [2022-02-11] umvr(ustrx, -0.01)
[15:49:44] [2022-02-11] umvr(ustrx, -0.01)
[15:49:43] [2022-02-11] umvr(ustrx, -0.01)
[15:49:42] [2022-02-11] umvr(ustrx, -0.01)
[15:49:41] [2022-02-11] umvr(ustrx, -0.01)
[15:49:40] [2022-02-11] umvr(ustrx, -0.01)
[15:49:39] [2022-02-11] umvr(ustrx, -0.01)
[15:49:38] [2022-02-11] umvr(ustrx, -0.01)
[15:49:35] [2022-02-11] umvr(ustrx, 0.01)
[15:49:34] [2022-02-11] umvr(ustrx, 0.01)
[15:49:33] [2022-02-11] umvr(ustrx, 0.01)
[15:47:09] [2022-02-11] umvr(ustrx, -0.20)
[15:46:28] [2022-02-11] umvr(ustrx, 0.050)
[15:46:24] [2022-02-11] umvr(ustrx, 0.150)
[15:46:21] [2022-02-11] umvr(ustrx, -0.150)
[15:46:18] [2022-02-11] umvr(ustrx, -0.150)
[15:46:17] [2022-02-11] umvr(ustrx, -0.150)
[15:46:14] [2022-02-11] umvr(ustrx, 0.150)
[15:45:50] [2022-02-11] slil(23)
[15:45:46] [2022-02-11] slil(25)
[15:45:12] [2022-02-11] umvr(ustrx, 0.005)
[15:45:10] [2022-02-11] umvr(ustrx, 0.005)
[15:45:06] [2022-02-11] umvr(ustrx, -0.005)
[15:45:05] [2022-02-11] umvr(ustrx, -0.005)
[15:45:04] [2022-02-11] umvr(ustrx, -0.005)
[15:45:03] [2022-02-11] umvr(ustrx, -0.005)
[15:45:02] [2022-02-11] umvr(ustrx, -0.005)
[15:45:01] [2022-02-11] umvr(ustrx, -0.005)
[15:45:00] [2022-02-11] umvr(ustrx, -0.005)
[15:44:57] [2022-02-11] umvr(ustrx, 0.005)
[15:44:56] [2022-02-11] umvr(ustrx, 0.005)
[15:44:39] [2022-02-11] slil(30)
[15:44:23] [2022-02-11] umvr(ustrx, 0.050)
[15:44:21] [2022-02-11] umvr(ustrx, 0.050)
[15:44:18] [2022-02-11] umvr(ustrx, -0.050)
[15:44:11] [2022-02-11] umvr(ustrx, -0.050)
[15:44:09] [2022-02-11] umvr(ustrx, -0.050)
[15:44:08] [2022-02-11] umvr(ustrx, -0.050)
[15:44:03] [2022-02-11] umvr(ustrx, 0.050)
[15:43:51] [2022-02-11] umvr(ustrx, 0.15)
[15:42:45] [2022-02-11] umvr(ustrx, 0.01)
[15:42:42] [2022-02-11] umvr(ustrx, -0.01)
[15:42:36] [2022-02-11] umvr(ustrx, -0.01)
[15:42:35] [2022-02-11] umvr(ustrx, -0.01)
[15:42:35] [2022-02-11] umvr(ustrx, -0.01)
[15:42:34] [2022-02-11] umvr(ustrx, -0.01)
[15:42:29] [2022-02-11] slil(24)
[15:42:24] [2022-02-11] slil(22)
[15:42:21] [2022-02-11] slil(28)
[15:42:18] [2022-02-11] slil(280)
[15:42:18] [2022-02-11] RuntimeError: Invalid value [280] (must be from 0 to 100 %)
[15:42:09] [2022-02-11] umvr(ustrx, -0.01)
[15:42:08] [2022-02-11] umvr(ustrx, -0.01)
[15:42:04] [2022-02-11] umvr(ustrx, -0.01)
[15:42:02] [2022-02-11] umvr(ustrx, -0.01)
[15:42:02] [2022-02-11] umvr(ustrx, -0.01)
[15:42:01] [2022-02-11] umvr(ustrx, -0.01)
[15:42:00] [2022-02-11] umvr(ustrx, -0.01)
[15:41:59] [2022-02-11] umvr(ustrx, -0.01)
[15:41:58] [2022-02-11] umvr(ustrx, -0.01)
[15:41:57] [2022-02-11] umvr(ustrx, -0.01)
[15:41:57] [2022-02-11] umvr(ustrx, -0.01)
[15:41:56] [2022-02-11] umvr(ustrx, -0.01)
[15:41:54] [2022-02-11] umvr(ustrx, -0.01)
[15:41:54] [2022-02-11] umvr(ustrx, -0.01)
[15:41:53] [2022-02-11] umvr(ustrx, -0.01)
[15:41:52] [2022-02-11] umvr(ustrx, -0.01)
[15:41:51] [2022-02-11] umvr(ustrx, -0.01)
[15:41:48] [2022-02-11] umvr(ustrx, 0.01)
[15:41:47] [2022-02-11] umvr(ustrx, 0.01)
[15:41:40] [2022-02-11] umvr(ustrx, 0.01)
[15:40:07] [2022-02-11] slil(30)
[15:38:24] [2022-02-11] umvr(ustrx, 0.01)
[15:38:23] [2022-02-11] umvr(ustrx, 0.01)
[15:38:22] [2022-02-11] umvr(ustrx, 0.01)
[15:38:21] [2022-02-11] umvr(ustrx, 0.01)
[15:38:20] [2022-02-11] umvr(ustrx, 0.01)
[15:38:19] [2022-02-11] umvr(ustrx, 0.01)
[15:38:18] [2022-02-11] umvr(ustrx, 0.01)


```
[15:38:17] [2022-02-11] umvr(ustrx, 0.01)
[15:38:16] [2022-02-11] umvr(ustrx, 0.01)
[15:38:15] [2022-02-11] umvr(ustrx, 0.01)
[15:38:14] [2022-02-11] umvr(ustrx, 0.01)
[15:38:11] [2022-02-11] umvr(ustrx, 0.01)
[15:36:37] [2022-02-11] umvr(ustrz, -0.1)
[15:36:35] [2022-02-11] umvr(ustrz, -0.1)
[15:36:33] [2022-02-11] umvr(ustrz, -0.1)
[15:36:32] [2022-02-11] umvr(ustrz, -0.1)
[15:36:31] [2022-02-11] umvr(ustrz, -0.1)
[15:36:29] [2022-02-11] umvr(ustrz, -0.1)
[15:36:28] [2022-02-11] umvr(ustrz, -0.1)
[15:36:27] [2022-02-11] umvr(ustrz, -0.1)
[15:36:25] [2022-02-11] umvr(ustrz, -0.1)
[15:36:24] [2022-02-11] umvr(ustrz, -0.1)
[15:36:23] [2022-02-11] umvr(ustrz, -0.1)
[15:34:44] [2022-02-11] sc()
[15:34:17] [2022-02-11] wm(ustrz)
```

[15:34:03] [2022-02-11] Actor aad724a1-cdfc-4118-8731-7533935fd69d failed with exception ustrz: discrepancy between dial (6.704788) and controller position (6.705795), aborting

Traceback:

```
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/__init__.py", line 838, in execute
    **self.initkwargs

File "/users/blissadm/local/daiquiri/daiquiri_id13/daiquiri_id13/implementors/imageviewer/move.py", line 8, in method
    kwargs["absol"] ["move_to"] (kwargs["absol"])

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/imageviewer/__init__.py", line 1083, in move_to_absol
    obj["motor"].move(obj["destination"])

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/motor.py", line 49, in move
    self.call("move", value)

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 196, in call
    ret = self._call(function, value, **kwargs)

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 478, in _call
    ret = getattr(self, "_call_{fn}".format(fn=function))(value, **kwargs)

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/bliss/motor.py", line 91, in _call_move
    self._object.move(value, wait=False)

File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 636, in func_wrapper
    return func(self, *args, **kwargs)

File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 1926, in move
    motion = self.get_motion(user_target_pos, relative, polling_time)

File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 636, in func_wrapper
    return func(self, *args, **kwargs)

File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 1856, in get_motion
    % (self.name, dial_initial_pos, hw_pos)
```

[15:34:02] [2022-02-11] Actor 9110c592-76b8-4a38-9409-91c87aea264b failed with exception ustrz: discrepancy between dial (6.704788) and controller position (6.705795), aborting

