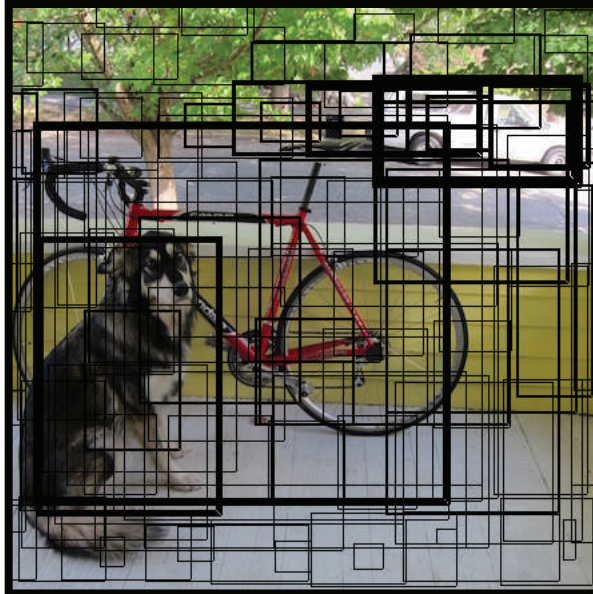




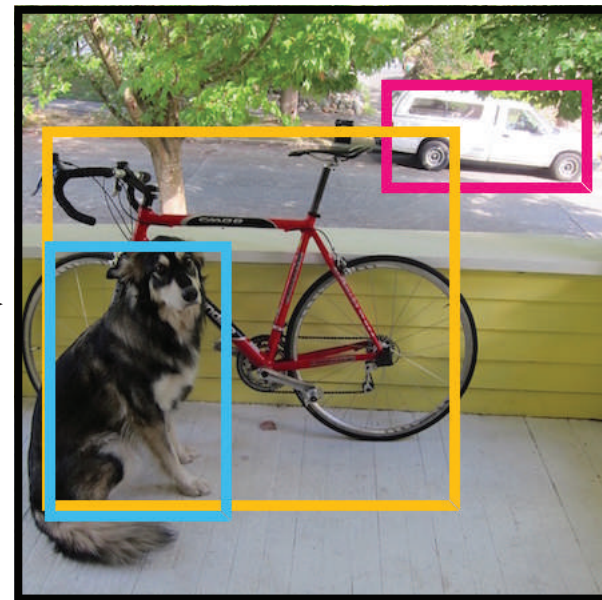
$S \times S$ grid on input



Bounding boxes + confidence



Class probability map



Final detections