

# Markov chain Monte Carlo

# Conditioning via MCMC

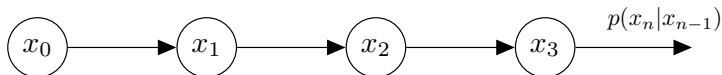
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  - ▶ Setting the proposal to the prior, as in likelihood weighting, has  $q(\mathbf{x}) = p(\mathbf{x})$ , which is rarely a very good choice.
  - ▶ A “good” proposal  $q(\mathbf{x})$  will be very close to the posterior  $p(\mathbf{x}|\mathbf{y})$ , which might be quite different than the prior

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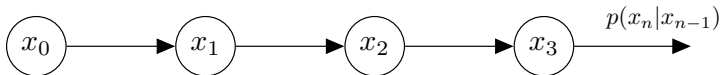
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- Idea: create a Markov chain such that the sequence of states  $\mathbf{x}_0, \mathbf{x}_1, \mathbf{x}_2, \dots$  are samples from  $p(\mathbf{x}|\mathbf{y})$ .



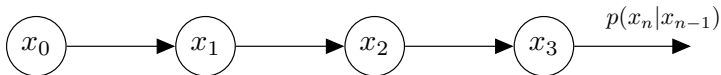
# Markov chains (1/2)



- A **Markov chain** is a sequence with a “memoryless” property; that is, with the factorization

$$p(\mathbf{x}_n | \mathbf{x}_1, \dots, \mathbf{x}_{n-1}) = p(\mathbf{x}_n | \mathbf{x}_{n-1}).$$

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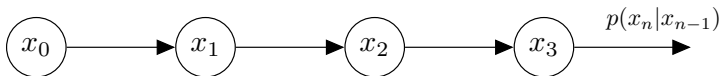
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- If this distribution is the same for all  $n$ , then it is said to be *homogeneous*, and we denote it as  $T$ , the transition probability  $T(\mathbf{x}_n | \mathbf{x}_{n-1}) = p(\mathbf{x}_n | \mathbf{x}_{n-1})$ .

## Markov chains (2/2)

- A distribution is **invariant** or **stationary** w.r.t. a Markov chain if each step leaves the distribution invariant. That is, a distribution  $p^*(\mathbf{x})$  is invariant for a homogeneous Markov Chain with transition  $T(\mathbf{x}'|\mathbf{x})$  if,

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- A sufficient (but not necessary) condition for  $p^*$  to be invariant is if we choose the transition probabilities  $T$  to satisfy the **detailed balance** property,

$$p^*(\mathbf{x})T(\mathbf{x}'|\mathbf{x}) = p^*(\mathbf{x}')T(\mathbf{x}|\mathbf{x}')$$

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- A Markov chain that satisfies detailed balance is said to be **reversible**.
- The one other property we will want is **ergodicity**, which guarantees that the same unique invariant distribution will be reached regardless of initial starting point  $\mathbf{x}_0$ .

# MCMC: Algorithm

- The MCMC proposal distribution makes **local** changes to a current value. We choose a  $q(\mathbf{x}'|\mathbf{x})$  defines a distribution of candidate values  $\mathbf{x}'$ , given a current value  $\mathbf{x}$ 
  - ▶ Default choice: add a small amount of Gaussian noise
- We use the proposal and the joint density to define an “acceptance ratio”

$$A(\mathbf{x} \rightarrow \mathbf{x}') = \min \left( 1, \frac{p(\mathbf{y}, \mathbf{x}')q(\mathbf{x}|\mathbf{x}')}{p(\mathbf{y}, \mathbf{x})q(\mathbf{x}'|\mathbf{x})} \right)$$

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- Performing this update repeatedly defines a sequence  $\mathbf{x}_0, \mathbf{x}_1, \mathbf{x}_2 \dots$  of **dependent** draws.
- Note this doesn't require the normalizing constant, just  $p(\mathbf{x}, \mathbf{y})$ !