Traceback:

```
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/__init__.py", line 838, in execute
    **self.initkwargs

File "/users/blissadm/local/daiquiri/daiquiri_id13/daiquiri_id13/implementors/imageviewer/move.py", line 8, in method
    kwargs["absol"] ["move_to"] (kwargs["absol"])

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/imageviewer/__init__.py", line 1083, in move_to_absol
    obj["motor"].move(obj["destination"])

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/motor.py", line 49, in move
    self.call("move", value)

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 196, in call
    ret = self._call(function, value, **kwargs)

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 478, in _call
    ret = getattr(self, "_call_{fn}".format(fn=function))(value, **kwargs)

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/bliss/motor.py", line 91, in _call_move
    self._object.move(value, wait=False)

File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 636, in func_wrapper
    return func(self, *args, **kwargs)

File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 1926, in move
    motion = self.get_motion(user_target_pos, relative, polling_time)

File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 636, in func_wrapper
    return func(self, *args, **kwargs)

File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 1856, in get_motion
    % (self.name, dial_initial_pos, hw_pos)
```

[15:34:02] [2022-02-11] Actor 3789b2d8-249b-429b-afd4-6b5096c62287 failed with exception ustrz: discrepancy between dial (6.704788) and controller position (6.705795), aborting

Traceback:

```
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/__init__.py", line 838, in execute
    **self.initkwargs

File "/users/blissadm/local/daiquiri/daiquiri_id13/daiquiri_id13/implementors/imageviewer/move.py", line 8, in method
    kwargs["absol"] ["move_to"] (kwargs["absol"])

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/imageviewer/__init__.py", line 1083, in move_to_absol
    obj["motor"].move(obj["destination"])

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/motor.py", line 49, in move
    self.call("move", value)
```

```

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 196, in call
    ret = self._call(function, value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 478, in _call
    ret = getattr(self, "_call_{fn}".format(fn=function))(value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/bliss/motor.py", line 91, in _call_move
    self._object.move(value, wait=False)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 636, in func_wrapper
    return func(self, *args, **kwargs)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 1926, in move
    motion = self.get_motion(user_target_pos, relative, polling_time)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 636, in func_wrapper
    return func(self, *args, **kwargs)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 1856, in get_motion
    % (self.name, dial_initial_pos, hw_pos)

[15:33:27] [2022-02-11] Actor 5b208e32-e8c5-4922-8a20-76304d52bcc9 failed with exception axis ustrz state is 'MOVING'
Traceback:
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/__init__.py", line 838, in execute
    **self.initkwargs
File "/users/blissadm/local/daiquiri/daiquiri_idl3/daiquiri_idl3/implementors/imageviewer/move.py", line 8, in method
    kwargs["absol"]["move_to"](kwargs["absol"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/imageviewer/__init__.py", line 1083, in move_to_absol
    obj["motor"].move(obj["destination"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/motor.py", line 49, in move
    self.call("move", value)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 196, in call
    ret = self._call(function, value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 478, in _call
    ret = getattr(self, "_call_{fn}".format(fn=function))(value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/bliss/motor.py", line 91, in _call_move
    self._object.move(value, wait=False)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 636, in func_wrapper
    return func(self, *args, **kwargs)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 1924, in move
    raise RuntimeError("axis %s state is %r" % (self.name, "MOVING"))

[15:32:47] [2022-02-11] Actor c4e2d760-5a7f-4d1a-a39f-afa465f57197 failed with exception axis ustrz state is 'MOVING'
Traceback:
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/__init__.py", line 838, in execute
    **self.initkwargs
File "/users/blissadm/local/daiquiri/daiquiri_idl3/daiquiri_idl3/implementors/imageviewer/move.py", line 8, in method
    kwargs["absol"]["move_to"](kwargs["absol"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/imageviewer/__init__.py", line 1083, in move_to_absol
    obj["motor"].move(obj["destination"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/motor.py", line 49, in move
    self.call("move", value)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 196, in call
    ret = self._call(function, value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 478, in _call
    ret = getattr(self, "_call_{fn}".format(fn=function))(value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/bliss/motor.py", line 91, in _call_move
    self._object.move(value, wait=False)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 636, in func_wrapper
    return func(self, *args, **kwargs)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 1924, in move
    raise RuntimeError("axis %s state is %r" % (self.name, "MOVING"))

[15:32:37] [2022-02-11] umvr(ustrx,0.01)
[15:32:36] [2022-02-11] umvr(ustrx,0.01)
[15:32:34] [2022-02-11] umvr(ustrx,0.01)
[15:32:33] [2022-02-11] umvr(ustrx,0.01)
[15:32:32] [2022-02-11] umvr(ustrx,0.01)
[15:32:28] [2022-02-11] umvr(ustrx,0.01)
[15:32:27] [2022-02-11] umvr(ustrx,0.01)
[15:32:27] [2022-02-11] umvr(ustrx,0.01)
[15:32:26] [2022-02-11] umvr(ustrx,0.01)
[15:32:25] [2022-02-11] umvr(ustrx,0.01)
[15:32:24] [2022-02-11] umvr(ustrx,0.01)
[15:32:23] [2022-02-11] umvr(ustrx,0.01)
[15:32:22] [2022-02-11] umvr(ustrx,0.01)
[15:32:21] [2022-02-11] umvr(ustrx,0.01)
[15:32:21] [2022-02-11] umvr(ustrx,0.01)
[15:32:20] [2022-02-11] umvr(ustrx,0.01)
[15:32:19] [2022-02-11] umvr(ustrx,0.01)
[15:32:18] [2022-02-11] umvr(ustrx,0.01)
[15:32:17] [2022-02-11] umvr(ustrx,0.01)
[15:32:16] [2022-02-11] umvr(ustrx,0.01)
[15:32:15] [2022-02-11] umvr(ustrx,0.01)
[15:32:14] [2022-02-11] umvr(ustrx,0.01)
[15:32:14] [2022-02-11] umvr(ustrx,0.01)
[15:32:13] [2022-02-11] umvr(ustrx,0.01)
[15:32:12] [2022-02-11] umvr(ustrx,0.01)
[15:32:12] [2022-02-11] umvr(ustrx,0.01)

