

Release: 09.02.2024
Deadline: 18.02.2024

In this HW, you can perform all arithmetic operations on matrices (e.g. multiplication, transforming into RREF, finding the inverse, etc) by a machine.

1. (1 point per item) Let \mathbb{V} and \mathbb{W} be two vector spaces; let \mathcal{A} and \mathcal{B} be an ordered basis for \mathbb{V} and \mathbb{W} , respectively; let $\varphi: \mathbb{V} \rightarrow \mathbb{W}$ be a linear transformation (that is, $\varphi \in \mathcal{L}(\mathbb{V}, \mathbb{W})$). Then, find the coordinate matrix of φ with respect to \mathcal{A} and \mathcal{B} (that is, find $T(\varphi, \mathcal{A}, \mathcal{B})$) if:

(a) $\mathbb{V} = \mathbb{R}[x; 3]^1$, $\mathbb{W} = \mathbb{R}[x; 2]$, $\mathcal{A} = (1 + x^3, x, 1 + x + x^2, 2 + x)$, $\mathcal{B} = (1, x^2, x)$, and

$$\varphi(ax^3 + bx^2 + cx + d) = 3ax^2 + 2bx + c, \quad \text{for every } ax^3 + bx^2 + cx + d \in \mathbb{R}[x, 3];$$

[hint: since $(1, x^2, x) \neq (1, x, x^2)$, be careful about the order of coefficients]

(b) $\mathbb{V} = \mathbb{W} = \mathbb{R}[x; 2]$, $\mathcal{A} = (1 + x^2, 1 - x, 1 - x + x^2)$, $\mathcal{B} = (2 + x, x^2, 1 + x + x^2)$, and

$$\varphi(ax^2 + bx + c) = bx^2 + cx, \quad \text{for every } ax^2 + bx + c \in \mathbb{R}[x, 2];$$

[remark: it is not a part of this problem, but it is advisable to verify that φ is indeed a linear transformation]

(c) $\mathbb{V} = \mathbb{W} = \text{Mat}_2(\mathbb{R})$, $\mathcal{A} = \mathcal{B} = \left(\begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 1 \end{bmatrix} \right)$, and $\varphi: A \mapsto A^T$, for every $A \in \text{Mat}_2(\mathbb{R})$.

Novosad Ivaq

$T(\varphi, \mathcal{A}, \mathcal{B})$ ✓ a) $\frac{d}{dx}(1+x^3) = 3x^2$ $T[1+x^3]_A = T(e_1)_A = [3x^2]_B = \begin{bmatrix} 0 \\ 3 \\ 0 \end{bmatrix}$

$\frac{d}{dx}(x) = 1$ $T[x]_A = T(e_2)_A = [1]_B = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$

$\frac{d}{dx}(1+x+x^2) = 1+2x$ $T[1+x+x^2]_A = T(e_3)_A = [1+2x]_B = \begin{bmatrix} 1 \\ 0 \\ 2 \end{bmatrix}$

$\frac{d}{dx}(2+x) = 1$ $T[2+x]_A = T(e_4)_A = [1]_B = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$

$\Rightarrow \begin{bmatrix} 0 & 1 & 1 & 1 \\ 3 & 0 & 0 & 0 \\ 0 & 0 & 2 & 0 \end{bmatrix} = T(\varphi, \mathcal{A}, \mathcal{B})$

✓ b) ✓ $T[1+x^2]_A = T(e_1)_A = [x]_B = \begin{bmatrix} -1 \\ -3 \\ 2 \end{bmatrix}$ $(2+x \quad x^2 \quad 1+x+x^2)$

$T = T(\varphi, \mathcal{A}, \mathcal{B})$ ✓ $T[1-x]_A = [-x^2+x]_B = T(e_2)_A = \begin{bmatrix} -1 \\ -3 \\ 2 \end{bmatrix}$

✓ $T[1-x+x^2]_A = [-x^2+x]_B = T(e_3)_A = \begin{bmatrix} -1 \\ -3 \\ 2 \end{bmatrix}$

\Downarrow

$T(\varphi, \mathcal{A}, \mathcal{B}) = \begin{bmatrix} -1 & -1 & -1 \\ -2 & -3 & -3 \\ 2 & 2 & 2 \end{bmatrix}$

$T(\varphi, \mathcal{A}, \mathcal{B})$ ✓ c)

(c) $\mathbb{V} = \mathbb{W} = \text{Mat}_2(\mathbb{R})$, $\mathcal{A} = \mathcal{B} = \left(\begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 1 \end{bmatrix} \right)$, and $\varphi: A \mapsto A^T$, for every $A \in \text{Mat}_2(\mathbb{R})$.