# Symmetric proposal distributions

Note that in the “default choice” of Gaussian noise,

$$q(\mathbf{x}'|\mathbf{x}) = \mathcal{N}(\mathbf{x}'|\mathbf{x}, \sigma^2\mathbf{I})$$

then the proposal is “symmetric”, in that  $q(\mathbf{x}'|\mathbf{x}) = q(\mathbf{x}|\mathbf{x}')$ . In this setting, we have a simplified expression

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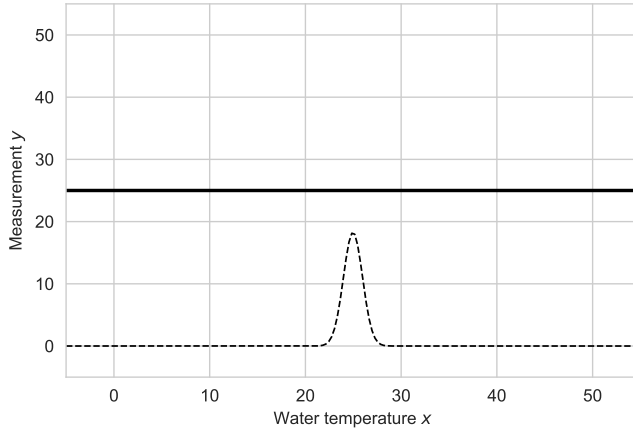
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Intuitively this looks like a noisy sort of hill climbing:

- sample a value  $\mathbf{x}' \sim q(\mathbf{x}'|\mathbf{x})$
- if  $p(\mathbf{y}, \mathbf{x}') > p(\mathbf{y}, \mathbf{x})$ , then move to  $\mathbf{x}'$
- otherwise, maybe move to  $\mathbf{x}'$

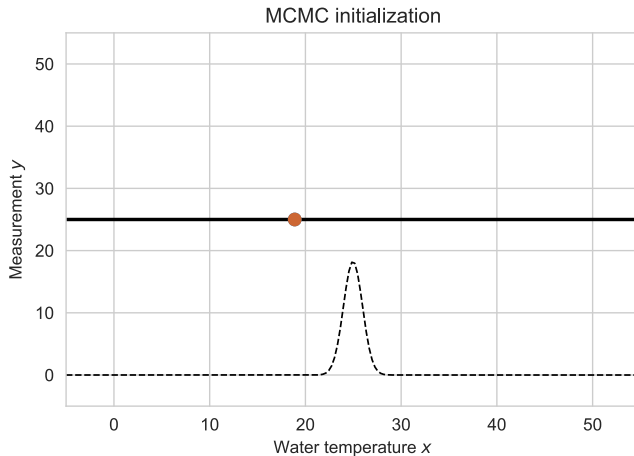
# MCMC schematic



The (unnormalized) joint distribution  $p(x, y)$  is shown as a dashed line

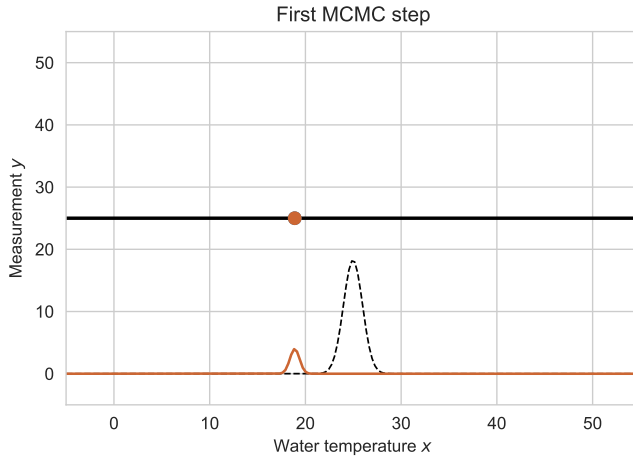


# MCMC schematic



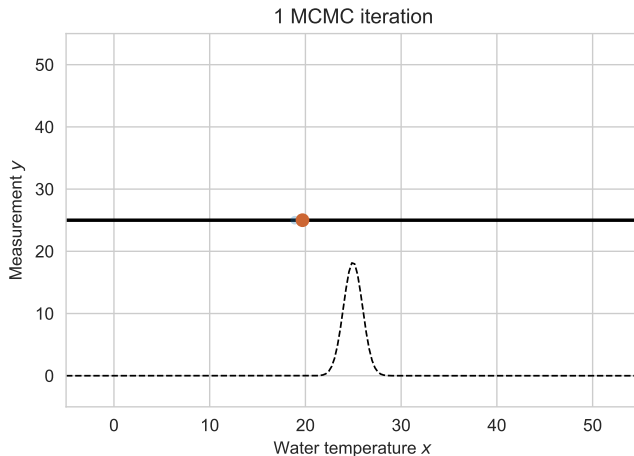
Initialize arbitrarily (e.g. with a sample from the prior)