```

```
[15:32:11] [2022-02-11] umvr(ustrx,0.01)
[15:32:10] [2022-02-11] umvr(ustrx,0.01)
[15:32:09] [2022-02-11] umvr(ustrx,0.01)
[15:32:05] [2022-02-11] umvr(ustrx,0.5)
[15:31:59] [2022-02-11] umvr(ustrx,-0.1)
[15:31:56] [2022-02-11] umvr(ustrx,-0.1)
[15:31:58] [2022-02-11] umvr(ustrx,-0.1)
[15:31:58] [2022-02-11] umvr(ustrx,-0.1)
[15:31:39] [2022-02-11] umvr(ustrx,-0.1)
[15:31:35] [2022-02-11] umvr(ustrx,-0.1)
[15:31:34] [2022-02-11] umvr(ustrx,-0.1)
[15:31:33] [2022-02-11] umvr(ustrx,-0.1)
[15:31:32] [2022-02-11] umvr(ustrx,-0.1)
[15:31:25] [2022-02-11] umvr(ustrx,0.01)
[15:31:24] [2022-02-11] umvr(ustrx,0.01)
[15:31:24] [2022-02-11] umvr(ustrx,0.01)
[15:31:22] [2022-02-11] umvr(ustrx,0.01)
[15:31:22] [2022-02-11] umvr(ustrx,0.01)
[15:31:21] [2022-02-11] umvr(ustrx,0.01)
[15:31:19] [2022-02-11] umvr(ustrx,0.01)
[15:31:17] [2022-02-11] umvr(ustrx,0.01)
[15:31:16] [2022-02-11] umvr(ustrx,0.01)
[15:31:15] [2022-02-11] umvr(ustrx,0.01)
[15:31:13] [2022-02-11] umvr(ustrx,0.01)
[15:31:14] [2022-02-11] umvr(ustrx,0.01)
[15:31:12] [2022-02-11] umvr(ustrx,0.01)
[15:31:11] [2022-02-11] umvr(ustrx,0.01)
[15:31:11] [2022-02-11] umvr(ustrx,0.01)
[15:31:10] [2022-02-11] umvr(ustrx,0.01)
[15:31:09] [2022-02-11] umvr(ustrx,0.01)
[15:31:08] [2022-02-11] umvr(ustrx,0.01)
[15:31:04] [2022-02-11] umvr(ustrx,-0.1)
[15:31:03] [2022-02-11] umvr(ustrx,-0.1)
[15:31:02] [2022-02-11] umvr(ustrx,-0.1)
[15:31:01] [2022-02-11] umvr(ustrx,-0.1)
[15:31:00] [2022-02-11] umvr(ustrx,-0.1)
[15:30:57] [2022-02-11] umvr(ustrx,0.1)
[15:30:56] [2022-02-11] umvr(ustrx,0.1)
[15:30:54] [2022-02-11] umvr(ustrx,0.1)

[15:30:34] [2022-02-11] Actor 042b40bc-8adb-45a8-9599-bc484eb4f4b3 failed with exception axis ustrz state is 'MOVING'

Traceback:

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/__init__.py", line 838, in execute
    **self.initkwargs

File "/users/blissadm/local/daiquiri/daiquiri_idl3/daiquiri_idl3/implementors/imageviewer/move.py", line 8, in method
    kwargs["absol"] ["move_to"] (kwargs["absol"])

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/imageviewer/__init__.py", line 1083, in move_to_absol
    obj["motor"].move(obj["destination"])

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/motor.py", line 49, in move
    self.call("move", value)

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 196, in call
    ret = self._call(function, value, **kwargs)

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 478, in _call
    ret = getattr(self, "_call_{fn}".format(fn=function))(value, **kwargs)

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/bliss/motor.py", line 91, in _call_move
    self._object.move(value, wait=False)

File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 636, in func_wrapper
    return func(self, *args, **kwargs)

File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 1924, in move
    raise RuntimeError("axis %s state is %r" % (self.name, "MOVING"))

[15:27:30] [2022-02-11] umvr(ustrx,0.01)
[15:27:27] [2022-02-11] umvr(ustrx,-0.01)
[15:27:25] [2022-02-11] umvr(ustrx,-0.01)
[15:27:26] [2022-02-11] umvr(ustrx,-0.01)
[15:27:25] [2022-02-11] umvr(ustrx,-0.01)
[15:27:24] [2022-02-11] umvr(ustrx,-0.01)
[15:27:23] [2022-02-11] umvr(ustrx,-0.01)
[15:27:22] [2022-02-11] umvr(ustrx,-0.01)
[15:27:22] [2022-02-11] umvr(ustrx,-0.01)
[15:27:21] [2022-02-11] umvr(ustrx,-0.01)
[15:27:17] [2022-02-11] umvr(ustrx,0.01)
[15:27:16] [2022-02-11] umvr(ustrx,0.01)

[15:25:30] [2022-02-11] Actor 9ad7176f-8ac3-4b74-91a9-fb1c0a88c8e7 failed with exception ustrz: discrepancy between dial (11.202988) and controller position (11.203995), aborting

Traceback:

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/__init__.py", line 838, in execute
    **self.initkwargs

File "/users/blissadm/local/daiquiri/daiquiri_idl3/daiquiri_idl3/implementors/imageviewer/move.py", line 8, in method
    kwargs["absol"] ["move_to"] (kwargs["absol"])

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/imageviewer/__init__.py", line 1083, in move_to_absol
    obj["motor"].move(obj["destination"])

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/motor.py", line 49, in move
    self.call("move", value)

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 196, in call
    ret = self._call(function, value, **kwargs)

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 478, in _call
    ret = getattr(self, "_call_{fn}".format(fn=function))(value, **kwargs)

File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/bliss/motor.py", line 91, in _call_move
    self._object.move(value, wait=False)

File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 636, in func_wrapper
    return func(self, *args, **kwargs)

File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 1926, in move
    motion = self.get_motion(user_target_pos, relative, polling_time)

File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 636, in func_wrapper
    return func(self, *args, **kwargs)
```



```

File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 1856, in get_motion
    % (self.name, dial_initial_pos, hw_pos)

[15:25:06] [2022-02-11]   umv(umicroz, 0)
[15:24:52] [2022-02-11]   umv(umicroz, 50)
[15:24:31] [2022-02-11]   umv(umicroz, 100)

[15:24:13]   [2022-02-11]   Actor 7ae36ebb-407a-4cac-9b65-a64cfc23bc41 failed with exception ustrz: discrepancy between dial (11.202988) and controller position (11.203995), aborting
Traceback:
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/__init__.py", line 838, in execute
    **self.initkwargs
File "/users/blissadm/local/daiquiri/daiquiri_id13/daiquiri_id13/implementors/imageviewer/move.py", line 8, in method
    kwargs["absol"] ["move_to"] (kwargs["absol"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/imageviewer/__init__.py", line 1083, in move_to_absol
    obj["motor"].move(obj["destination"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/motor.py", line 49, in move
    self.call("move", value)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 196, in call
    ret = self._call(function, value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 478, in _call
    ret = getattr(self, "_call_{fn}".format(fn=function))(value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/bliss/motor.py", line 91, in _call_move
    self._object.move(value, wait=False)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 636, in func_wrapper
    return func(self, *args, **kwargs)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 1926, in move
    motion = self.get_motion(user_target_pos, relative, polling_time)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 636, in func_wrapper
    return func(self, *args, **kwargs)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 1856, in get_motion
    % (self.name, dial_initial_pos, hw_pos)

[15:24:12]   [2022-02-11]   Actor d0d46cdb-2f4a-4661-b729-140215587bb9 failed with exception ustrz: discrepancy between dial (11.202988) and controller position (11.203995), aborting
Traceback:
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/__init__.py", line 838, in execute
    **self.initkwargs
File "/users/blissadm/local/daiquiri/daiquiri_id13/daiquiri_id13/implementors/imageviewer/move.py", line 8, in method
    kwargs["absol"] ["move_to"] (kwargs["absol"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/imageviewer/__init__.py", line 1083, in move_to_absol
    obj["motor"].move(obj["destination"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/motor.py", line 49, in move
    self.call("move", value)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 196, in call
    ret = self._call(function, value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 478, in _call
    ret = getattr(self, "_call_{fn}".format(fn=function))(value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/bliss/motor.py", line 91, in _call_move
    self._object.move(value, wait=False)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 636, in func_wrapper
    return func(self, *args, **kwargs)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 1926, in move
    motion = self.get_motion(user_target_pos, relative, polling_time)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 636, in func_wrapper
    return func(self, *args, **kwargs)
File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 1856, in get_motion
    % (self.name, dial_initial_pos, hw_pos)

[15:24:10]   [2022-02-11]   Actor 3f284996-79bc-4fb2-bcce-37b796e30239 failed with exception ustrz: discrepancy between dial (11.202988) and controller position (11.203995), aborting
Traceback:
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/__init__.py", line 838, in execute
    **self.initkwargs
File "/users/blissadm/local/daiquiri/daiquiri_id13/daiquiri_id13/implementors/imageviewer/move.py", line 8, in method
    kwargs["absol"] ["move_to"] (kwargs["absol"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/components/imageviewer/__init__.py", line 1083, in move_to_absol
    obj["motor"].move(obj["destination"])
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/motor.py", line 49, in move
    self.call("move", value)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 196, in call
    ret = self._call(function, value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/abstract/__init__.py", line 478, in _call
    ret = getattr(self, "_call_{fn}".format(fn=function))(value, **kwargs)
File "/users/blissadm/local/daiquiri/daiquiri/daiquiri/core/hardware/bliss/motor.py", line 91, in _call_move