$T\left(\begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}\right) = \left(\begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix}\right)_A = \left(\begin{bmatrix} 1 & 0 \\ 1 & 0 \end{bmatrix}\right)_B \stackrel{\checkmark}{=} \begin{bmatrix} 1 \\ -1 \\ 0 \end{bmatrix}$

$T\left(\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}\right) = \left(\begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}\right)_A \stackrel{\checkmark}{=} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$

$T\left(\begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}\right) = \left(\begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}\right)_A \stackrel{\checkmark}{=} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$

$T\left(\begin{bmatrix} 0 & 0 \\ 1 & 1 \end{bmatrix}\right) = \left(\begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix}\right)_A \stackrel{\checkmark}{=} \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$

$\Rightarrow T(\varphi, \mathcal{A}, \mathcal{B}) = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -1 & 0 & 1 & 1 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 0 & 1 \end{bmatrix}$

2. (0.5 points per matrix) Let \mathbb{V} be a vector space over the field of reals; let $\mathcal{A} = (\mathbf{e}_1, \mathbf{e}_2)$ and $\mathcal{B} = (\mathbf{e}_1 + \mathbf{e}_2, 2\mathbf{e}_1 + \mathbf{e}_2)$ be two ordered bases for \mathbb{V} ; let $\varphi: \mathbb{V} \rightarrow \mathbb{V}$ be a linear transformation which is defined as:

$$\varphi: \begin{bmatrix} x \\ y \end{bmatrix}_{\mathcal{A}} \mapsto \begin{bmatrix} x+2y \\ x-y \end{bmatrix}_{\mathcal{B}}, \quad \text{for every } x \cdot \mathbf{e}_1 + y \cdot \mathbf{e}_2 \in \mathbb{V}.$$

Then, find $T(\varphi, \mathcal{A}, \mathcal{A})$, $T(\varphi, \mathcal{A}, \mathcal{B})$, $T(\varphi, \mathcal{B}, \mathcal{A})$, and $T(\varphi, \mathcal{B}, \mathcal{B})$.

[hint: see Problem 3 from Seminar 19]

$$H: \left(\begin{bmatrix} 1 \\ 0 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} \right) \quad B: \left(\begin{bmatrix} 1 \\ 1 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \end{bmatrix} \right)$$

$$T(\varphi, A, B):$$

$$\begin{aligned} \varphi(\mathbf{e}_1) &= \varphi\left(\begin{bmatrix} 1 \\ 0 \end{bmatrix}_A\right) = \begin{bmatrix} 1 \\ 1 \end{bmatrix}_B \\ \varphi(\mathbf{e}_2) &= \varphi\left(\begin{bmatrix} 0 \\ 1 \end{bmatrix}_A\right) = \begin{bmatrix} 2 \\ -1 \end{bmatrix}_B \end{aligned} \Rightarrow T(\varphi, A, B) = \begin{bmatrix} 1 & 2 \\ 1 & -1 \end{bmatrix}$$

$$T(\varphi, A, A):$$

$$T(\varphi, A, A) = C(A, B) T(\varphi, A, B) = \begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 1 & -1 \end{bmatrix} = \begin{bmatrix} 3 & 0 \\ 2 & 1 \end{bmatrix}$$

$$C(A, B) = \begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix};$$

$$T(\varphi, B, B)$$

$$(\mathbb{V}, A) \xrightarrow{\varphi} (\mathbb{V}, A) \Rightarrow (\mathbb{V}, B) \xrightarrow{\varphi} (\mathbb{V}, B)$$

$$\text{Thus: } H \rightarrow H; B \rightarrow H; A' \rightarrow B; B' \rightarrow B; W \rightarrow V \Rightarrow T(\varphi, H, B') = C(B', B) T(\varphi, A, B) C(H, A') \Rightarrow$$

$$\Rightarrow C(B, H) \cdot T(\varphi, A, H) C(A, B) = \begin{bmatrix} -1 & 2 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 3 & 0 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix} = \begin{bmatrix} 3 & 4 \\ 0 & 1 \end{bmatrix}$$

$$T(\varphi, B, A) = C(A, B) T(\varphi, B, B) C(B, B) \overset{\text{"I}_2}{=} =$$

$$= \begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 3 & 4 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 3 & 6 \\ 3 & 5 \end{bmatrix}$$