# MCMC schematic



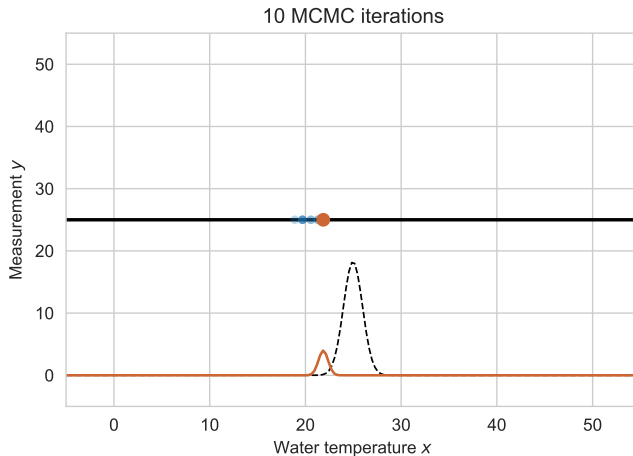
Propose a local move on  $x$  from a transition distribution

# MCMC schematic



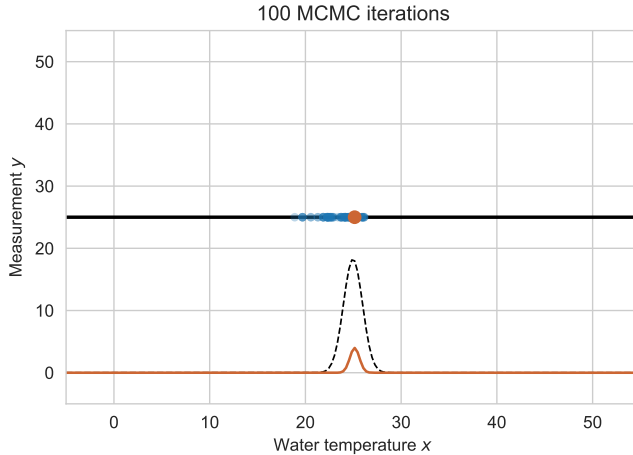
Here, we proposed in a region of higher probability density, and accepted

# MCMC schematic



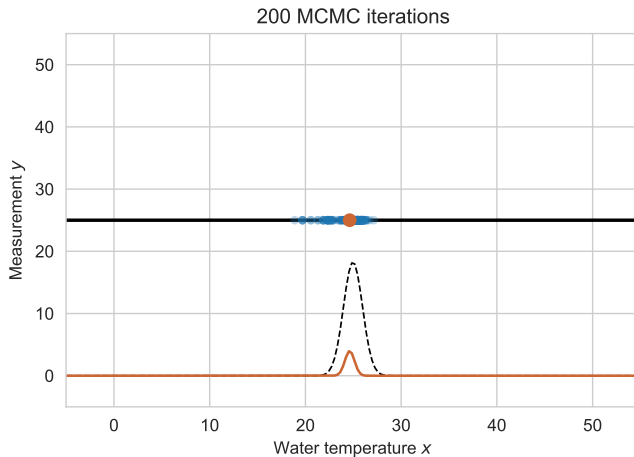
Continue: propose a local move, and accept or reject.  
At first this will look like a stochastic search algorithm!

# MCMC schematic



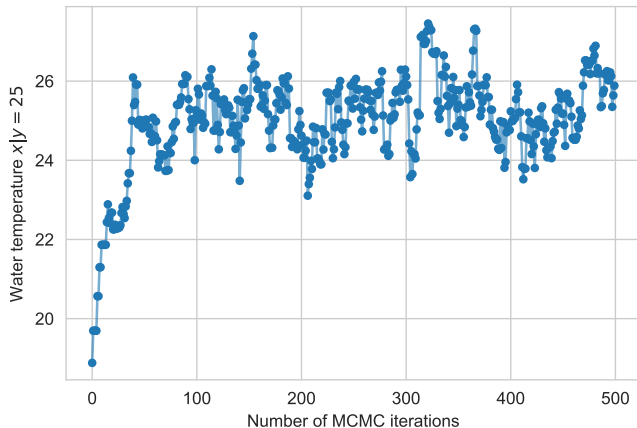
Once in a high-density region, it will explore the space