```

```

self._object.move(value, wait=False)

File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 636, in func_wrapper
    return func(self, *args, **kwargs)

File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 1926, in move
    motion = self.get_motion(user_target_pos, relative, polling_time)

File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 636, in func_wrapper
    return func(self, *args, **kwargs)

File "/users/blissadm/local/bliss.git/bliss/common/axis.py", line 1856, in get_motion
    % (self.name, dial_initial_pos, hw_pos)

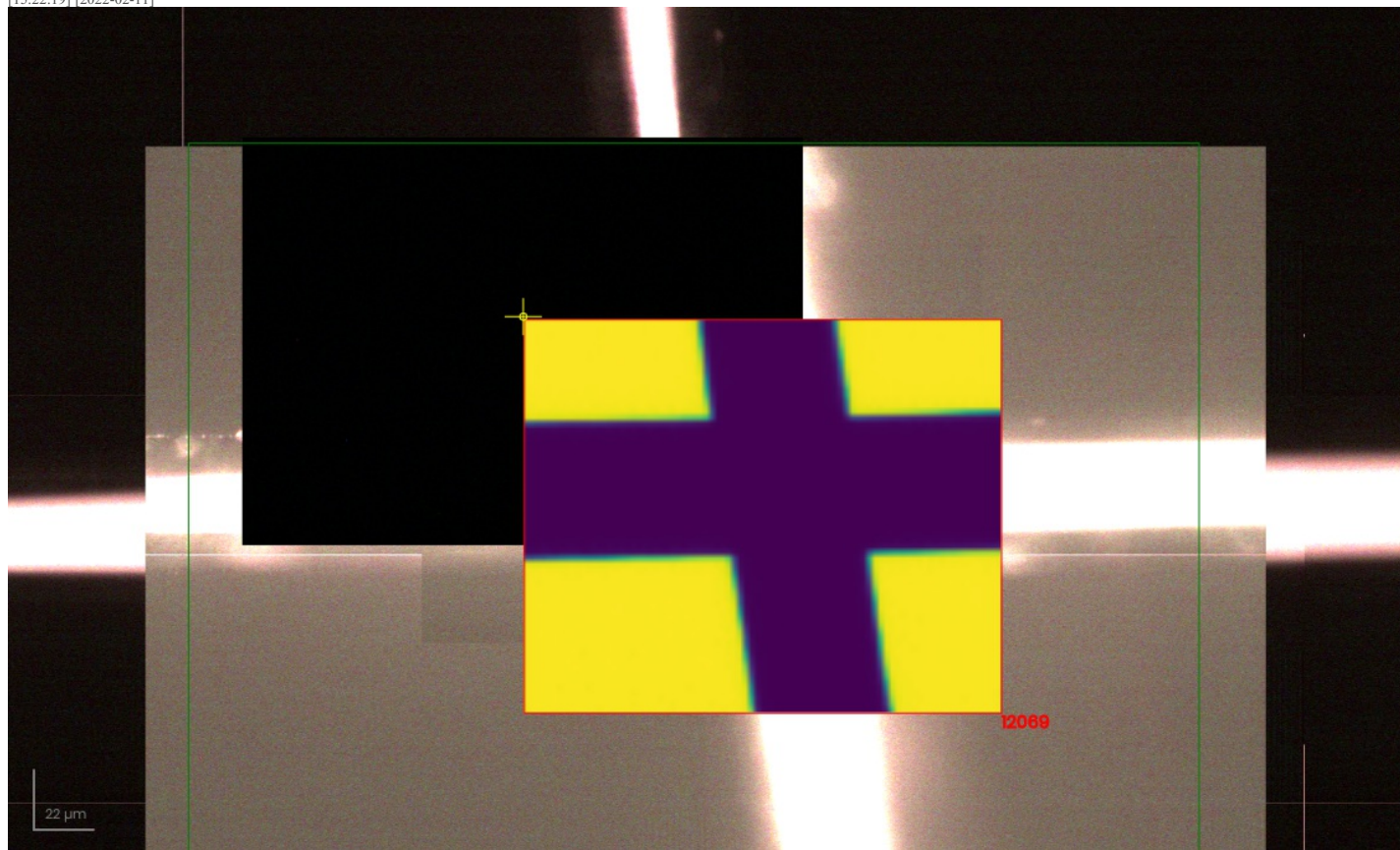
```

```

[15:23:39] [2022-02-11] slil(25)
[15:23:07] [2022-02-11] slil(25)
[15:22:37] [2022-02-11] so()
[15:22:19] [2022-02-11] Saved current acquisition image for sample mro_calib

```

```
[15:22:19] [2022-02-11]
```



```

[15:22:12] [2022-02-11] Dataset roi12069_13899 (mro_calib) has been sent to archive. files=3 size=224971 bytes
[15:22:12] [2022-02-11] Dataset roi12069_13899 (mro_calib) has been stored into ICAT successfully

```

```
[15:19:41] [2022-02-11] Starting KmapActor
```

```
dataset: mro_calib_roi12069_13899.h5
```

```
steps_x: 85
```

```
steps_y: 70
```

```
step_size_x: 2.0
```

```
step_size_y: 2.0
```

```
dwel1: 0.01
```

```
energy:
```

```

[15:18:35] [2022-02-11] so()
[15:18:04] [2022-02-11] umvr(umicroz, 191)
[15:17:47] [2022-02-11] slil(0)
[15:15:08] [2022-02-11] umvr(umicrox, -0.012)
[15:14:33] [2022-02-11] Dataset roi12069_13896 (mro_calib) has been sent to archive. files=3 size=225096 bytes
[15:14:33] [2022-02-11] Dataset roi12069_13896 (mro_calib) has been stored into ICAT successfully
[15:13:33] [2022-02-11] umicroz.position = 0
[15:12:47] [2022-02-11] umvr(umicrox, 0.025)
[15:12:03] [2022-02-11] umvr(umicroy, 0.002)
[15:11:45] [2022-02-11] umvr(umicrox, 0.005)
[15:11:42] [2022-02-11] umvr(umicrox, 0.005)
[15:11:41] [2022-02-11] umvr(umicrox, 0.005)
[15:11:40] [2022-02-11] umvr(umicrox, 0.005)
[15:11:39] [2022-02-11] umvr(umicrox, 0.005)
[15:11:38] [2022-02-11] umvr(umicrox, 0.005)
[15:11:37] [2022-02-11] umvr(umicrox, 0.005)
[15:11:35] [2022-02-11] umvr(umicrox, -0.005)
[15:11:26] [2022-02-11] umvr(umicrox, -0.05)
[15:11:24] [2022-02-11] umvr(umicrox, -0.05)
[15:11:17] [2022-02-11] umvr(umicrox, 0.05)
[15:11:04] [2022-02-11] umvr(umicroz, -0.01)
[15:10:23] [2022-02-11] umvr(umicrox, -0.005)
[15:10:22] [2022-02-11] umvr(umicrox, -0.005)
[15:10:19] [2022-02-11] umvr(umicrox, -0.005)
[15:10:10] [2022-02-11] umvr(umicrox, -0.005)
[15:10:09] [2022-02-11] umvr(umicrox, -0.005)
[15:10:08] [2022-02-11] umvr(umicrox, -0.005)
[15:10:06] [2022-02-11] umvr(umicrox, -0.005)
[15:10:05] [2022-02-11] umvr(umicrox, -0.005)
[15:10:05] [2022-02-11] umvr(umicrox, -0.005)