3. (1 point per item) Let V and W be two vector spaces over the field of reals; let $\mathcal{A} = (\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3)$ and $\mathcal{A}' = (\mathbf{e}'_1, \mathbf{e}'_2, \mathbf{e}'_3)$ be two ordered bases for V ; let $\mathcal{B} = (\mathbf{f}_1, \mathbf{f}_2, \mathbf{f}_3)$ and $\mathcal{B}' = (\mathbf{f}'_1, \mathbf{f}'_2, \mathbf{f}'_3)$ be two ordered bases for W .

Suppose that:

$$[\mathbf{e}'_1]_{\mathcal{A}} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \quad [\mathbf{e}'_2]_{\mathcal{A}} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}, \quad [\mathbf{e}'_3]_{\mathcal{A}} = \begin{bmatrix} -2 \\ -1 \\ 1 \end{bmatrix}, \quad [\mathbf{f}'_1]_{\mathcal{B}} = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}, \quad [\mathbf{f}'_2]_{\mathcal{B}} = \begin{bmatrix} -3 \\ -3 \\ -2 \end{bmatrix}, \quad [\mathbf{f}'_3]_{\mathcal{B}} = \begin{bmatrix} 3 \\ 1 \\ 1 \end{bmatrix}.$$

and a linear transformation $\varphi \in \mathcal{L}(V, W)$ is given by its coordinate matrix:

$$T(\varphi, \mathcal{A}, \mathcal{B}) = \begin{bmatrix} -13 & 19 & -7 \\ -20 & 29 & -11 \\ -11 & 16 & -6 \end{bmatrix}.$$

Then:

(a) find $T(\varphi, \mathcal{A}', \mathcal{B}')$:

[hint: use Theorem 19.3]

$$a) C(A, A') = \begin{bmatrix} 1 & 1 & -2 \\ 1 & 2 & -1 \\ 1 & 3 & 1 \end{bmatrix} \quad C(B, B') = \begin{bmatrix} 1 & -3 & 3 \\ 2 & -3 & 1 \\ 1 & -2 & 1 \end{bmatrix}$$

$$T(\varphi, A, B): (V, A) \xrightarrow{\varphi} (W, B) \\ (V, A') \xrightarrow{\varphi} (W, B')$$

$$T(\varphi, A', B') = C(B', B) T(\varphi, A, B) C(A, A')$$

$$\underline{T(\varphi, A', B')} = \begin{bmatrix} 1 & -3 & 3 \\ 2 & -3 & 1 \\ 1 & -2 & 1 \end{bmatrix}^{-1} \begin{bmatrix} -13 & 19 & -7 \\ -20 & 29 & -11 \\ -11 & 16 & -6 \end{bmatrix} \begin{bmatrix} 1 & 1 & -2 \\ 1 & 2 & -1 \\ 1 & 3 & 1 \end{bmatrix} =$$

$$= \begin{bmatrix} 1 & 3 & -6 \\ 1 & 2 & -5 \\ 1 & 1 & -3 \end{bmatrix} \begin{bmatrix} -1 & 4 & 0 \\ -2 & 5 & 0 \\ -1 & 3 & 0 \end{bmatrix} = \begin{bmatrix} -1 & 1 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

(b) find $[\varphi(2\mathbf{e}_1 - \mathbf{e}_2 + \mathbf{e}_3)]_{\mathcal{B}'}$:

[hint: use Item 4) of Theorem 15.1 and Item 1 of Theorem 19.1]

$$\begin{aligned} & [\varphi(2\mathbf{e}_1 - \mathbf{e}_2 + \mathbf{e}_3)]_{\mathcal{B}'} \\ & \quad \quad \quad \parallel \\ & T(\varphi, A, B') \cdot [2\mathbf{e}_1 - \mathbf{e}_2 + \mathbf{e}_3]_A \end{aligned}$$

$$T(\varphi, A, B): (V, A) \xrightarrow{\varphi} (V, B) \\ (V, A) \rightarrow (V, B')$$

$$T(\varphi, A, B') = C(B', B) T(\varphi, A, B)$$

$$T(\varphi, A, B') = \begin{bmatrix} 1 & -3 & 3 \\ 2 & -3 & 1 \\ 1 & -2 & 1 \end{bmatrix}^{-1} \begin{bmatrix} -13 & 19 & -7 \\ -20 & 29 & -11 \\ -11 & 16 & -6 \end{bmatrix} =$$

$$= \begin{bmatrix} -7 & 10 & -4 \\ 2 & -3 & 1 \\ 0 & 0 & 0 \end{bmatrix};$$

$$[2\mathbf{e}_1 - \mathbf{e}_2 + \mathbf{e}_3]_A = \begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix}$$

$$[\varphi(2\mathbf{e}_1 - \mathbf{e}_2 + \mathbf{e}_3)]_{\mathcal{B}'} = \begin{bmatrix} -7 & 10 & -4 \\ 2 & -3 & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix} = \begin{bmatrix} -28 \\ 8 \\ 0 \end{bmatrix}$$

$$T(\varphi, A, B): (V, A) \rightarrow (W, B) \\ (V, A') \rightarrow (W, B')$$

$$T(\varphi, A'', B'') = C(B'', B) T(\varphi, A, B) C(A, A'')$$

$$T(\varphi, A'', B'') = C(B'', B') T(\varphi, A', B') C(A', A'')$$

$$\begin{bmatrix} -13 & 19 & -7 \\ -20 & 29 & -11 \\ -11 & 16 & -6 \end{bmatrix} \xrightarrow{\text{RREF}} \begin{bmatrix} 1 & 0 & 2 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} \Rightarrow \dim(\text{Im}(\varphi)) = 2 \\ \dim(\text{Ker}(\varphi)) = 1$$

$$\Rightarrow \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -2a \\ -1a \\ a \end{bmatrix}$$

$$\text{hence } A'' = \left(\begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -2 \\ -1 \\ 1 \end{bmatrix} \right) \\ \downarrow \varphi \quad \searrow \varphi \quad \xrightarrow{\varphi} 0$$

$$\text{hence } B'' = \left(\begin{bmatrix} -13 \\ -20 \\ -11 \end{bmatrix}, \begin{bmatrix} 19 \\ 29 \\ 16 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right)$$

$$\text{Let's prove it: } \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} = C(B'', B) T(\varphi, A, B) C(A, A'')$$

$$\begin{bmatrix} -13 & 19 & 0 \\ -20 & 29 & 0 \\ -11 & 16 & 1 \end{bmatrix}^{-1} \begin{bmatrix} -13 & 19 & -7 \\ -20 & 29 & -11 \\ -11 & 16 & -6 \end{bmatrix} \begin{bmatrix} 1 & 0 & -2 \\ 0 & 1 & -1 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 29/3 & -19/3 & 0 \\ 20/3 & -13/3 & 0 \\ -1/3 & -1/3 & 1 \end{bmatrix} \begin{bmatrix} -13 & 19 & 0 \\ -20 & 29 & 0 \\ -11 & 16 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

