

# Assignment1(Group 18)

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## Ex.1

(i)Consider using unbounded array to realise the list. We only consider *append(insert)* and *delete* operations since other operations rely on them.

Each *append/insert* operation is  $O(1)$  and we assume the cost is 1 and we consider the *delete* operation as the last operation. Suppose there are  $n_0$  elements in the list now, we consider the sequence of *append/insert* operations after the previous *delete* operation.

There is at least  $n_0$  *append/insert* operations and the total cost is  $n_0$ .

The *delete* operation has a cost  $k$  and  $k \leq n_0$ , so we let the cost be  $n_0$ . And if the *delete* operation makes a deallocation (before or after), which will copy at most  $n_0$  to a new list, so the cost is also  $n_0$ . We can *deallocate* at most  $\log_2(n_0)$  times each time the cost will be  $n_0/2, n_0/4 \dots$  The total cost of *deallocate* is no more than  $2n_0$ . Thus for the operation sequence before last *delete* (or from an empty list), the total cost is no more than  $4n_0$ , the amortised complexity is  $O(\frac{4n_0}{n_0}) = O(1)$  for each operation.

For double-linked list, the *insert* cost is the same  $n_0$  from one *delete* to the next, and the cost of *delete* is  $n_0$  because no deallocation we need to do. The total cost of at most  $n_0$  operations are  $2n_0$ , thus the amortised complexity is  $O(\frac{2n_0}{n_0}) = O(1)$ .

In both cases, the complexity is  $O(1)$ , independent of  $k$ .

## Ex.2

(i)Since if the list  $l$  and parameters  $[e, f, g]$  are determined, the result of  $src[e, f, g]$  is also uniquely defined, the well-defined conditions are those that ensure the uniqueness of the result with given parameters.

For any split of a list  $l, l = l_1 + l_2, g(src[e, f, g](l_1), src[e, f, g](l_2)) = src[e, f, g](l)$  must be the same.

Or we can see  $g$  is associative with respect to the concatenation of the same (sub)list  $l$ .

$l = l_1 + l_2 + l_3$  then  $g(src[e, f, g](l_1), g(src[e, f, g](l_2), src[e, f, g](l_3))) = src[e, f, g](l_1 + l_2 + l_3) = g(g(src[e, f, g](l_1), src[e, f, g](l_2)), src[e, f, g](l_3))$

Also we have a natural element  $e$  of  $g$  such that  $g(src[e, f, g](l), e) = g(e, src[e, f, g](l)) = g(src[e, f, g](l), src[e, f, g](\square)) = src[e, f, g](l)$ .

(ii)(1) Let the length function  $len(l) = src[0, 1, +](l)$ , we let

$$\begin{aligned} len(\square) &= e = 0 \\ len([x]) &= f(x) = 1 \\ len(l_1 + l_2) &= g(len(l_1), len(l_2)) = len(l_1) + len(l_2) \\ T' &= N_{\geq 1} \end{aligned}$$

(2) Let the function implemented is  $F : T \rightarrow P$ , let  $func(l) = src[\square, [F(x)], +](l)$ , which  $+$  operation concatenates two lists. Then we have

$$\begin{aligned} func(\square) &= e = \square \\ func([x]) &= f(x) = [F(x)] \\ func(l_1 + l_2) &= g(func(l_1), func(l_2)) = func(l_1) + func(l_2) \\ T' &= \{l'\} \end{aligned}$$

where  $l'$  are lists with elements  $\in P$ .

(3) Let the sub function  $sub(l) = src[\square, f(x), +](l)$ , we have

$$\begin{aligned} sub(\square) &= e = \square \\ sub([x]) &= f(x) = \begin{cases} [x], & \varphi(x) \\ \square, & else \end{cases} \\ sub(l_1 + l_2) &= g(sub(l_1), sub(l_2)) = sub(l_1) + sub(l_2) \\ T' &= \{l'' | l'' \subset l\} \end{aligned}$$

(iii) Let the length of the whole list be  $n$ , let  $x, x \in T$  be a single element of the list, let  $y_1, y_2 \in T'$ .

We apply  $f(x)$  exactly  $n$  times and  $g(y_1, y_2)$  exactly  $n - 1$  times, suppose each time cost of  $f(x)$  is  $T_f$ , each time cost of  $g(y_1, y_2)$  is  $T_g$ , the total complexity is  $O(n * T_f + (n - 1) * T_g) = O(n * \max(T_f, T_g))$

Since the complexity of  $g$  may depend on how the list is realised and how to do the structural recursion (e.g. When we want to combine sublists, the complexity of  $g$  varies with your strategies), the real complexity will improve if choosing more effective ways to implement  $f$  and  $g$ .

Furthermore, the complexity of  $f(x)$  and  $g(y_1, y_2)$  also changes with different parameters, so we use the average time, the total complexity is  $O(n * \max(\overline{T_f}, \overline{T_g}))$ .

## Ex.3

(i)*pushback(l, x)* can be expressed by *append(l, x)*.

*pushfront(l, x)* can be expressed by *insert(l, 1, x)*.

*popback(l)* can be expressed by  $n = l.getlength()$  and *l.getitem(n)* and *remove(l, n)*.

*popfront(l)* can be expressed by *l.getitem(1)* and *remove(l, 1)*.