```

```

[15:10:04] [2022-02-11] umvr(umicrox, -0.005)
[15:10:03] [2022-02-11] umvr(umicrox, -0.005)
[15:10:02] [2022-02-11] umvr(umicrox, -0.005)
[15:10:01] [2022-02-11] umvr(umicrox, -0.005)
[15:10:00] [2022-02-11] umvr(umicrox, -0.005)
[15:09:58] [2022-02-11] umvr(umicrox, 0.005)
[15:09:57] [2022-02-11] umvr(umicrox, 0.005)
[15:09:54] [2022-02-11] umvr(umicrox, 0.005)
[15:09:53] [2022-02-11] umvr(umicrox, 0.005)
[15:09:51] [2022-02-11] umvr(umicrox, 0.005)
[15:09:46] [2022-02-11] slil(36)
[15:09:42] [2022-02-11] slil(38)
[15:09:38] [2022-02-11] umvr(umicrox, 0.005)
[15:09:23] [2022-02-11] slil(40)
[15:09:17] [2022-02-11] slil(33)
[15:09:02] [2022-02-11] slil(30)
[15:08:55] [2022-02-11] umvr(umicrox, 0.05)
[15:07:53] [2022-02-11] umvr(umicroy, 0.03)
[15:06:30] [2022-02-11] slil(30)
[15:06:14] [2022-02-11] umv(umicroz, 0)
[15:06:05] [2022-02-11] umv(umicroz, 50)
[15:05:49] [2022-02-11] umv(umicroz, 100)
[15:05:33] [2022-02-11] so()

[15:02:03] [2022-02-11] Starting KmapActor

dataset: mro_calib_roi12069_13896.h5

steps_x: 85

steps_y: 70

step_size_x: 2.0

step_size_y: 2.0

dwell: 0.01

energy:

[15:01:29] [2022-02-11] Dataset roi12067_13894 (mro_calib) has been stored into ICAT successfully
[15:01:29] [2022-02-11] Dataset roi12067_13894 (mro_calib) has been sent to archive. files=3 size=127832 bytes

[14:58:05] [2022-02-11] Starting KmapActor

dataset: mro_calib_roi12067_13894.h5

steps_x: 36

steps_y: 30

step_size_x: 10.0

step_size_y: 10.0

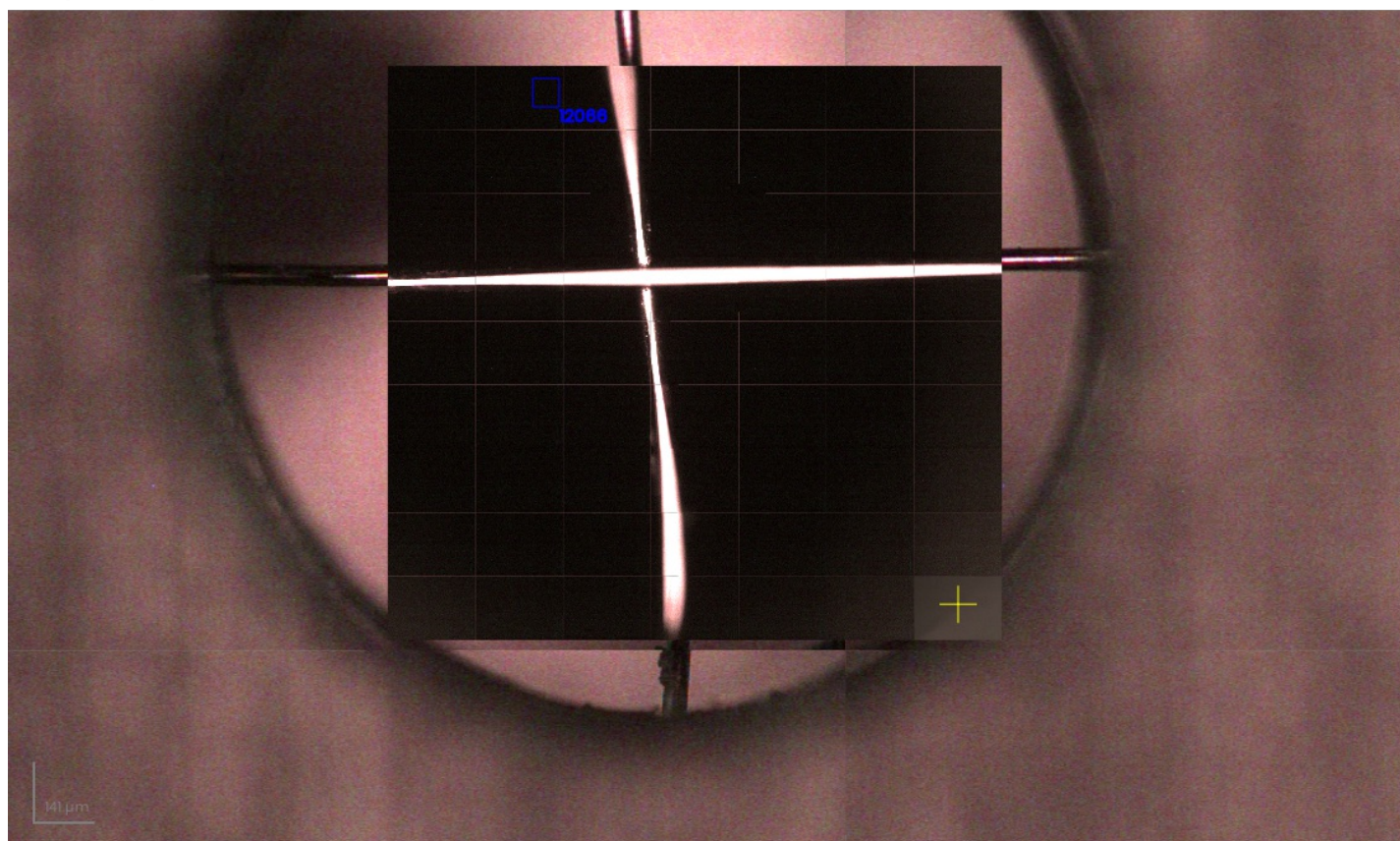
dwell: 0.01

energy:

[14:56:37] [2022-02-11] so()
[14:55:40] [2022-02-11] umv(ucryoy, 150)
[14:55:35] [2022-02-11] NameError: name 'ucryo' is not defined
[14:55:35] [2022-02-11] umv(ucryo, 150)
[14:54:57] [2022-02-11] umv(ubsey, -100)
[14:54:14] [2022-02-11] umv(ubsey, 0)
[14:53:19] [2022-02-11] umv(ucryoy, 0)
[14:52:30] [2022-02-11] umv(umicroz, 191)
[14:52:11] [2022-02-11] slil(0)
[14:52:03] [2022-02-11] so()
[14:44:36] [2022-02-11] ls()

[14:44:32] [2022-02-11]

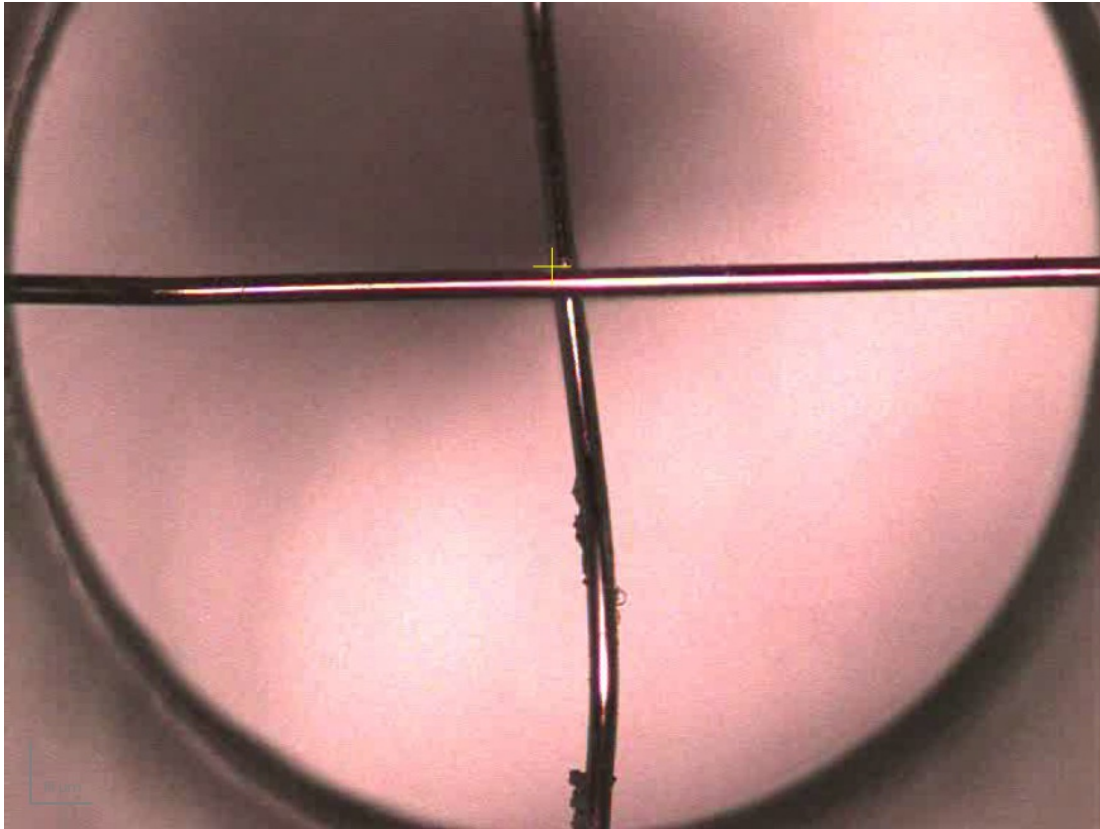
```



[14:44:32] [2022-02-11] Saved current acquisition image for sample mro_calib

[14:35:37] [2022-02-11] slil(23)
[14:33:24] [2022-02-11] wmv(ustry, ustrz)
[14:33:12] [2022-02-11] umvr(ustrz, 0.1)
[14:33:09] [2022-02-11] umvr(ustrz, -0.1)
[14:32:55] [2022-02-11] umvr(ustry, -0.1)
[14:32:51] [2022-02-11] umvr(ustry, 0.1)

[14:30:22] [2022-02-11]