4. (2 points) Let $\mathcal{A} = (\mathbf{a}_1, \mathbf{a}_2, \mathbf{a}_3, \mathbf{a}_4)$ be an ordered basis for a vector space V , $\mathcal{B} = (\mathbf{b}_1, \mathbf{b}_2, \mathbf{b}_3)$ be an ordered basis for a vector space W , and $\mathcal{C} = (\mathbf{c}_1, \mathbf{c}_2, \mathbf{c}_3, \mathbf{c}_4, \mathbf{c}_5)$ be an ordered basis for a vector space Z . Then, it can be easily verified that $\mathcal{E} = (3\mathbf{a}_1 + 2\mathbf{a}_3 - \mathbf{a}_4, 4\mathbf{a}_2 + 3\mathbf{a}_3 - \mathbf{a}_4, \mathbf{a}_1 + \mathbf{a}_2 + \mathbf{a}_3, \mathbf{a}_1 - \mathbf{a}_2 - \mathbf{a}_3 + \mathbf{a}_4)$ is an ordered basis for V , both $\mathcal{F} = (3\mathbf{b}_1 + \mathbf{b}_3, -\mathbf{b}_1 + \mathbf{b}_2, \mathbf{b}_1 + \mathbf{b}_2 + \mathbf{b}_3)$ and $\mathcal{G} = (2\mathbf{b}_1 - 2\mathbf{b}_2 + \mathbf{b}_3, \mathbf{b}_1 + \mathbf{b}_2, 2\mathbf{b}_1 - \mathbf{b}_2 + \mathbf{b}_3)$ are ordered bases for W , and $\mathcal{H} = (\mathbf{c}_1 + \mathbf{c}_2, \mathbf{c}_2 + \mathbf{c}_3, \mathbf{c}_3, \mathbf{c}_4 + \mathbf{c}_5, \mathbf{c}_5)$ is an ordered basis for Z . Suppose that linear transformations $\varphi \in \mathcal{L}(V, W)$ and $\psi \in \mathcal{L}(W, Z)$ are given by the coordinate matrices:

$$T(\varphi, \mathcal{E}, \mathcal{F}) = \begin{bmatrix} 1 & 1 & -7 & 1 \\ 0 & -2 & 3 & -2 \\ 2 & 0 & -3 & 2 \end{bmatrix} \quad \text{and} \quad T(\psi, \mathcal{G}, \mathcal{H}) = \begin{bmatrix} 1 & 1 & -7 \\ 0 & -2 & 3 \\ 1 & 1 & -3 \\ -1 & 0 & 1 \\ 2 & -1 & -2 \end{bmatrix}.$$

Then, find $T(\psi \circ \varphi, \mathcal{A}, \mathcal{C})$.

[hint: see a similar problem from Seminar 19]

Novosad Ivan!

$$A = (\bar{a}_1; \bar{a}_2; \bar{a}_3; \bar{a}_4) \text{ for } V$$

$$E = \begin{pmatrix} 3\bar{a}_1 + 2\bar{a}_3 - \bar{a}_4 & 4\bar{a}_2 + 3\bar{a}_3 - \bar{a}_4 \\ \bar{a}_1 + \bar{a}_2 + \bar{a}_3 & \bar{a}_1 - \bar{a}_2 - \bar{a}_3 + \bar{a}_4 \end{pmatrix} \text{ for } V$$

$$B = (\bar{b}_1; \bar{b}_2; \bar{b}_3) \text{ for } W$$

$$F = (3\bar{b}_1 + \bar{b}_3; -\bar{b}_1 + \bar{b}_2; \bar{b}_1 + \bar{b}_2 + \bar{b}_3) \text{ for } W$$

$$G = (2\bar{b}_1 - 2\bar{b}_2 + \bar{b}_3; \bar{b}_1 + \bar{b}_2; 2\bar{b}_1 - \bar{b}_2 + \bar{b}_3) \text{ for } W$$

$$C = (\bar{c}_1; \bar{c}_2; \bar{c}_3; \bar{c}_4; \bar{c}_5) \text{ for } Z$$

$$H = (\bar{c}_1 + \bar{c}_2; \bar{c}_2 + \bar{c}_3; \bar{c}_3; \bar{c}_4 + \bar{c}_5; \bar{c}_5) \text{ for } Z$$

$$\text{req: } T(\psi \circ \varphi, A, C) = \underline{T(\psi, B, C)} \cdot \underline{T(\varphi, A, B)}$$

$$T(\varphi, E, F) : (V, E) \xrightarrow{\varphi} (W, F) \\ \Downarrow \\ (V, A) \xrightarrow{\varphi} (W, B)$$

$$\underline{T(\varphi, A, B)} = C(B, F) \cdot T(\varphi, E, F) \cdot C(E, A)$$

$$B = (\bar{b}_1; \bar{b}_2; \bar{b}_3) \quad F = (3\bar{b}_1 + \bar{b}_3; -\bar{b}_1 + \bar{b}_2; \bar{b}_1 + \bar{b}_2 + \bar{b}_3)$$