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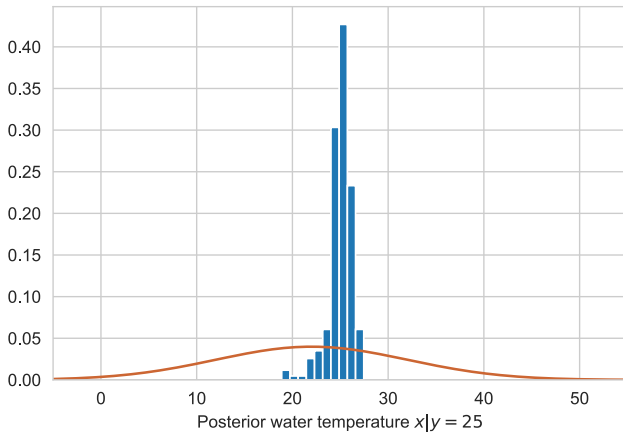
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# Helpful diagnostic



Helpful diagnostic: a **trace plot** shows the coordinate  $x$  on the y-axis, against iterations on the x-axis, showing the progression of the Markov chain.

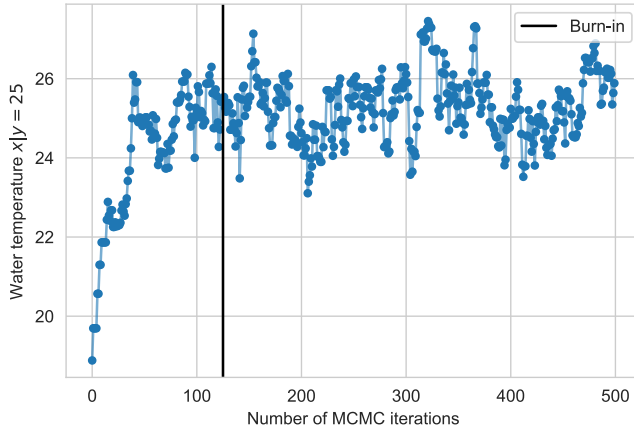
# MCMC schematic



Histogram of trace plot, overlaid on prior probability density.  
Notice the “tail” off to the left. . .

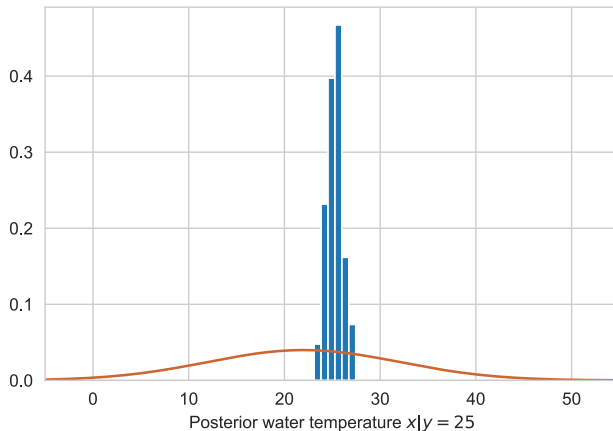


# Solution: discard “burnin”



It can take a while before the MCMC chain can reach its equilibrium distribution.  
It's customary to discard early samples until the chain has “burned in”...

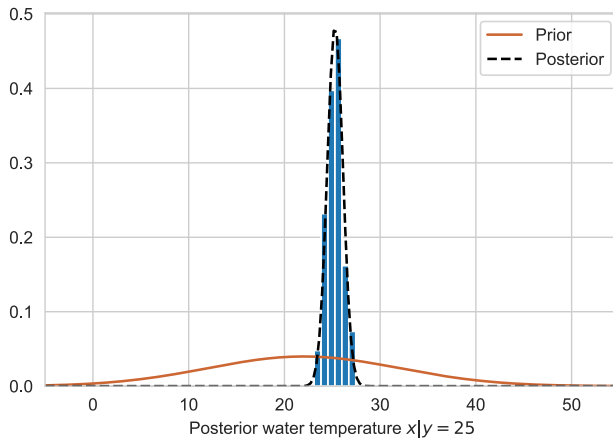
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# Estimating a parametric approximation



Gaussian approximation:  $\hat{\mu} = \frac{1}{S-s_0} \sum_{s=s_0}^S x^{(s)}; \hat{\sigma}^2 = \frac{1}{S-s_0} \sum_{s=s_0}^S (x^{(s)} - \hat{\mu})^2$

# Pitfalls

- How do we choose the proposal?
- Bad proposals can lead to **low acceptance rates**, or **very small steps** — both are problematic
- Diagnosing convergence can be tricky; when has “burn-in” ended? What happens if we have disconnected modes?
- In large data settings, evaluating the acceptance ratio can be expensive

We'll talk about some of these things later on, when we re-visit MCMC.