[14:30:22] [2022-02-11] Saved current acquisition image for sample mro_calib

[14:28:54] [2022-02-11] slil(22)
[14:28:51] [2022-02-11] slil(3)
[14:27:51] [2022-02-11] slil(30)
[14:27:40] [2022-02-11] slil(28)
[14:27:09] [2022-02-11] slil(22)
[14:24:32] [2022-02-11] slil(28)
[14:22:46] [2022-02-11] slil(25)
[14:22:41] [2022-02-11] slil(30)
[14:22:18] [2022-02-11] slil(0)
[14:22:09] [2022-02-11] umvr(ustrx, -0.01)
[14:22:08] [2022-02-11] umvr(ustrx, -0.01)
[14:22:04] [2022-02-11] umvr(ustrx, 0.01)
[14:22:03] [2022-02-11] umvr(ustrx, 0.01)
[14:22:02] [2022-02-11] umvr(ustrx, 0.01)
[14:22:01] [2022-02-11] umvr(ustrx, 0.01)
[14:21:59] [2022-02-11] umvr(ustrx, 0.01)
[14:21:45] [2022-02-11] umvr(ustrx, -0.01)
[14:21:43] [2022-02-11] umvr(ustrx, -0.01)
[14:21:43] [2022-02-11] umvr(ustrx, -0.01)
[14:21:31] [2022-02-11] umvr(ustrx, -0.01)
[14:21:29] [2022-02-11] umvr(ustrx, -0.01)
[14:21:28] [2022-02-11] umvr(ustrx, -0.01)
[14:21:27] [2022-02-11] umvr(ustrx, -0.01)
[14:21:26] [2022-02-11] umvr(ustrx, -0.01)
[14:21:25] [2022-02-11] umvr(ustrx, -0.01)
[14:21:23] [2022-02-11] umvr(ustrx, -0.05)
[14:21:19] [2022-02-11] umvr(ustrx, 0.05)
[14:21:14] [2022-02-11] umvr(ustrx, 0.05)
[14:20:54] [2022-02-11] umvr(ustrx, 0.05)
[14:20:29] [2022-02-11] umvr(ustrx, 0.005)
[14:20:24] [2022-02-11] umvr(ustrx, 0.005)
[14:20:23] [2022-02-11] umvr(ustrx, 0.005)
[14:20:20] [2022-02-11] umvr(ustrx, 0.05)
[14:20:16] [2022-02-11] umvr(ustrx, -0.05)
[14:20:11] [2022-02-11] umvr(ustrx, -0.005)
[14:20:09] [2022-02-11] umvr(ustrx, -0.005)
[14:20:07] [2022-02-11] umvr(ustrx, -0.005)
[14:20:05] [2022-02-11] umvr(ustrx, -0.005)
[14:19:35] [2022-02-11] umvr(ustrx, -0.01)
[14:19:34] [2022-02-11] umvr(ustrx, -0.01)
[14:19:28] [2022-02-11] umvr(ustrx, 0.005)
[14:19:27] [2022-02-11] umvr(ustrx, 0.005)
[14:19:25] [2022-02-11] umvr(ustrx, 0.005)
[14:19:20] [2022-02-11] umvr(ustrx, 0.005)
[14:19:17] [2022-02-11] umvr(ustrx, 0.005)
[14:19:14] [2022-02-11] umvr(ustrx, 0.005)
[14:19:13] [2022-02-11] umvr(ustrx, 0.005)
[14:19:12] [2022-02-11] umvr(ustrx, 0.005)
[14:19:08] [2022-02-11] umvr(ustrx, -0.005)
[14:19:07] [2022-02-11] umvr(ustrx, -0.005)
[14:19:06] [2022-02-11] umvr(ustrx, -0.005)
[14:19:05] [2022-02-11] umvr(ustrx, -0.005)
[14:18:10] [2022-02-11] umvr(ustrx, -0.005)
[14:18:08] [2022-02-11] umvr(ustrx, -0.005)
[14:18:05] [2022-02-11] umvr(ustrx, -0.005)
[14:18:00] [2022-02-11] umvr(ustrx, -0.005)
[14:17:57] [2022-02-11] umvr(ustrx, -0.003)
[14:17:56] [2022-02-11] umvr(ustrx, -0.003)
[14:17:55] [2022-02-11] umvr(ustrx, -0.003)
[14:17:54] [2022-02-11] umvr(ustrx, -0.003)
[14:17:54] [2022-02-11] umvr(ustrx, -0.003)
[14:17:53] [2022-02-11] umvr(ustrx, -0.003)
[14:17:52] [2022-02-11] umvr(ustrx, -0.003)
[14:17:49] [2022-02-11] umvr(ustrx, 0.003)
[14:17:47] [2022-02-11] umvr(ustrx, 0.003)
[14:17:37] [2022-02-11] slil(30)
[14:17:18] [2022-02-11] umvr(ustrx, 0.003)
[14:17:17] [2022-02-11] umvr(ustrx, 0.003)
[14:17:12] [2022-02-11] umvr(ustrx, 0.005)
[14:17:10] [2022-02-11] umvr(ustrx, 0.005)
[14:17:09] [2022-02-11] umvr(ustrx, 0.005)
[14:17:08] [2022-02-11] umvr(ustrx, 0.005)
[14:17:07] [2022-02-11] umvr(ustrx, 0.005)

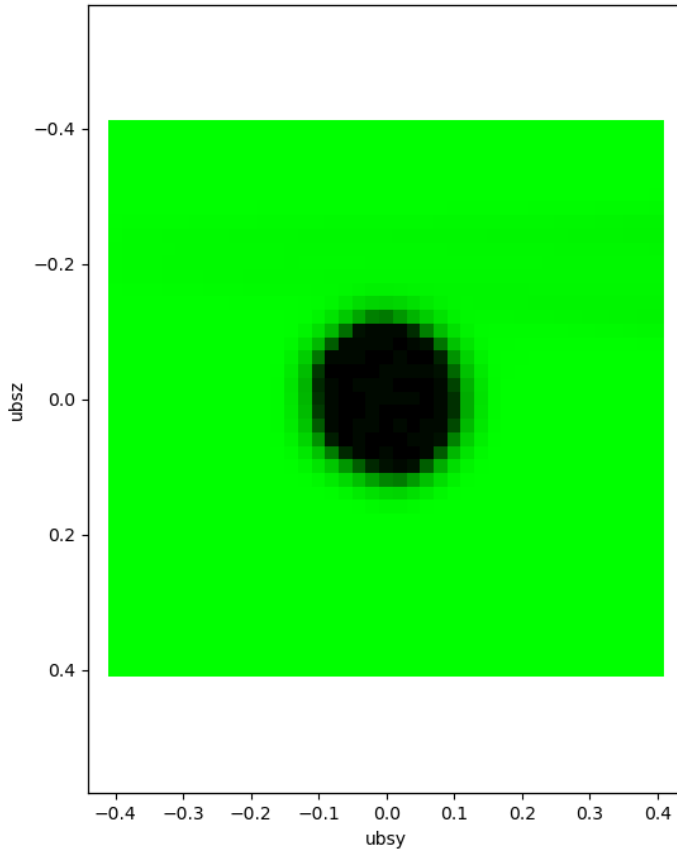
```

[14:17:06] [2022-02-11] umvr(ustrx, 0.005)
[14:17:04] [2022-02-11] umvr(ustrx, 0.005)
[14:16:57] [2022-02-11] umvr(ustrx, 0.001)
[14:16:55] [2022-02-11] umvr(ustrx, 0.001)
[14:16:54] [2022-02-11] umvr(ustrx, 0.001)
[14:16:49] [2022-02-11] umvr(ustrx, 0.01)
[14:16:48] [2022-02-11] umvr(ustrx, 0.01)
[14:16:15] [2022-02-11] umvr(ustrx, 0.1)
[14:16:13] [2022-02-11] umvr(ustrx, 0.1)
[14:16:12] [2022-02-11] umvr(ustrx, 0.1)
[14:16:12] [2022-02-11] umvr(ustrx, 0.1)
[14:16:09] [2022-02-11] umvr(ustrx, 0.01)
[14:16:08] [2022-02-11] umvr(ustrx, 0.01)
[14:16:07] [2022-02-11] umvr(ustrx, 0.01)
[14:16:02] [2022-02-11] NameError: name 'ustrx' is not defined
[14:16:01] [2022-02-11] umvr(ustrx, 0.01)
[14:15:46] [2022-02-11] slil(22)
[14:12:40] [2022-02-11] slil(22)
[14:12:26] [2022-02-11] umv(umicroz, 0)
[14:12:03] [2022-02-11] umv(umicroz, 50)
[14:11:47] [2022-02-11] umv(umicroz, 100)
[14:11:41] [2022-02-11] umvr(umicroz, 100)
[14:11:41] [2022-02-11] ValueError: umicroz: move to '291.000000' (with -0.078125 backlash) would exceed high limit (192.313359)
[14:11:26] [2022-02-11] umvr(ustrx, -2)
[14:11:23] [2022-02-11] umvr(ustrx, -3)
[14:11:16] [2022-02-11] umvr(ustrx, -5)
[13:54:18] [2022-02-11] umvr(ustrx, 10)
[13:53:56] [2022-02-11] umv(ubsy, -100)
[13:53:36] [2022-02-11] wm(ubsy)
[13:30:57] [2022-02-11] sc()

[13:29:21] [2022-02-11]