$$E = \begin{pmatrix} 3\bar{a}_1 + 2\bar{a}_3 - \bar{a}_4 & 4\bar{a}_2 + 3\bar{a}_3 - \bar{a}_4 \\ \bar{a}_1 + \bar{a}_2 + \bar{a}_3 & \bar{a}_1 - \bar{a}_2 - \bar{a}_3 + \bar{a}_4 \end{pmatrix} \quad A = (\bar{a}_1; \bar{a}_2; \bar{a}_3; \bar{a}_4) \text{ for } V$$

$$C(B, F) = \begin{bmatrix} 3 & -1 & 1 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix} \quad C(A, E) = \begin{bmatrix} 3 & 0 & 1 & 1 \\ 0 & 4 & 1 & -1 \\ 2 & 3 & 1 & -1 \\ -1 & -1 & 0 & 1 \end{bmatrix}$$

$$T(\psi, B, C) = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & -7 \\ 0 & -2 & 3 \\ 1 & 1 & -3 \\ -1 & 0 & 1 \\ 2 & -1 & -2 \end{bmatrix} \begin{bmatrix} 2 & 1 & 2 \\ -2 & 1 & -1 \\ 1 & 0 & 1 \end{bmatrix}^{-1} =$$

$$= \begin{bmatrix} 1 & 1 & -7 \\ 1 & -1 & -4 \\ 1 & -1 & 0 \\ -1 & 0 & 1 \\ 1 & -1 & -1 \end{bmatrix} \begin{bmatrix} 1 & -1 & -3 \\ 1 & 0 & -2 \\ -1 & 1 & 4 \end{bmatrix} = \underline{\underline{\begin{bmatrix} 9 & -8 & -33 \\ 4 & -5 & -17 \\ 0 & -1 & -1 \\ -2 & 2 & 7 \\ 1 & -2 & -5 \end{bmatrix}}}$$

$$T(\varphi, A, B) = \begin{bmatrix} 3 & -1 & 1 \\ 0 & 1 & 1 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 & -7 & 1 \\ 0 & -2 & 3 & -2 \\ 2 & 0 & -3 & 2 \end{bmatrix} \begin{bmatrix} 3 & 0 & 1 & 1 \\ 0 & 4 & 1 & -1 \\ 2 & 3 & 1 & -1 \\ -1 & -1 & 0 & 1 \end{bmatrix}^{-1} =$$

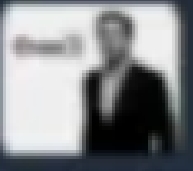
$$= \begin{bmatrix} 5 & 5 & -27 & 7 \\ 2 & -2 & 0 & 0 \\ 3 & 1 & -10 & 3 \end{bmatrix} \begin{bmatrix} 1 & 1 & -2 & -2 \\ 2 & 3 & -5 & -4 \\ -5 & -7 & 13 & 11 \\ 3 & 4 & -7 & -5 \end{bmatrix} = \begin{bmatrix} 171 & 237 & -435 & -362 \\ -2 & -4 & 6 & 4 \\ 64 & 88 & -162 & -135 \end{bmatrix}$$

$$T(\psi \circ \varphi, A, C) = \begin{bmatrix} 9 & -8 & -33 \\ 4 & -5 & -17 \\ 0 & -1 & -1 \\ -2 & 2 & 7 \\ 1 & -2 & -5 \end{bmatrix} \begin{bmatrix} 171 & 237 & -435 & -362 \\ -2 & -4 & 6 & 4 \\ 64 & 88 & -162 & -135 \end{bmatrix}$$

$$\begin{bmatrix} -557 & -739 & 1383 & 1165 \\ -394 & -528 & 984 & 827 \\ -62 & -84 & 156 & 131 \\ 102 & 134 & -252 & -213 \\ -145 & -195 & 363 & 305 \end{bmatrix}$$

Ans

Ans for checking

Vladislav 

Это типа как задача в 1 классе, где надо верно сопоставить буквы а, б, в с числами 1, 2, 3, но только легче, потому что любой ответ будет правильный))

11:18 AM