```

amesh ubsy -0.4 0.4 40 ubsz -0.4 0.4 40 0.05 (#26) (finished)
ct22: 41 × 41



```

[13:24:54] [2022-02-11] dmesh(ubsy, -0.4, 0.4, 40, ubsz, -0.4, 0.4, 40, 0.05)
[13:23:11] [2022-02-11] bsalign()
[13:23:06] [2022-02-11] where()
[13:23:03] [2022-02-11] goc(ubsy)
[13:22:36] [2022-02-11] dscan(ubsy, -1, 1, 100, 0.1)
[13:22:08] [2022-02-11] where()
[13:22:05] [2022-02-11] goc(ubsz)
[13:22:01] [2022-02-11] goc()
[13:22:01] [2022-02-11] TypeError: goc() missing 1 required positional argument: 'mot'
[13:21:10] [2022-02-11] dscan(ubsz, -0.5, 0.5, 40, 0.1)
[13:20:47] [2022-02-11] where()
[13:20:37] [2022-02-11] gop(46)
[13:20:31] [2022-02-11] gop(ubsz, 46)
[13:20:31] [2022-02-11] TypeError: gop() takes 1 positional argument but 2 were given
[13:20:24] [2022-02-11] gop(ubsz, 46)
[13:20:25] [2022-02-11] TypeError: gop() takes 1 positional argument but 2 were given
[13:19:26] [2022-02-11] bsalign()
[13:17:11] [2022-02-11] dmesh(ubsy, -0.4, 0.4, 20, ubsz, -0.4, 0.4, 20, 0.1)
[13:17:03] [2022-02-11] so()
[13:14:15] [2022-02-11] sc()
[13:11:00] [2022-02-11] dmesh(ubsy, -0.4, 0.4, 20, ubsz, -0.4, 0.4, 20, 0.1)
[13:10:19] [2022-02-11] so()
[13:10:03] [2022-02-11] sc()
[13:09:23] [2022-02-11] bsalign()
[13:08:39] [2022-02-11] bsalign()
[13:08:34] [2022-02-11] where()
[13:08:31] [2022-02-11] goc(ubsy)
[13:08:05] [2022-02-11] dscan(ubsy, -1, 1, 100, 0.1)
[13:07:42] [2022-02-11] where()
[13:07:20] [2022-02-11] goc(ubsz)
[13:07:13] [2022-02-11] AssertionError:
[13:07:13] [2022-02-11] goc(ubsy)
[13:04:24] [2022-02-11] dscan(ubsz, -2, 1, 300, 0.05)
[13:03:25] [2022-02-11] umvr(ubsy, -0.5)
[13:03:20] [2022-02-11] umvr(ubsy, -1)
[13:01:57] [2022-02-11] dscan(ubsz, -1, 1, 50, 0.1)

```

```
[13:01:43] [2022-02-11] umvr(ubsy, 2)
[13:01:16] [2022-02-11] ctt()
[13:01:13] [2022-02-11] mgd()
[13:00:26] [2022-02-11] bsalign()
[12:59:53] [2022-02-11] so()
[12:46:56] [2022-02-11] sc()
[12:40:16] [2022-02-11] dmesh(ubsy, -0.4, 0.4, 40, ubsz, -0.4, 0.4, 40, 0.1)
[12:38:46] [2022-02-11] bsalign()
[12:38:31] [2022-02-11] RuntimeError: Synchronization error for axis 'uhum_sp'
[12:38:30] [2022-02-11] RuntimeError: Synchronization error for axis 'uhexrx'
[12:38:30] [2022-02-11] RuntimeError: Synchronization error for axis 'uhexry'
[12:38:30] [2022-02-11] sync()
[12:38:30] [2022-02-11] RuntimeError: Synchronization error for axis 'uhextz'
[12:38:30] [2022-02-11] RuntimeError: Synchronization error for axis 'uhexrz'
[12:38:30] [2022-02-11] RuntimeError: Synchronization error for axis 'uhextx'
[12:38:30] [2022-02-11] RuntimeError: Synchronization error for axis 'uhexty'
[12:37:36] [2022-02-11] bsalign()
[12:37:21] [2022-02-11] bsalign()
[12:37:21] [2022-02-11] NameError: name 'bsalign' is not defined
[12:37:14] [2022-02-11] where()
[12:37:10] [2022-02-11] goc(ubsy)
[12:37:03] [2022-02-11] goc()
[12:37:03] [2022-02-11] TypeError: goc() missing 1 required positional argument: 'mot'
[12:36:45] [2022-02-11] dscan(ubsy, -0.4, 0.4, 50, 0.1)
[12:36:14] [2022-02-11] where()
[12:36:10] [2022-02-11] goc(ubsz)
[12:36:04] [2022-02-11] TypeError: goc() missing 1 required positional argument: 'mot'
[12:36:04] [2022-02-11] goc()
[12:34:26] [2022-02-11] dscan(ubsz, -1, 1, 100, 0.1)
[12:33:46] [2022-02-11] ctt()
[12:33:40] [2022-02-11] so()
[12:33:36] [2022-02-11] sc()
[12:32:49] [2022-02-11] mgd()
[12:32:43] [2022-02-11] so()
[12:32:26] [2022-02-11] umvr(ubsy,-1)
[12:32:24] [2022-02-11] umvr(ubsy,-1)
[12:31:43] [2022-02-11] umv(ubsy,0)
[12:21:09] [2022-02-11] umv(ucryoy, 150)
[12:20:32] [2022-02-11] umv(ucryoy, 0)
[12:20:16] [2022-02-11] wmv(ucryoy)
[12:20:00] [2022-02-11] umvr(ucryoy, 20)
[12:19:55] [2022-02-11] hcag(ucryoy, 21)
[12:19:34] [2022-02-11] umvr(ucryoy, 30)
[12:19:31] [2022-02-11] hcag(ucryoy, 31)
[12:19:08] [2022-02-11] umvr(ucryoy, 30)
[12:19:08] [2022-02-11] ValueError: ucryoy: move to '130.000000' would exceed high limit (120.000000)
[12:18:43] [2022-02-11] umvr(ucryoy, 50)
[12:18:19] [2022-02-11] umvr(ucryoy, 50)
[12:17:52] [2022-02-11] ucryoy.position = 0
[12:17:37] [2022-02-11] ucryoy
[12:17:14] [2022-02-11] umvr(ucryox, 5)
[12:17:10] [2022-02-11] umvr(ucryox, 5)
[12:16:31] [2022-02-11] lcag(ucryox, 0)
[12:13:19] [2022-02-11] umvr(ucryox, -1)
[12:13:19] [2022-02-11] ValueError: ucryox: move to '133.000000' would exceed low limit (133.900000)
[12:13:18] [2022-02-11] umvr(ucryox, -1)
[12:13:17] [2022-02-11] umvr(ucryox, -1)
[12:13:16] [2022-02-11] umvr(ucryox, -1)
[12:13:15] [2022-02-11] umvr(ucryox, -1)
[12:13:06] [2022-02-11] umvr(ucryox, -1)
[12:13:02] [2022-02-11] umvr(ucryox, -10)
[12:12:57] [2022-02-11] umvr(ucryox, -10)
[12:12:27] [2022-02-11] umvr(ucryox, -10)
[12:12:24] [2022-02-11] umvr(ucryox, -10)
[12:12:21] [2022-02-11] umvr(ucryox, -0)
[12:12:15] [2022-02-11] umvr(ucryox, -20)
[12:11:22] [2022-02-11] umvr(ucryox, -20)
[12:11:18] [2022-02-11] umvr(ucryox, -20)
[12:11:14] [2022-02-11] umvr(ucryox, -20)
[12:11:09] [2022-02-11] umvr(ucryox, -5)
[12:11:06] [2022-02-11] umvr(ucryox, -5)
[12:11:05] [2022-02-11] umvr(ucryox, -5)
[12:11:04] [2022-02-11] umvr(ucryox, -5)
[12:10:58] [2022-02-11] umvr(ucryox, -5)
[12:10:57] [2022-02-11] umvr(ucryox, -5)
[12:10:56] [2022-02-11] umvr(ucryox, -5)
[12:10:54] [2022-02-11] umvr(ucryox, -5)
[12:10:53] [2022-02-11] umvr(ucryox, -5)
[12:10:38] [2022-02-11] umvr(ucryox, -5)
[12:10:37] [2022-02-11] umvr(ucryox, -5)
[12:10:35] [2022-02-11] umvr(ucryox, -5)
[12:10:34] [2022-02-11] umvr(ucryox, -5)
[12:10:33] [2022-02-11] umvr(ucryox, -5)
[12:10:31] [2022-02-11] umvr(ucryox, -5)
[12:10:30] [2022-02-11] umvr(ucryox, -5)
[12:10:29] [2022-02-11] umvr(ucryox, -5)
[12:10:27] [2022-02-11] umvr(ucryox, -5)
[12:10:26] [2022-02-11] umvr(ucryox, -5)
[12:10:20] [2022-02-11] umvr(ucryox, -5)
[12:10:19] [2022-02-11] umvr(ucryox, -5)
[12:10:17] [2022-02-11] umvr(ucryox, -5)
[12:10:16] [2022-02-11] umvr(ucryox, -5)
[12:10:15] [2022-02-11] umvr(ucryox, -5)
[12:10:13] [2022-02-11] umvr(ucryox, -5)
[12:10:12] [2022-02-11] umvr(ucryox, -5)
[12:10:10] [2022-02-11] umvr(ucryox, -5)
[12:08:44] [2022-02-11] umvr(ucryoy, -5)
[12:08:42] [2022-02-11] umvr(ucryoy, -5)
[12:08:31] [2022-02-11] umvr(ucryoy, -5)
[12:08:26] [2022-02-11] umvr(ucryoy, -5)
[12:08:23] [2022-02-11] lcag(ucryoy, -20)
[12:08:20] [2022-02-11] lcage(ucryoy, -20)
[12:08:20] [2022-02-11] NameError: name 'lcage' is not defined
[12:08:05] [2022-02-11] umvr(ucryoy, -5)
[12:08:05] [2022-02-11] ValueError: ucryoy: move to '-63.443750' would exceed low limit (-58.443750)
[12:08:03] [2022-02-11] umvr(ucryoy, -5)
[12:07:50] [2022-02-11] umvr(ucryoy, -5)
[12:07:45] [2022-02-11] umvr(ucryoy, -5)
[12:07:41] [2022-02-11] umvr(ucryoy, -5)
[12:07:40] [2022-02-11] umvr(ucryoy, -5)
[12:07:22] [2022-02-11] umvr(ucryoy, -5)
[12:07:19] [2022-02-11] umvr(ucryoy, -5)
[12:07:17] [2022-02-11] umvr(ucryoy, -5)
[12:07:08] [2022-02-11] umvr(ucryoy, -5)
[12:07:07] [2022-02-11] umvr(ucryoy, -5)
[12:07:05] [2022-02-11] umvr(ucryoy, -5)
[12:06:58] [2022-02-11] umvr(ucryoy, 5)
[12:06:53] [2022-02-11] cage(ucryoy, -50, 50)
[12:06:30] [2022-02-11] wmv(ucryoy)
[12:06:19] [2022-02-11] umvr(ucryoy, 5)
[12:06:20] [2022-02-11] ValueError: ucryoy: move to '-3.443750' would exceed high limit (-7.531250)
[12:06:16] [2022-02-11] umvr(ucryoy, -5)
[12:06:16] [2022-02-11] ValueError: ucryoy: move to '-13.443750' would exceed low limit (-9.531250)
[12:06:12] [2022-02-11] umvr(ucryoy, -10)
[12:06:12] [2022-02-11] ValueError: ucryoy: move to '-18.443750' would exceed low limit (-9.531250)
[12:05:48] [2022-02-11] umvr(ufuoy, -10)
[12:03:58] [2022-02-11] umvr(ufuoy, 10)
[12:02:31] [2022-02-11] umvr(ufuoy, -3)
[12:02:15] [2022-02-11] umvr(ufuoy, 3)
[12:02:06] [2022-02-11] umvr(ufuoy, -3)
[12:01:52] [2022-02-11] ValueError: ufuoy: move to '-58.000000' would exceed low limit (-55.100000)
[12:01:52] [2022-02-11] umvr(ufuoy, -10)
[10:24:44] [2022-02-11] umvr(ubsy, -100)
[10:24:27] [2022-02-11] wmv(ubsy)
[10:16:49] [2022-02-11] umvr(umicroz, 191)
[10:16:40] [2022-02-11] slil(0)
[10:16:26] [2022-02-11] umvr(ustrx, -0.1)
[10:16:25] [2022-02-11] umvr(ustrx, -0.1)
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[10:16:24] [2022-02-11] umvr(ustrx, -0.1)
[10:16:23] [2022-02-11] umvr(ustrx, -0.1)
[10:16:22] [2022-02-11] umvr(ustrx, -0.1)
[10:16:21] [2022-02-11] umvr(ustrx, -0.1)
[10:16:20] [2022-02-11] umvr(ustrx, -0.1)
[10:16:20] [2022-02-11] umvr(ustrx, -0.1)
[10:16:19] [2022-02-11] umvr(ustrx, -0.1)
[10:16:18] [2022-02-11] umvr(ustrx, -0.1)
[10:16:17] [2022-02-11] umvr(ustrx, -0.1)
[10:16:17] [2022-02-11] umvr(ustrx, -0.1)
[10:16:16] [2022-02-11] umvr(ustrx, -0.1)
[10:16:15] [2022-02-11] umvr(ustrx, -0.1)
[10:16:14] [2022-02-11] umvr(ustrx, -0.1)
[10:16:14] [2022-02-11] umvr(ustrx, -0.1)
[10:16:13] [2022-02-11] umvr(ustrx, -0.1)
[10:16:12] [2022-02-11] umvr(ustrx, -0.1)
[10:16:11] [2022-02-11] umvr(ustrx, -0.1)
[10:16:10] [2022-02-11] umvr(ustrx, -0.1)
[10:16:10] [2022-02-11] umvr(ustrx, -0.1)
[10:16:09] [2022-02-11] umvr(ustrx, -0.1)
[10:16:08] [2022-02-11] umvr(ustrx, -0.1)
[10:16:07] [2022-02-11] umvr(ustrx, -0.1)
[10:16:06] [2022-02-11] umvr(ustrx, -0.1)
[10:16:05] [2022-02-11] umvr(ustrx, -0.1)
[10:16:05] [2022-02-11] umvr(ustrx, -0.1)
[10:16:02] [2022-02-11] umvr(ustrx, 0.1)
[10:15:41] [2022-02-11] umvr(ustrx, 0.5)
[10:15:36] [2022-02-11] umvr(ustrx, 0.5)
[10:12:59] [2022-02-11] umvr(ustrx, 0.5)
[10:12:57] [2022-02-11] umvr(ustrx, 0.5)
[10:12:56] [2022-02-11] umvr(ustrx, 0.5)
[10:12:55] [2022-02-11] umvr(ustrx, 0.5)
[10:12:54] [2022-02-11] umvr(ustrx, 0.5)
[10:12:45] [2022-02-11] umvr(ustrx, -0.5)
[10:12:44] [2022-02-11] umvr(ustrx, -0.5)
[10:12:43] [2022-02-11] umvr(ustrx, -0.5)
[10:12:42] [2022-02-11] umvr(ustrx, -0.5)
[10:12:41] [2022-02-11] umvr(ustrx, -0.5)
[10:12:40] [2022-02-11] umvr(ustrx, -0.5)
[10:12:36] [2022-02-11] umvr(ustrx, -0.1)
[10:12:35] [2022-02-11] umvr(ustrx, -0.1)
[10:12:34] [2022-02-11] umvr(ustrx, -0.1)
[10:12:33] [2022-02-11] umvr(ustrx, -0.1)
[10:12:29] [2022-02-11] umvr(ustrx, -0.1)
[10:12:28] [2022-02-11] umvr(ustrx, -0.1)
[10:12:26] [2022-02-11] umvr(ustrx, -0.1)
[10:11:02] [2022-02-11] slil(23)
[10:10:54] [2022-02-11] umvr(ustrx, -1)
[10:10:45] [2022-02-11] umvr(ustrx, 1)
[10:10:36] [2022-02-11] umvr(ustrx, 1)
[10:10:17] [2022-02-11] slil(25)
[10:10:09] [2022-02-11] umv(umicroz, 0)
[10:10:01] [2022-02-11] umv(umicroz, 10)
[10:09:51] [2022-02-11] umv(umicroz, 50)
[10:09:35] [2022-02-11] umv(umicroz, 100)
[10:08:50] [2022-02-11] umvr(ustrx, -2)
[10:08:48] [2022-02-11] umvr(ustrx, -2)
[10:08:44] [2022-02-11] umvr(ustrx, -5)
[10:08:40] [2022-02-11] umvr(ustrx, -5)
[09:57:34] [2022-02-11] exit()
[09:57:18] [2022-02-11] dmyscan()

[09:57:08] [2022-02-11] Dataset set to 'nodataset'

Data path: /data/idl3/inhouse3/DATAPOLICY_I3_1/eh2/inhouse/ihsc1691/idl3/nosample/nosample_nodataset

[09:56:57] [2022-02-11] Dataset collection set to 'nosample'

Data path: /data/idl3/inhouse3/DATAPOLICY_I3_1/eh2/inhouse/ihsc1691/idl3/nosample/nosample_0001

[09:56:40] [2022-02-11] Proposal set to 'ihsc1691'

Data path: /data/idl3/inhouse3/DATAPOLICY_I3_1/eh2/inhouse/ihsc1691/idl3/sample/sample_0001

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